

```
class Car():

    def __init__(self, make, model, year):

        self.make = make

        self.model = model

        self.year = year

        self.odometer_reading = 0

    def get_descriptive_name(self):

        long_name = str(self.year) + ' ' + self.make + ' ' + self.model

        return long_name.title()

    def read_odometer(self):

        print("This car has " + str(self.odometer_reading) + " miles on it.")

    def update_odometer(self, mileage):

        if mileage >= self.odometer_reading:

            self.odometer_reading = mileage

        else:

            print("You can't roll back an odometer!")

    def increment_odometer(self, miles):

        self.odometer_reading += miles

class Battery():
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def __init__(self, battery_size=60):

    self.battery_size = battery_size


def describe_battery(self):

    print("This car has a " + str(self.battery_size) + "-kWh battery.")


def get_range(self):

    if self.battery_size == 70:

        range = 240

    elif self.battery_size == 85:

        range = 270

    message = "This car can go approximately " + str(range)

    message += " miles on a full charge."

    print(message)

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class ElectricCar(Car):

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    def __init__(self, make, model, year):

        super().__init__(make, model, year)

        self.battery = Battery()

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c1 = car("Audi", "A4" , 2016)

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C2 = Electric_car("Tesa", "Model S", 2016)

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print(c1.get_full_name())

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print(c2.get_full_name())
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c1.increment_odometer(30)
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c2.increment_odometer(60)
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```
c1.print_odometer()
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```
c2.print_odometer()c2.battery.print_range()
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