

**NE 255, Fa16**  
**Simplified  $P_N$  Equations**  
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In slab geometry the  $P_N$  equations can be written as a system of 1-D diffusion equations; this is not true in general geometry. This is the motivation behind the simplified  $P_N$  equations: what would happen if the  $P_N$  method in general geometry was as nice as it is in slab geometry?

Gelbard introduced the  $SP_N$  equations in a series of papers in 1962; however, they were not widely accepted as an approximate transport method because of the lack of a true theoretical foundation. For approximately 30 years, the  $SP_N$  equations were occasionally mentioned in American Nuclear Society conference talks and brief publications. It was not until the early 1990s that theoretical work was published demonstrating that the  $SP_N$  approximations have a valid mathematical foundation, and can be derived from either an asymptotic or a variational analysis.

### “Heuristic” Derivation of the $SP_N$ Equations

Consider the planar (slab) geometry  $P_N$  equations as before: for  $l' = 0, 1, \dots$ , we have

$$\left( \frac{l' + 1}{2l' + 1} \right) \frac{d}{dx} \phi_{l'+1}(x) + \left( \frac{l'}{2l' + 1} \right) \frac{d}{dx} \phi_{l'-1}(x) + \Sigma_t(x) \phi_{l'} = \Sigma_{sl'}(x) \phi_{l'}(x) + s_{l'}(x),$$

with  $\phi_{-1} = 0$  and

$$\phi_{N+1} = 0 \quad \text{or} \quad \frac{d}{dx} \phi_{N+1} = 0.$$

The second-order form of the planar geometry  $P_1$  equations with Marshak boundary conditions is the diffusion equation

$$\begin{aligned} -\frac{d}{dx} D \frac{d\phi_0}{dx} + \Sigma_a(x) \phi_0(x) &= s_0(x), \quad 0 < x < X, \\ \frac{1}{2} \phi_0(0) - D \frac{d\phi_0}{dx}(0) &= 2J^+(0), \\ \frac{1}{2} \phi_0(X) + D \frac{d\phi_0}{dx}(X) &= 2J^-(X), \end{aligned}$$

where

$$D = \frac{1}{3 [\Sigma_t(x) - \Sigma_{s1}(x)]}.$$

This can be generalized to 3-D by making the two **formal** modifications:

1. Replace the 1-D diffusion operator

$$\frac{d}{dx} D \frac{d}{dx}$$

by the 3-D diffusion operator

$$\nabla \cdot D \nabla \equiv \frac{\partial}{\partial x} D \frac{\partial}{\partial x} + \frac{\partial}{\partial y} D \frac{\partial}{\partial y} + \frac{\partial}{\partial z} D \frac{\partial}{\partial z};$$

2. In the boundary conditions, replace the derivative terms

$$\pm \frac{d}{dx}$$

by the outward normal derivative

$$\vec{n} \cdot \nabla$$

Making these formal modifications, we obtain the standard 3-D diffusion ( $P_1$ ) equations

$$\begin{aligned} -\nabla \cdot D \nabla \phi_0(\vec{r}) + \Sigma_a(\vec{r}) \phi_0(\vec{r}) &= s_0(\vec{r}), \vec{r} \in V, \\ \frac{1}{2} \phi_0(\vec{r}) + D \vec{n} \cdot \nabla \phi_0 &= 2J^-(\vec{r}), \vec{r} \in \partial V. \end{aligned}$$

These equations obviously reduce to the standard 1-D diffusion equations in planar geometry.

We carry out the same procedure for the general  $SP_N$  equations. First, for odd values of  $l'$ ,  $\phi_{l'}$  is replaced by a vector:

$$\phi_{l'} \rightarrow \vec{\phi}_{l'} = (\phi_{l'}^x, \phi_{l'}^y, \phi_{l'}^z)^t.$$

