Discrete and Algorithmic Geometry Sheet 4

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Problem G*. Enumerate, up to combinatorial equivalence, all balanced configurations V of n vectors in \mathbb{Z}^e whose coordinates are all at most m in absolute value, such that

- (1) the maximum m is achieved by some $v \in \mathcal{V}$,
- (2) and such that no hyperplane spanned by e-1 of the vectors strictly separates exactly one vector from the others.

For this, recall that a vector configuration $\mathcal{V} = (v_1, \ldots, v_n)$ is balanced if $\sum_i v_i = 0$; that no hyperplane defined by e-1 elements of \mathcal{V} separates exactly one vector from the others iff the Gale dual of \mathcal{V} is in convex position; and that two vector configurations are combinatorially equivalent if they define the same oriented matroid.

This problem can be divided in two parts

- 1. Find all "different" vector configurations
- 2. Identify those configurations that correspond to the same polytope.

Pseudocode

Trivial algorithm: check all the possibilities and after that check if they are combinatorially equivalent. $\mathcal{O}(m^{e(n-1)})$. This is really inefficient!

Note that up to combinatorial equivalence we can reduce the number of possibilities to $\mathcal{O}(m^{e(n-1)}/(|BC_e|n!))$ and $|BC_e| = 2^e e!$, so, it can be done much more efficiently than the algorithm above.

1. Dynamic programming? Calculate the V(n, e, m) using all the other configurations V(n', e', m') where n' < n, e' < e and m' < m.

Basic cases: For m = 0, the only configuration we can choose is n zero vectors. For n = 1, we can take every possible vector. (Estic molt espès i no se m'acudeixen altres casos base, a banda e = 0, que és una parida i no semblen rellevants. Si e = 1, triar n vectors en dimensió 1 ja és prou merda.)

Induction: (We add a vector to the configuration) $\mathcal{V}(n+1,e,m)$ Take a configuration $v=\{v_1,\ldots,v_n\}\in\mathcal{V}(n,e,m)$ for each vector v_i in this configuration consider all the configurations that keep constant this v_i and at all the other v_j $(j \neq i)$, we add the vectors of all the configurations of $\mathcal{V}(n,e,m)$ and the spare vector take as the n+1.

 $\mathcal{V}(n, e+1, m)$

(We incrementally consider larger boxes) $\mathcal{V}(n, e, m+1)$ Assume we have generated all configurations in $\mathcal{V}(n, e, m)$, then the only new configurations are the ones with at least one vector of length m+1. So, for every $i \in [1, n]$, choose i vectors in the boundary and n-i as in $\mathcal{V}(n-i, e, m)$. It remains to be checked which vectors of the boundary can be avoided