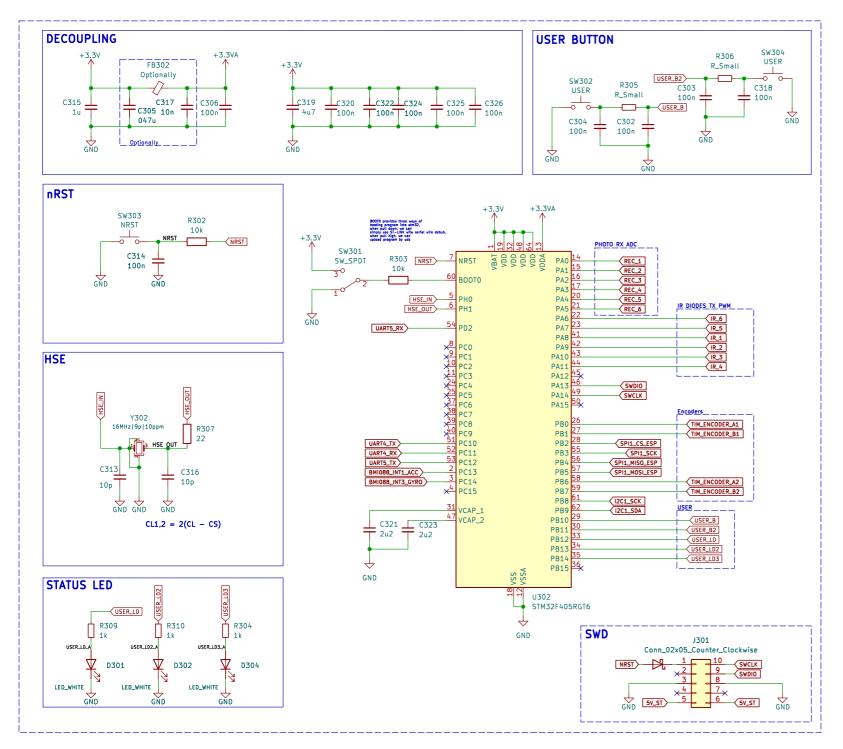
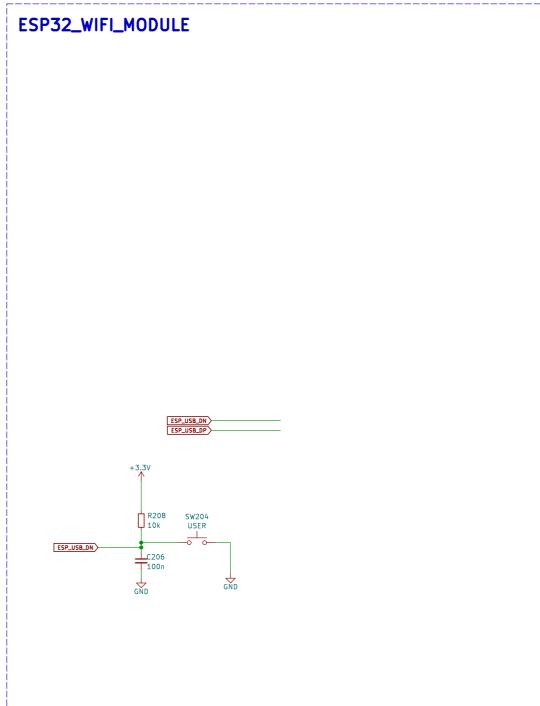


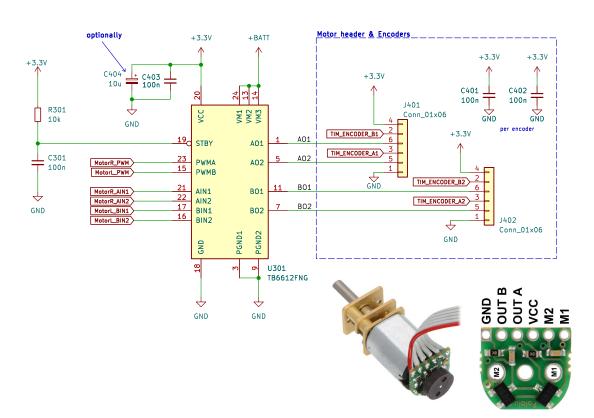
[3] Microcontroller & WIFI module





Sheet: /Micro	ocontroller/	
File: Microco	ntroller.kicad_sch	
Title:		
Size: A3	Date:	Rev:
KiCad E.D.A.	kicad 7.0.8	ld: 3/6
	7	8

[4] MOTORS

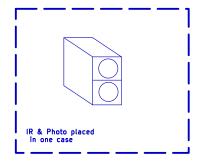


TRZEBA DODAĆ UCHWYTY TO MOCOWANIA SILNIKÓW!

Sheet: /Motor: File: Motors.ki			
Title:			
Size: User	Date:	Rev:	
KiCad E.D.A. kicad 7.0.8		ld: 4/6	

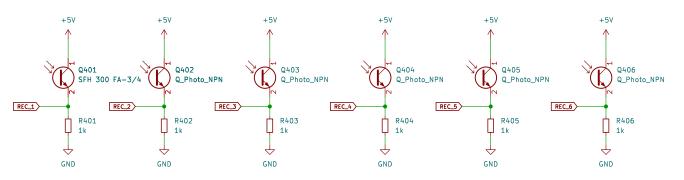
[5] IR RECEIVERS & EMITTERS

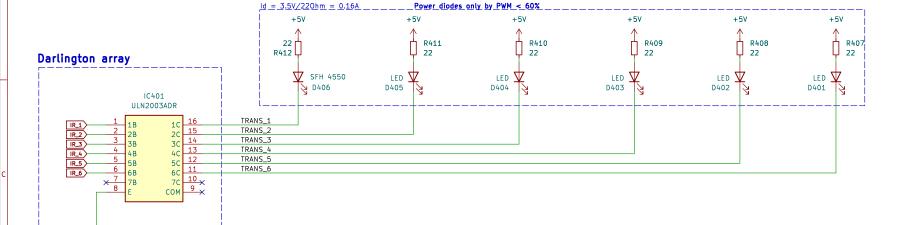
Diode max dc current = 100mA



GND

up to 500mA per channel





| Sheet: /Distance_sensors/ File: DistanceSensors.kicad_sch

 Title:

 Size: A4
 Date:
 Rev:

 KiCad E.D.A. kicad 7.0.8
 Id: 5/6

[6] Accelerometer & gyroscope I2C addr. Acc: 0011000 << 1 Gyro: 1101000 << 1 +3.3V +3.3V IC601 **BMI088** VDD BMIOSS INTL ACC C609 ____C610 CSB1 100n 100 n SCL/SCK - I2C1_SCK BMI088_INT3_GYRO SDA/SDI 12C1_SDA GND GND SD02 SD01 *Note BMI088 komunikuje sie przez I2C lub SPÍ, wada spi w tym sensorze jest taka, że potrzebne są dwa piny cs jeden dla akcelerometru, drugi dla żyroskopu **BMI088** Sheet: /IMU/ File: imu.kicad sch Title: Rev: Size: A5 Date: KiCad E.D.A. kicad 7.0.8 ld: 6/6