# A Comparison of Antenna Placement Algorithms

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#### **Contributions**

- ► Formulation of the antenna placement problem
- Evaluation of standard stochastic algorithms on a real-world problem
- Able to achieve global optimum with as low as 25% evaluations of search space

#### Outline of this talk

- ► Part 1: Introduction to the antenna placement problem
- ► Part 2: Description of stochastic algorithms, their properties and operators
- ► Part 3: Evaluation of test cases



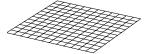
Part 1: Introduction to the antenna placement problem

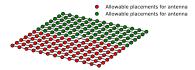


#### **Antenna Placement Problem**

Given, platform

allowable placements of antennas



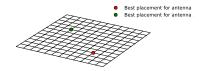


#### **Antenna Placement Problem**





#### **Problem:** find best antenna placements



#### **Antenna Placement Problem**

#### Given:

- ▶ platform *P* with its surface gridded such that end points represent possible antenna placements
- ▶ set of *m* antennas  $A = A_1, A_2, ..., A_m$  such that m > 1
- ▶ for each  $A_i$ ,  $L_i$  denote the set of allowable placements  $\in \mathbb{R}^3$  such that  $|L_i| = n_i$  and  $\forall i, n_i > 1$ ;  $L_i = \{(x_1, y_1, z_1) ... (x_{n_i}, y_{n_i}, z_{n_i})\}$

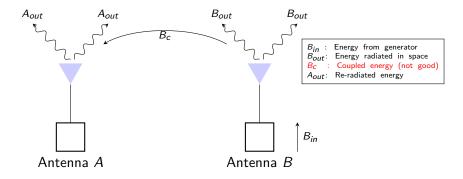
**Problem**: Find a set of n optimal antenna placements on P

Question: How is a good antenna placement quantified in the context of platform and other antennas?



# **Mutual Coupling**

When two antennas are in proximity, and one is transmitting, the second will receive some of the transmitted energy.



# Minimize Mutual Coupling

$$F_{MC} = \sum_{i=1}^{n-1} \sum_{j=i+1}^{n} CP(A_i, A_j), \tag{1}$$

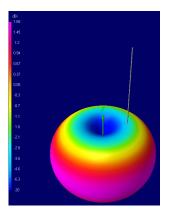
#### where

►  $CP(\cdot,\cdot) \in \mathbb{R}$  is the coupling between two antennas, and computed using a simulator

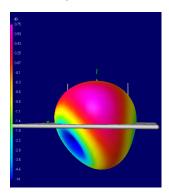
Example: If n = 3, then  $F_{MC} = CP(A_1, A_2) + CP(A_1, A_3) + CP(A_2, A_3)$ 

#### Radiation Pattern

Free-space pattern without platform or other antennas

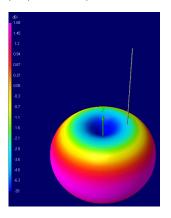


In-situ pattern with platform and random antenna placements

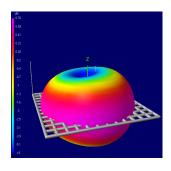


#### **Radiation Pattern**

Free-space pattern without platform or other antennas



In-situ pattern with platform and best antenna placements chosen by the algorithm



#### Minimize Difference in Radiation Pattern

$$F_{RP} = \sum_{i=1}^{n} \sum_{\theta=0}^{\pi} \sum_{\phi=0}^{2\pi} (FSG_i(\theta, \phi) - ISG_i(\theta, \phi))^2, \qquad (2)$$

#### where

- θ, φ spherical coordinates
- ►  $FSG(\cdot, \cdot) \in \mathbb{R}$  is the free-space gain pattern computed by the simulator
- ►  $ISG(\cdot, \cdot) \in \mathbb{R}$  is the in-situ gain pattern computed by the simulator

## **Objective Function**

Find a placement such that F is minimal:

$$F = \alpha F_{MC} + \beta F_{RP}, \tag{3}$$

where  $\alpha,\beta$  are adjustable weights for each of the objectives

# Part 2: Stochastic Algorithms



# **Stochastic Algorithms**

We will consider algorithms which rely on randomization principle.

