**Li\_bot**

robond@udacity:~/catkin\_ws$ rostopic list

/amcl/parameter\_descriptions

/amcl/parameter\_updates

/amcl\_pose

/clicked\_point

/clock

/cmd\_vel

/gazebo/link\_states

/gazebo/model\_states

/gazebo/parameter\_descriptions

/gazebo/parameter\_updates

/gazebo/set\_link\_state

/gazebo/set\_model\_state

/initialpose

/joint\_states

/li\_bot/camera1/camera\_info

/li\_bot/camera1/image\_raw

/li\_bot/camera1/image\_raw/compressed

/li\_bot/camera1/image\_raw/compressed/parameter\_descriptions

/li\_bot/camera1/image\_raw/compressed/parameter\_updates

/li\_bot/camera1/image\_raw/compressedDepth

/li\_bot/camera1/image\_raw/compressedDepth/parameter\_descriptions

/li\_bot/camera1/image\_raw/compressedDepth/parameter\_updates

/li\_bot/camera1/image\_raw/theora

/li\_bot/camera1/image\_raw/theora/parameter\_descriptions

/li\_bot/camera1/image\_raw/theora/parameter\_updates

/li\_bot/camera1/parameter\_descriptions

/li\_bot/camera1/parameter\_updates

/li\_bot/laser/scan

/map

/map\_metadata

/move\_base/NavfnROS/plan

/move\_base/TrajectoryPlannerROS/cost\_cloud

/move\_base/TrajectoryPlannerROS/global\_plan

/move\_base/TrajectoryPlannerROS/local\_plan

/move\_base/TrajectoryPlannerROS/parameter\_descriptions

/move\_base/TrajectoryPlannerROS/parameter\_updates

/move\_base/cancel

/move\_base/current\_goal

/move\_base/feedback

/move\_base/global\_costmap/costmap

/move\_base/global\_costmap/costmap\_updates

/move\_base/global\_costmap/footprint

/move\_base/global\_costmap/inflation\_layer/parameter\_descriptions

/move\_base/global\_costmap/inflation\_layer/parameter\_updates

/move\_base/global\_costmap/obstacle\_layer/parameter\_descriptions

/move\_base/global\_costmap/obstacle\_layer/parameter\_updates

/move\_base/global\_costmap/parameter\_descriptions

/move\_base/global\_costmap/parameter\_updates

/move\_base/global\_costmap/static\_layer/parameter\_descriptions

/move\_base/global\_costmap/static\_layer/parameter\_updates

/move\_base/goal

/move\_base/local\_costmap/costmap

/move\_base/local\_costmap/costmap\_updates

/move\_base/local\_costmap/footprint

/move\_base/local\_costmap/inflation\_layer/parameter\_descriptions

/move\_base/local\_costmap/inflation\_layer/parameter\_updates

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/move\_base/local\_costmap/obstacle\_layer/parameter\_updates

/move\_base/local\_costmap/parameter\_descriptions

/move\_base/local\_costmap/parameter\_updates

/move\_base/parameter\_descriptions

/move\_base/parameter\_updates

/move\_base/result

/move\_base/status

/move\_base\_simple/goal

/odom

/particlecloud

/rosout

/rosout\_agg

/tf

/tf\_static

/udacity\_bot/laser/scan

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**Udacity\_bot**

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/move\_base/global\_costmap/obstacle\_layer/parameter\_updates

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/move\_base/global\_costmap/parameter\_updates

/move\_base/global\_costmap/static\_layer/parameter\_descriptions

/move\_base/global\_costmap/static\_layer/parameter\_updates

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/udacity\_bot/camera1/image\_raw/compressed/parameter\_updates

/udacity\_bot/camera1/image\_raw/compressedDepth

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/udacity\_bot/camera1/image\_raw/theora/parameter\_updates

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/udacity\_bot/camera1/parameter\_updates

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