

Navier – Stokes Equations Finite Element Discretization (as in Libmesh Example 13)

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References

J.Donea. *Finite Element Methods for Flow Problems*

J.C.Heinrich. *Intermediate Finite Element Method*

B.Kirk, J.W.Peterson, R.H.Stogner, and G.F.Carey. *libMesh* ...

In[2056]:=

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Clear["Global`*"]; dim = 2;

For[i = 1, i < dim + 1, i++, e0 = ConstantArray[0, dim]; e0[[i]] = 1; ei = e0];
For[i = 1, i < dim + 2, i++, e0 = ConstantArray[0, dim + 1]; e0[[i]] = 1; eei = e0];
variables = {u, v, w,  $\delta$ , w1, w2, w3, ukk, uk, vkk, vk, wkk, wk,  $\mu$ , p, pkk, uold, vold, wold, pold};
wfunctions = {w1, w2, w3, w4};
unknowns = {u, v, w, p};
unknownskk = {ukk, vkk, wkk, pkk};
condition = NonConstants  $\rightarrow$  variables;
Replacer2 = {};
Replacer3 = {};
Replacer4 = {{}, {}, {}, {}}; (* erases weighting functions*)
Replacer5 = {}; (*Second derivatives*)
Replacer6 = {ukk  $\rightarrow$  u, vkk  $\rightarrow$  v, wkk  $\rightarrow$  w}; (*Used for getting tangent stiffness matrix*)
Replacer7 = {{}, {}, {}, {}}; (*erases unknownskk*)
X1 = x; X2 = y; X3 = z;
Xdim+1 = p;
For[i = 1, i < Dimensions[unknowns][[1]] + 1, i++,
  For[mm = 1, mm < dim + 1, mm++,
    AppendTo[Replacer7[[i]], Symbol["d" <> SymbolName[unknownskk[[i]]] <> "d" <> SymbolName[Xmm]]  $\rightarrow$  0];
    AppendTo[Replacer7[[i]], unknownskk[[i]]  $\rightarrow$  0];
  ]];

For[mm = 1, mm < dim + 1, mm++,
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For[i = 1, i < Dimensions[unknowns][[1]] + 1, i++,
  AppendTo[Replacer6, Symbol["d" <> SymbolName[unknowns[[i]]] <> "kkd" <> SymbolName[Xmm]]
    → Symbol["d" <> SymbolName[unknowns[[i]]] <> "d" <> SymbolName[Xmm]]];
  AppendTo[Replacer6, Symbol["d2" <> SymbolName[unknowns[[i]]] <> "kkd" <> SymbolName[Xmm] <> "2"]
    → Symbol["d2" <> SymbolName[unknowns[[i]]] <> "d" <> SymbolName[Xmm] <> "2"]];
];
For[j = 1, j < Dimensions[wfunctions][[1]] + 1, j++,
  For[i = 1, i < Dimensions[wfunctions][[1]] + 1, i++,
    If[i ≠ j,
      AppendTo[Replacer4[[j]], wfunctions[[i]] → 0];
      For[mm = 1, mm < dim + 1, mm++,
        AppendTo[Replacer4[[j]], Symbol["d" <> SymbolName[wfunctions[[i]]] <> "d" <> SymbolName[Xmm] → 0]
          ]]]];
For[mm = 1, mm < dim + 1, mm++,
  For[i = 1, i < Dimensions[variables][[1]] + 1, i++,
    AppendTo[Replacer2, D[variables[[i]], Xmm, condition] → Symbol["d" <> SymbolName[variables[[i]]] <> "d"
    AppendTo[Replacer5, D[variables[[i]],
      {Xmm, 2}, condition] → Symbol["d2" <> SymbolName[variables[[i]]] <> "d" <> SymbolName[Xmm] <> "2"]];
  ];
For[i = 1, i < Dimensions[variables][[1]] + 1, i++,
  AppendTo[Replacer2, D[variables[[i]], t, condition] → Symbol["d" <> SymbolName[variables[[i]]] <> "d" <>
  AppendTo[Replacer3, Symbol["d" <> SymbolName[variables[[i]]] <> "d" <> SymbolName[t]] → (Symbol[SymbolNam
    - Symbol[SymbolName[variables[[i]]] <> "old"])/Δt];]
Dc[a_, b_] := D[a, b, condition] /. Replacer2; (*Dc equals partial derivative*)
Scalar2d[a_, b_] := a[[1]] * b[[1]] + a[[2]] * b[[2]];
Grad[V_] := Module[{output = {}}, For[i = 1, i < dim + 1, i++, AppendTo[output, Dc[V, Xi]]]; output]
Dyad[A_, B_] :=  $\sum_{i=1}^{\text{dim}} \left( \sum_{j=1}^{\text{dim}} (A[[i, j]] * B[[i, j]]) \right)$ ;
SplitByTrial[func_] := Module[{output = {}},
  For[j = 1, j < dim + 2, j++, AppendTo[output, func /. Replacer4[[j]]]]; output];
Laplacian[func_] := Sum[D[D[func, Xi, condition], Xi, condition], {i, dim}] /. Replacer5 /. Replacer2;
Scalar[A_, B_] := Module[{size = Dimensions[A][[1]], output}, output = Sum[A[[i]] * B[[i]], {i, size}]; outp
Div[A_] := Sum[Dc[A[[i]], Xi], {i, dim}];
SplitByUnknown[V_] := Module[{output = {}}, auxiliary,
  For[j = 1, j < dim + 1, j++, AppendTo[output, V - (V /. Replacer7[[j]])]]];

