

AE 706

Assignment 5: Computation of Lid-Driven Cavity Flow Using Vorticity-Stream Function Formulation

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Contents

1	Problem Statement	4
2	Governing Equations	4
2.1	Vorticity Transport Equation	4
2.2	Stream Function Equation (Poisson Equation)	5
3	Boundary Conditions	5
3.1	Lid (Top Wall, $y = 1$ m)	5
3.2	Bottom and Side Walls ($y = 0$ m, $x = 0$ m, $x = 1$ m)	5
4	Convergence Criteria	5
4.1	Velocity Residuals (Time Iteration)	6
5	Time Step Calculation	6
5.1	Convective Time Step	6
5.2	Diffusive Time Step	6
5.3	Final Time Step	6
6	Results	7
7	Conclusion	10
8	Flowchart	11

List of Figures

1	Lid driven cavity	4
2	C Stream Function Contours	7
3	Streamlines of the flow	7
4	Distribution of the x-component of velocity vector (u) along the mid vertical line	8
5	Distribution of the y-component of velocity vector (v) along the mid horizontal line	8
6	u -velocity along mid vertical line compared between CFD result and Ghia	9
7	v -velocity along mid horizontal line compared between CFD result and Ghia	9
8	Convergence history for $(RMS)u$ and $(RMS)v$ with iterations	10

1 Problem Statement

The goal of this assignment is to numerically solve the steady-state lid-driven cavity (as shown in Figure 1) flow using the Vorticity-Stream Function formulation. The flow is incompressible and two-dimensional. The velocity field is derived from the stream function, and the vorticity transport equation governs the evolution of vorticity in the domain

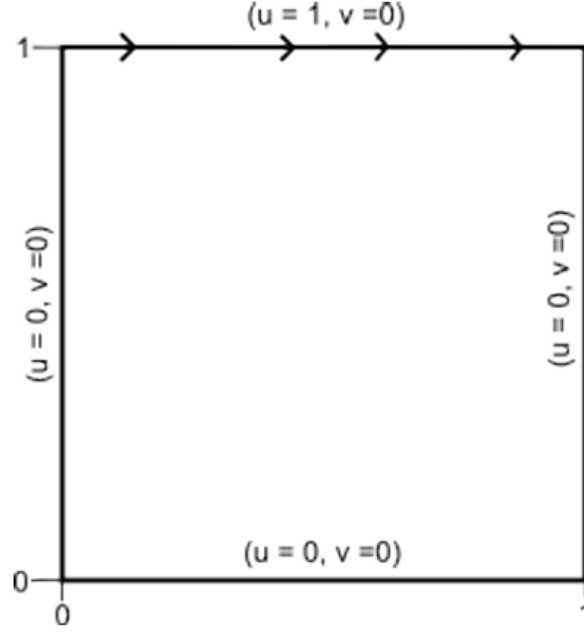


Figure 1: Lid driven cavity

The problem involves computing the flow field for a Reynolds number of 100, where the flow is governed by the Navier-Stokes equations expressed in terms of vorticity and stream function.

2 Governing Equations

The Navier-Stokes equations in terms of vorticity (ω) and stream function (ψ) are given as:

2.1 Vorticity Transport Equation

The vorticity transport equation is given by:

$$\frac{\partial \omega}{\partial t} + u \frac{\partial \omega}{\partial x} + v \frac{\partial \omega}{\partial y} = \nu \left(\frac{\partial^2 \omega}{\partial x^2} + \frac{\partial^2 \omega}{\partial y^2} \right) \quad (1)$$

where

$$\omega = \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \quad (\text{vorticity}) \quad (2)$$

and

$$u = \frac{\partial \psi}{\partial y}, \quad v = -\frac{\partial \psi}{\partial x} \quad (\text{velocity components}) \quad (3)$$

Here, ν is the kinematic viscosity.

2.2 Stream Function Equation (Poisson Equation)

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = -\omega \quad (4)$$

This equation ensures that the velocity field satisfies the incompressibility condition

3 Boundary Conditions

3.1 Lid (Top Wall, $y = 1 \text{ m}$)

Driven by the lid:

$$\hat{u} = 1 \text{ m/s}, \quad \hat{v} = 0 \text{ m/s}$$

Imposed via vorticity:

$$\omega_{i,J} = -\frac{2(\psi_{i,J-1} - \psi_{i,J})}{\Delta y^2} - \frac{2\hat{u}_{i,J}}{\Delta y}$$

where an $I \times J$ grid is used; $i = 1, 2, \dots, I$ and $j = 1, 2, \dots, J$.

