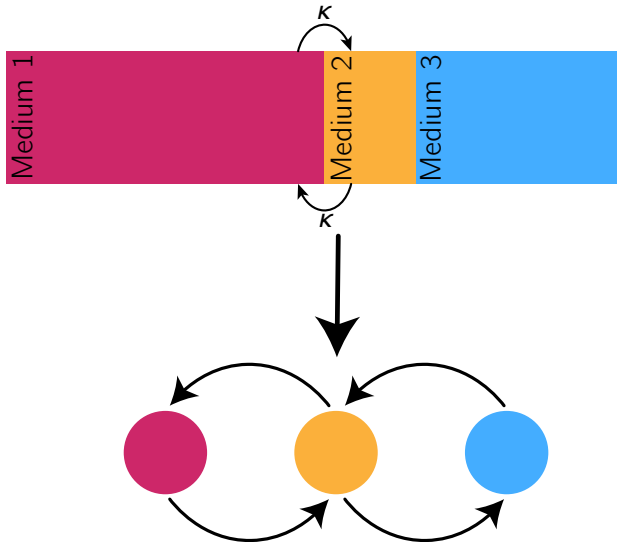


# Local time subordinating Poisson processes to model semi-permeable membranes

A. Brown — Hathcock group

January 7, 2026

# Coarse-graining



# Local time

- Let  $X_t$  denote a stochastic process on a state space  $S \subseteq \mathbb{R}^d$ . For a point  $y \in S$ , we define the **local time** process as

$$L_t^y = \int_0^t \delta(X_s - y) d[X_s] \quad (1)$$

- If  $X_t$  is a real-valued diffusion,  $dX_t = \mu(X, t) dt + \sigma(X, t) dW_t$ , then the quadratic variation is  $[X_t] = \int_0^t \sigma^2(X_s, s) ds$  and so  $d[X_t] = \sigma^2(X_t, t) dt$ . Local time thus has units  $[\text{length}]^{n+1}$  where  $n < d$  is the dimension of the (local) manifold

# Local time

- Let  $X_t$  denote a stochastic process on a state space  $S \subseteq \mathbb{R}^d$ . For a point  $y \in S$ , we define the **local time** process as

$$L_t^y = \int_0^t \delta(X_s - y) d[X_s] \quad (1)$$

- If  $X_t$  is a real-valued diffusion,  $dX_t = \mu(X, t) dt + \sigma(X, t) dW_t$ , then the quadratic variation is  $[X_t] = \int_0^t \sigma^2(X_s, s) ds$  and so  $d[X_t] = \sigma^2(X_t, t) dt$ . Local time thus has units  $[\text{length}]^{n+1}$  where  $n < d$  is the dimension of the (local) manifold
- Can reframe our problem as follows: A particle moves in a confining domain. When near the domain boundary, it is transported through to another domain, in a manner dependent upon the “number of attempts” to cross it (i.e., local time)<sup>1</sup>

# Poisson point processes

- Choose  $\Omega$  to be a domain with a smooth boundary  $\partial\Omega$ . The boundary local time is naturally defined as

$$L_t^{\partial S} = \int_{\partial\Omega} L_t^x d^{d-1}x \quad (2)$$

# Poisson point processes

- Choose  $\Omega$  to be a domain with a smooth boundary  $\partial\Omega$ . The boundary local time is naturally defined as

$$L_t^{\partial\Omega} = \int_{\partial\Omega} L_t^x d^{d-1}x \quad (2)$$

- The crossing process of a semi-permeable membrane located at  $\partial\Omega$  can be represented by a Poisson point process subordinated by the boundary local time  $\ell_t := L_t^{\partial\Omega}$ ,<sup>2</sup>

$$\mathbb{P}(N(\ell) = n) = \frac{(q\ell)^n}{n!} e^{-q\ell}, \quad (3)$$

where  $q = \kappa/D$  with  $\kappa$  the permeability of the membrane and  $D$  the (bulk) diffusivity<sup>1</sup>

# The Skorokhod equation

- For a single domain  $\Omega \subseteq \mathbb{R}^n$ , whereby after reaction, the particle is absorbed by the boundary, the motion is described by the Skorokhod equation<sup>3,1</sup>,

$$dX_t = \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (4)$$

where  $\hat{n}$  is the unit normal vector (of fixed orientation) to the boundary  $\partial\Omega$

# The Skorokhod equation

- For a single domain  $\Omega \subseteq \mathbb{R}^n$ , whereby after reaction, the particle is absorbed by the boundary, the motion is described by the Skorokhod equation<sup>3,1</sup>,

$$dX_t = \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (4)$$

where  $\hat{n}$  is the unit normal vector (of fixed orientation) to the boundary  $\partial\Omega$

