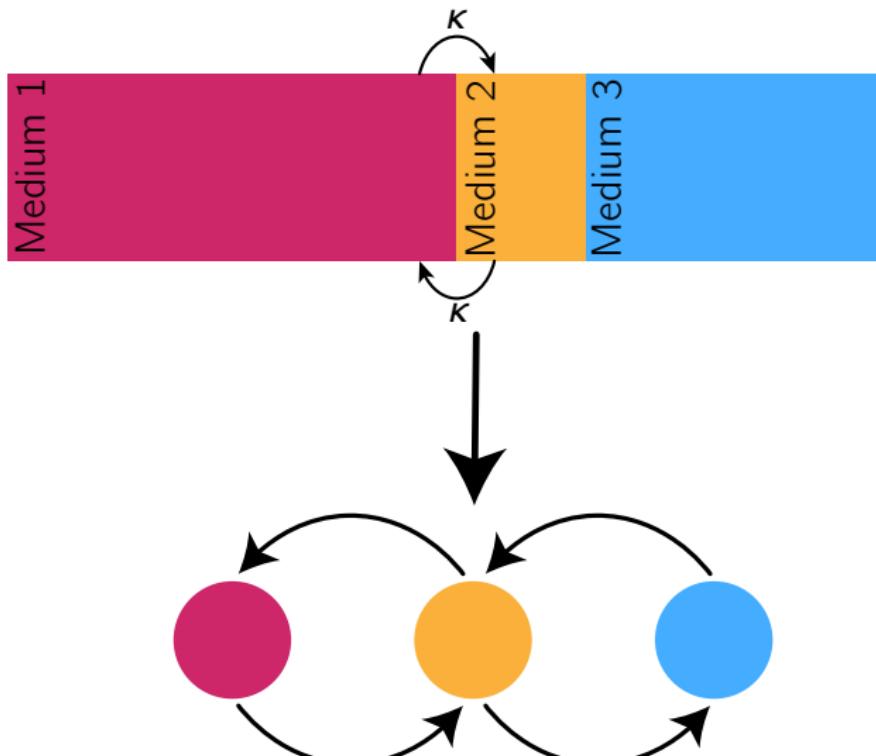


Local time subordinating Poisson processes to model semi-permeable membranes

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Coarse-graining



Local time

- Let X_t denote a stochastic process on a state space $S \subseteq \mathbb{R}^d$. For a point $y \in S$, we define the **local time** process as

$$L_t^y = \int_0^t \delta(X_s - y) d[X_s] \quad (1)$$

- If X_t is a real-valued diffusion, $dX_t = \mu(X, t) dt + \sigma(X, t) dW_t$, then the quadratic variation is $[X_t] = \int_0^t \sigma^2(X_s, s) ds$ and so $d[X_t] = \sigma^2(X_t, t) dt$. Local time thus has units $[\text{length}]^{n+1}$ where $n < d$ is the dimension of the (local) manifold

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- Can reframe our problem as follows: A particle moves in a confining domain. When near the domain boundary, it is transported through to another domain, in a manner dependent upon the “number of attempts” to cross it (i.e., local time)¹

Poisson point processes

- Choose Ω to be a domain with a smooth boundary $\partial\Omega$. The boundary local time is naturally defined as

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- The crossing process of a semi-permeable membrane located at $\partial\Omega$ can be represented by a Poisson point process subordinated by the boundary local time $\ell_t := L_t^{\partial\Omega}$,²

$$\mathbb{P}(N(\ell) = n) = \frac{(q\ell)^n}{n!} e^{-q\ell}, \quad (3)$$

where $q = \kappa/D$ with κ the permeability of the membrane and D the (bulk) diffusivity¹

The Skorokhod equation

- For a single domain $\Omega \subseteq \mathbb{R}^n$, whereby after reaction, the particle is absorbed by the boundary, the motion is described by the Skorokhod equation^{3,1},

$$dX_t = \hat{n}(X) d\ell_t + \sqrt{2D} dW_t, \quad (4)$$

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- A further extension is to promote the noise to be multiplicative with the boundary separating the media,

$$D(X) = D_1 \mathbb{I}_\Omega(X) + D_2 \mathbb{I}_{\mathbb{R}^d \setminus \Omega}(X)$$

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- Following KG 2025², we make use of

The forward Feynman-Kac equation

Let $L^* = \mu\partial + \frac{1}{2}\sigma\partial^2$ denote the (adjoint) diffusion generator and $dX_t = b(X_t, t)dt + \sigma(X_t, t)dW_t$ its corresponding diffusion process. Given the conditional expectation of a test function ϕ can be written

$$\int_{\Omega} \phi(y) q(y, t | x_0) dy = \mathbb{E}_{x_0} \left[\exp \left(- \int_0^t V(X_s, s) ds \right) \phi(X_t) \right] \quad (6)$$

for a potential function V , then the (backwards-time) density q satisfies

$$\partial_t q(x, t | x_0) = (Lq)(x, t | x_0) - V(x, t)q(x, t | x_0) \quad (7)$$

with $q(x, t | x_0) = \delta(x - x_0)$ and appropriate boundary conditions on $\partial\Omega$.

