CVPR 2017

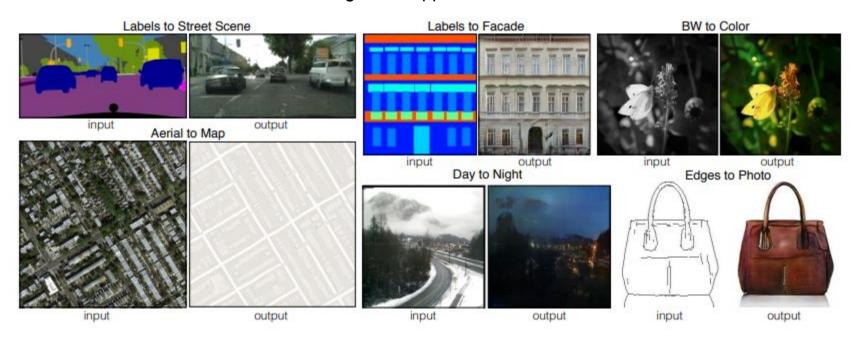
Image-to-Image Translation with Conditional Adversarial Nets

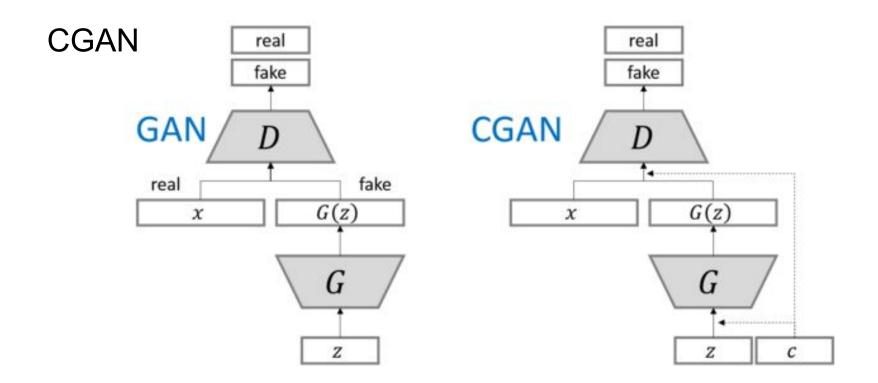
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Pix2Pix

CGAN을 사용한 image-to-image translation 메서드 제안 (논문 제목)

다양한 task에 공통적으로 활용할 수 있는 generic approach로 사용 가능



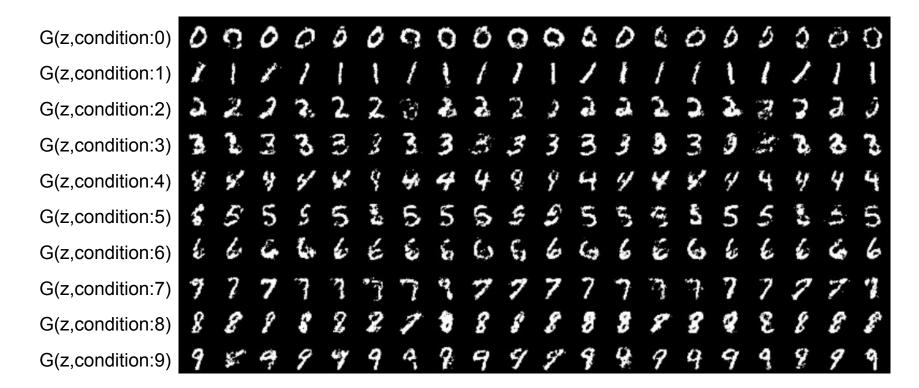


 $\text{GAN loss: } \min_{G} \max_{D} V(D,G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x})] + \mathbb{E}_{\boldsymbol{z} \sim p_{z}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z})))].$

 $\text{CGAN loss: } \min_{G} \max_{D} V(D,G) = \mathbb{E}_{\boldsymbol{x} \sim p_{\text{data}}(\boldsymbol{x})}[\log D(\boldsymbol{x}|\boldsymbol{y})] + \mathbb{E}_{\boldsymbol{z} \sim p_{z}(\boldsymbol{z})}[\log(1 - D(G(\boldsymbol{z}|\boldsymbol{y})))].$

⊎ithub.com/terra2007

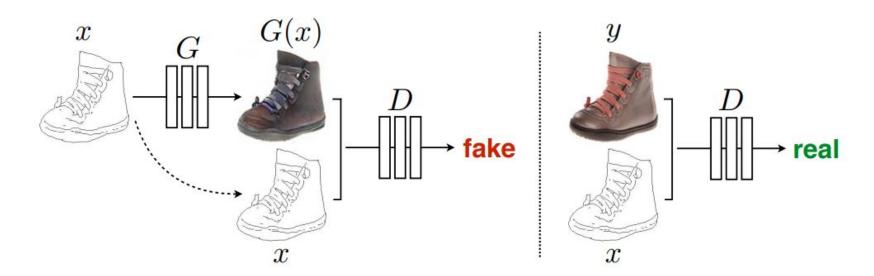
CGAN



Pix2Pix

Pix2Pix는 학습 과정에서 이미지 x를 Condition으로 입력받는 CGAN의 유형

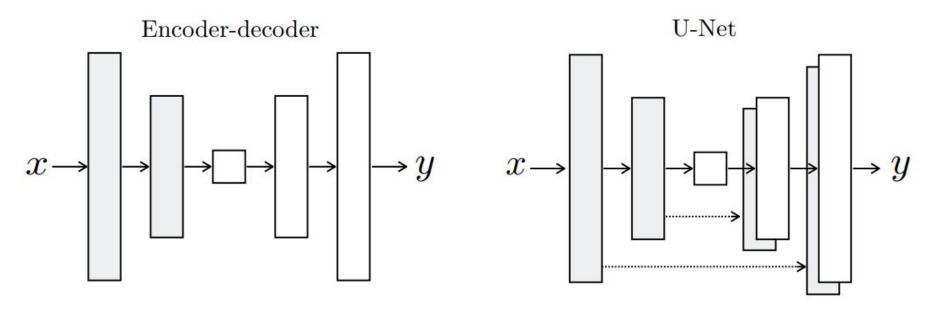
노이즈 z를 사용하지 않기 때문에 deterministic outputs