Then, in the even  $l'$  equations the derivative in  $x$  is replaced by a divergence:

$$\frac{d}{dx} \rightarrow \nabla \cdot;$$

and in the odd  $l'$  equations the  $x$  derivative is changed to a gradient:

$$\frac{d}{dx} \rightarrow \nabla$$

This allows us to write the first-order form of the  $\text{SP}_N$  equations as

$$\begin{aligned}\nabla \cdot \vec{\phi}_1 + \Sigma_a \phi_0 &= s_0 , \\ \left( \frac{l' + 1}{2l' + 1} \right) \nabla \phi_{l'+1} + \left( \frac{l'}{2l' + 1} \right) \nabla \phi_{l'-1} + \Sigma_t \vec{\phi}_{l'} &= \Sigma_{s l'} \vec{\phi}_{l'} + s_{l'} , & \text{for odd } l' , \\ \left( \frac{l' + 1}{2l' + 1} \right) \nabla \cdot \vec{\phi}_{l'+1} + \left( \frac{l'}{2l' + 1} \right) \nabla \cdot \vec{\phi}_{l'-1} + \Sigma_t \phi_{l'} &= \Sigma_{s l'} \phi_{l'} + s_{l'} , & \text{for even } l' > 0 .\end{aligned}$$

The boundary conditions for the  $\text{SP}_N$  equations can be obtained from the  $\text{P}_N$  Marshak boundary conditions by replacing  $\phi_{l'}$  with the  $\text{SP}_N$  unknowns and  $\mu$  with  $\vec{n} \cdot \hat{\Omega}$ , where  $\vec{n}$  is the unit inward normal to the boundary.

## The $\text{SP}_3$ Equations

Assuming an isotropic source, the  $\text{SP}_3$  equations in their first-order form are

$$\begin{aligned}\nabla \cdot \vec{\phi}_1 + \Sigma_a \phi_0 &= s_0 , \\ \frac{1}{3} \nabla \phi_0 + \frac{2}{3} \nabla \phi_2 + [\Sigma_t - \Sigma_{s1}] \vec{\phi}_1 &= 0 , \\ \frac{2}{5} \nabla \cdot \vec{\phi}_1 + \frac{3}{5} \nabla \cdot \vec{\phi}_3 + [\Sigma_t - \Sigma_{s2}] \phi_2 &= 0 , \\ \frac{3}{7} \nabla \phi_2 + [\Sigma_t - \Sigma_{s3}] \vec{\phi}_3 &= 0 .\end{aligned}$$

We can rewrite them in their second-order form by using the relation

$$\vec{\phi}_{l'} = -\frac{1}{\Sigma_t - \Sigma_{s l'}} \left( \frac{l'}{2l' + 1} \nabla \phi_{l'-1} + \frac{l' + 1}{2l' + 1} \nabla \phi_{l'+1} \right) ,$$

yielding

$$\begin{aligned}-\nabla \cdot \frac{1}{3[\Sigma_t - \Sigma_{s1}]} \nabla \phi_0 - \nabla \cdot \frac{2}{3[\Sigma_t - \Sigma_{s1}]} \nabla \phi_2 + \Sigma_a \phi_0 &= s_0 , \\ -\nabla \cdot \frac{2}{15[\Sigma_t - \Sigma_{s1}]} \nabla \phi_0 - \nabla \cdot \left( \frac{4}{15[\Sigma_t - \Sigma_{s1}]} + \frac{9}{35[\Sigma_t - \Sigma_{s3}]} \right) \nabla \phi_2 + [\Sigma_t - \Sigma_{s2}] \phi_2 &= 0 .\end{aligned}$$

The second-order form is useful because it makes the  $\text{SP}_N$  equations look like a set of coupled diffusion equations.

The  $\text{SP}_3$  equations can be manipulated into a form that resembles a two group diffusion equation

by defining  $\hat{\phi}_0 = \phi_0 + 2\phi_2$ . Using this new variable, we can write

$$\begin{aligned} -\nabla \cdot \frac{1}{3[\Sigma_t - \Sigma_{s1}]} \nabla \hat{\phi}_0 + \Sigma_a \hat{\phi}_0 &= 2\Sigma_a \phi_2 + s_0, \\ -\nabla \cdot \frac{9}{35[\Sigma_t - \Sigma_{s3}]} \nabla \phi_2 + \left( [\Sigma_t - \Sigma_{s2}] + \frac{4}{5}\Sigma_a \right) \phi_2 &= \frac{2}{5} [\Sigma_a \hat{\phi}_0 - s_0]. \end{aligned}$$

These equations can be solved with a two-group diffusion code by properly setting the diffusion coefficients and cross-sections or with a one-group diffusion code utilizing an iteration strategy for the coupling terms (FLIP).

