1 AE332: Modelling and Analysis Lab

1.1 Session 3: Simulating Shells and Rockets

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```
[1]: import numpy as np
  import pandas as pd
  import matplotlib.pyplot as plt
  import scipy.integrate as sci
  import scipy.interpolate as inp
  import Atmosphere as atm
  from matplotlib.patches import Rectangle
  plt.rcParams['text.usetex'] = True
```

1.1.1 Importing the data from excel

```
[2]: df = pd.read_excel('data-shell.xlsx')
     print(df.head())
     CAjoff = np.array([[0.4309, 0.4331, 0.434, 0.4084, 0.3876, 0.4582, 0.461, 0.
      \rightarrow4688, 0.4953, 0.6134],
                [0.4683, 0.4709, 0.4729, 0.4599, 0.4171, 0.4716, 0.578, 0.5858, 0.
      \rightarrow6139, 0.7416],
                [0.6796, 0.6774, 0.6797, 0.67, 0.6197, 0.6678, 0.7619, 0.7686, 0.7932]
      \rightarrow 0.9058].
                [0.7946, 0.7922, 0.7945, 0.7867, 0.7334, 0.7771, 0.8632, 0.8694, 0.
      \rightarrow8922, 0.9964],
                [0.8887, 0.886, 0.8883, 0.8826, 0.8263, 0.8663, 0.9456, 0.9513, 0.
      \rightarrow 9724, 1.069],
                [0.9595, 0.9575, 0.9602, 0.9578, 0.8943, 0.9361, 1.0177, 1.023, 1.
      \rightarrow0426, 1.1323],
                [1.0027, 1.0004, 1.0031, 1.0036, 0.9379, 0.9756, 1.0529, 1.0578, 1.
      →0761, 1.1601],
                [0.842, 0.8389, 0.8413, 0.8445, 0.8003, 0.8048, 0.8664, 0.9805, 0.
      \rightarrow 9964, 1.0696],
                [0.7338, 0.7298, 0.7317, 0.7356, 0.7049, 0.6887, 0.7387, 0.832, 0.
      \rightarrow8455, 0.9076],
                [0.6602, 0.6552, 0.6567, 0.6605, 0.645, 0.611, 0.6512, 0.7246, 0.
      \rightarrow7357, 0.7873],
                [0.6441, 0.6389, 0.6402, 0.644, 0.6295, 0.5943, 0.6328, 0.7026, 0.
      \rightarrow7134, 0.7632],
                [0.62, 0.6142, 0.6153, 0.6186, 0.607, 0.5696, 0.6045, 0.6664, 0.
      \rightarrow6764, 0.7226],
                [0.5946, 0.5951, 0.5959, 0.5983, 0.5896, 0.5507, 0.5829, 0.6385, 0.
      \rightarrow6479, 0.6915],
```

```
[0.5499, 0.5502, 0.5508, 0.5526, 0.5454, 0.5062, 0.5363, 0.5867, 0.

→5958, 0.638],

[0.5347, 0.5349, 0.5352, 0.5366, 0.5311, 0.4915, 0.5199, 0.5659, 0.

→5747, 0.6154]

])
```

```
Mach CNAlpha
                  XCPLen MachJoff
                                     Hjoff
0
   0.2
          14.57 0.842868
                              0.4
                                       0.0
  0.4
          14.43 0.851050
                              0.6
1
                                    5000.0
2
  0.6
          14.86 0.850584
                              0.8 10000.0
   0.8
          15.16 0.848138
                              0.9 20000.0
3
   0.9
          15.67 0.851823
                               1.0 30000.0
```

1.1.2 Interpolation Functions

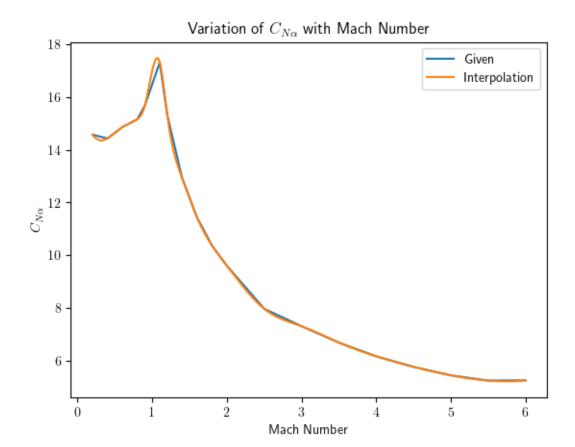
```
[3]: CNAlphaInterp = inp.interp1d(df.Mach, df.CNAlpha, kind='cubic')

