ACM/CS 114 Parallel algorithms for scientific applications

Michael A. G. Aïvázis

California Institute of Technology

Winter 2012

Approximating Li₂ using a numerical quadrature

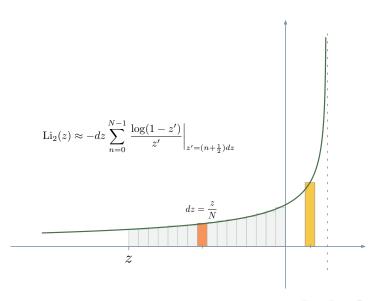
▶ the second homework assignment involved $Li_2(z)$, defined by

$$\text{Li}_2(z) := -\int_0^z dz' \, \frac{\log(1-z')}{z'}$$

▶ the assignment asked for approximating this integral using a simple quadrature based on the mid-point rule

$$\operatorname{Li}_2(z) pprox \operatorname{Li}_2(z, N) := -\frac{z}{N} \sum_{n=0}^{N-1} \left. \frac{\log(1-z')}{z'} \right|_{z'=(n+\frac{1}{2})\frac{z}{N}}$$

Quadrature rule



Implementations

- three implementations
 - sequential: to get a feeling for how to convert the algorithm into a functioning program
 - parallel using threads: to walk through the parallelization steps and use pthreads to get better performance
 - parallel using MPI: to get a feel for how MPI-based programs solve the task partitioning problem
- ▶ let's walk through composing, building and running
 - ▶ on my desktop, and on shc.cacr.caltech.edu

▶ the preamble

```
#include <getopt.h> // for getopt and friends
#include <cstdlib> // for atof
#include <cmath> // for the correct abs, log

#include <map>
#include <iostream>
#include <iomanip>
```

quadrature using the midpoint rule to avoid the singularities

```
8 // dilog
9 double dilog(double z, long N) {
     // initialize
   double dx = z/N;
   double x = dx/2:
   double sum = 0;
    // loop
     for (long i=0; i < N; i++) {
        sum += std::log(1-x)/x;
        x += dx;
     }
18
     // return; don't forget the sign
     return -dx * sum;
20
21
```

 \triangleright using the command line to set z and the number of subdivisions N

```
23 // main program
  int main(int argc, char* argv[]) {
     // default values for the command line options
     long N = 1000;
     double z = 1.0;
28
     // read the command line
29
     int command;
30
     while ((command = getopt(argc, argv, "z:N:")) != -1) {
31
        switch (command) {
        // get the argument of the dilogarithm
        case 'z':
34
            z = atof(optarg);
           break;
36
        // get the number of subdivisions
        case 'N':
38
           N = (long) atof(optarg);
30
           break:
40
```

error checking and computation of the numerical integral

```
// error checking
     // abort if N < 1
     if (N < 1) {
45
         std::cout
46
            << "the number of subdivisions must be positive"
            << std::endl:
48
         return 0;
      }
50
51
52.
     // abort for z > 1 to avoid dealing with the imaginary part
53
     if (z > 1.0) {
         std::cout << "math domain error: z > 1" << std::endl;</pre>
54
        return 0;
55
56
     // compute
58
     double value = dilog(z, N);
59
```

computing the error and printing out the results

```
60
     // build a naive database of the known dilogarithm values
     const double pi = M_PI;
61
     std::map<double, double> answers;
     answers[1.0] = pi*pi/6;
     answers[-1.0] = -pi*pi/12;
     // print out the value
66
     std::cout << "Li2(" << z << ")="
        << std::setprecision(17) << std::endl
68
        << " computed: " << value << std::endl:
69
     // check whether we know the right answer
70
     std::map<double,double>::const iterator lookup = answers.find(z);
     if (lookup != answers.end()) {
        // and if we do, print it out
        double exact = lookup->second:
74
        std::cout << " exact: " << exact << std::endl;
76
        // compute the approximation error and print it out
        double error = std::abs(exact-value)/exact;
        std::cout
78
           << std::setiosflags(std::ios base::scientific)
79
           << " error: " << error << std::endl;
80
81
     return 0:
84
```

Building and running the sequential driver

Threaded implementation - part 1

► the preamble

```
#include <getopt.h> // for getopt and friends
#include <pthread.h>

#include <cstdio>
#include <cstdlib> // for atof
#include <cmath>

#include <map>
#include <iostream>
#include <iomanip>
```

Threaded implementation - part 2

private and shared data structures

```
12 // shared information
13 struct problem {
    int workers: // total number of threads
14
    double dz;
                     // the width of each subdivision
16
     double sum; // storage for the partial computations
     pthread mutex t lock; // mutex to control access to the sum
19
  };
20
  // thread specific information
22 struct context {
    // thread info
24
    int id;
     pthread t descriptor:
    // the workload for this thread
26
     long subdivisions; // number of subdivisions
     double z_low; // the lower limit of integration
28
     double partial; // record the partial sum computed by this thread
29
     // the shared problem information
30
     problem* info;
31
32 };
```

Threaded implementation - part 3

▶ the coarse grain task

```
33 // worker
34 void* worker(void* arg) {
     context* ctxt = (context *) arg;
35
     // pull the problem information from the thread context
36
     double dz = ctxt->info->dz:
     double z = ctxt -> z low + dz/2;
38
     // loop over the subdivisions assigned to this thread
     double sum = 0.0:
40
     for (long i=0; i < ctxt->subdivisions; i++) {
41
         sum += std::log(1-z)/z;
42
        z += dz;
43
44
     // multiply by the width of each subdivision and adjust the sign
45
     sum *= -dz:
46
     // grab the lock
48
     pthread mutex lock(&(ctxt->info->lock));
     // store the result
50
     ctxt->info->sum += sum;
51
     // and release the lock
52.
     pthread_mutex_unlock(&(ctxt->info->lock));
53
54
     // all done
55
     return 0:
56
57
```