3.2 Bottom and Side Walls ($y = 0 \text{ m}$, $x = 0 \text{ m}$, $x = 1 \text{ m}$)

No-slip condition:

$$\hat{u} = 0 \text{ m/s}, \quad \hat{v} = 0 \text{ m/s}$$

Imposed via vorticity:

$$\begin{aligned} \text{Left wall} \quad \omega_{1,j} &= -\frac{2(\psi_{2,j} - \psi_{1,j})}{\Delta x^2} \\ \text{Right wall} \quad \omega_{I,j} &= -\frac{2(\psi_{I-1,j} - \psi_{I,j})}{\Delta x^2} \\ \text{Bottom wall} \quad \omega_{i,1} &= -\frac{2(\psi_{i,2} - \psi_{i,1})}{\Delta y^2} \end{aligned}$$

4 Convergence Criteria

The residual $R_{i,j}$ at an internal grid point is the difference between the left-hand side (LHS) and the right-hand side (RHS) of the discretized streamfunction equation:

$$R_{i,j} = \frac{\psi_{i+1,j} - 2\psi_{i,j} + \psi_{i-1,j}}{\Delta x^2} + \frac{\psi_{i,j+1} - 2\psi_{i,j} + \psi_{i,j-1}}{\Delta y^2} + \omega_{i,j} \quad (5)$$

A global residual norm is used to check for convergence. The most common choice is the ****Root Mean Square (RMS) Residual****, defined as:

$$R_2 = \sqrt{\frac{1}{N} \sum_{i=2}^{I-1} \sum_{j=2}^{J-1} R_{i,j}^2}, \quad \text{where } N = (I-2) \times (J-2) \quad (6)$$

Terminate the ****Jacobi**** or ****Gauss-Seidel**** iteration when $R_2 \leq 10^{-2}$, as this level of residual reduction is sufficient to obtain steady-state results.

4.1 Velocity Residuals (Time Iteration)

Terminate the ****time iteration**** when the ****Root Mean Square (RMS) residuals**** of the velocity components u and v fall below a threshold (i.e., 10^{-8}).

The RMS residual of a variable f (representing either u or v) is defined as:

$$\text{RMS}_f = \sqrt{\frac{1}{N} \sum_{i=2}^{I-1} \sum_{j=2}^{J-1} (f_{i,j}^{n+1} - f_{i,j}^n)^2} \quad (7)$$

Here, the superscript n indicates the time level.

5 Time Step Calculation

The time step Δt is determined based on stability conditions:

5.1 Convective Time Step

$$\Delta t_c = \sigma_c \frac{\Delta x \Delta y}{\|u_{\max}\| \Delta y + \|v_{\max}\| \Delta x} \quad (8)$$

where $\sigma_c = 0.4$ is the Courant number.

5.2 Diffusive Time Step

$$\Delta t_d = \sigma_d \frac{1}{2\nu} \cdot \frac{\Delta x^2 \Delta y^2}{\Delta x^2 + \Delta y^2} \quad (9)$$

where $\sigma_d = 0.6$ is the diffusion number.

