Ajay Narasimha Mopidevi

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EDUCATION

University of Colorado Boulder

Masters of Science in Computer Science — GPA: 4.0/4.0

Indian Institute of Technology, Guwahati (IITG)

Bachelors of Technology in Electronics and Communication Engineering

Publications

- "RMap: Millimiter-Wave Radar Mapping through Volumetric Upsampling" (under review at ICRA 2024)
- "Tell Me Where to Go: A Composable Framework for Context-Aware Embodied Robot Navigation" (Accepted at CoRL 2023)
- "MultiNavCon: An Architecture for Language-Directed Navigation of Multiple Robots" (under review at ICRA 2024)
- "Grouped BERT for Multi-Label classification to reason the human values behind the arguments", Proceedings of the The 17th International Workshop on Semantic Evaluation (SemEval-2023)

EXPERIENCE

Autonomous Robotics and Perception Group

Boulder, CO

Boulder, CO

Guwahati, India

Aug. 2022 - May 2024

Aug. 2013 - May 2017

Research Assistant

Sep 2022 - Present

- Developed the state-of-the-art generative transformer, **UpPoinTr**, for enhancing volumetric maps from sparse and noisy radar scans, surpassing the prior models by **8%** in performance and generate lidar-like navigable maps
- Designed NavCon, a low bandwidth robot navigation framework using Large Language Models(LLMs), achieving a 71.3% success rate in guiding a Spot robot through intricate human commands in various environments
- Improved the odometry estimation with only the noisy and radar scans by 8%, using transformer and DeepVO architectures

Vignesh Kasinath Lab

Boulder, CO

Research Assistant

Apr 2023 - Present

- Devised Multi-UNet architecture, seamlessly integrating the segmentation of multiple structures, resulting in a substantial 13% boost in F1-score
- Designed U-NeXt architectures, combining the ConvNeXt and U-Net, specifically tailored for tomograms captured at different scales, resulting in a f1 score of 85% for segmentation

Samsung Semiconductors India R&D

Bangalore, India

Computer Vision Research Engineer, Advanced Multimedia Solutions Team

July 2020 - July 2022

- Developed 3D scene reconstruction algorithm, only leveraging depth from ToF sensors, optimized to 20fps
- Improved the accuracy by 5% by detecting and removing outliers and also automated the pose alignment of output 3D scene with groundtruth to eliminate the manual alignment in MeshLab
- Reduced the latency of Remosaic deep learning models for 200M pixel camera sensor using quantization and pruning techniques by 10 % with an unnoticeable degradation of 0.1% in perceptual quality

Qualcomm

Bangalore, India

Software Engineer, Audio Quality Validation Team

Aug. 2017 – June 2020

- Spearheaded the development and maintenance of python audio library to evaluate both the objective and perceptual audio quality of Bluetooth headsets
- Enhanced python automated test framework with new features that populate test vectors and visualize audio output signals, leading to a 10%-15% reduction in both the validation and development teams' efforts

Eagle Eye Networks

Bangalore, India

Research Intern

May 2017 - July 2017

• Leveraged YOLO for object localization, optical flow for trajectory estimation, achieving 83% accuracy in detecting location and trajectory anomalies through Incremental Spherical Clustering and frequency heatmap

TECHNICAL SKILLS

Languages: Python, C/C++, Matlab

Machine Learning Frameworks: Keras, Pytorch, Tensorflow

Libraries: OpenCV, ROS, Open3D, OpenCL, OpenGL, OpenMP, scikit-learn, pandas, NumPy, Matplotlib

Tools: Git, Meshlab, CloudCompare, Visual Studio, PyCharm, Eclipse