DPT Exercise 3 github.com/aiulus/dpt-ss25

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Emphasis points

1) Formal modeling of random experiments;

"groper probability space construction
    2) Law of total probability, Bayes Theorem
      3) Conditional probabilities
Laplace distr., (Continuous) Uniform distr.

podí's /colf's, vandom variables
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Exercise 1. We consider a fair tetrahedron whose faces are labeled with the numbers $\{1, 2, 3, 4\}$. Assume the tetrahedron is rolled $k \ge 1$ times. Let E be the event that the same number appears in each roll. Furthermore, let \underline{F} be the event that the product of the k rolled numbers is even.

(i) Compute the probability of E.

(ii) Compute the probability of F.

(iii) Compute the probability of $E \cup F$.

$$ncf disj. \Rightarrow \dots = \dots - PlE nF)$$

(i)
$$E = \{w = (n \dots n) \mid n \in [A]\}$$
; $|E| = |[A]| = 4$

$$\Rightarrow P(E) = \frac{|E|}{|A|} = \frac{4}{Ah} = \frac{1}{A^{h-1}}$$

F: product odd
$$\forall w: \forall w_1: w_1: \{1,3\} \Rightarrow |f^c| = |\{1,3\}^h| = 2^h$$

$$F^{c}: \text{ product odd} \qquad 47$$

$$P(F) = 1 - P(F^{c}) = 1 - \frac{|F^{c}|}{|\mathcal{M}|} = 1 - \frac{1}{|\mathcal{M}|} = 1 - \left(\frac{1}{1}\right)^{\frac{1}{2}}$$

$$EnF = \{ w = (n - n) \mid n \in \{1, 1, 3\} \} \Rightarrow |Enf| = |\{1, 1, 3\} = 2$$

$$\Rightarrow P(EUF) = \frac{4}{4h} + 1 - \left(\frac{1}{2}\right)^{h} - \frac{|EnF|}{|U|}$$

$$= \frac{4}{4h} + 1 - \left(\frac{1}{2}\right)^{h} - \frac{2}{4h} = 1 - \left(\frac{1}{2}\right)^{h} + \frac{2}{4h}$$

Definition 1.16 (measure, measure space). Let (Ω, \mathcal{A}) be a measurable space. We call $\mu: \mathcal{A} \to [0, \infty]$ a *measure* if

$$(i) \mu(\emptyset) = 0,$$

(ii) it is non-negative, i.e., for all $A \in \mathcal{A}$ we have $\mu(A) \geq 0$, and

(iii) it is σ -additive, i.e., for all countable collections $(A_i)_{i\in\mathbb{N}}$ of pairwise disjoint sets in \mathcal{A} , we have

$$\mu\left(\bigcup_{i\in\mathbb{N}}A_i\right)=\sum_{i\in\mathbb{N}}\mu(A_i)$$
.

The triple $(\Omega, \mathcal{A}, \mu)$ is then called a *measure space*.

Definition 1.18 (probability measure, probability space). Let (Ω, \mathcal{A}) be a measurable space. A measure $P: \mathcal{A} \to [0, \infty]$ is called *probability measure* if $P(\Omega) = 1$. The triple (Ω, \mathcal{A}, P) is then called *probability space*. In this case, \mathcal{A} is called the *event space* or *set of events of interest*.

Exercise 2. Let (Ω, \mathcal{A}, P) be a probability space, $B \in \mathcal{A}$ with P(B) > 0 and I a countable index set. Show the following statements:

(i) The map

$$\widetilde{P}: \mathcal{A} \to [0,1], \quad A \mapsto \widetilde{P}(A) := P(A \mid B)$$

is a probability measure on (Ω, \mathcal{A}) . The probability space $(B, \mathcal{A}|_B, \widetilde{P}|_B)$ is called *trace of* (Ω, \mathcal{A}, P) *on* B.

3. l.s.;
$$\tilde{P}(\bigcup_{n \in N} A_n) = \sum_{n \in N} \tilde{P}(A_n)$$

$$\tilde{P}(\bigcup_{n \in N} A_n) = P(\bigcup_{n \in N} A_n \mid B) = \frac{P((\bigcup_{n \in N} A_n) \mid nB)}{P(B)} = \frac{P((\bigcup_{n \in N} A_n) \mid nB)}{P(B)}$$

$$= \sum_{n \in N} \frac{P(A_n \mid B)}{P(B)} = \sum_{n \in N} \frac{P(A_n \mid B)}{P(B)} = \sum_{n \in N} P(A_n \mid B) = \sum_{n \in N} \tilde{P}(A_n)$$