5.3 Final Time Step

$$\Delta t = \min(\Delta t_c, \Delta t_d) \quad (10)$$

6 Results

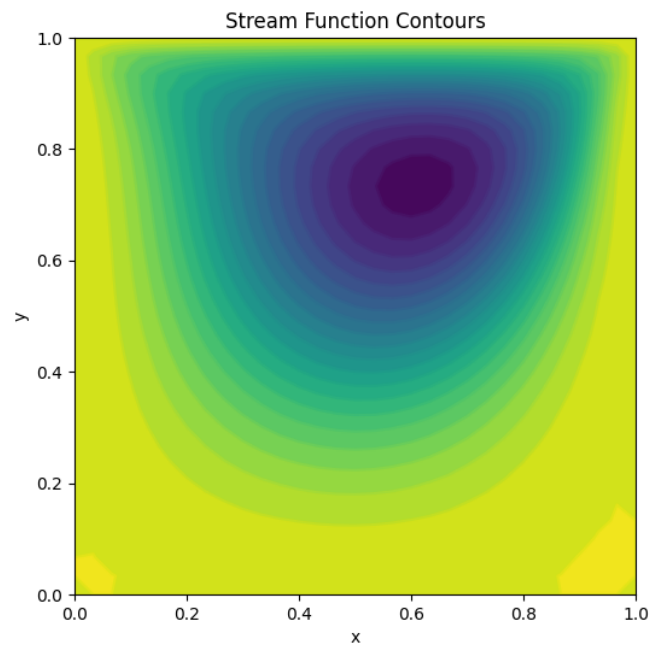


Figure 2: C Stream Function Contours

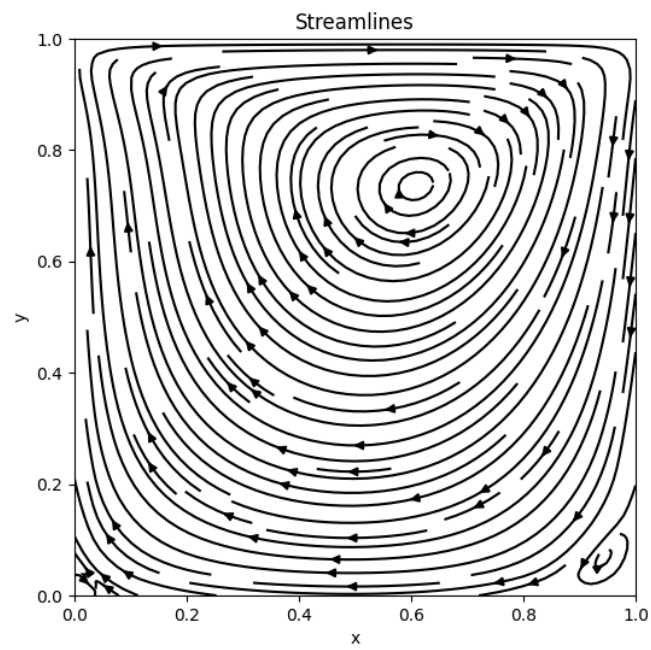


Figure 3: Streamlines of the flow

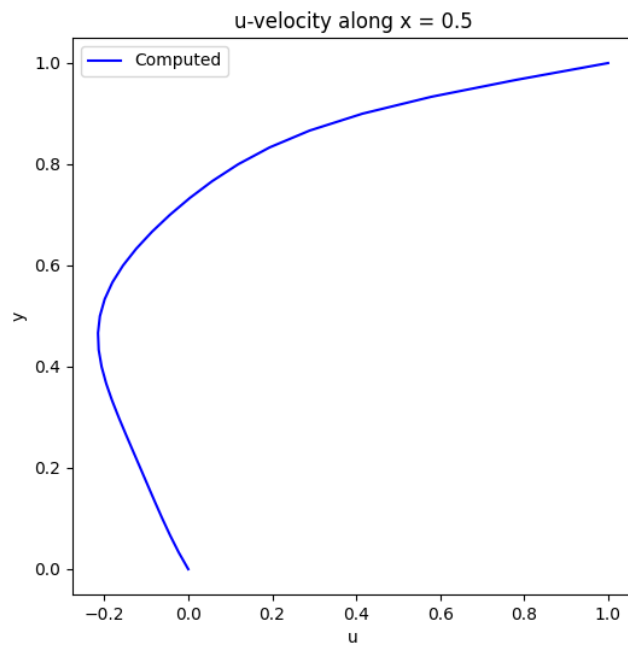


Figure 4: Distribution of the x-component of velocity vector (u) along the mid vertical line

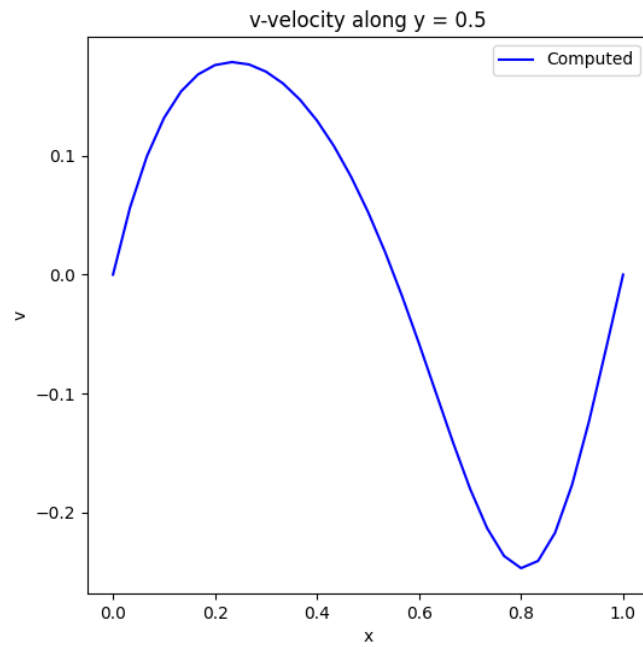


Figure 5: Distribution of the y-component of velocity vector (v) along the mid horizontal line