CPInterp = inp.interp1d(df.Mach, df.CNAlpha, kind='cubic')

CAInterp = inp.RectBivariateSpline(df.MachJoff[:15], df.Hjoff[:10], CAjoff)
```

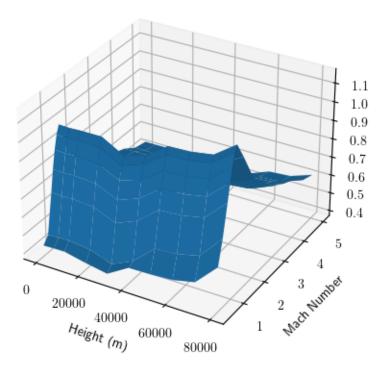
```
[4]: mach = np.linspace(0.2, 6, 10000)
  plt.plot(df.Mach, df.CNAlpha, label='Given')
  plt.plot(mach, CNAlphaInterp(mach),label='Interpolation')
  ax = plt.gca()
  ax.set_xlabel('Mach Number')
  ax.set_ylabel(r'$C_{N\alpha}$')
  plt.legend()
  ax.set_title(r'Variation of $C_{N\alpha}$ with Mach Number')
```

[4]: Text(0.5, 1.0, 'Variation of \$C_{N\alpha}\$ with Mach Number')



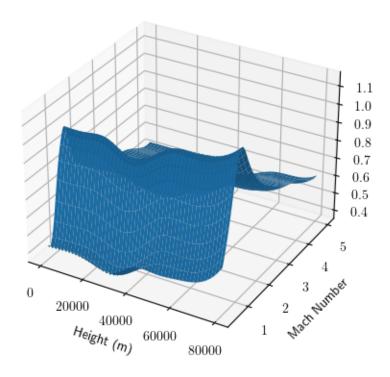
```
[5]: fig, ax = plt.subplots(subplot_kw={"projection": "3d"})
    xx, yy = np.meshgrid(df.Hjoff[:10], df.MachJoff[:15])
    surf = ax.plot_surface(xx,yy, CAjoff)
    plt.xlabel('Height (m)')
    plt.ylabel('Mach Number')
    plt.title(r'$C_A$ = $f($Mach Number, Height$)$')
    plt.show()
```

$C_A = f(\mathsf{Mach\ Number}, \mathsf{Height})$



```
fig, ax = plt.subplots(subplot_kw={"projection": "3d"})
hh = np.linspace(0, 80000, 100000)
mm = np.linspace(0.4, 5, 1000)
xx, yy = np.meshgrid(hh,mm)
surf = ax.plot_surface(xx, yy, CAInterp(mm,hh))
plt.xlabel('Height (m)')
plt.ylabel('Mach Number')
plt.title('2D Interpolation of Mach Number and Height to obtain $C_A$')
plt.show()
```

2D Interpolation of Mach Number and Height to obtain C_A

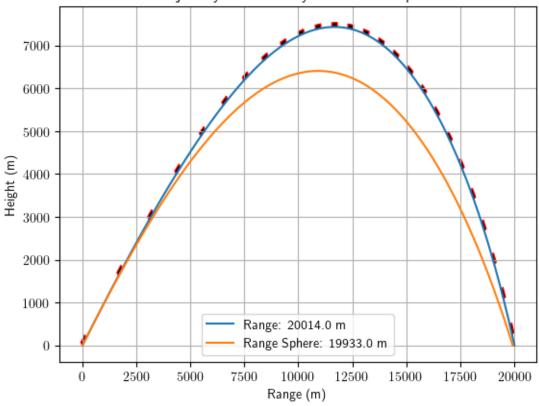


1.1.3 Simulation of Shell