- Naturally extended to include motion after surface reaction by inverting the direction of the boundary<sup>2</sup>

$$dX_t = (-1)^{N(\ell_t)} \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (5)$$



# The Skorokhod equation

- For a single domain  $\Omega \subseteq \mathbb{R}^n$ , whereby after reaction, the particle is absorbed by the boundary, the motion is described by the Skorokhod equation<sup>3,1</sup>,

$$dX_t = \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (4)$$

where  $\hat{n}$  is the unit normal vector (of fixed orientation) to the boundary  $\partial\Omega$

- Naturally extended to include motion after surface reaction by inverting the direction of the boundary<sup>2</sup>

$$dX_t = (-1)^{N(\ell_t)} \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (5)$$

- A further extension is to promote the noise to be multiplicative with the boundary separating the media,

$$D(X) = D_1 \mathbb{I}_\Omega(X) + D_2 \mathbb{I}_{\mathbb{R}^d \setminus \Omega}(X)$$

- We now wish to validate that Eq. (5) with multiplicative noise correctly recapilates the PDE form we found previously

- We now wish to validate that Eq. (5) with multiplicative noise correctly recapitulates the PDE form we found previously
- Following KG 2025<sup>2</sup>, we make use of

## The forward Feynman-Kac equation

Let  $L^* = \mu\partial + \frac{1}{2}\sigma\partial^2$  denote the (adjoint) diffusion generator and  $dX_t = b(X_t, t)dt + \sigma(X_t, t)dW_t$  its corresponding diffusion process. Given the conditional expectation of a test function  $\phi$  can be written

$$\int_{\Omega} \phi(y) q(y, t | x_0) dy = \mathbb{E}_{x_0} \left[ \exp \left( - \int_0^t V(X_s, s) ds \right) \phi(X_t) \right] \quad (6)$$

for a potential function  $V$ , then the (backwards-time) density  $q$  satisfies

$$\partial_t q(x, t | x_0) = (Lq)(x, t | x_0) - V(x, t)q(x, t | x_0) \quad (7)$$

with  $q(x, t | x_0) = \delta(x - x_0)$  and appropriate boundary conditions on  $\partial\Omega$ .

# Application of the Feynman-Kac equation

- In the “extended” Skorokhod equation (ESE), need to consider three processes:  $N_t$ ,  $\ell_t$  and  $W_t$

# Application of the Feynman-Kac equation

- In the “extended” Skorokhod equation (ESE), need to consider three processes:  $N_t$ ,  $\ell_t$  and  $W_t$
- Probability of  $n$  crossings is cond. independent from RBM  $Z_t$ ,

$$u(z, n, t \mid x_0) = \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} p(z, \ell, t \mid x_0) d\ell \quad (8)$$

- Take the Laplace transform of the propagator  $p(z, \ell, t \mid x_0)$ ,

$$\begin{aligned} P(z, \alpha, s \mid x_0) &= \int_0^\infty e^{-\alpha\ell} p(z, \ell, t \mid x_0) d\ell \\ &= \mathbb{E}_{x_0} [e^{-\alpha\ell_t} \delta(Z_t - z)] \end{aligned}$$

# Application of the Feynman-Kac equation

- In the “extended” Skorokhod equation (ESE), need to consider three processes:  $N_t$ ,  $\ell_t$  and  $W_t$
- Probability of  $n$  crossings is cond. independent from RBM  $Z_t$ ,

$$u(z, n, t \mid x_0) = \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} p(z, \ell, t \mid x_0) d\ell \quad (8)$$

- Take the Laplace transform of the propagator  $p(z, \ell, t \mid x_0)$ ,

$$\begin{aligned} P(z, \alpha, s \mid x_0) &= \int_0^\infty e^{-\alpha\ell} p(z, \ell, t \mid x_0) d\ell \\ &= \mathbb{E}_{x_0} [e^{-\alpha\ell_t} \delta(Z_t - z)] \end{aligned}$$

- Identify  $V = \alpha\delta(Z_t)$ , amounting to a PDE (by FK)

$$\partial_t P(x, \alpha, t \mid x_0) = [L^* - \alpha\delta(x)] P(x, \alpha, t \mid x_0), \quad (9)$$

with the boundary condition  $J(x, t) = 0$  for all  $x \in \partial\Omega$

# Stochastic to probabilistic

- Converting the PDE Eq. (9) back to in terms of the local time<sup>2</sup>,

$$\partial_t p(x, \ell, t \mid x_0) = [L^* - \delta(x) (\partial_\ell - \delta(\ell^+))] p(x, \ell, t \mid x_0) \quad (10)$$

- Compute the time derivative of the density  $u$ , Eq. (8),

$$\begin{aligned} \partial_t u &= \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} \partial_t p \, d\ell \\ &= \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} [L^* - \delta(x) (\partial_\ell + \delta(\ell^+))] p \, d\ell \\ &= L^* u - \delta(x) \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} \partial_\ell p \, d\ell \\ &= L^* u + \delta(x) \int_0^\infty \frac{qe^{-q\ell}}{n!} [(q\ell)^{n-1} - (q\ell)^n] p \, d\ell \end{aligned}$$

# References

- [1] D. S. Grebenkov, Phys. Rev. Lett. **125**, 078102 (2020).
- [2] T. Kay and L. Giuggioli, Phys. Rev. Res. **7**, 013097 (2025).
- [3] A. V. Skorokhod, Theory of Probability & Its Applications **6**, 264 (1961).