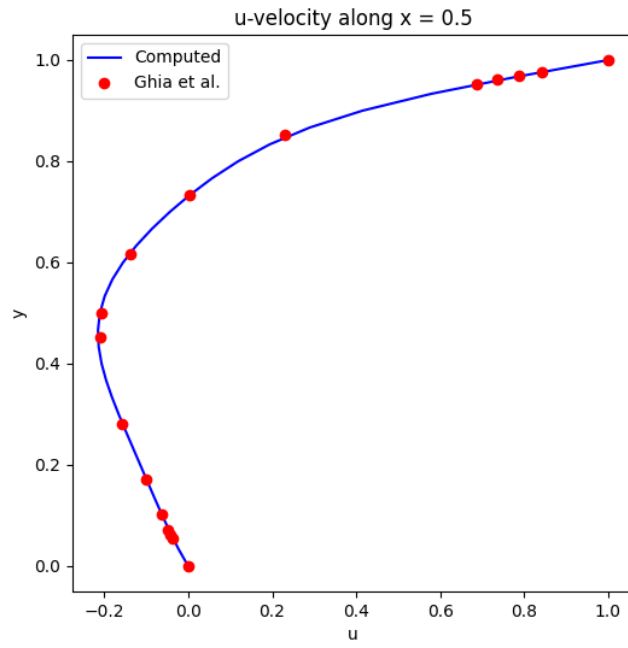


Figure 6: u-velocity along mid vertical line compared between CFD result and Ghia

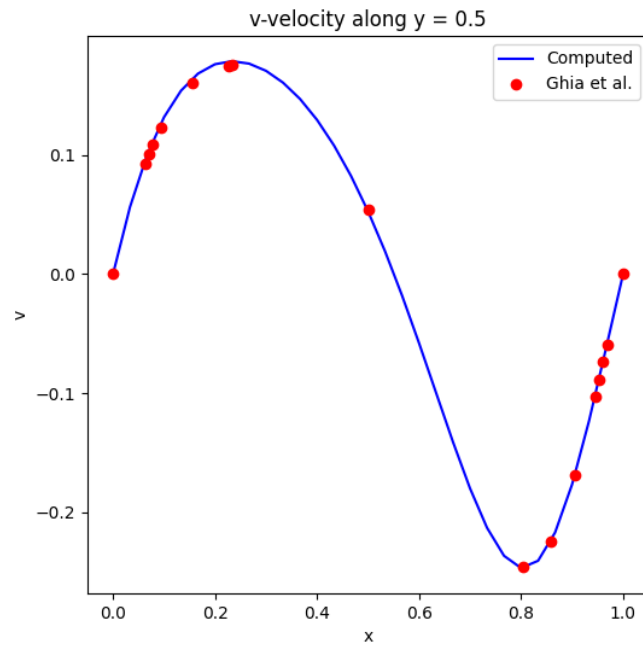


Figure 7: v-velocity along mid horizontal line compared between CFD result and Ghia

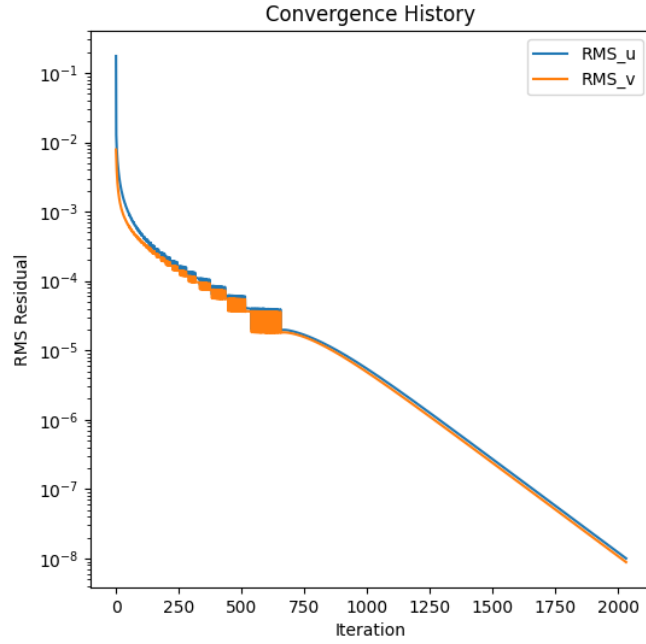


Figure 8: Convergence history for (RMS)u and (RMS)v with iterations

7 Conclusion

The numerical simulation effectively captured the key characteristics of lid-driven cavity flow at a Reynolds number of 100. The results demonstrate strong agreement with established benchmark data, thereby validating the implementation. The vorticity–stream function formulation proved to be a robust and efficient approach for solving this two-dimensional incompressible flow problem.

References

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- [2] Hoffmann, K. A., & Chiang, S. T., *Computational Fluid Dynamics for Engineers*, Vol. I, 4th ed., Engineering Education Systems, 2000.
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8 Flowchart