```
[38]: 1 = 1.115
                            m = 40
                             I = 4.29
                             S = 80.12e-4
                             com = 0.70769
                             U = 867
                             g = 9.8
                             theta0 = np.radians(45)
                             sol0 = np.array([0, U*np.cos(theta0), 0, U*np.sin(theta0), theta0, 0, 0.5*m*U*U])
                             def deriv(t,x):
                                                theta = x[4]
                                                alpha = theta - np.arctan2(x[3],x[1])
                                                v = np.hypot(x[1],x[3])
                                                prm = atm.atmParam(x[2],v) #Temp(h), Density(h), Viscosity(h), Mach(h,v), Usity(h), Mach(h,v), Mach(h,v
                                  \hookrightarrow logRe(h,v), Cd(h,v)
                                                fN = 0.5*prm[1]*v*v*S*CNAlphaInterp(prm[3])*alpha
                                                fA = 0.5*prm[1]*v*v*S*CAInterp(prm[3], x[2])[0][0]
                                                s = np.sin(theta)
                                                c = np.cos(theta)
                                                xddot = (-fN*s - fA*c)/m
```

```
yddot = (fN*c - fA*s - m*g)/m
                        thetaddot = -fN * (CPInterp(prm[3])*l - com) / I
                        if (alpha > np.radians(2)):
                                  raise ValueError("Alpha more than 2 Degrees")
                        return [x[1], xddot, x[3], yddot, x[5], thetaddot, fA*v]
              t0, tf = 0, 100
              t_eval = np.linspace(0,100, 100000)
              def hit_ground(t,y):
                        return y[2]
              hit_ground.terminal = True
              hit_ground.direction = -1
[39]: | sol = sci.solve_ivp(deriv, (t0, tf), sol0, t_eval = t_eval, dense_output=True,__
                ⇒events=hit_ground, atol=1e-12, rtol=1e-12)
[40]: v = np.hypot(sol.y[1], sol.y[3])
              E = m*g*sol.y[2] + 0.5*m*v*v + sol.y[6]
              print("Error: ",np.max(E) - np.min(E))
            Error: 0.016091778874397278
[41]: u = 710
              theta = np.radians(45)
              m = 20000
              rho_s = 8000
              d = np.cbrt((6*m)/(np.pi*rho_s))
              s = np.pi*d*d/4
              sol\_sphere0 = np.array([0, u*np.cos(theta), 0, u*np.sin(theta), 0.5*m*u*u])
              def derive(t,u):
                       v = np.hypot(u[1],u[3])
                        prm = atm.atmParam(u[2],v) #Temp(h), Density(h), Viscosity(h), Mach(h,v), Usity(h), Mach(h,v), Mach(h
                \rightarrow logRe(h,v), Cd(h,v)
                        fd = 0.5*prm[1]*v*s*prm[5]
                        return [u[1], -fd*u[1]/m, u[3], -g - (fd*u[3]/m), fd * v *v]
[42]: sol_sphere = sci.solve_ivp(derive, (t0, tf), sol_sphere0, t_eval = t_eval,__
                 →dense_output=True, events=hit_ground)
[43]: plt.plot(sol.y[0], sol.y[2], label='Range: {} m'.format(np.round(np.max(sol.
                \rightarrow y[0]),5))
              plt.plot(sol_sphere.y[0], sol_sphere.y[2], label='Range Sphere: {} m'.format(np.
                \rightarrowround(np.max(sol_sphere.y[0])),5))
              plt.xlabel('Range (m)')
              plt.ylabel('Height (m)')
              plt.grid()
```





```
sol0 = np.array([0, U*np.cos(theta0),0, U*np.sin(theta0), theta0, 0, 0.