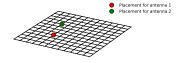
- ► Genetic Algorithm
- Evolutionary Strategy
- Simulated Annealing
- Hill Climbing

Each algorithm maintains a candidate solution or pool of candidate solutions called population

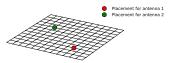
# **Stochastic Algorithms: Operand**

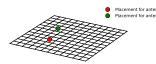
**Candidate solution** or an **individual** is a member of a set of possible solutions.

 Simulated Annealing and Hill Climbing maintain single individual



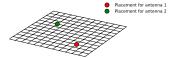
 Genetic Algorithm and Evolutionary Strategy maintain a population of individuals



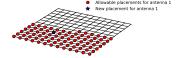


# **Stochastic Algorithms: Mutation Operator**

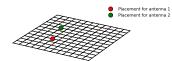
1. Given an individual, select an antenna uniformly at random, let's say antenna 1:



2. For antenna 1, select any other allowable placement:

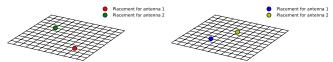


3. Change position for antenna 1 in individual:



# **Stochastic Algorithms: Crossover Operator**

1. Select two individuals from population:



2. Select a crossover point, and swap placements prior to the point:



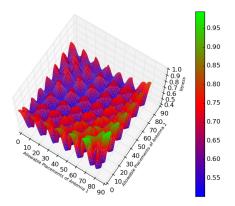
3. Two new offsprings created:



Question: Why use stochastic algorithms?



# Multi-Modal Search Space



Search space for one of the test cases evaluated. There are multiple local minimas which makes convergence difficult. z-axis is the combined fitness F (refer Eq. 3)



# **Genetic Algorithm**

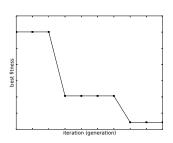
```
1 P \leftarrow \text{generate } p \text{ random individuals. Compute}
    fitness(ind_i), i \in [1, p];
 i = 0:
    while i < gen_{max} do
          Elitism: Select n_e fittest individuals to add to P';
          for (p-n_e)/2 times do

| /* 'select' returns a pair of individuals
 5
                                                                          */
                M \leftarrow select(P,2);
                if rand(0,1) < p_c then
                      \mathbf{O} \leftarrow crossover(\mathbf{M});
                      Add O to P':
                else
10
                      Add M to P';
11
          Uniformly select p_m \cdot (p - n_e) individuals from P,
12
          and apply mutation operator to each;
          Update P \leftarrow P':
13
          Compute fitness(ind_i); i \in [1, p];
14
          Update i \leftarrow i + 1:
15
```

# **Genetic Algorithm**

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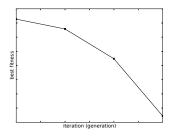
Plateaus suggesting stagnation of search

# **Evolutionary Strategy**

```
    P← generate μ random individuals;
    i = 0;
    while i < gen<sub>max</sub> do
    Create λ/μ offsprings from each μ individuals by applying mutation operator;
    Add all offsprings to P;
    Compute fitness(ind<sub>i</sub>), i ∈ [1, λ + μ];
    Keep μ best individuals in P, and discard remaining λ - μ individuals;
    Update i ← i + 1
```

# **Evolutionary Strategy**

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```



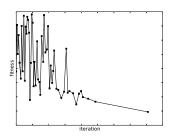
Less likely to stagnate search space exploration

# **Simulated Annealing**

```
c ← generate a random individual;
 i = 0:
    while i < i_m ax do
         n \leftarrow mutate(c);
         if fitness(c) < fitness(n) then
               if rand(0,1) < e^{-\delta f/T} then
 6
                     /* replace current individual by a higher
                         fitness (less fitter) individual
                                                                         */
 7
          else
           c ← n;
         T \leftarrow T \cdot f_{cooling}; i \leftarrow i + 1;
10
11
```

# **Simulated Annealing**

```
1 c \leftarrow generate \ a \ random \ individual \ ;
2 i=0;
3 while i < i_m ax \ do
4 n \leftarrow mutate(c);
5 if \ fitness(c) < fitness(n) \ then
6 if \ \frac{rand(0,1) < e^{-\delta f/T}}{fitness \ (less \ fitter) \ individual} \ y \ a \ higher fitness \ (less \ fitter) \ individual \ */
7 else
9 c \leftarrow n;
10 T \leftarrow T \cdot f_{cooling};
11 i \leftarrow i+1;
```



