

CALM

1. Make sure everything is turned ON and connect properly by moving with a stylus.
2. Install ROS. [Link](#)
3. Check the USB devices by running [this](#) script and you should see `/dev/ttyACM0 - Teensyduino_USB_Serial_6311670`
4. `source devel/setup.bash`
5. `roscore`
6. `roslaunch rosserial_python serial_node.py /dev/ttyACM0 _baud:=115200`
7. `rostopic pub /ralp_msgs/teensy_input ralp_msgs/teensy_input "buttons: 1 deltax: 0.001 deltax: 0.001"`