$\int 5*m*U*U]$)

try:

    sol = sci.solve_ivp(deriv, (t0, tf), sol0, t_eval = t_eval, 
$\int \text{dense_output=True, events=hit_ground}$)

    RangeL[i] = np.max(sol.y[0])

except ValueError as ve:
    print(ve)

    RangeL[i] = 0

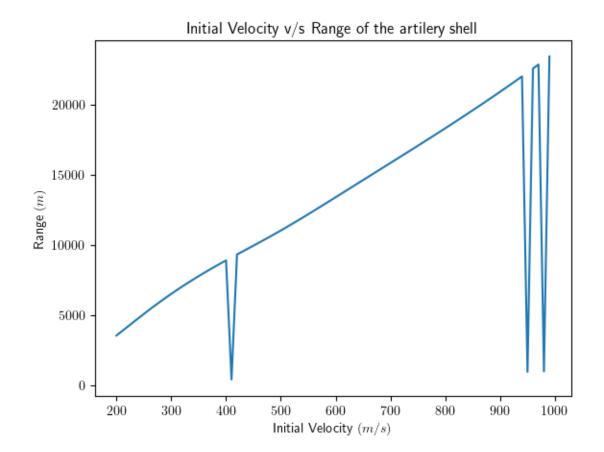
200
210
```

```
220
230
240
250
260
270
280
290
300
310
320
330
340
350
360
370
380
390
400
410
Alpha more than 2 Degrees
420
430
440
450
460
470
480
490
500
510
520
530
```

```
550
560
570
580
590
600
610
620
630
640
650
660
670
680
690
700
710
720
730
740
750
760
770
780
790
800
810
820
830
840
850
860
870
880
890
900
910
920
930
940
950
Alpha more than 2 Degrees
960
970
Alpha more than 2 Degrees
990
```

```
[25]: plt.plot(U_L, RangeL)
    plt.xlabel('Initial Velocity $(m/s)$')
    plt.ylabel('Range $(m)$')
    plt.title('Initial Velocity v/s Range of the artilery shell')
```

[25]: Text(0.5, 1.0, 'Initial Velocity v/s Range of the artilery shell')



The range of the artilery shell increases almost linearly with the initial velocity of the shell.

1.2 Simulation of rocket

```
[26]: dfR = pd.read_excel('data-rocket.xlsx')
      print(dfR.head())
      CAjon=np.array([[0.3835,
                                                                                            0.
                                           0.3857,
                                                            0.3866,
                                                                             0.361,
       →3401,
                        0.4108,
                                         0.4123,
                                                          0.4162,
                                                                           0.428,
                                                                                           0.
       →4786],
       [0.4158,
                                                          0.4074,
                        0.4184,
                                          0.4204,
                                                                            0.3646,
                                                                                            0.
       →4191,
                        0.5255,
                                         0.5307,
                                                          0.549,
                                                                          0.6322],
       [0.6169,
                        0.6147,
                                         0.617,
                                                          0.6073,
                                                                          0.557,
                                                                                          0.
        \hookrightarrow6051,
                        0.6991,
                                         0.7039,
                                                          0.7214,
                                                                           0.801],
```

