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#### Topics in LA

- Solve linear equations
- Matrices operations
  - Matrices addition/ multiplication / transformation
  - Eigenvalue/ Eigenvector
  - Transpose, projection ...
- Vector space
- **...**





#### Loops

- LA operations are often basic building blocks in scientific applications
- Three basic types of loops
  - Perfectly parallel loops
  - Reduction loops
  - Recursive loops
  - Combination of different loops



#### Perfectly parallel loops

```
■ Example Z_m = \lambda X_m + Y_m
for ( i = 0; i < m; i ++ ){
Z[i] = \lambda * X[i] + Y[i];}
```

MPI Scatter and MPI Gather



#### Reduction loops

- Limited parallelism
- Example: Dot production s = X•Y<sup>T</sup>

```
for ( i = 0; i < m; i ++ ) {
    s += X[i] + Y[i];
}
```

```
X P1 P2 P3 P4 P5 P6 .... Pn
Y P1 P2 P3 P4 P5 P6 .... Pn
```

MPI\_Reduce, MPI\_Allreduce



#### Recursive loops

- Each iteration depends on the previous one
- Hardly parallelize, "serial" loop
- Example



#### Nested loops

- Often the order of loops can be interchanged → for maximal parallelism, choose the perfectly-parallel loops as outmost, and parallelize over it.
- Example: Matrix-Vector multiplication

```
for ( <u>i</u> = 0; <u>i</u> < m; <u>i</u>++){

for ( <u>j</u> = 0; <u>j</u> < m; <u>j</u>++){

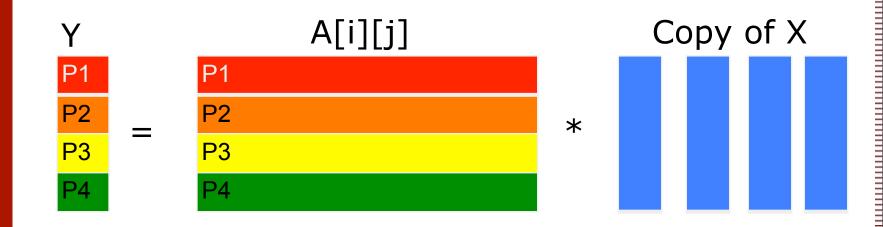
Y[i] += A[i][j] * X[j];

}
```



#### Nested loops – Alt 1

Row-wise partition



All processors have a copy of X, one piece of A and Y.



#### Nested loop – Alt. 2

Block algorithm with 1D partition



- Step 1: Compute Y[i] = A[i][i] \* X[i] in process i, and then shift X[i] circular one step up.
- Step 2: Compute again, in which j=(i+1) mod p, shift X circular one step up.
- Repeat, in total (p-1) step



#### Nested loop – Alt. 2 cont.

- Non-blocking communication to shift X, before computation. MPI\_Isend, MPI\_Irecv, MPI\_wait
- Which one is more efficient?
  - \* Alt. 2 is more memory efficient.
  - \* CPU efficient is all depends on the problem size, computer systems, implementations of MPI functions, etc.



#### Nested loop – Alt. 3

- Block algorithm 2D partition
- Processor block  $\sqrt{p} * \sqrt{p}$ ,
- Step 1: Divide A<sub>mn</sub> to √p \* √p blocks, X to √p parts
- Step 2: Processor  $P_{ij}$  get block  $A_{ij}$  and  $X_{j}$ , and hold  $Y_{i}^{(j)} = \mathbf{0}$
- Step 3:  $P_{ij}$  computes  $Y_i^{(j)} = A_{ij} * X_j$
- Step 4: Accumulate Y<sub>i</sub> in each row.