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AppendTo[output, V - (V /. Replacer7[[4]])];
auxiliar = V;
For[j = 1, j < 5, j++, auxiliar = auxiliar /. Replacer7[[j]]];
AppendTo[output, auxiliar];
Transpose[FullSimplify[output]]];
SplitByBoth[func_] := SplitByUnknown[SplitByTrial[func]];

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u1 = u; u2 = v; u3 = w;
u21 = ukk *  $\theta$  + (1 -  $\theta$ ) * uold;
u22 = vkk *  $\theta$  + (1 -  $\theta$ ) * vold;
u23 = wkk *  $\theta$  + (1 -  $\theta$ ) * wold;
p2 = pkk *  $\theta$  + (1 -  $\theta$ ) * pold;
 $\Delta U_1$  = ukk - u;
 $\Delta U_2$  = vkk - v;
 $\Delta U_3$  = wkk - w;
 $\Delta U_4$  = pkk - p;
Vkk1 = ukk;
Vkk2 = vkk;
Vkk3 = wkk;

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V = Sum[ui * ei, {i, dim}]; (*Velocity Vector*)
W = Sum[wfunctions[[i]] * ei, {i, dim}]; (*velocity weighting functions*)
V2 = Sum[u2i * ei, {i, dim}];
Vkk = Sum[Vkki * ei, {i, dim}];
U = Sum[unknowns[[i]] * eei, {i, dim}] + p * eedim+1;
 $\Delta U$  = Sum[ $\Delta U_i$  * eei, {i, dim}] +  $\Delta U_4$  * eedim+1; (*where ukk = uk+1 is the value of u for the next iteration, ar
Ukk = U +  $\Delta U$ ;

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(*Stress tensor*)
 $\tau[u\_]$  := Module[{t2 = ConstantArray[ConstantArray[0, dim], dim]}, For[i = 1, i < dim + 1, i++,
  For[j = 1, j < dim + 1, j++, t2[[j, i]] =  $\mu$  * (Dc[u[[i]], Xj]])] (*+Dc[u[[j]], xi] = 0 when div[ $\rho v$ ]=0 *) ; t2