```
[0.7267,
                 0.7244,
                                  0.7267,
                                                   0.7189,
                                                                    0.6655,
                                                                                     0.
<del>→</del>7093,
                 0.7954,
                                  0.7999,
                                                   0.8163,
                                                                   0.8914],
[0.8158,
                 0.8131,
                                  0.8154,
                                                   0.8096,
                                                                    0.7534,
                                                                                     0.
<del>→</del>7933,
                 0.8726,
                                  0.8768,
                                                                   0.9629],
                                                   0.8922,
[0.8902,
                 0.8882,
                                                                    0.825.
                                                                                    0.
                                  0.8909,
                                                   0.8885,
<del>~</del>8668,
                 0.9484.
                                  0.9524.
                                                   0.9668,
                                                                   1.0329].
[0.9371,
                 0.9348,
                                  0.9375,
                                                   0.938,
                                                                   0.8722,
                                                                                    0.
→91,
               0.9872,
                                                                 1.067],
                               0.9909,
                                                1.0045,
[0.7873,
                 0.7842,
                                  0.7866,
                                                   0.7898,
                                                                    0.7456,
                                                                                     0.
\hookrightarrow7501,
                 0.8117,
                                  0.9258,
                                                   0.9379,
                                                                   0.9939],
[0.6864,
                 0.6824,
                                  0.6843.
                                                   0.6882,
                                                                    0.6575.
                                                                                     0.
                 0.6913,
                                  0.7846,
                                                   0.7953,
0.8446],
[0.6208,
                 0.6158,
                                  0.6173,
                                                   0.6212,
                                                                    0.6056,
                                                                                     0.
<u>→</u>5716,
                 0.6118,
                                  0.6852,
                                                   0.6944,
                                                                   0.7369],
[0.6077,
                 0.6024,
                                  0.6038,
                                                   0.6075.
                                                                    0.593,
                                                                                    0.
⇒5578,
                 0.5964,
                                                                   0.7164],
                                  0.6661,
                                                   0.6751,
[0.5872,
                                                                    0.5742,
                 0.5814,
                                  0.5825,
                                                   0.5858,
                                                                                     0.
<u>→</u>5367,
                 0.5716,
                                  0.6336,
                                                   0.642,
                                                                  0.681],
[0.5654,
                 0.5659.
                                  0.5667,
                                                   0.5691,
                                                                    0.5605.
                                                                                     0.
⇒5216,
                                                                   0.6547],
                 0.5537,
                                  0.6093,
                                                   0.6174,
[0.5316,
                 0.532,
                                 0.5325,
                                                  0.5344,
                                                                   0.5272,
                                                                                    0.
<u></u>488,
                0.5181,
                                 0.5685,
                                                 0.5763,
                                                                   0.6128],
[0.5193,
                 0.5194,
                                  0.5198,
                                                   0.5211,
                                                                    0.5156,
                                                                                     0.
                                                                   0.5936]])
4761.
                 0.5045.
                                  0.5504,
                                                   0.5581,
```

	Mach	C_N_Alpha	x_CP	Majoff	${\tt hAjoff}$	Majon	hAon	tm	\
0	0.2	14.57	0.842868	0.4	0.0	0.4	0.0	0.000	
1	0.4	14.43	0.851050	0.6	5000.0	0.6	5000.0	0.040	
2	0.6	14.86	0.850584	0.8	10000.0	0.8	10000.0	0.041	
3	0.8	15.16	0.848138	0.9	20000.0	0.9	20000.0	0.042	
4	0.9	15.67	0.851823	1.0	30000.0	1.0	30000.0	0.043	

```
massExpelled
   thrustKN
0
      0.000
                     0.000
      5.921
                     0.000
1
                     0.002
2
      6.335
3
      7.164
                     0.006
4
      7.933
                     0.011
```

1.2.1 Interpolation Functions

```
[27]: CNAlphaInterpR = inp.interp1d(dfR.Mach[:19], dfR.C_N_Alpha[:19], kind='cubic')

CPInterpR = inp.interp1d(dfR.Mach[:19], dfR.x_CP[:19], kind='cubic')

CA_joffInterpR = inp.RectBivariateSpline(dfR.Majoff[:15], dfR.hAjoff[:10], GAjoff)