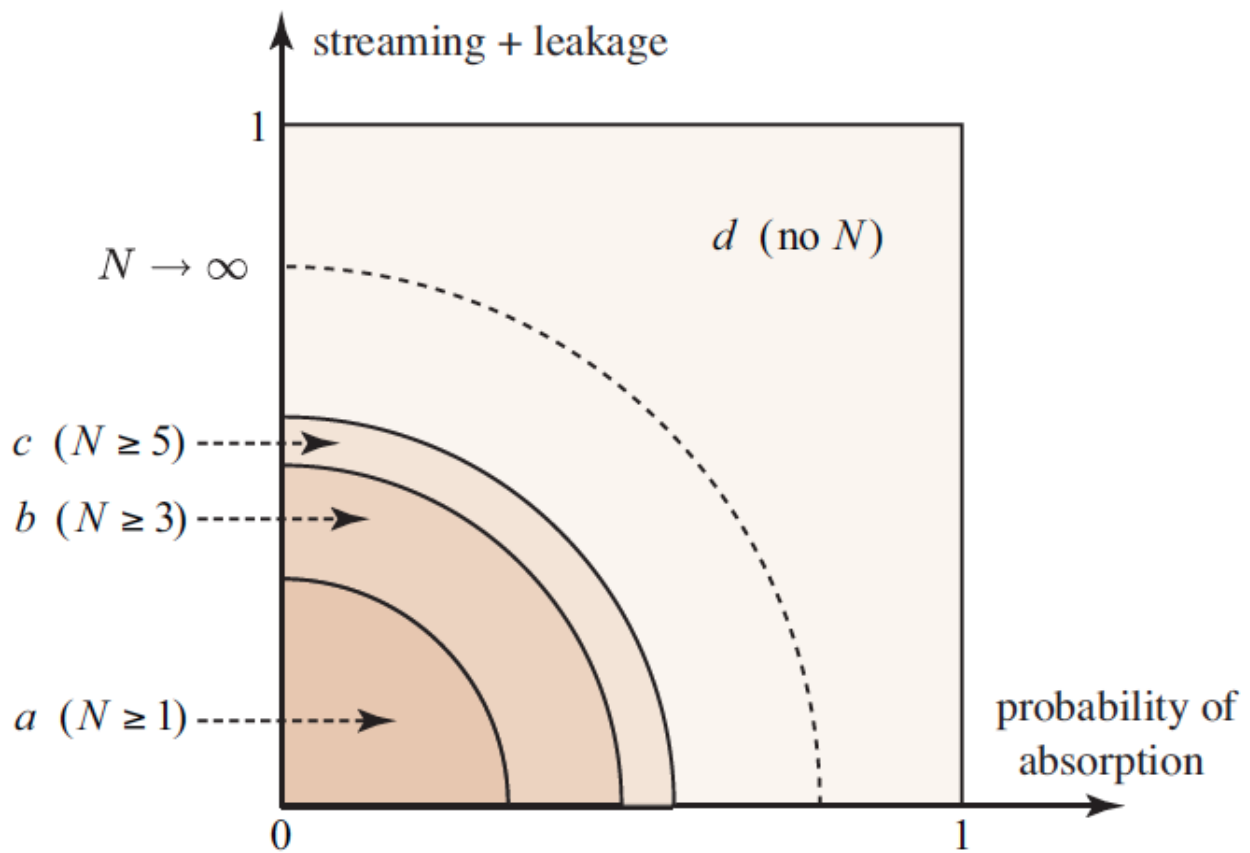
## General Properties of the $SP_N$ Equations

The  $SP_N$  equations can be understood as a “super” diffusion theory. The structure of the  $SP_N$  equations is that of a coupled system of diffusion equations, and the class of problems for which the  $SP_N$  equations are accurate encompasses the class of problems for which diffusion theory is accurate.