# Extended Skorokhod equation I

- We treat the one dimensional case with a single barrier at the origin. Kay & Giuglioli (2025)<sup>2</sup> showed that the correction EoM is

$$X_t = (-1)^{N(L_t^0)} \left| x_0 + \sqrt{2D}W_t \right| \quad (11)$$

- Consider the reflected Brownian motion,  $Z_t = |Y_t| = \left| x_0 + \sqrt{2D}W_t \right|$ . By Tanaka's formula, this can be written

$$Z_t = \int_0^t \operatorname{sgn} \left( x_0 + \sqrt{2D}W_s \right) dY_s + L_t^0 \quad (12)$$

which can be written in differential form as

$$dZ_t = \sqrt{2D}d\tilde{W}_t + dL_t^0, \quad (13)$$

using that the stochastic integral is itself a Brownian motion and  $dY_t = \sqrt{2D}dW_t$

# Extended Skorokhod equation II

- We can now use the product rule to determine the differential form of  $X_t$ , with  $\sigma_t = (-1)^{N(\ell_t)}$ , so  $dX_t = \sigma_t dZ_t + Z_t d\sigma_t$ , but  $d\sigma_t \propto dL_t^0$  is only non-zero when  $Z_t = 0$  so the second term is identically zero
- Recognize that  $\sigma_t d\tilde{W}_t$  remains white noise,

$$dX_t = \sigma_t dZ_t = \sqrt{2D} dW_t + (-1)^{N(L_t^0)} dL_t^0, \quad (14)$$

which we call the “extended” Skorokhod, equation, since it allows for motion on all of  $\mathbb{R}$  instead of  $\mathbb{R}^+$  as in the initial work of Skorokhod<sup>3</sup>

# Feynman-Kac equation I

Let  $V$  be a function with sufficient regularity conditions,  $\phi$  a test function and  $X_t$  a diffusion process with generator  $L = \mu_i \partial^i + \frac{1}{2} \sigma^2 \partial^2$ . We define the process

$$M_t = e^{-A_t} \phi(X_t), \quad A_t = \int_0^t V(X_s) ds.$$

By the chain rule, we have

$$dM_t = [(L\phi)(X_t, t) - V(X_t, t)\phi(X_t)] e^{-A_t} dt + \partial_i \phi \sigma_i e^{-A_t} dW_t.$$

Taking the expectation value the noise process vanishes, leaving

$$\frac{d}{dt} \mathbb{E}_{x_0}[M_t] = \mathbb{E}_{x_0} [e^{-A_t} (L - V(X_t, t)) \phi(X_t)].$$

# Feynman-Kac equation II

Since we define the FK-weighted, conditional backwards-time propagator  $q$  to act as

$$\int_{\Omega} q(y, t \mid x_0) \phi(y) dy = \mathbb{E}_{x_0} [e^{-A_t} \phi(X_t)] .$$

Comparing with the time derivative of  $\mathbb{E}_{x_0}[M_t]$ , we write

$$\frac{d}{dt} \int_{\Omega} q(y, t \mid x_0) \phi(y) dy = \int_{\Omega} q(y, t \mid x_0) (L - V(y, t)) \phi(y) dy .$$

Formally, integration by parts leaves the regular (non-adjoint) generator  $L$  acting on  $q$

# Feynman-Kac equation III

For the sake of concreteness, in one spatial dimension,

$$\begin{aligned}\int_a^b q(L\phi)dy &= \int_a^b q(y, t \mid x_0) \left( \mu \frac{d\phi}{dy} + \frac{1}{2} \sigma^2 \frac{d^2\phi}{dy^2} \right) dy \\ &= \int_a^b \phi L^* q dy + \left[ J\phi + \frac{1}{2} q \sigma^2 \phi' \right]_a^b,\end{aligned}$$

where  $J$  is the probability current  $J(x, t) = \mu q - \frac{1}{2}(\sigma^2 q)'$ . If we take  $a$  and  $b$  to be reflecting then we impose a Neumann-type BC  $J(a, t) = J(b, t) = 0$  and likewise  $\phi'(a) = \phi'(b) = 0$  (restrict space of test functions)