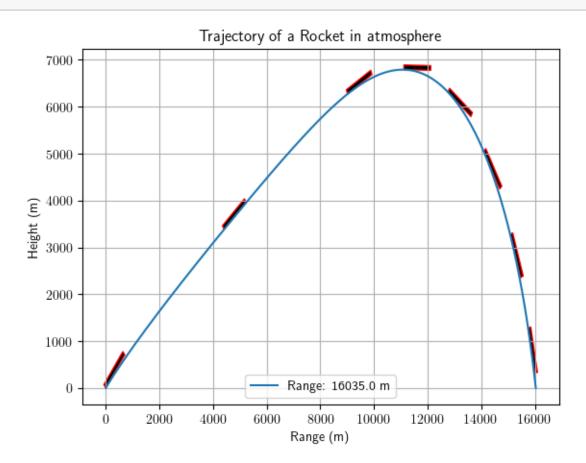
CA_jonInterpR = inp.RectBivariateSpline(dfR.Majon[:15], dfR.hAon[:10], CAjon)

ThrustKNInterp = inp.interp1d(dfR.tm, dfR.thrustKN, kind='cubic')
```

```
massExpl_Interp = inp.interp1d(dfR.tm, dfR.massExpelled, kind='cubic')
```

```
[134]: 1 = 2.277
                 mO = 88
                 R = 287
                 S = np.pi*0.207*0.207/4 #
                 AE = np.pi*0.125*0.125/4
                 com = 0.70769
                 U = 100
                 g = 9.8
                 mp0 = 48.771
                 mS = 39.229
                 t_{eval} = np.linspace(0,1000, 100000)
                 tthrust = 11.778
                 theta0 = np.radians(45)
                 sol0 = np.array([0, U*np.cos(theta0), 0, U*np.sin(theta0), theta0, 0, 0.5*m0*U*U])
                 def deriv(t,x):
                            theta = x[4]
                            alpha = theta - np.arctan2(x[3],x[1])
                            v = np.hypot(x[1],x[3])
                            prm = atm.atmParam(x[2],v) #Temp(h), Density(h), Viscosity(h), Mach(h,v), Using the state of t
                    \rightarrow logRe(h,v), Cd(h,v)
                            fN = 0.5*prm[1]*v*v*S*CNAlphaInterpR(prm[3])*alpha
                            if t <= tthrust:</pre>
                                      fA = 0.5*prm[1]*v*v*S*CA_jonInterpR(prm[3], x[2])[0][0]
                                      T = ThrustKNInterp(t)*1000 - prm[0]*prm[1]*R*AE
                                      mp_expl = massExpl_Interp(t)
                                      X = (43.681 + 1.4735*mp_expl)/(39.229 + mp_expl)
                                      I = 16.318 + 39.229*(1.1135-X)**2 + (0.0979 + (1.4735 - X)**2)*mp_expl
                            else:
                                      fA = 0.5*prm[1]*v*v*S*CA_joffInterpR(prm[3], x[2])[0][0]
                                      T = 0
                                      mp_expl = 48.771
                                      X = 1.1135
                                      I = 16.318
                           m = mp0 - mp_expl + mS
                            s = np.sin(theta)
                            c = np.cos(theta)
                            xddot = (T*c -fN*s - fA*c)/m
                            yddot = (fN*c + T*s - fA*s - m*g)/m
                            thetaddot = -fN * (CPInterpR(prm[3])*1 - X) / I
                            if (alpha > np.radians(2)):
                                      raise ValueError("Alpha more than 2 Degrees")
                           return [x[1], xddot, x[3], yddot, x[5], thetaddot, fA*v]
                 t0, tf = 0, 1000
                 def hit_ground(t,y):
                           return y[2]
```

