



TITLE

# SMART FARMING INNOVATION

Automatic Crop Protection from Rain!



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## **ABSTRACT**

This project presents an **automatic crop protection system** designed to safeguard crops from unexpected rainfall using **Arduino-based automation**. A **rain sensor module** detects the presence of rain and activates a **DC motor with a horizontal sliding mechanism** to deploy a protective cover over the crops. When the rain stops, the system retracts the cover automatically, ensuring minimal human intervention. The system aims to reduce **crop damage due to excessive water exposure**, enhance **farm efficiency**, and support **smart agriculture practices**. The setup is cost-effective, easy to implement, and scalable for small farms, greenhouses, and home gardens.

## **COMPONENTS:**

### **1. Arduino UNO (Microcontroller)**

- **Role:** Acts as the brain of the system.
  - **Function:** Reads data from the rain sensor and controls the motor driver to move the cover.
  - **usage:** It is easy to program, cost-effective, and widely used for automation and IoT projects.
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### **2. Rain Sensor Module (e.g., FC-37)**

- **Role:** Detects rainfall.
  - **Function:** When raindrops fall on the sensor plate, its resistance changes, producing an analog signal. Arduino reads this value to decide whether to cover the crops.
  - **Usage:** Simple and reliable way to detect the presence of rain.
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### 3. DC Motor (or Gear Motor)

- **Role:** Moves the horizontal cover over the crops.
  - **Function:** Rotates in **forward direction** to extend the cover and **reverse direction** to retract it.
  - **Usage:** DC motors can move covers of larger sizes, making them suitable for horizontal sliding mechanisms.
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### 4. L298N Motor Driver

- **Role:** Controls the DC motor.
  - **Function:** Acts as an interface between the Arduino (low power) and the motor (high power). It allows **bidirectional control** (forward and reverse) of the motor.
  - **Usage:** Arduino alone cannot supply enough current to drive a DC motor directly.
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### 5. Power Supply

- **Role:** Provides necessary power for the motor and Arduino.
  - **Function:** Typically, **12V** powers the DC motor through the L298N, and **5V** powers the Arduino and rain sensor.
  - **Usage:** To ensure reliable operation of both logic circuits and motors.
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### 6. Horizontal Cover Mechanism (Custom Frame)

- **Role:** The physical structure that slides to cover the crops.
- **Function:** Converts the motor's rotation into horizontal movement (using a pulley, gear, or rack-and-pinion setup).
- **Usage:** To provide physical protection to crops from rain.

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## 7. (Optional) Limit Switches

- **Role:** Stop the motor when the cover is fully opened or closed.
- **Function:** When the cover reaches an endpoint, the switch is pressed, and the motor stops to avoid damage.
- **Usage:** To ensure safe and precise cover movement.