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(*Terms of the Navier Stokes Equation*)
TEMPORAL = SplitByTrial[Scalar[Dc[ $\rho$ *V, t], W]] /. Replacer3 ;
DIFUSSION = SplitByTrial[Dyad[Grad[W],  $\tau$ [V2]]]; (*Dyad Product Between Grad[w] and the stress tensor*)
CONVECTION = SplitByTrial[ $\rho$ *Scalar[(Scalar[Grad[V2], V]), W]];
PRESSURE = SplitByTrial[Scalar[Grad[p2], W]];
CONTINUITY = SplitByTrial[w3*Div[Vkk]];
DD = TEMPORAL + CONVECTION + DIFUSSION + PRESSURE + CONTINUITY ;
TANGENT[func_] := Module[{DDu2 = ConstantArray[ConstantArray[0, dim + 1], dim + 1], i},
  For[i = 1, i < dim + 2, i++,
    DDDu2[[i]] = D[Sum[func[[i]], {i, dim + 1}], Scalar[U, eei]]; SplitByTrial[DDu2 /. Replacer6]];
NEWTON = TANGENT[DD]. $\Delta$ U; (*Newton Term*)

Print["VARIABLES"];
Print["ukk,vkk,pkk are the unknowns to solve by the linear system"];
Print[" u,v,p are previous Newton iterations"];
Print[" uold,vold,pold are previous timesteps"];
Print[" $\tau$ [V] =  $\mu$ *Grad[V] = ",  $\tau$ [V]];
Print["V = ", V, " = Velocity Vector"];
Print["Vkk = ", Vkk];
Print["W = ", W, " = Trial Functions for velocities"];
Print["V2 = ", V2];
Print["U = ", U];
Print["Ukk = ", Ukk, " = Unknowns vector"];
Print[" $\Delta$ U = ",  $\Delta$ U];
Print["\n PART 1"];
Print["TEMPORAL = Scalar[Dc[ $\rho$ *V,t],W] = ", TEMPORAL // MatrixForm];
Print["DIFUSSION = Dyad[Grad[W], $\tau$ [V2]] = ", DIFUSSION // MatrixForm];
Print["CONVECTION =  $\rho$ *Scalar[(Scalar[Grad[V2],V]),W] = ", CONVECTION // MatrixForm];
Print[" PRESSURE = Scalar[Grad[p2],W] = ", PRESSURE // MatrixForm];
Print["CONTINUITY = w3*Div[Vkk] = ", CONTINUITY // MatrixForm];
Print["DD = TEMPORAL+CONVECTION+DIFUSSION+PRESSURE + CONTINUITY = ", DD // MatrixForm];
Print["DD'[V] = ", TANGENT[DD], " = Tangent stiffness matrix of DD"];
Print["NEWTON = DD'[u]. $\Delta$ U = ", NEWTON // MatrixForm]

