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# Caleb Schultz Kisby

Neuro-Symbolic AI Researcher

## **EDUCATION**

## Ph.D. Candidate, Computer Science (in progress)

Fall 2018 - Present

GitHub: ais-climber

LinkedIn: caleb-kisby

Indiana University

Concentration: Neuro-Symbolic Learning and Reasoning

**B.S.** Computer Science and Mathematics

Spring 2018 GPA: 3.97

GPA: 3.75

University of South Carolina

#### **EXPERIENCE**

Research Assistant Spring 2022 – Present

Indiana University

Fall 2018 - Spring 2019

• See Projects below. Supported by a DoD Trusted AI grant for which I co-wrote the grant proposal.

Teaching Assistant

Summer 2019 – Fall 2021

Indiana University

• Planned and taught recitations for Theory of Computation, Honors Discrete Math, and Intro to Programming

## **PROJECTS**

## à la Mode: Neural Network Model Checking & Building

[GitHub]

- Independently developed a suite for checking and building neural networks from symbolic constraints (using Tensorflow).
- Proved that the neuro-symbolic translation at the heart of the program is formally sound (see FLAIRS paper below).

Notakto Player [GitHub][Report]

- Augmented the AlphaZero CNN with light knowledge-based features to better play Thane Plambeck's Notakto (a game for which AlphaZero fails to learn a winning strategy see the linked Report).
- Wrote testbed code (using Tensorflow) to compare the supplemented net against the original AlphaZero net.

## An Efficient & Light Cardinality Reasoner

[Github]

- Proved completeness for a computationally light logic that reasons about cardinalities with intersection in polynomial time.
- Collaborated with co-authors on proof (see AAAI paper below); Independently implemented model-building in Python.

#### **COBB:** Case-Based Confidence for Black Box Predictions

[Github]

• Co-developed a hybrid neuro-symbolic system that uses a case-based reasoner to assess confidence and explain a neural network's predictions (using Scikit-Learn). Larry Gates and I divided all work evenly. (See ICCBR paper below.)

### Sense-Able: Obstacle Sensor for Visually Impaired

[GitHub][Tutorial]

- Collaborated with a team to develop a proof-of-concept LIDAR sensor for our clients at P. B. Mumola, Ph.D., LLC.
- Wrote core C++ code for object detection and the GUI (in Qt); Independently wrote a tutorial for the LIDAR SDK.

## **SKILLS**

Deep Learning. Supervised & Reinforcement Learning, Tensorflow (Keras), Scikit-Learn, NLP (Word2Vec, NLTK)

Symbolic AI. Knowledge Representation & Reasoning, Model-Building, First-Order & Modal Logics, Natural Language Semantics

Languages. Python, C++, C, Java, Agda, Lisp (Racket), miniKanren, Lean, Prolog

Other Tools. Git, LaTeX, TexMacs, Jupyter Notebook (Google Colab), Visual Studio Code, Emacs, Linux

## **PUBLICATIONS**

FLAIRS 2022	The Logic of Hebbian Learning	[pdf]
	with Saúl A. Blanco and Lawrence Moss. Presented at FLAIRS 2022, Jensen Beach FL.	
	Nominated for Best Student Paper.	

#### AAAI 2020 Logics for Sizes with Union or Intersection

[pdf]

with Saúl A. Blanco, Alex Kruckman, and Lawrence Moss. Presented at AAAI'20, New York NY

#### ICCBR 2019 CBR Confidence as a Basis for Confidence in Black Box Systems

[pdf]

with Lawrence Gates and David Leake. Presented at ICCBR 2019, Otzenhausen Germany.