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// Class that represents a directed graph.
class Graph {
    // Representation of the graph:
    // * The graph is represented by 3 ordered dictionaries (std::map),
    //   one that stores the inbound edges for each vertex, one that stores
    //   the outbound edges for each vertex, and one that stores the cost
    //   associated to each edge.
    // * The existence of a vertex can be checked by simply checking if it
    //   exists as a key in either the `_inbound` or `_outbound` dictionaries.
    // * The existence of an edge can be checked by simply checking if it exists
    //   as a key in the `_cost` dictionary.
    // * The Graph class contains a default constructor, copy constructor and
    //   move constructor, so copying the data from one graph to another is as
    //   easy as writing `Graph g2 = g;`.
    std::map<int, std::vector<int>> _inbound, _outbound;
    std::map<std::pair<int, int>, int> _cost;

public:
    // Creates a graph with `vertexCount` vertices numbered from 0
    // to `vertexCount` - 1, and `edgeCount` randomly generated edges.
    // Throws: std::invalid_argument if `edgeCount` > `vertexCount` ^ 2.
    static Graph randomGraph(int vertexCount, int edgeCount);

    // Reads a graph from the given stream, which is expected
    // to be in the "old" format (that assumes the graph contains all
    // vertices from 0 to n - 1).
    // Throws: std::invalid_argument if edge count > vertex count ^ 2.
    static Graph fromStreamOld(std::istream& is);

    // Returns the number of vertices in the graph.
    int vertexCount() const;

    // Checks whether the graph contains the specified vertex.
    // Returns: `true` if the vertex exists in the graph, otherwise `false`.
    bool isVertex(int vertex) const;

    // Returns a vector containing all vertices in the graph, in ascending order.
    std::vector<int> vertices() const;

    // Checks whether there exists an edge between the 2 vertices.
    // Returns: `true` if there exists an edge between the 2 vertices,
    // otherwise `false`.
    // Throws: std::out_of_range if either of the vertices is not in the graph.
    bool existsEdge(int vertex1, int vertex2) const;

    // Returns the in degree of the specified vertex.

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// Throws: std::out_of_range if the specified vertex is not in the graph.
int inDegree(int vertex) const;

// Returns the out degree of the specified vertex.
// Throws: std::out_of_range if the specified vertex is not in the graph.
int outDegree(int vertex) const;

// Returns a vector containing all the inbound edges of the specified vertex.
// Throws: std::out_of_range if the specified vertex is not in the graph.
// Law: forall v. forall v2 in inbound(v). existsEdge(v2, v)
const std::vector<int>& inbound(int vertex) const;

// Returns a vector containing all the outbound edges of the specified vertex.
// Throws: std::out_of_range if the specified vertex is not in the graph.
// Law: forall v. forall v2 in outbound(v). existsEdge(v, v2)
const std::vector<int>& outbound(int vertex) const;

// Returns the cost associated to the edge between `vertex1` and `vertex2`.
// Throws:
//   * std::out_of_range if either vertex is not in the graph.
//   * std::invalid_argument if there is no edge between vertex1 and vertex2.
int getCost(int vertex1, int vertex2) const;

// Sets the cost associated to the edge between `vertex1` and `vertex2` to
// be equal to `cost`.
// Throws:
//   * std::out_of_range if either vertex is not in the graph.
//   * std::invalid_argument if there is no edge between vertex1 and vertex2.
void setCost(int vertex1, int vertex2, int cost);

// Adds a new edge between `vertex1` and `vertex2`, with the cost equal
// to `cost`.
// Throws:
//   * std::out_of_range if either vertex is not in the graph.
//   * std::invalid_argument if there already exists an edge between
//     vertex1 and vertex2.
void addEdge(int vertex1, int vertex2, int cost);

// Removes the edge between `vertex1` and `vertex2`.
// Throws:
//   * std::out_of_range if either vertex is not in the graph.
//   * std::invalid_argument if there is no edge between vertex1 and vertex2.
void removeEdge(int vertex1, int vertex2);

// Adds the specified vertex to the graph.
// Throws: std::invalid_argument if the vertex already exists.

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void addVertex(int vertex);

// Removes the specified vertex from the graph.
// Throws: std::invalid_argument if the vertex is not in the graph.
void removeVertex(int vertex);
};

// Reads a graph from the given stream.
inline std::istream& operator >>(std::istream& is, Graph& g);

// Writes the graph to the stream.
inline std::ostream& operator <<(std::ostream& os, const Graph& g);

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