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Print["\n PART 2"];
force = {f1, f2};
 $\sigma$  = -p * IdentityMatrix[dim] +  $\tau$ [V];
RESIDUAL[V2_] := Dc[V2, t] + Scalar[V2, Grad[V]] -  $\mu$  * Laplacian[V2] + Grad[p2] - f;
SUPGTEMPORAL = tsupg * SplitByTrial[Scalar[Scalar[V, Grad[W]], Dc[V, t]] /. Replacer3];
SUPGDIFFUSION = tsupg * SplitByTrial[Scalar[Scalar[V, Grad[W]], - $\mu$  * Laplacian[V2]]];
SUPGCONVECTION = tsupg * SplitByTrial[Scalar[Scalar[V, Grad[W]], Scalar[V, Grad[V2]]]];
SUPGPRESSURE = tsupg * SplitByTrial[Scalar[Scalar[V, Grad[W]], Grad[p2]]];
SUPGFORCE = tsupg * SplitByTrial[Scalar[Scalar[V2, Grad[W]], -force]];
SUPGNEWTONDIFFUSION = TANGENT[SUPGDIFFUSION]. $\Delta U$ ;
SUPGNEWTONCONVECTION = FullSimplify[TANGENT[SUPGCONVECTION]. $\Delta U$ ];
SUPGNEWTONPRESSURE = FullSimplify[TANGENT[SUPGPRESSURE]. $\Delta U$ ];
SUPGNEWTONFORCE = FullSimplify[TANGENT[SUPGFORCE]. $\Delta U$ ];
Print["SUPGTEMPORAL = tsupg*Scalar[Scalar[V,Grad[W]],Dc[V,t] = ", SUPGTEMPORAL // MatrixForm];
Print["SUPGDIFFUSION = tsupg*Scalar[Scalar[V,Grad[W]],-Mu/Ree*Laplacian[V2]] = ", SUPGDIFFUSION // MatrixForm];
Print["SUPGCONVECTION = tsupg*Scalar[Scalar[V,Grad[W]],Scalar[V,Grad[V2]]] = ", SUPGCONVECTION // MatrixForm];
Print["SUPGPRESSURE = Scalar[Scalar[V,Grad[W]],Grad[p2]] = ", SUPGPRESSURE // MatrixForm];
Print["SUPGFORCE = Scalar[Scalar[V2,Grad[W]],-force] = ", SUPGFORCE // MatrixForm];
Print["SUPGNEWTONDIFFUSION = TANGENT[SUPGDIFFUSION]. $\Delta U$  = ", SUPGNEWTONDIFFUSION // MatrixForm];
Print["SUPGNEWTONCONVECTION = TANGENT[SUPGCONVECTION]. $\Delta U$  = \n", SUPGNEWTONCONVECTION // MatrixForm];
Print["SUPGNEWTONPRESSURE = TANGENT[SUPGPRESSURE]. $\Delta U$  = ", SUPGNEWTONPRESSURE // MatrixForm];
Print["SUPGNEWTONFORCE = TANGENT[SUPGFORCE]. $\Delta U$  = ", SUPGNEWTONFORCE // MatrixForm];

GLOBALRESULT = {};
AppendTo[GLOBALRESULT, SplitByUnknown[TEMPORAL]];
AppendTo[GLOBALRESULT, SplitByUnknown[DIFUSSION]];
AppendTo[GLOBALRESULT, SplitByUnknown[CONVECTION]];
AppendTo[GLOBALRESULT, SplitByUnknown[PRESSURE]];
AppendTo[GLOBALRESULT, SplitByUnknown[CONTINUITY]];
AppendTo[GLOBALRESULT, SplitByUnknown[NEWTON]];
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGTEMPORAL]];
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGCONVECTION]];
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGPRESSURE]];
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGFORCE]];
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGNEWTONDIFFUSION]];

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AppendTo[GLOBALRESULT, SplitByUnknown[SUPGNEWTONCONVECTION]] ;
AppendTo[GLOBALRESULT, SplitByUnknown[SUPGNEWTONPRESSURE]] ;
GLOBALRESULT = GLOBALRESULT /. { $\theta \rightarrow$  theta,  $\rho \rightarrow$  Rho,  $\mu \rightarrow$  Mu,  $\Delta t \rightarrow$  dt} ;

```

VARIABLES

ukk,vkk,pkk are the unknowns to solve by the linear system

u,v,p are previous Newton iterations

uold,vold,pold are previous timesteps

$$\tau[V] = \mu * \text{Grad}[V] = \begin{pmatrix} \frac{du}{dx} \mu & \frac{dv}{dx} \mu \\ \frac{du}{dy} \mu & \frac{dv}{dy} \mu \end{pmatrix}$$

$V = \{u, v\}$ = Velocity Vector

$V_{kk} = \{u_{kk}, v_{kk}\}$

$W = \{w1, w2\}$ = Trial Functions for velocities

$V2 = \{uold(1 - \theta) + u_{kk}\theta, vold(1 - \theta) + v_{kk}\theta\}$

$U = \{u, v, p\}$

$U_{kk} = \{u_{kk}, v_{kk}, p_{kk}\}$ = Unknowns vector

$\Delta U = \{u_{kk} - u, v_{kk} - v, p_{kk} - p\}$

PART 1

$$\text{TEMPORAL} = \text{Scalar}[\text{Dc}[\rho * V, t], W] = \begin{pmatrix} \frac{(u_{kk} - uold) w1 \rho}{\Delta t} \\ \frac{(v_{kk} - vold) w2 \rho}{\Delta t} \\ 0 \end{pmatrix}$$

$$\text{DIFUSSION} = \text{Dyad}[\text{Grad}[W], \tau[V2]] = \begin{pmatrix} \frac{dw1}{dx} (duold_{dx} (1 - \theta) + dukk_{dx} \theta) \mu + \frac{dw1}{dy} (duold_{dy} (1 - \theta) + dukk_{dy} \theta) \mu \\ \frac{dw2}{dx} (dvold_{dx} (1 - \theta) + dvkk_{dx} \theta) \mu + \frac{dw2}{dy} (dvold_{dy} (1 - \theta) + dvkk_{dy} \theta) \mu \\ 0 \end{pmatrix}$$

$$\text{CONVECTION} = \rho * \text{Scalar}[(\text{Scalar}[\text{Grad}[\text{V2}], \text{V}]), \text{W}] = \begin{pmatrix} w1 (u (\text{duolddx} (1 - \theta) + \text{dukkdx} \theta) + v (\text{duolddy} (1 - \theta) + \text{dukkdy} \theta)) \rho \\ w2 (u (\text{dvolddx} (1 - \theta) + \text{dvkkdx} \theta) + v (\text{dvolddy} (1 - \theta) + \text{dvkkdy} \theta)) \rho \\ 0 \end{pmatrix}$$

$$\text{PRESSURE} = \text{Scalar}[\text{Grad}[\text{p2}], \text{W}] = \begin{pmatrix} w1 (\text{dpolddx} (1 - \theta) + \text{dpkkdx} \theta) \\ w2 (\text{dpolddy} (1 - \theta) + \text{dpkkdy} \theta) \\ 0 \end{pmatrix}$$

$$\text{CONTINUITY} = w3 * \text{Div}[\text{Vkk}] = \begin{pmatrix} 0 \\ 0 \\ (\text{dukkdx} + \text{dvkkdy}) w3 \end{pmatrix}$$

$$\text{DD} = \text{TEMPORAL} + \text{CONVECTION} + \text{DIFUSSION} + \text{PRESSURE} + \text{CONTINUITY} = \begin{pmatrix} w1 (\text{dpolddx} (1 - \theta) + \text{dpkkdx} \theta) + \text{dw1dx} (\text{duolddx} (1 - \theta) + \text{dukkdx} \theta) \\ w2 (\text{dpolddy} (1 - \theta) + \text{dpkkdy} \theta) + \text{dw2dx} (\text{dvolddx} (1 - \theta) + \text{dvkkdx} \theta) \\ 0 \end{pmatrix}$$