```
hit_ground.terminal = True
       hit_ground.direction = -1
[135]: sol = sci.solve_ivp(deriv, (t0, tf), sol0, t_eval = t_eval, dense_output=True,__
        →events=hit_ground)
[136]: plt.plot(sol.y[0], sol.y[2], label='Range: {} m'.format(np.round(np.max(sol.
       \rightarrowy[0])),5))
       plt.xlabel('Range (m)')
       plt.ylabel('Height (m)')
       plt.grid()
       plt.legend(loc='lower center')
       plt.title('Trajectory of a Rocket in atmosphere')
       for x in range(0,sol.y[0].size,1000):
           plt.gca().add_patch(Rectangle((sol.y[0][x],sol.y[2][x]),1000,100,
                           angle=np.degrees(sol.y[4][x]),
                           edgecolor='red',
                           facecolor='black'))
```

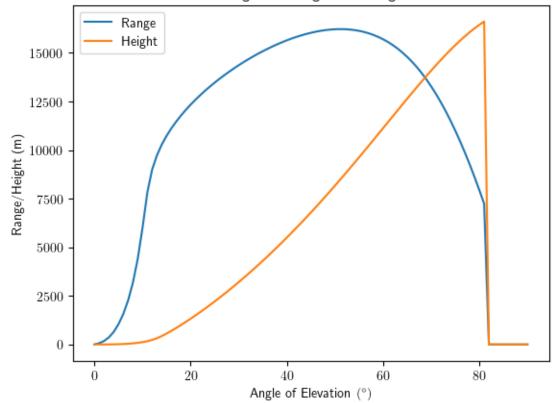


```
[137]: angle = np.arange(0,91,1)
       Range_L = np.empty_like(angle)
       Height_L = np.empty_like(angle)
       for i in range(angle.size):
           print(angle[i])
           theta0 = np.radians(angle[i])
           sol0 = np.array([0, U*np.cos(theta0), 0, U*np.sin(theta0), theta0, 0, 0.
        \hookrightarrow5*m0*U*U])
           try:
               sol = sci.solve_ivp(deriv, (t0, tf), sol0, t_eval = t_eval,__
        →dense_output=True, events=hit_ground)
               Range_L[i] = np.max(sol.y[0])
               Height_L[i] = np.max(sol.y[2])
           except ValueError as ve:
               print(ve)
               Range_L[i] = 0
               Height_L[i] = 0
```

1

```
79
      80
      81
      82
      Alpha more than 2 Degrees
      A value (0.1992947543409542) in x_new is below the interpolation range's minimum
      value (0.2).
      84
      A value (0.19852833995424451) in x_new is below the interpolation range's
      minimum value (0.2).
      85
      A value (0.19983626107992858) in x_new is below the interpolation range's
      minimum value (0.2).
      86
      A value (0.19218277921761642) in x_new is below the interpolation range's
      minimum value (0.2).
      87
      A value (0.19726823119067527) in x_new is below the interpolation range's
      minimum value (0.2).
      88
      A value (0.19177844846277248) in x_new is below the interpolation range's
      minimum value (0.2).
      89
      A value (0.1879083369270822) in x_new is below the interpolation range's minimum
      value (0.2).
      90
      Alpha more than 2 Degrees
[138]: print("Angle with Maximum Range: ", angle[np.where(Range_L==np.max(Range_L))][0])
      print("Angle with Maximum Height: ", angle[np.where(Height_L==np.
        →max(Height_L))][0])
      Angle with Maximum Range: 51
      Angle with Maximum Height: 81
[139]: plt.plot(angle, Range_L, label='Range')
      plt.plot(angle, Height_L, label='Height')
      plt.title("Variation of Range and Height with angle of elevation")
      plt.xlabel("Angle of Elevation $(^\circ)$")
      plt.ylabel("Range/Height (m)")
      plt.legend()
[139]: <matplotlib.legend.Legend at 0x2c2397d8210>
```





Therefore, we get the maximum range at 49 Degrees and maximum height at 83 Degrees for the intitial velocity of 100 m/s.