# Section 1. Bayesian Inference

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### **Overview**

### What is Bayesian Statistics?

Method of statistical inference that incorporates prior knowledge to make probabilistic statements about quantities of interest

- · Write a probabilistic model/data generating process
- Add prior/penalize parameters in model
- Fit model to data (experiment)
- Use fitted model to produce estimate; quantify uncertainty in estimate
- · Model checking, diagnostics

Contrast with: machine learning, classical statistics, econometrics

# Why Bayes?

- · Computation
- · Prior information
- · Regularization
- Coherence
- · Explicit uncertainty, theory

# Why Not Bayes?

- · Computation
- · Prior subjectivity
- DGP subjectivity
- · Ideology over accuracy
- Parsimony over accuracy

# Models

### **Probabilistic Models**

- · Joint probability distribution over data
- · Sequence of distributional and independence assumptions

$$z \mid x, u \sim \mathsf{Bernoulli}(\mathsf{logit}^{-1}(x\beta^z + \zeta^z u)),$$
  
 $y \mid x, u, z \sim \mathsf{Normal}(x\beta^y + \zeta^y u + \tau z, \sigma_y^2),$   
 $u \sim \mathsf{Bernoulli}(\theta).$ 

- · Plausible story for data generation and measurement noise
- · Model (roughly) determines subsequent steps

### **Running Example: Trump**

- · Sample random New Yorkers and poll support for Trump
- · Collect other data points, income, age, height, sex, ...

Build a model for height:

height ~ Normal (baseline + 
$$eta_1 \cdot \log(\text{income})$$
 +  $eta_2 \cdot \text{vote\_trump} + \cdots$  ,  $\sigma^2$ )

### **Notation**

- · Random variables: y, u
- Observed data:  $y = \{y_1, \dots, y_N\}$
- · Covariates  $x : N \times P$  matrix,  $x_i$  column vector
- y is modeled data, x is unmodeled data
- Inference is conditional on x
- Random variables express what could have happened (repetition)

y is "overloaded", meaning context-specific

### **Notation Continued**

- $\cdot \alpha$ ,  $\beta$  parameters;  $\theta$  vector
- $\cdot p(\cdot; \theta)$  probability density *indexed* by  $\theta$
- ·  $p(\cdot \mid \theta)$  conditional probability density

Overload 
$$p: p(y \mid \alpha, \beta, \sigma), p(\alpha, \beta \mid \sigma), p(\sigma)$$

### Common parameters:

- $\cdot \mu$ : mean, expected value
- ·  $\sigma$ : scale, standard deviation
- $\cdot \alpha$ ,  $\beta$ : regression intercept, slope

### **Notation Continued**

### Predictive quantities:

- $\tilde{x}$ : point for which we would like to make a prediction
- $\tilde{y}$ : prediction at  $\tilde{x}$

### Simulated quantities:

·  $\theta^{(m)}$ : draw of  $\theta$  from a distribution,  $p(\theta \mid y)$ 

### Estimated quantities:

•  $\hat{\theta}$ : point estimate of  $\theta$  (MLE, MAP, MM)

### Common assumptions:

• y independent after controlling for covariates:  $y_i \perp \!\!\! \perp y_j \mid x$  for  $i \neq j$ 

# **Running Example: Trump**

- ·  $y_1, ..., y_N$ : height of individuals in sample, 1 through N
- $\cdot x_1, \dots, x_N$ : column vectors of predictors for individuals
- $x: N \times P$  matrix of predictors, 1st column 1s
- $g: N \times Q$  matrix, Q num of zip-codes, rows of g "select" zip-code for individuals
- $\cdot$   $\beta$ : individual coefficients
- $\alpha$ : zip-code offsets

$$y \sim \text{Normal}(x\beta + g\alpha, \sigma^2)$$

# Comparison with Comp-sci & Econ

Objective function:

$$f(\alpha, \beta) = \|y - x\beta - g\alpha\|^2$$

- · Find  $\operatorname{argmin}_{\alpha,\beta} f$
- $\cdot$  Possibly regularize adding penalty term to f

Estimating equation:

$$y = x\beta + q\alpha + \epsilon$$

- Estimate  $\alpha$ ,  $\beta$  by BLUP
- Correct correlations in error by using cluster robust standard errors

### Where Do Models Come From?

- Sometimes model comes first, based on substantive considerations
  - toxicology, economics, ecology, ...
- · Sometimes model chosen based on data collection
  - traditional statistics of surveys and experiments
- · Other times the data comes first
  - observational studies, meta-analysis, ...
- Usually its a mix

**Bayesian Modeling** 

# **Bayesian Overview**

### "Classically":

- · Write down model/data generating process
- Find parameter values that maximize likelihood of observations
- · Use interval procedure to quantify uncertainty

### Bayesian:

- Model/DGP
- · Incorporate priors over parameters
- Compute posterior distribution of parameters (or QOIs)
- · Summarize posterior distribution by mean, quantiles

### Likelihood

- Probability density/mass of data as viewed as function of its parameters
- $p(y;\theta) \equiv L(\theta)$
- · Not a distribution
- · Central role in classical statistics
- · Maximize for estimate, curvature for approx uncertainty

Bayesian: prior + likelihood → posterior

### **Bayesian Differences**

- · Estimands are point and intervals
- · Make probabilistic statements about procedures used

VS

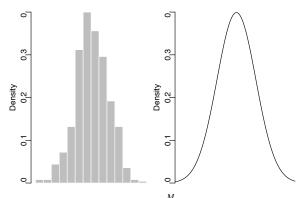
- Estimand is a distribution
- Make probabilistic statements about parameters

### **Distributions As Estimands**

Use Bayes' rule to compute posterior:

$$p(\theta \mid y) = p(y, \theta)/p(y),$$
$$= \frac{p(y \mid \theta)p(\theta)}{p(y)}.$$