### **CODE:**

```
// Pin definitions
```

```
int ENA = 9;
```

```
int IN1 = 8;
```

```
int IN2 = 7;
```

```
int rainSensorPin = A0;
```

```
int rainThreshold = 400;
```

```
int rainValue = 0;
```

```
void setup() {
```

```
    pinMode(ENA, OUTPUT);
```

```
    pinMode(IN1, OUTPUT);
```

```
    pinMode(IN2, OUTPUT);
```

```
    pinMode(rainSensorPin, INPUT);
```

```
    Serial.begin(9600);
```

```
    Serial.println("Horizontal Crop Cover System Started");
```

```
}
```

```
void loop()
{
    rainValue = analogRead(rainSensorPin);
    Serial.print("Rain Sensor Value: ");
    Serial.println(rainValue);

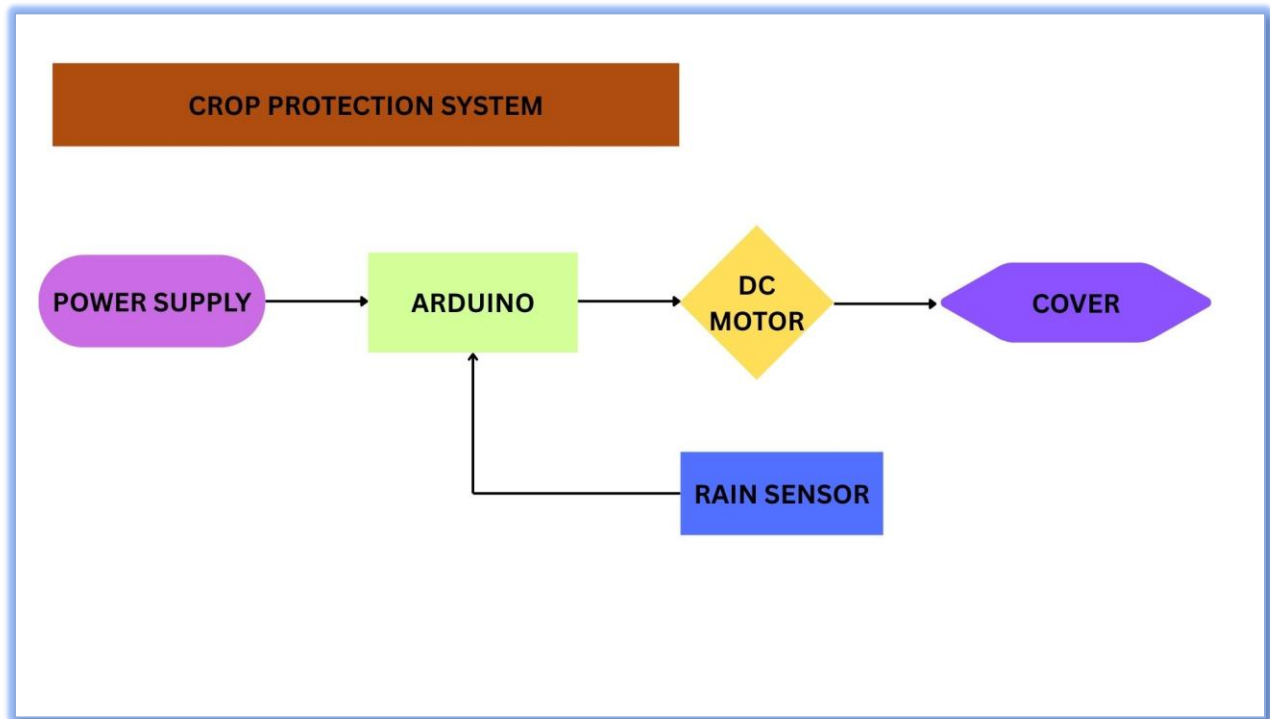
    if (rainValue < rainThreshold)
    {
        Serial.println("Rain detected! Closing cover...");
        moveCoverForward();
        delay(3000);
        stopMotor();
    }
    else
    {
        Serial.println("No rain. Opening cover...");
        moveCoverBackward();
        delay(3000);
        stopMotor();
    }
    delay(1000);
}
```

```
void moveCoverForward()
{
    digitalWrite(IN1, HIGH);
    digitalWrite(IN2, LOW);
    analogWrite(ENA, 200); // Speed (0-255)
}
```

```
void moveCoverBackward()
{
    digitalWrite(IN1, LOW);
    digitalWrite(IN2, HIGH);
    analogWrite(ENA, 200);
}
```

```
void stopMotor()
{
    digitalWrite(IN1, LOW);
    digitalWrite(IN2, LOW);
}
```

## BLOCK DIAGRAM:



## CONCLUSION :

The **Automatic Crop Protection System** successfully demonstrates how **Arduino-based automation** can safeguard crops from unexpected rain using a **rain sensor** and a **horizontal cover mechanism**. The system minimizes manual intervention, reduces crop damage, and supports farmers by providing a cost-effective and reliable solution. This project showcases the potential of **IoT and embedded systems** in modern agriculture, enabling smarter and more efficient farming practices.