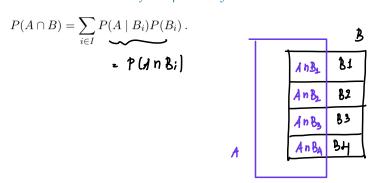
$$J. \tilde{P}(J) = 1$$

$$\tilde{P}(J) = \frac{P(J \cap B)}{P(B)} = \frac{P(B)}{P(B)} ; P(B) > 0$$

$$= 1$$

Exercise 2. Let (Ω, \mathcal{A}, P) be a probability space, $B \in \mathcal{A}$ with P(B) > 0 and I a countable index set. Show the following statements:

(ii) Let $\{B_i \mid i \in I\} \subseteq A$ be a measurable *partition* of B, i.e., $\bigcup_{i \in I} B_i = B$ and $B_i \cap B_j = \emptyset$ for all $i, j \in I$ with $i \neq j$. For all $A \in \mathcal{A}$ we then have the *law of total probability*



$$P(AnB) = P(An(\bigcup_{i \in I} B_i)) = P(\bigcup_{i \in I} AnB_i) = \sum_{i \in I} P(AnB_i) = \sum_{i \in I} \frac{P(AnB_i)}{P(B_i)}$$

$$P(AnB) = P(An(\bigcup_{i \in I} B_i)) = P(\bigcup_{i \in I} AnB_i)$$

$$P(AnB_i) = P(AnB_i) = \sum_{i \in I} \frac{P(AnB_i)}{P(B_i)} = \sum_{i \in I} \frac{P(AnB_i)}{P(B_i)}$$

$$P(AnB_i) = P(AnB_i) = \sum_{i \in I} \frac{P(AnB_i)}{P(B_i)} = \sum_{i \in I} \frac{P(AnB_i)}{P(AnB_i)} = \sum_{i \in I} \frac{P$$

$$An\left(\bigcup_{i\in\mathcal{I}}B_i\right)=\bigcup_{i\in\mathcal{I}}\left(AnB_i\right)$$

Exercise 2. Let (Ω, \mathcal{A}, P) be a probability space, $B \in \mathcal{A}$ with P(B) > 0 and I a countable index set. Show the following statements:

(iii) For each $A \in \mathcal{A}$ with P(A) > 0 and every measurable partition $\{B_i \mid i \in I\}$ of Ω with $P(B_i) > 0$ for all $i \in I$, we have the *Bayes rule*

$$P(B_i \mid A) = \frac{P(A \mid B_i)P(B_i)}{\sum_{j \in I} P(A \mid B_j)P(B_j)} \quad \text{for all } i \in I \;.$$

$$P(B; |A) = \frac{P(B; nA)}{P(A|B)} \xrightarrow{P(A|B_i) \cdot P(B_i)} P(A|B_i) \cdot P(B_i)$$

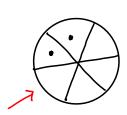
In
$$P(A) = P(A \cap L) = P(A \cap (\bigcup_{j' \in N} B_{\delta})) = P(\bigcup_{j' \in N} (A \cap B_{\delta})) = \sum_{j \in N} P(A \cap B_{\delta})$$

$$= \sum_{j \in N} P(A \cap B_{\delta}) \cdot P(B_{\delta})$$

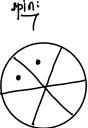
$$= \sum_{j \in N} P(A \cap B_{\delta}) \cdot P(B_{\delta})$$

Exercise 3. For each of the following settings provide all modeling details and rigorous computations for your results.

(i) You play Russian roulette with a six shooter revolver and there are precisely two bullets in neighboring chambers. Your opponent goes first, spins the barrel, pulls the trigger and the gun does not fire. Now it is your turn. Should you spin the barrel again or pull the trigger right away? What is the probability of survival in each case?



 $P(nsurvival^* \mid X_1 = 'nb') = P(X_2 = 'nb') X_1 = 'nb')$ (*)

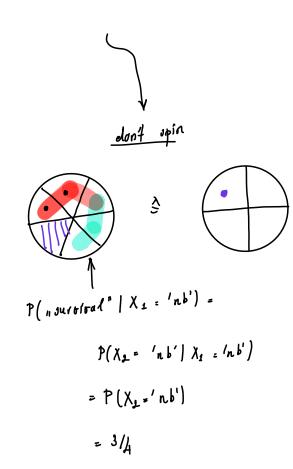


$$P(n \text{ survival}^n \mid X_1 = 'nb') =$$

$$P(x_1 = (nb)) = P(x_2 = (nb)) = P(x_2 = (nb))$$

$$= P(x_2 = (nb))$$

$$= 1/2$$



Exercise 3. For each of the following settings provide all modeling details and rigorous computations for your results.