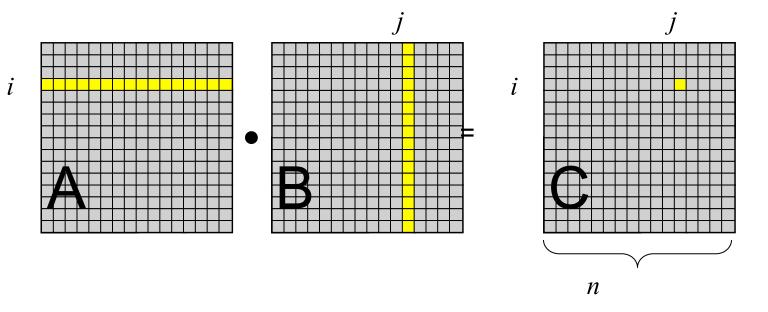
#### Nested loop – Alt. 3

$Y_0$	$\left[\begin{array}{c} \sum_{j} \end{array}\right]$	$Y_0^0 = A_{00} X_0$	$Y_0^1 = A_{01}^* X_1$	$Y_0^2 = A_{02} X_2$	$Y_0^3 = A_{03}^* X_3$
$Y_1$	$\begin{bmatrix} \leftarrow \frac{Z_j}{\nabla} \end{bmatrix}$	$Y_1^0 = A_{01}^* X_0$		•••	
$Y_2$	$-\frac{Z_{j}}{\nabla}$	$Y_2^0 = A_{02} X_0$		•••	
$Y_3$	] ← <b>∠</b> j	$Y_3^0 = A_{03} X_0$	$Y_3^1 = A_{13}^* X_1$	$Y_3^2 = A_{23}^* X_2$	$Y_3^3 = A_{33}^* X_3$

- Efficient for large matrices.
- Scalability? 2D > 1D. For many processors, 1D partition strips become so thin and communications increases faster.



#### Matrix-Matrix Multi.



$$C(i,j) = \Sigma_k A(i,k) B(k,j)$$



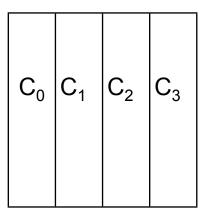
#### More nested Loops

- Example : Matrix-Matrix Multiplication
- i and j are perfectly parallel loops, k is reduction loop



#### Matrix-Matrix Multi.

■ 1D partitioning – choose j as the outmost loop → partition data column wise



 $A_0$   $A_1$   $A_2$   $A_3$ 

B <sub>00</sub>	B <sub>01</sub>	B <sub>02</sub>	B <sub>03</sub>
B <sub>10</sub>			
B <sub>20</sub>			
B <sub>30</sub>			B <sub>33</sub>

$$C_0 = A_0 * B_{00} + A_1 * B_{10} + A_2 * B_{20} + A_3 * B_{30}$$





#### C = A\*B, 1D partition

- A is needed in every processor.
- Alt. 1 : Every processor has completed A,
  - → Not scalable (memory?!)
- Alt. 2: Shift A around.
- → Similar idea to matrix-vector alt. 2.
  - For many processors, the stripes (block-columns) become thin and comm. overhead becomes large.

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### C = A\*B, 2D partition

- Choose both i and j outmost.
- √p \* √p blocks, each processor gets one block of each matrix.
- In processor  $P_{ij}$ , compute  $C_{ij} = \sum_{k=0}^{\sqrt{p}-1} A_{ik} * B_{kj}$ 
  - ightharpoonup P<sub>ij</sub> need all blocks A<sub>ik</sub> in block row i, and B<sub>ki</sub> in block column j
    - → Communications needed.



#### C = A\*B, 2D partition, Alt. 1

- Simple and naïve method.
- Simply distribute A in each block row, and distribute of B in each block column, using MPI\_functions
  - limited scalability due to memory.
    - → Bad performance if data don't fit in catch



### C = A\*B, 2D partition, Alt. 2 Cannon's Algorithm (1969)

- Shift and compute. M\*M mesh (√p \* √p blocks processors, data).
- Phase 1: shift
  - Shift the i th block row of A i steps cyclically to the left.
  - Shift the j th block column of B j steps cyclically upwards

A <sub>00</sub>	A <sub>01</sub>	A <sub>02</sub>	A <sub>03</sub>
A <sub>11</sub>			A <sub>10</sub>
A <sub>22</sub>	A <sub>23</sub>		A <sub>21</sub>
A <sub>33</sub>	A <sub>30</sub>	A <sub>31</sub>	A <sub>32</sub>

B <sub>00</sub>	B <sub>11</sub>	B <sub>22</sub>	B <sub>33</sub>
B <sub>10</sub>			B <sub>03</sub>
			B <sub>13</sub>
			B <sub>23</sub>

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### C = A\*B, 2D partition, Alt. 2 Cannon's Algorithm Cont.