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$$u(z, n, t \mid x_0) = \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} p(z, \ell, t \mid x_0) d\ell \quad (8)$$

- Take the Laplace transform of the propagator $p(z, \ell, t \mid x_0)$,

$$\begin{aligned} P(z, \alpha, s \mid x_0) &= \int_0^\infty e^{-\alpha\ell} p(z, \ell, t \mid x_0) d\ell \\ &= \mathbb{E}_{x_0} [e^{-\alpha\ell_t} \delta(Z_t - z)] \end{aligned}$$

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- Identify $V = \alpha\delta(Z_t)$, amounting to a PDE (by FK)

$$\partial_t P(x, \alpha, t \mid x_0) = [L^* - \alpha\delta(x)] P(x, \alpha, t \mid x_0), \quad (9)$$

with the boundary condition $J(x, t) = 0$ for all $x \in \partial\Omega$

Stochastic to probabilistic

- Converting the PDE Eq. (9) back to in terms of the local time²,

$$\partial_t p(x, \ell, t | x_0) = [L^* - \delta(x) (\partial_\ell - \delta(\ell^+))] p(x, \ell, t | x_0) \quad (10)$$

- Compute the time derivative of the density u , Eq. (8),

$$\begin{aligned} \partial_t u &= \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} \partial_t p d\ell \\ &= \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} [L^* - \delta(x) (\partial_\ell + \delta(\ell^+))] p d\ell \\ &= L^* u - \delta(x) \int_0^\infty \frac{(q\ell)^n}{n!} e^{-q\ell} \partial_\ell p d\ell \\ &= L^* u + \delta(x) \int_0^\infty \frac{qe^{-q\ell}}{n!} [(q\ell)^{n-1} - (q\ell)^n] p d\ell \end{aligned}$$

References

- [1] D. S. Grebenkov, Phys. Rev. Lett. **125**, 078102 (2020).
- [2] T. Kay and L. Giuggioli, Phys. Rev. Res. **7**, 013097 (2025).
- [3] A. V. Skorokhod, Theory of Probability & Its Applications **6**, 264 (1961).

Extended Skorokhod equation I

- We treat the one dimensional case with a single barrier at the origin. Kay & Giuggioli (2025)² showed that the correction EoM is

$$X_t = (-1)^{N(L_t^0)} \left| x_0 + \sqrt{2D} W_t \right| \quad (11)$$

- Consider the reflected Brownian motion,
 $Z_t = |Y_t| = \left| x_0 + \sqrt{2D} W_t \right|$. By Tanaka's formula, this can be written

$$Z_t = \int_0^t \operatorname{sgn} \left(x_0 + \sqrt{2D} W_s \right) dY_s + L_t^0 \quad (12)$$

which can be written in differential form as

$$dZ_t = \sqrt{2D} d\tilde{W}_t + dL_t^0, \quad (13)$$

using that the stochastic integral is itself a Brownian motion and
 $dY_t = \sqrt{2D} dW_t$

Extended Skorokhod equation II

- We can now use the product rule to determine the differential form of X_t , with $\sigma_t = (-1)^{N(\ell_t)}$, so $dX_t = \sigma_t dZ_t + Z_t d\sigma_t$, but $d\sigma_t \propto dL_t^0$ is only non-zero when $Z_t = 0$ so the second term is identically zero
- Recognize that $\sigma_t d\tilde{W}_t$ remains white noise,

$$dX_t = \sigma_t dZ_t = \sqrt{2D} dW_t + (-1)^{N(L_t^0)} dL_t^0, \quad (14)$$

which we call the “extended” Skorokhod, equation, since it allows for motion on all of \mathbb{R} instead of \mathbb{R}^+ as in the initial work of Skorokhod³

Feynman-Kac equation I

Let V be a function with sufficient regularity conditions, ϕ a test function and X_t a diffusion process with generator $L = \mu_i \partial^i + \frac{1}{2} \sigma^2 \partial^2$. We define the process

$$M_t = e^{-A_t} \phi(X_t), \quad A_t = \int_0^t V(X_s) ds.$$

By the chain rule, we have

$$dM_t = [(L\phi)(X_t, t) - V(X_t, t)\phi(X_t)] e^{-A_t} dt + \partial_i \phi \sigma_i e^{-A_t} dW_t.$$

Taking the expectation value the noise process vanishes, leaving

$$\frac{d}{dt} \mathbb{E}_{x_0}[M_t] = \mathbb{E}_{x_0} [e^{-A_t} (L - V(X_t, t)) \phi(X_t)].$$

Feynman-Kac equation II

Since we define the FK-weighted, conditional backwards-time propagator q to act as

$$\int_{\Omega} q(y, t | x_0) \phi(y) dy = \mathbb{E}_{x_0} [e^{-A_t} \phi(X_t)].$$

Comparing with the time derivative of $\mathbb{E}_{x_0}[M_t]$, we write

$$\frac{d}{dt} \int_{\Omega} q(y, t | x_0) \phi(y) dy = \int_{\Omega} q(y, t | x_0) (L - V(y, t)) \phi(y) dy.$$

Formally, integration by parts leaves the regular (non-adjoint) generator L acting on q

Feynman-Kac equation III

For the sake of concreteness, in one spatial dimension,

$$\begin{aligned} \int_a^b q(L\phi) dy &= \int_a^b q(y, t | x_0) \left(\mu \frac{d\phi}{dy} + \frac{1}{2} \sigma^2 \frac{d^2\phi}{dy^2} \right) dy \\ &= \int_a^b \phi L^* q dy + \left[J\phi + \frac{1}{2} q\sigma^2 \phi' \right]_a^b, \end{aligned}$$

where J is the probability current $J(x, t) = \mu q - \frac{1}{2}(\sigma^2 q)'$. If we take a and b to be reflecting then we impose a Neumann-type BC $J(a, t) = J(b, t) = 0$ and likewise $\phi'(a) = \phi'(b) = 0$ (restrict space of test functions)