1. In 1-D planar geometry,  $SP_N$  and  $P_N$  are identical
2. In multidimensional problems,  $SP_N$  form a system of  $(N + 1)$  equations;  $P_N$  form a much larger system of  $(N + 1)^2$  equations
3. The  $SP_N$  equations have the same “diffusion” (elliptic) structure as the  $P_1$  equations; the  $P_N$  equations have a more complicated (hyperbolic) mathematical structure.
4. The above derivation of the  $SP_N$  equations assumes as its starting point a 1-group transport problem. However, applying the same procedures to a multigroup transport problem is straightforward. The only complication is that the diffusion coefficients can become non-diagonal matrices. Thus, unlike standard multigroup diffusion theory (but like standard multigroup  $P_1$  theory), the multigroup  $SP_N$  equations generally have non-diagonal matrix diffusion coefficients.
5. In principle, the 2-D or 3-D  $SP_N$  equations can be implemented in a 2-D or 3-D diffusion code without fundamentally rewriting the code. This is not the case for the  $P_N$  equations.
6. The  $SP_N$  equations contain more “transport physics” than the diffusion equations. For this reason, solutions of the  $SP_N$  equations can contain boundary layers that are not present in  $P_1$  solutions. In order to properly resolve these boundary layers, it may be necessary to use a finer spatial grid for the  $SP_N$  equations than for the diffusion equation. Alternatively, the

use of nodal methods with extra expansion terms capable of expressing the boundary layer effects may be required.

7. The multigroup  $SP_3$  equations are about twice as costly to solve as the multigroup  $P_1$  equations. However,  $SP_3$  solutions are usually much more accurate (transport-like) than  $P_1$  solutions.
8. In the limit as  $N \rightarrow \infty$ , the  $P_N$  solutions converge to the transport solution.
9. In the limit as  $N \rightarrow \infty$ , the  $SP_N$  solutions do not generally converge to the transport solution—unless the underlying problem is 1-D. Therefore, high-order  $SP_N$  equations cannot be used to obtain arbitrarily accurate solutions of neutron transport problems in 2 or 3 dimensions.
10. For 3-D problems, the system of  $P_N$  equations is much more complicated in structure and greater in number than the system of  $SP_N$  equations. Also, for problems having 1D symmetry, the  $P_N$  and  $SP_N$  equations become identical. For these reasons, it is widely believed that the 3-D  $SP_N$  equations can be derived by discarding the proper terms (and equations) from the 3D  $P_N$  equations. However, this has never been shown. In fact, the precise relationship between the 3D  $P_N$  and the 3D  $SP_N$  equations is not known.
11. For problems in which the  $P_1$  solution is accurate, the  $SP_3$  solution is generally much more accurate. As problems become less “diffusive” (absorption, streaming, or leakage become increasingly important), the  $P_1$  and  $SP_3$  solutions both degrade in accuracy. However, the  $P_1$  solutions degrade more rapidly, and the  $SP_3$  solutions can remain accurate well into the range in which  $P_1$  solutions are not accurate. When the problem becomes sufficiently “difficult”, the  $P_1$  and  $SP_N$  solutions both become inaccurate (see figure in the next page).



This figure shows the (qualitative) range of validity of the  $SP_N$  equations. The amounts of absorption and streaming/leakage are indicated on arbitrary scales ranging from 0 to 1. In region *a*, where streaming, leakage, and absorption are weak, the  $P_1$  and all  $SP_N$  solutions are accurate. As absorption or streaming increase (region *b*),  $P_1$  becomes inaccurate but  $SP_N$  with  $N \geq 3$  is still accurate. As absorption or streaming increase further (region *c*),  $P_1$  and  $SP_3$  are inaccurate but  $SP_N$  with  $N \geq 5$  is still accurate. In region *d*, no  $SP_N$  solution is accurate.

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These notes are derived from Edward Larsen's class notes for NE 644 at the University of Michigan, and from Ryan McClarren's review paper on the  $SP_N$  equations: "Theoretical Aspects of the Simplified  $P_n$  Equations", *Transport Theory and Statistical Physics* 39: 73–109, 2011.