(ii) I have two cards in a closed opaque box, one is red on both sides and the other is red on one and blue on the other side. I pull out one card and place it on the table and a red side faces up. What's the probability that the other side is also red?

P(nother side red" |
$$X_{col} = n \text{ red}^n$$
) = $P(X_{cord} = 1 \mid X_{col} = n \text{ red}^n)$
= $P(X_{col} = n \text{ red}^n \mid X_{cord} = 1) \cdot P(X_{cord} = 1 \mid X_{col} = n \text{ red}^n)$
 $P(X_{col} = n \text{ red}^n \mid X_{cord} = 1) \cdot P(X_{cord} = 1)$
 $P(X_{col} = n \text{ red}^n \mid X_{cord} = n) \cdot P(X_{cord} = n)$
 $P(X_{col} = n \text{ red}^n \mid X_{cord} = 1) \cdot P(X_{cord} = n)$
= $P(X_{col} = n \text{ red}^n \mid X_{cord} = 1) \cdot P(X_{cord} = n) \cdot P$

$$= \frac{P(X_{col} = y \text{ ved}^n | X_{card} = 1) \cdot P(X_{card} = n) + P(X_{col} = y \text{ ved}^n | X_{card} = n) \cdot P(X_{card} = n)}{P(X_{col} = y \text{ ved}^n | X_{card} = n) \cdot P(X_{card} = n)}$$

$$\frac{1}{1} \cdot \left(1 + \frac{1}{2}\right) = \frac{112}{\frac{1}{2} \cdot \frac{3}{2}} = \frac{1}{3}$$

Exercise 4. We uniformly choose a real number from [0,1], square it, and represent the result by a real-valued random variable X.

- (i) What is the cumulative distribution function of *X*?
- (ii) What is the probability density function of *X*?
- (iii) What is the probability that $X > \frac{1}{4}$. Try to find an answer in your head intuitively first.

Definition 1.10 (measurable space, measurable sets). A measurable space is a tuple (Ω, \mathcal{A}) , where Ω is a set and \mathcal{A} is a σ -algebra on Ω . The elements of \mathcal{A} are then called measurable sets

Definition 1.16 (measure, measure space). Let (Ω, \mathcal{A}) be a measurable space. We call $\mu : \mathcal{A} \to [0, \infty]$ a *measure* if

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- (iii) it is σ -additive, i.e., for all countable collections $(A_i)_{i\in\mathbb{N}}$ of pairwise disjoint sets in \mathcal{A} , we have

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.

The triple $(\Omega, \mathcal{A}, \mu)$ is then called a *measure space*.

Proposition 1.17 (basic properties of measures). Let $(\Omega, \mathcal{A}, \mu)$ be a measure space, $A, B \in \mathcal{A}$, and $(A_i)_{i \in \mathbb{N}} \subseteq \mathcal{A}$. Then

- $\mu(A \cup B) + \mu(A \cap B) = \mu(A) + \mu(B)$,
- $\mu(B \setminus A) = \mu(B) \mu(A)$, if $A \subseteq B$ and $\mu(A) < \infty$,
- μ is monotone, meaning that whenever $A \subseteq B$ we have $\mu(A) \leq \mu(B)$,
- μ is continuous from below, i.e., $\mu(A_k) \uparrow \mu\left(\bigcup_{i \in \mathbb{N}} A_i\right)$ for $A_0 \subseteq A_1 \subseteq A_2 \subseteq \ldots$,
- μ is continuous from above, i.e., $\mu(A_k) \downarrow \mu\left(\bigcap_{i \in \mathbb{N}} A_i\right)$ for $A_0 \supseteq A_1 \supseteq A_2 \supseteq \dots$ with $\mu(A_0) < \infty$,
- μ is σ -subadditive, meaning that

$$\mu\Big(\bigcup_{i\in\mathbb{N}}A_i\Big)\leq\sum_{i\in\mathbb{N}}\mu(A_i)$$
.

Definition 1.18 (probability measure, probability space). Let (Ω, \mathcal{A}) be a measurable space. A measure $P: \mathcal{A} \to [0, \infty]$ is called *probability measure* if $P(\Omega) = 1$. The triple (Ω, \mathcal{A}, P) is then called *probability space*. In this case, \mathcal{A} is called the *event space* or *set of events of interest*.