Tools and Algorithms for Deciding Timed Relations

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Mihir Mehta

Department of Computer Science and Engineering Indian Institute of Technology, Delhi.

cs1090197@cse.iitd.ac.in

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Overview

- Bisimilarity and related notions
- Kanellakis and Smolka's algorithm
- Fernandez' algorithm
- Paige and Tarjan's algorithm
- Timed Automata
- Equivalences on Timed Automata
- Code written so far

Bisimilarity and related notions

- ► Labeled Transition System: This is a triple $(Proc, Act, \{\stackrel{a}{\rightarrow} | a \in Act\})$ where
 - Proc is a set of states (also called processes or configurations.)
 - Act is a set of actions (also called labels.)
 - ▶ $\stackrel{a}{\rightarrow}$ ⊆ $Proc \times Proc$ is a transition relation.
- ▶ CCS expression: Defined by the following grammar:
 - ▶ *P* ::= *K*
 - $P ::= \alpha.P$
 - \triangleright $P ::=_{i \in I} P_i$
 - P := P | Q
 - ▶ P ::= P[f]
 - ▶ *P* ::= *P*Ł

Bisimilarity and related notions

- Equivalence for CCS processes.
- ▶ Trace equivalence: Traces(P) = Traces(Q)
- Unsatisfactory (differences in deadlock behaviour.)
- ▶ Strong bisimulation: A binary relation R is a strong bisimulation if and only if, for all $(s_1, s_2)\epsilon R$ and $a\epsilon Act$. $\forall s_1'(s_1 \xrightarrow{a} s_1' \Rightarrow \exists s_2'.(s_2 \xrightarrow{a} s_2' \land (s_1', s_2')\epsilon R)) \land \forall s_2'(s_2 \xrightarrow{a} s_2' \Rightarrow \exists s_1'.(s_1 \xrightarrow{a} s_1' \land (s_1', s_2')\epsilon R))$
- It can be shown that the union of all strong bisimulations over the set of states is a strong bisimulation. This binary relation is called *strong bisimilarity*, denoted by \sim .

Bisimilarity and related notions

- Better notion of equivalence than trace equivalence: picks up differences in the deadlock behaviour of processes under study.
- ightharpoonup Failing: does not account for the invisible nature of au transitions in CCS processes.
- ▶ Weak bisimulation: A binary relation R is a weak bisimulation if and only if, for all $(s_1, s_2) \in R$ and $a \in Act$.

$$\forall s_1'(s_1 \xrightarrow{a} s_1' \Rightarrow \exists s_2'.(s_2 \xrightarrow{a} s_2' \land (s_1', s_2') \in R)) \land \forall s_2'(s_2 \xrightarrow{a} s_2' \Rightarrow \exists s_1'.(s_1 \xrightarrow{a} s_1' \land (s_1', s_2') \in R))$$

- It can be shown that the union of all weak bisimulations over the set of states is a weak bisimulation. This binary relation is called *weak bisimilarity*, denoted by \approx .
- ▶ Better suited to CCS processes, as it ignores τ transitions, thus disregarding hidden behaviour within a process.

Kanellakis and Smolka's algorithm

- This is a naive algorithm for determining the bisimilarity relation for the set of processes in a labelled transition system.
- ▶ This relies on the notion of a splitter.
- Let $\pi = \{B_0, ..., B_k\}, k \ge 0$ be a partition of the set of states Pr in a labeled transition system.
- ▶ A splitter for a block B_i ϵ π is a block B_j ϵ π such that for some action a ϵ Act, some states in B_i have a-labelled transitions whose targets lie in B_j while other states in B_i do not.
- ▶ This suggests a refinement of π : replace block B_i with $B_i^1 = B_i \cap T_a^{-1}[B_j]$ $B_i^2 = B_i B_i^1$
- ▶ Refinements of this kind constitute the steps of this algorithm.

Kanellakis and Smolka's algorithm

Return π ;

```
Initialise \pi to Pr;

while there exist splitters among the elements of \pi do

Pick a splitter B;

foreach B_j \in \pi do

foreach a \in Act do

Split B_j with respect to B for action a;

end

end

end
```

▶ The time complexity of this algorithm is O(mn), since there can be at most n iterations, and all m edges are scanned in each iteration.