Pix2Pix architecture

Pix2Pix는 이미지를 Condition으로 입력받아, 이미지를 출력

이를 효과적으로 처리할 수 있는 U-Net 기반 architecture 사용



Objective function

GAN은 VAE같은 다른 생성 모델에 비해 blurry 한 결과가 적음 성능 향상을 위해 L1 loss를 사용

$$G^* = \arg\min_{G} \max_{D} \mathcal{L}_{cGAN}(G, D) + \lambda \mathcal{L}_{L1}(G).$$

$$\mathcal{L}_{cGAN}(G, D) = \mathbb{E}_{x,y}[\log D(x, y)] + \\ \mathbb{E}_{x,z}[\log(1 - D(x, G(x, z))]$$

$$\mathcal{L}_{L1}(G) = \mathbb{E}_{x,y,z}[\|y - G(x, z)\|_{1}].$$

$$\mathcal{L}_{L1}(G) = \mathbb{E}_{x,y,z}[\|y - G(x,z)\|_1].$$

L1 loss, L2 loss

L1 loss
$$L = \sum_{i=1} |y_i - f(x_i)|$$

L2 loss
$$L = \sum_{i=1}^{n} (y_i - f(x_i))^2$$

patchGAN

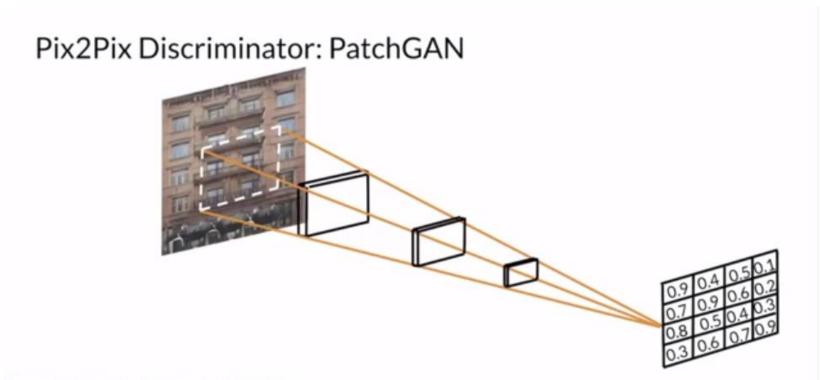
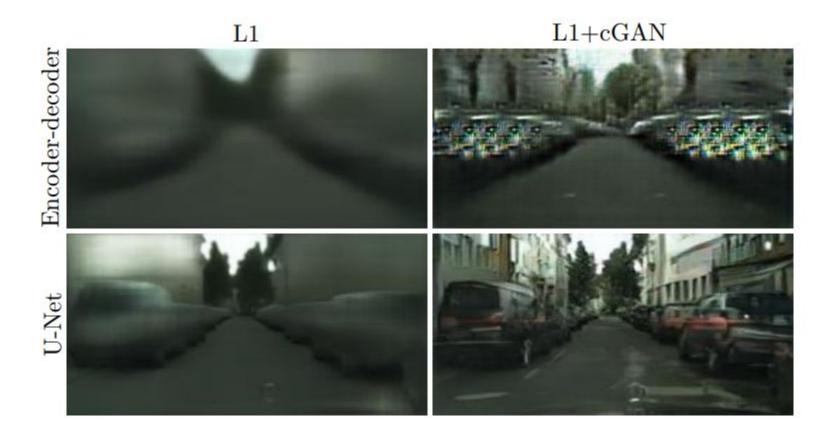


Image available from: https://arxiv.org/abs/1611.07004 Based on: https://arxiv.org/abs/1803.07422



github.com/terra2007



| U-net (L1) | 0.48 | 0.18 | 0.13 | |
|-----------------|------|------|------|--|
| U-net (L1+cGAN) | 0.55 | 0.20 | 0.14 | |
| | | | | |
| | | | | |
| | | | | |

Per-pixel acc.

0.35

0.29

Per-class acc.

0.12

0.09

Loss

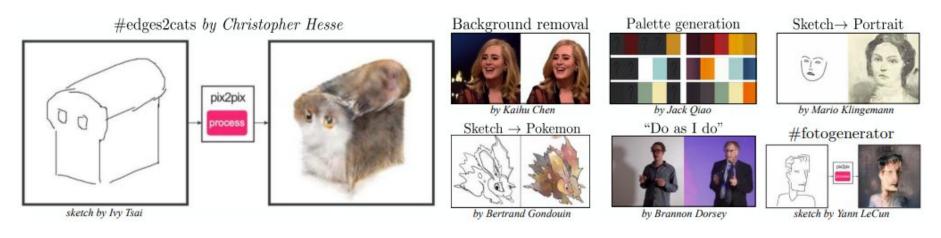
Encoder-decoder (L1)

Encoder-decoder (L1+cGAN)

Class IOU

0.08

0.05







Pix2Pix의 한계점

