

Information Processing and the Brain 2019/2020

Course work #2: The different forms of learning in the brain

For this course work you are asked to implement and explore the behaviour of one classical supervised, reinforcement or unsupervised learning algorithm, and discuss how they relate to learning in the brain. You only need to select one of the topics below. You can choose your language of preference, but we would recommend using Python or Matlab. **Deadline: 6th December at noon (i.e. 12:00pm).**

1. Supervised: The backpropagation algorithm

The backpropagation algorithm is often used in machine learning to solve the credit assignment problem. Here you are going to contrast its different elements (e.g. error backpropagation, or symmetric weights) to how the brain is organised. You should use a simple feedforward neural network with one hidden layer and sigmoidal units to teach the network to compute logic gates (AND, OR *and* XOR). Do not use autograd tools as in pytorch for this simple task. You are asked to include a snippet of your code in your report. *Note:* Although here you are asked to implement the backprop algorithm in a supervised setting, backprop is also used in unsupervised (e.g. autoencoders) and reinforcement learning (e.g. deep RL). Optional: Test your network with the widely used handwritten digit recognition dataset ([MNIST](#)).

You can use these papers as *references* when contrasting backprop with the brain:

- Blake and Lillicrap, Dendritic solutions to the credit assignment problem, Current Opinion in Neurobiology 2018 ([link](#))
- Sacramento et al., Neural Information Processing Systems 2018 ([link](#))

2. Reinforcement: Temporal difference learning

Implement the basic TD learning algorithm (i.e. tabular TD(0)) to find a good path (given by a policy) for an agent exploring the environment from a starting point to a reward location in a simple environment. You will use the classical gridworld formulation of reinforcement learning. Use the following grid structure (or variations):

| | | | | | | | |
|---|---|---|---|---|---|---|--|
| | | | | | | | |
| | W | W | W | W | W | | |
| | W | E | | | W | | |
| | | W | | | W | W | |
| | | W | | | | | |
| S | W | | | | | | |

Where **S** is the starting location and **E** the end location where reward is received. **W** represent walls, which can not be crossed over. The output of the algorithm should

be the strategy taken (i.e. set of actions) given by the value $V(S)$ and a specific policy, for example:

| | | | | | | | |
|---|---|---|---|---|---|---|---|
| 3 | 3 | 3 | 3 | 3 | 3 | 3 | 2 |
| 1 | W | W | W | W | W | 3 | 2 |
| 1 | W | E | 4 | 4 | W | 1 | 2 |
| 1 | 4 | W | 3 | 1 | W | W | 2 |
| 1 | 4 | W | 2 | 1 | 3 | 3 | 2 |
| S | W | 3 | 4 | 1 | 4 | 4 | 4 |

1 - Up; 2 - Down; 3 - Right; 4 - Left (these are the only possible actions)
You should also show the value function and plot how this changes over learning.

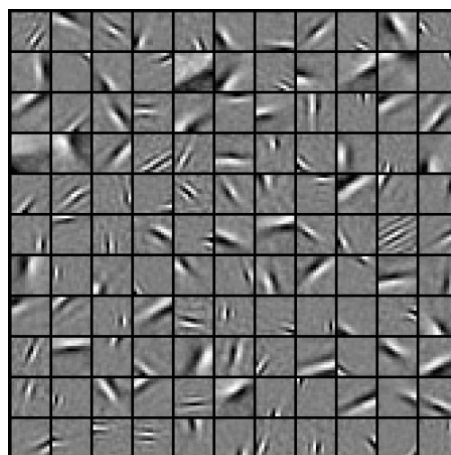
As the policy you can either use a deterministic one (e.g. always take the highest value) or a stochastic one (e.g. random exploration or epsilon-greedy). This [applet](#) should help.

References:

Sutton and Barto 1998/2018 (Chapter 6, available [here](#));
[W Schultz](#), [P Dayan](#), [PR Montague](#) 1997 [Science](#)

3. Unsupervised: Sparse coding

Implement the classical sparse coding model of [Olshausen and Field 1996 Nature](#) for extracting features from natural images. Use the same natural images used in that paper available [here](#) and the algorithm described in the paper/lectures. Note that they also provide Matlab/C code, but you should give your own implementation. You should obtain receptive fields/weights similar to these ones:



References: [Ko et al Nature 2011](#) (recent experimental paper demonstrating orientation/edge selectivity in the visual cortex).

Questions

For the topic you have chosen you should implement the algorithm from scratch and address the following points:

1. How does the algorithm work? Plot the different components of the algorithm over learning to help you explain its behaviour (e.g. what are the weight changes given by backprop, how the policy/value function of TD-learning changes over learning, or/and plot the features/weights at different points during learning). You should also plot the performance (i.e. cost or value) of the algorithm over learning iterations (i.e. the learning curve). You should include a snippet of the key component of your code in your report. [3/10 marks, max 500 words]
2. How does the algorithm relate to the brain? For example, which brain areas might implement it, and/or which neural circuits? Does it explain particular data observed in neuroscience? [3/10 marks, max 500 words]
3. Discuss what are its key advantages over the other two learning algorithms/paradigms both in terms of performance/data needs and biological plausibility. [2/10 marks, max 200 words]
4. What about disadvantages in terms of performance/data needs and biological plausibility? And how could this be improved upon? [2/10 marks, max 200 words]

Submit your report on Blackboard (IPB > Assessment, submission and feedback). No need to submit your full code (only add a snippet in the report), only the report in pdf or similar.

Note 1: Where possible cite papers and/or use simulations/plots to support your claims.

Note 2: Collaborative work is encouraged (e.g. for coding and understanding of the algorithm), but every submission should be individual/unique.

Other relevant references:

- Doyak, Complementary roles of basal ganglia and cerebellum in learning and motor control. Curr Opin Neurobiol (2000) ([link](#)) [This review points out how different brain areas can be mapped onto *unsupervised learning*, *supervised learning* and *reinforcement learning*.]