Fernandez' algorithm

- ▶ More efficient algorithm (O(m log n)).
- Relies on Paige and Tarjan's technique of three-way splitting.
- Splitters can now be 'simple' or 'compound'.
- Stability: A partition π is said to be stable with respect to a compound block S if S is not a splitter for any block in π for any action.
- ▶ For a compound block S, having a constituent simple block B satisfying $n(B) \le 0.5 * n(S)$, and with respect to which π is stable, we can split a block B_i on an action a as follows:

$$B_i^1 = (B_i \cap T_a^{-1}[B]) - T_a^{-1}[S - B]$$

$$B_i^2 = (B_i \cap T_a^{-1}[S - B]) - T_a^{-1}[B]$$

$$B_i^3 = B_i \cap T_a^{-1}[B] \cap T_a^{-1}[S - B]$$

Fernandez' algorithm

```
Initialise \pi = \{Pr\};
Initialise W = \{Pr\} while W is not empty do
   Choose a splitter B from W, removing it;
   if B is a simple splitter then
       Perform a two-way split on each action with respect to B
       and update W;
   else
       Perform a three-way split on each action with respect to B
       and update W;
   end
end
```

Paige and Tarjan's Algorithm

- ► Technique of three way splitting came from here.
- Special case of Fernandez' algorithm when there's only one kind of action.

Timed Automata

- ▶ Formally, a timed automaton over a finite set of clocks C and a finite set of actions Act is a 4-tuple (L, I_0, E, I) .
- L is a finite set of locations.
- I₀ is the initial location.
- ▶ $E \subseteq L \times B(C) \times Act \times 2^C \times L$ is a finite set of edges.
- ▶ $I: L \rightarrow B(C)$ assigns invariants to each edge location.
- ▶ B(C) is the set of clock constraints over C. An element of B(C) can be an equality, a slack inequality, a strict inequality, or an AND combination of such constraints.

- ▶ Timed bisimulation: A binary relation R is a timed bisimulation if and only if, for all $(s_1, s_2) \in R$, $a \in Act$, $d \in R_{\geq 0}$ $\forall s_1'(s_1 \xrightarrow{a} s_1' \Rightarrow \exists s_2'.(s_2 \xrightarrow{a} s_2' \land (s_1', s_2') \in R)) \land \forall s_2'(s_2 \xrightarrow{a} s_2' \Rightarrow \exists s_1'.(s_1 \xrightarrow{a} s_1' \land (s_1', s_2') \in R)) \land \forall s_1'(s_1 \xrightarrow{d} s_1' \Rightarrow \exists s_2'.(s_2 \xrightarrow{d} s_2' \land (s_1', s_2') \in R)) \land \forall s_2'(s_2 \xrightarrow{d} s_2' \Rightarrow \exists s_1'.(s_1 \xrightarrow{d} s_1' \land (s_1', s_2') \in R))$
- ▶ It can be shown that the union of all timed bisimulations over the set of (location, valuation) pairs is a timed bisimulation. This binary relation is called *timed bisimilarity*, denoted by ~.

► Time abstracted bisimulation: A binary relation R is a time abstracted bisimulation if and only if, for all $(s_1, s_2)\epsilon R$, $a\epsilon Act$, $d\epsilon R_{>0}$

$$\forall s_{1}'(s_{1} \xrightarrow{a} s_{1}' \Rightarrow \exists s_{2}'.(s_{2} \xrightarrow{a} s_{2}' \wedge (s_{1}', s_{2}') \epsilon R)) \wedge$$

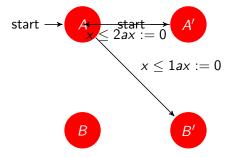
$$\forall s_{2}'(s_{2} \xrightarrow{a} s_{2}' \Rightarrow \exists s_{1}'.(s_{1} \xrightarrow{a} s_{1}' \wedge (s_{1}', s_{2}') \epsilon R)) \wedge$$

$$\forall s_{1}'(s_{1} \xrightarrow{d} s_{1}' \Rightarrow \exists (s_{2}', d').(s_{2} \xrightarrow{d'} s_{2}' \wedge (s_{1}', s_{2}') \epsilon R)) \wedge$$

$$\forall s_{2}'(s_{2} \xrightarrow{d} s_{2}' \Rightarrow \exists (s_{1}', d').(s_{1} \xrightarrow{d'} s_{1}' \wedge (s_{1}', s_{2}') \epsilon R)) \wedge$$

It can be shown that the union of all time abstracted bisimulations over the set of (location, valuation) pairs is a time abstracted bisimulation. This binary relation is called time abstracted bisimilarity, denoted by \sim_u .