- Phase 2: Compute and shift
- For each iteration do:
  - \* Compute  $C_{ij} = A_{ik} * B_{kj}$  in each processor  $P_{ij}$ , where k = (i+j+l) mod M, where l is the number of iterations (start from 0).
  - Shift A one step left, B one step upwards
- In total, M-1 steps. We can do shift with nonblocking communication, and compute while sending.
- Read more on-line <u>Cannon's algorithm</u>.



## C = A\*B, 2D partition, Alt. 3 Fox's Algorithm

- In total M-1 step.
- For each step k (k = 0,1,..., M-1)
  - Broadcast block n of A within each block row i (n = (i+k) mod M)
  - Multiply the broadcasted block with B-block in each processor (C<sub>ii</sub> += A<sub>in</sub>\*B<sub>ni</sub>)
  - \* Shift blocks of B, one step upwards.



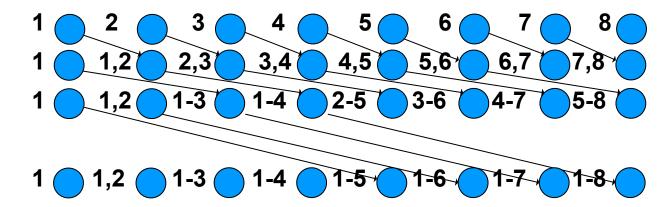
#### C = A\*B, 2D partition

- Both Cannon's and fox's algorithm is scalable.
- Which is more efficient?
  - Depends on problem size, computer system, efficiency of MPI, etc
- Read more about efficient on Fox and Cannon.



# Advanced Topic: Recursive loop

Example:





#### Assignment 1

- Dense matrix-matrix multiplication.
- Fortran/C/C++ and MPI.
- Two parameters:
  - The number of process
  - The size of matrices
- Randomly generate A and B
- Distribute data
- Implement Fox's algorithm
- Collect data and output.



#### Assignment 1, cont.

- Data generation (at rank 0): srand(), rand() / CALL RANDOM\_SEED(), CALL RANDOM\_NUMBER()
- Data distribution: use MPI\_Type\_vector, MPI\_Cart\_rank, MPI\_Isend, MPI\_Recv
- Data Collection: MPI\_Probe, MPI\_Cart\_coords, MPI\_Recv, MPI\_wait



#### Assignment 1, cont.

- C structure / C++ class is helpful to make a nicer code.
  - Name space works for large project.
- Good <u>coding style</u> makes your code more understandable and maintainable.
- Write comments in your code to help yourself and others.



# More Advanced Topic: BLAS

#### CPUs:

- Armadillo: Matlab style, C++ coding.
- \* CBLAS : GNU supported.
- Support: AMD -> ACML; IBM -> ESSL;
   Apple -> Accelerate framework; HP -> MLIB;
   SUN -> Sun Performance Library,
   Intel Math Kernel Library
- GPUs: NVIDIA -> CuBLAS

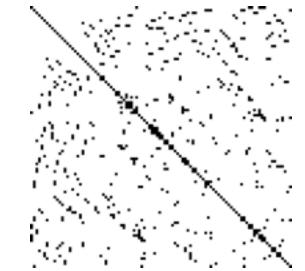
OPENCL: third part support.



### More Advanced Topic: Sparse Matrix

A sparse matrix is a matrix populated primarily with zeros.

- Save sparse matrix:
  - Dictionary of keys
  - List of lists
  - Coordinate list
  - Yale format
  - \* Etc.





# More Advanced Topic: Application using LA

- PageRank: imaging incredible large matrix
- Modern <u>Digital imaging</u>.
  - Video tracking: Xbox Kinect
- Genetics
- Cryptography
- Economic
- More ...



# More Advanced Topic: Application using LA

- Schedule & auto tuning
  - Test cases and pre-determined
  - Dynamically schedule
- Kernel and Convolution
  - Performs in parallel computers, edges of each blocks need to fix, according to the size of the kernel



#### Questions?

■ Find me at room P2304, or email: jing.liu@it.uu.se

Thanks.