- Occasionally, can compute  $p(\theta \mid y)$  directly
- · Most often, use **samples** from  $p(\theta \mid y)$  as summary



$$\begin{split} \Pr[\, \theta \leq t \mid y \,] &\approx \frac{1}{M} \sum_{m=1}^{M} \mathsf{I}[\, \theta^{(m)} \leq t \,], \\ \tilde{\theta} &\sim p(\theta \mid y). \end{split}$$

# **Linear Model Example**

$$y \mid \beta \sim \text{Normal}(x\beta, \sigma^2),$$
  
 $\beta \sim \text{Normal}(0, 5^2).$ 

 $\sigma^2$  fixed

$$p(\beta \mid y) = p(y \mid \beta)p(\beta)/p(y),$$

$$= \prod_{i=1}^{N} \left[ \sqrt{2\pi\sigma^2} e^{-\frac{1}{2\sigma^2}(y_i - x_i^{\mathsf{T}}\beta)^2} \right] \times$$

$$\prod_{j=1}^{P} \left[ \sqrt{2\pi5^2} e^{-\frac{1}{2\cdot5^2}\beta_j^2} \right] / p(y).$$

# **Linear Model Example Cont**

$$p(\beta \mid y) = (2\pi\sigma^2)^{-N/2} \exp\left\{-\frac{1}{2\sigma^2} \sum_{i=1}^{N} (y_i - x_i^{\top} \beta)^2\right\} \times (2\pi 5^2)^{-P/2} \exp\left\{-\frac{1}{2 \cdot 5^2} \sum_{i=1}^{P} \beta_j^2\right\} / p(y)$$

Bundle constants into C

$$p(\beta \mid y) = C \exp \left\{ -\frac{1}{2} \left[ \frac{1}{\sigma^2} \sum_{i=1}^{N} (y_i - x_i^{\top} \beta)^2 + \frac{1}{5^2} \sum_{i=1}^{P} \beta_j^2 \right] \right\}.$$

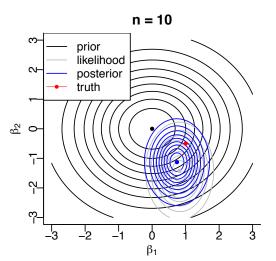
Write  $p(\beta \mid y) \propto \text{and drop } C$ 

# **Linear Model Example Cont**

$$\begin{split} p(\beta \mid y) &\propto \exp\left\{-\frac{1}{2}\left[\frac{1}{\sigma^2}(y-x\beta)^\top(y-x\beta) + \frac{1}{5^2}\beta^\top\beta\right]\right\},\\ &\propto \exp\left\{-\frac{1}{2}\left[\beta^\top x^\top x\beta/\sigma^2 + \beta^\top\beta/5^2 - 2\beta^\top x^\top y/\sigma^2\right]\right\},\\ &\propto \exp\left\{-\frac{1}{2}(\beta-\Sigma_{\beta\mid y}x^\top y/\sigma^2)^\top \Sigma_{\beta\mid y}^{-1}(\beta-\Sigma_{\beta\mid y}x^\top y/\sigma^2)\right\}. \end{split}$$

Where 
$$\Sigma_{\beta|y} = (x^{T}x/\sigma^{2} + I_{p}1/5^{2})^{-1}$$
.

$$\beta \mid y \sim \text{Normal}\left(\Sigma_{\beta \mid y} x^{\mathsf{T}} y / \sigma^2, \Sigma_{\beta \mid y}\right).$$



# **Logistic Example**

Instead predict voting

$$y \mid \beta \sim \text{Bernoulli}\left(\text{logit}^{-1}(x\beta)\right),$$
  
 $\beta \sim \text{Normal}(0, 5^2).$ 

$$\begin{split} p(\beta \mid y) &\propto p(y \mid \beta) p(\beta), \\ &\propto \prod_{i=1}^{N} \left[ y_i \frac{e^{x_i^{\mathsf{T}}\beta}}{1 + e^{x_i^{\mathsf{T}}\beta}} + (1 - y_i) \frac{1}{1 + e^{x_i^{\mathsf{T}}\beta}} \right] \times \\ &\exp \left\{ -\frac{1}{2 \cdot 5^2} \beta^{\mathsf{T}} \beta \right\}. \end{split}$$

### **Prior Choice**

- · Prior information
- · Conjugate
- Uninformative
- · Jeffreys'
- · Weakly informative

### **Posterior Predictive Distribution**

- · Predict new data  $\tilde{y}$  based on observed data y
- · Marginalize out parameters from posterior

$$p(\tilde{y} \mid y) = \int p(\tilde{y}, \theta \mid y) d\theta,$$
  
= 
$$\int p(\tilde{y} \mid \theta) p(\theta \mid y) d\theta.$$

- Averages predictions  $p(\tilde{y} \mid \theta)$  weighting by posterior  $p(\theta \mid y)$
- · Allows continuous, discrete, or mixed parameters
  - integral notation shorthand for sums and/or integrals

# **Diagnostics**

### **Model Checking**

- · Do the inferences make sense?
  - are parameter values consistent with model's prior?
  - does simulating from parameter values produce reasonable fake data?
  - are marginal predictions consistent with the data?
- Do predictions and event probabilities for new data make sense?
- Not: Is the model true?
- Not: What is Pr[model is true]?
- · Not: Can we "reject" the model?

### **Model Improvement**

- Expanding the model
  - hierarchical and multilevel structure ...
  - more flexible distributions (overdispersion, covariance)
  - more structure (geospatial, time series)
  - more modeling of measurement methods and errors
  - ...
- · Including more data
  - breadth (more predictors or kinds of observations)
  - depth (more observations)