- ▶ Equivalence of valuations: Two valuations v and v' of a timed automaton are said to be equivalent $(v \equiv v')$ if and only if:
 - ▶ For each $x \in C$, either both v(x) and v'(x) are greater than c_x or $\lfloor v(x) \rfloor = \lfloor v'(x) \rfloor$
 - ▶ For each $x \in C$ such that $v(x) \le c_x$, frac(v(x)) = 0 if and only if frac(v'(x)) = 0.
 - ▶ For all $x, y \in C$ such that $v(x) \le c_x$ and $v(y) \le c_y$, we have $frac(v(x)) \le frac(v(y))$ if and only if $frac(v'(x)) \le frac(v'(y))$.
- ► Under this notion of equivalence, an equivalence class is known as a region. The equivalence class containing a valuation v is denoted by [v]₌.



Region graph: the region graph of a timed automaton A with clock set C and action set Act is an LTS

clock set
$$C$$
 and action set Act is an LTS $T_r(A) = (Proc, Act \cup \{\varepsilon\}, \{\stackrel{a}{\rightarrow} | a\epsilon Act \cup \{\varepsilon\}\})$ where $Proc = \{(I, [v]_{\equiv}) | I\epsilon L, v : C \rightarrow R_{\geq 0}\}$ (these states are called symbolic states)

The transitions are defined as follows:

- ► For each $a \in A$, $(I, [v]_{\equiv}) \stackrel{a}{\Rightarrow} (I', [v']_{\equiv})$ iff $(I, v) \stackrel{a}{\rightarrow} (I', v')$
- ▶ $(I, [v]_{\equiv}) \xrightarrow{a} (I, [v']_{\equiv})$ if for some $d \in R_{\geq 0}$, $(I, v) \xrightarrow{d} (I, v')$

► Extended Clock Constraints: These are described by the grammar

$$g ::= x \bowtie n | x - y \bowtie n | g_1 \wedge g_2$$

- ▶ The set of extended clock constraints is denoted by $B^+(C)$
- Zones: A zone is a set of valuations represented by an extended clock constraint.

$$Z = v | v \epsilon g_Z$$

▶ Symbolic state: For a timed automaton A, a symbolic state is an ordered pair of a location and a zone, that is, (I, Z).

- ► Reachability graph: The reachability graph of a timed automaton is a directed graph in which the nodes are symbolic states and the edges are given by the reachability relation:
 - (I, Z') is reachable from (I, Z) if there exists a valuation belonging Z' which can be obtained from Z by applying a time delay which does not violate the invariant at I.
 - (I', Z') is reachable from (I, Z) if I has an action transition to I' and there exists a valuation in Z' which violates neither the guard of the transition nor the invariant at I' after performing the clock resets required by the transition.

Code written so far

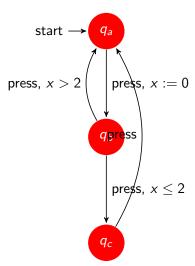
- ► Fernandez' algorithm: We expect to need this algorithm while building the software, so we built a module implementing it in Ocaml (primary language for this project.)
- ► Grammar: We implemented a lexer and parser in Ocaml to build a representation of a timed automaton from a specification in a text file.

Timed automaton example

```
states 3 trans 6 clocks 1 X
state: 0 invar: TRUE trans: TRUE => RESET X; goto 1
state: 1 invar: TRUE trans: X <= 2 => RESET ; goto 0 X
> 2 => RESET ; goto 2
state: 2 invar: TRUE trans: TRUE => RESET ; goto 0
```

Example taken from Reactive Systems

Timed automaton example



Timed automaton example

Regions in this graph:

$$[x = 0]_{\equiv}, [x = 1]_{\equiv}, [x = 2]_{\equiv}$$

•
$$[0 < x < 1]_{\equiv}$$
, $[1 < x < 2]_{\equiv}$

▶
$$[2 < x]_{\equiv}$$

References

 Reactive Systems: Modeling, Specification and Verification -Luca Aceto, Anna Ingolfsdottir, Kim Larsen, Jiri Srba.