Fluctuation in fitness gradually reduces due to cooling

# Hill Climbing

```
1 Initialize c \leftarrow generate \ a \ random \ inidividual;

2 Compute fitness(c);

3 i = 0;

4 while i < i_{max} \ do

5 | n \leftarrow mutate(c);

6 | if fitness(n) < fitness(c) then

7 | c \leftarrow n

8 | i \leftarrow i + 1
```

# Hill Climbing

```
Initialize \mathbf{c} \leftarrow \text{generate a random inidividual};

Compute fitness(\mathbf{c});

i = 0;

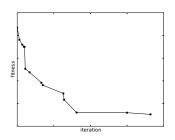
while i < i_{max} do

\mathbf{n} \leftarrow mutate(\mathbf{c});

if \underbrace{fitness(n) < fitness(c)}_{\mathbf{c}} then

\underbrace{\mathbf{c} \leftarrow \mathbf{n}}_{\mathbf{c}}

i \leftarrow i + 1
```



Greedy approach to accept only fitter(low fitness) individuals

# Part 3: Evaluation of test cases

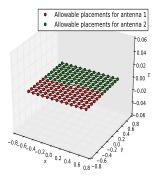


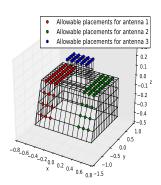
## **Experimental Setup**

- 1. All test cases describe platforms which are replicas of real-world use cases like mobile devices, tanks, and cars
- 2. We use a popular NEC2 simulator  $^1$  to get fitness parameters
- 3. Evaluate the entire search space using an exhaustive algorithm to find the optimal antenna locations



### **Experiments: Test Cases**



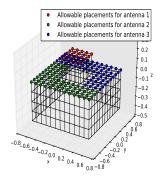


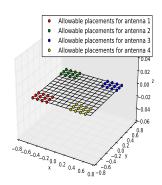
Test Case #1 with 7056 (84x84) allowable placements

Test Case #2 with 50625 (45x45x45) allowable placements



### **Experiments: Test Cases**

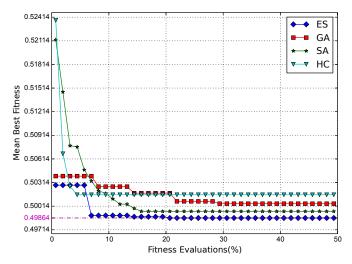


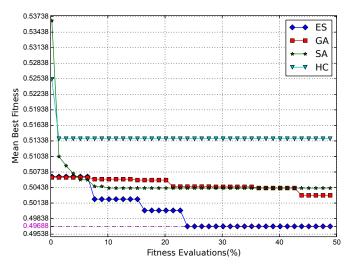


Test Case #3 with 126025 (71 $\times$ 71 $\times$ 25) allowable placements

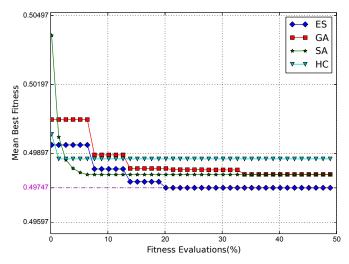
Test Case #4 with 20736 (12x12x12x12) allowable placements

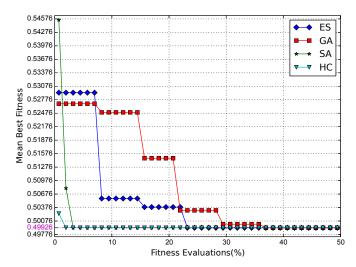






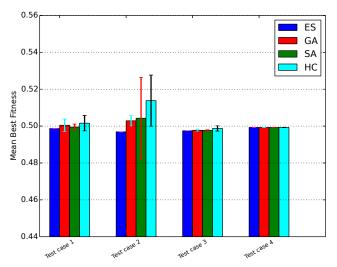




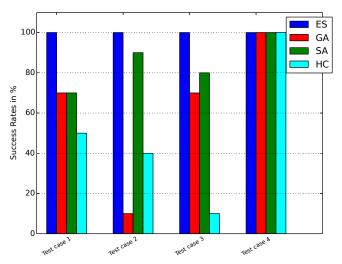




#### Results - Mean Best Fitness With Std. Dev.



#### **Results - Success Rates**



#### Conclusion

- ► Formulation of the antenna placement problem
- Generic problem formulation to accommodate multiple antennas and platforms
- ► Optimal placements found using Evolutionary Strategy with at most 25% evaluations of search space