$$\text{DD}'[\text{V}] = \begin{pmatrix} w1 (\text{duolddx} (1 - \theta) + \text{dudx} \theta) \rho & w1 (\text{duolddy} (1 - \theta) + \text{dudy} \theta) \rho & 0 \\ w2 (\text{dvolddx} (1 - \theta) + \text{dvdx} \theta) \rho & w2 (\text{dvolddy} (1 - \theta) + \text{dvdy} \theta) \rho & 0 \\ 0 & 0 & 0 \end{pmatrix} = \text{Tangent stiffness matrix of DD}$$

$$\text{NEWTON} = \text{DD}'[\text{u}].\Delta \text{U} = \begin{pmatrix} (\text{ukk} - u) w1 (\text{duolddx} (1 - \theta) + \text{dudx} \theta) \rho + (\text{vkk} - v) w1 (\text{duolddy} (1 - \theta) + \text{dudy} \theta) \rho \\ (\text{ukk} - u) w2 (\text{dvolddx} (1 - \theta) + \text{dvdx} \theta) \rho + (\text{vkk} - v) w2 (\text{dvolddy} (1 - \theta) + \text{dvdy} \theta) \rho \\ 0 \end{pmatrix}$$

PART 2

$$\text{SUPGTEMPORAL} = \text{tsupg} * \text{Scalar}[\text{Scalar}[\text{V}, \text{Grad}[\text{W}]], \text{Dc}[\text{V}, \text{t}]] = \begin{pmatrix} \frac{\text{tsupg} (\text{ukk} - \text{uold}) (\text{dw1dx} u + \text{dw1dy} v)}{\Delta t} \\ \frac{\text{tsupg} (\text{dw2dx} u + \text{dw2dy} v) (\text{vkk} - \text{vold})}{\Delta t} \\ 0 \end{pmatrix}$$

$$\text{SUPGDIFFUSION} = \text{tsupg} * \text{Scalar}[\text{Scalar}[\text{V}, \text{Grad}[\text{W}]], -\text{Mu}/\text{Ree} * \text{Laplacian}[\text{V2}]] = \begin{pmatrix} -\text{tsupg} (\text{dw1dx} u + \text{dw1dy} v) (\text{d2uolddx2} (1 - \theta) + \text{d2uolddy2} (1 - \theta) + \text{dw1dx} u + \text{dw1dy} v) \\ -\text{tsupg} (\text{dw2dx} u + \text{dw2dy} v) (\text{d2volddx2} (1 - \theta) + \text{d2volddy2} (1 - \theta) + \text{dw2dx} u + \text{dw2dy} v) \\ 0 \end{pmatrix}$$

$$\text{SUPGCONVECTION} = \text{tsupg} * \text{Scalar}[\text{Scalar}[\mathbf{V}, \text{Grad}[\mathbf{W}]], \text{Scalar}[\mathbf{V}, \text{Grad}[\mathbf{V2}]]] = \begin{pmatrix} \text{tsupg} (\text{dw1dx } u + \text{dw1dy } v) (u (\text{duolddx} (1 - \theta) + \text{dukkdx } \theta) + v (\text{duolddy} (\\ \text{tsupg} (\text{dw2dx } u + \text{dw2dy } v) (u (\text{dvolddx} (1 - \theta) + \text{dvkkdx } \theta) + v (\text{dvolddy} (\\ 0 \end{pmatrix}$$

$$\text{SUPGPRESSURE} = \text{Scalar}[\text{Scalar}[\mathbf{V}, \text{Grad}[\mathbf{W}]], \text{Grad}[\mathbf{p2}]] = \begin{pmatrix} \text{tsupg} (\text{dw1dx } u + \text{dw1dy } v) (\text{dpolddx} (1 - \theta) + \text{dpkkdx } \theta) \\ \text{tsupg} (\text{dw2dx } u + \text{dw2dy } v) (\text{dpolddy} (1 - \theta) + \text{dpkkdy } \theta) \\ 0 \end{pmatrix}$$

$$\text{SUPGFORCE} = \text{Scalar}[\text{Scalar}[\mathbf{V2}, \text{Grad}[\mathbf{W}]], -\text{force}] = \begin{pmatrix} -\text{f1 } \text{tsupg} (\text{dw1dx } (u_{\text{old}} (1 - \theta) + \text{ukk } \theta) + \text{dw1dy } (v_{\text{old}} (1 - \theta) + \text{vkk } \theta)) \\ -\text{f2 } \text{tsupg} (\text{dw2dx } (u_{\text{old}} (1 - \theta) + \text{ukk } \theta) + \text{dw2dy } (v_{\text{old}} (1 - \theta) + \text{vkk } \theta)) \\ 0 \end{pmatrix}$$

