ACM/CS 114 Parallel algorithms for scientific applications

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Point to point communication

to send a message

```
int MPI_Send(
void* buffer, int count, MPI_Datatype datatype,
int destination, int tag, MPI_Comm communicator
);
```

▶ to receive a message

```
int MPI_Recv(
void* buffer, int count, MPI_Datatype datatype,
int source, int tag, MPI_Comm communicator
);
```

- ▶ the tag enables choosing the order you may receive pending messages
- but for a given (source,tag,communicator) messages are received in the order they were sent
- ► receiving via wildcards: MPI_ANY_SOURCE and MPI_ANY_TAG
- in standard communication mode, sending and receiving messages are blocking, so the function does not return until you can safely access the buffer
 - ▶ to read, free, etc.

Communication modes

- in standard mode, the specification does not explicitly mention buffering strategy
 - buffering messages would remove some of the access constraints but it requires time and storage for the multiple copies
 - portability across implementations implies conservative assumptions about the order of initiation of sends and receives to avoid deadlock
- in ready mode, you must post a receive before the matching send can be initiated
 - ▶ MPI_Rsend, MPI_Rrecv
- in buffered mode, sends can be initiated, and may complete, regardless of when the matching receive is initiate
 - ▶ MPI_Bsend, MPI_Brecv
- in synchronous mode, sends can be initiated regardless of whether the matching receive has been initiated, but the send will not return until the message has been received
 - ▶ MPI_Ssend.MPI_Srecv



Asynchronous communication

there are non-blocking versions of all these

```
int MPI_Isend(
void* buffer, int count, MPI_Datatype datatype,
int destination, int tag,
MPI_Comm communicator, MPI_Request* request
);
```

- faster, but you must take care to not access the message buffers until the messages have been delivered
- ▶ more details later in the course, as needed
- for sends
 - standard mode: MPT Isend
 - ▶ ready mode: MPI_Irsend
 - buffered mode: MPI_Ibsend
 - ▶ synchronous mode: MPI_Issend
- ▶ only one call for receives: MPI_Irecv
- extra request argument to check for completion of the request
 - ► MPI_Test, MPI_Wait and their relatives



Creating communicators and groups

- communicators and groups are intertwined
 - you cannot create a group without a communicator
 - you cannot create a communicator without a group
- ▶ the cycle is broken by MPI_COMM_WORLD

```
#include <mpi.h>
  int main(int argc, char* argv[]) {
     /* declare a communicator and a couple of groups */
      MPI Comm workers:
      MPI Group world_grp, workers_grp;
      /* initialize MPI: for brevity all status checks are omitted */
      MPI Init (&argc, &argv):
      /* get the world communicator to build its group */
      MPI Comm group (MPI COMM WORLD, &world grp);
14
      /* build another group by excluding a process */
15
      MPI_Group_excl(world_grp, 1, 0, &workers_grp);
16
      /* now build a communicator out of the processes in workers grp */
18
      MPI Comm create (MPI COMM WORLD, worker grp. &workers):
2.0
      /+ etc.... +/
      /* shut down MPI */
      MPI Finalize();
24
      return 0;
26
```

Manipulating communicators and groups

releasing resources

```
int MPI_Group_free(MPI_Group* group);
int MPI_Comm_free(MPI_Comm* communicator);
int MPI_Comm_disconnect(MPI_Comm* communicator);
```

you can make a new group by adding or removing processes from an existing one

```
int MPI_Group_incl(
    MPI_Group grp, int n, int* ranks, MPI_Group* new_group);
int MPI_Group_excl(
    MPI_Group grp, int n, int* ranks, MPI_Group* new_group);
```

or by using set operations

```
int MPI_Group_union(
    MPI_Group grp1, MPI_Group grp2, MPI_Group* new_group);
int MPI_Group_intersection(
    MPI_Group grp1, MPI_Group grp2, MPI_Group* new_group);
int MPI_Group_difference(
    MPI_Group grp1, MPI_Group grp2, MPI_Group* new_group);
```

Timing

- ▶ the function
- double MPI_Wtime();

returns the time in seconds from some arbitrary time in the past

- guaranteed not to change only for the duration of the process
- you can compute the elapsed time for any program segment by making calls at the beginning and the end and computing the difference
- no guarantees about synchronized clocks among different processes
- you can compute the clock resolution by using
 - double MPI_Wtick();

Other collective operations

▶ MPI_Scan computes partial reductions: the p^{th} process receives the result from processes 0 through p-1

```
int MPI_Scan(
void* send_buffer, void* recv_buffer,
int count, MPI_Datatype datatype, MPI_Op operation,
MPI_Comm communicator
);
```

▶ MPI_Reduce collects the result at only the given process root

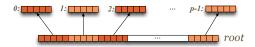
synchronization is also a global operation:

```
int MPI_Barrier(MPI_Comm communicator);
participating processes block at a barrier until they have all reached it
```

Scatter

▶ MPI_Scatter sends data from root to all processes

```
int MPI_Scatter(
    void* send_buffer, int send_count, MPI_Datatype send_datatype,
    void* recv_buffer, int recv_count, MPI_Datatype recv_datatype,
    int root, MPI_Comm communicator
);
```

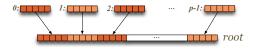


- ▶ it is as if the data in send_buffer were split in p segments, and the ith process receives the ith segment
- the send_xxx arguments are only meaningful for root; they are ignored for other processes
- ▶ the arguments root and communicator must be passed identical values by all processes

Gather

the converse is MPI_Gather with root receiving data from all processes

```
int MPI_Gather(
    void* send_buffer, int send_count, MPI_Datatype send_datatype,
    void* recv_buffer, int recv_count, MPI_Datatype recv_datatype,
    int root, MPI_Comm communicator
);
```



- ▶ it is as if *p* messages, one from each processes, were concatenated in rank order and placed at recv_buffer
- the recv_xxx arguments are only meaningful for root; they are ignored for other processes
- ▶ the arguments root and communicator must be passed identical values by all processes



Broadcasting operations

► MPI_Alltoall sends data from all processes to all processes in a global scatter/gather

```
int MPI_Alltoall(
    void* send_buffer, int send_count, MPI_Datatype send_datatype,
    void* recv_buffer, int recv_count, MPI_Datatype recv_datatype,
    MPI_Comm communicator
);
```

• use MPI_Bcast to send the contents of a buffer from root to all processes in a communicator

```
int MPI_Bcast(
void* buffer, int count, MPI_Datatype datatype,
int root, MPI_Comm communicator
);
```

Data movement patterns for the collective operations