$$\text{SUPGNEWTONDIFFUSION} = \text{TANGENT}[\text{SUPGDIFFUSION}].\Delta \mathbf{U} = \begin{pmatrix} -\text{dw1dx } \text{tsupg} (\text{ukk} - u) (\text{d2uolddx}^2 (1 - \theta) + \text{d2uolddy}^2 (1 - \theta) + \text{d2udx}^2 \theta + \text{d2udy} \\ -\text{dw2dx } \text{tsupg} (\text{ukk} - u) (\text{d2volddx}^2 (1 - \theta) + \text{d2volddy}^2 (1 - \theta) + \text{d2vdx}^2 \theta + \text{d2vdy} \end{pmatrix}$$

$$\text{SUPGNEWTONCONVECTION} = \text{TANGENT}[\text{SUPGCONVECTION}].\Delta \mathbf{U} =$$

$$\begin{pmatrix} \text{tsupg} (\text{ukk} - u) (-\text{duolddy } \text{dw1dx } v (\theta - 1) - \text{duolddx} (2 \text{dw1dx } u + \text{dw1dy } v) (\theta - 1) + (2 \text{dudx } \text{dw1dx } u + \text{dudy } \text{dw1dx } v + \text{dudx } \text{dw1dy } v) \theta) + \text{tsupg} (\text{vkk} - v) (\\ \text{tsupg} (\text{ukk} - u) (-\text{dvolddy } \text{dw2dx } v (\theta - 1) - \text{dvolddx} (2 \text{dw2dx } u + \text{dw2dy } v) (\theta - 1) + (2 \text{dvdx } \text{dw2dx } u + \text{dvdy } \text{dw2dx } v + \text{dvdx } \text{dw2dy } v) \theta) + \text{tsupg} (\text{vkk} - v) (\\ 0 \end{pmatrix}$$

$$\text{SUPGNEWTONPRESSURE} = \text{TANGENT}[\text{SUPGPRESSURE}].\Delta \mathbf{U} = \begin{pmatrix} \text{tsupg} (\text{dw1dx } (\text{ukk} - u) + \text{dw1dy } (\text{vkk} - v)) (-\theta \text{dpolddx} + \text{dpolddx} + \text{dpdx } \theta) \\ \text{tsupg} (\text{dw2dx } (\text{ukk} - u) + \text{dw2dy } (\text{vkk} - v)) (-\theta \text{dpolddy} + \text{dpolddy} + \text{dpdy } \theta) \\ 0 \end{pmatrix}$$

$$\text{SUPGNEWTONFORCE} = \text{TANGENT}[\text{SUPGFORCE}].\Delta U = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

In[1812]:=

```
Clear[tsupg];
fname = FileNameJoin[{"D:\Documentos 2010\Mathematica Projects", "pre_stokes4cpp.txt"}];
s = OpenWrite[fname];
For[i = 1, i < dim + 2, i++,
  WriteString[s, "F" <> SymbolName[U[[i]]] <> "(i) += JxW[qp]*(\n");
  For[k = 1, k < Dimensions[GLOBALRESULT][[1]] + 1, k++,
    WriteString[s, "
                                +"]; Write[s, -GLOBALRESULT[[k, i, 4]]];
  ];
  WriteString[s, "
                                );\n \n"];
];

For[i = 1, i < dim + 2, i++,
  For[j = 1, j < dim + 2, j++,
    WriteString[s, "K" <> SymbolName[U[[i]]] <> SymbolName[U[[j]]] <> "(i,j) += JxW[qp]*(\n");
    For[k = 1, k < Dimensions[GLOBALRESULT][[1]] + 1, k++,
      WriteString[s, "
                                +"]; Write[s, GLOBALRESULT[[k, i, j]]];
    ];
    WriteString[s, "
                                );\n \n"];
  ]];

Close[s];
```

In[792]:= Dimensions[GLOBALRESULT]

Out[792]= {12, 3, 4}