

NE 255, Fa16
Simplified P_N Equations
October 04, 2016

In slab geometry the P_N equations can be written as a system of 1-D diffusion equations; this is not true in general geometry. This is the motivation behind the simplified P_N equations: what would happen if the P_N method in general geometry was as nice as it is in slab geometry?

Gelbard introduced the SP_N equations in a series of papers in 1962; however, they were not widely accepted as an approximate transport method because of the lack of a true theoretical foundation. For approximately 30 years, the SP_N equations were occasionally mentioned in American Nuclear Society conference talks and brief publications. It was not until the early 1990's that theoretical work was published demonstrating that the SP_N approximations have a valid mathematical foundation, and can be derived from either an asymptotic or a variational analysis.

“Heuristic” Derivation of the SP_N Equations

Consider the planar (slab) geometry P_N equations as before: for $l' = 0, 1, \dots$, we have

$$\left(\frac{l' + 1}{2l' + 1} \right) \frac{d}{dx} \phi_{l'+1}(x) + \left(\frac{l'}{2l' + 1} \right) \frac{d}{dx} \phi_{l'-1}(x) + \Sigma_t(x) \phi_{l'} = \Sigma_{sl'}(x) \phi_{l'}(x) + s_{l'}(x) ,$$

with $\phi_{-1} = 0$ and

$$\phi_{N+1} = 0 \quad \text{or} \quad \frac{d}{dx} \phi_{N+1} = 0 .$$

The second-order form of the planar geometry P_1 equations with Marshak boundary conditions is the diffusion equation

$$\begin{aligned} -\frac{d}{dx} D \frac{d\phi_0}{dx} + \Sigma_a(x) \phi_0(x) &= s_0(x) , 0 < x < X , \\ \frac{1}{2} \phi_0(0) - D \frac{d\phi_0}{dx}(0) &= 2J^+(0) , \\ \frac{1}{2} \phi_0(X) + D \frac{d\phi_0}{dx}(X) &= 2J^-(X) , \end{aligned}$$

where

$$D = \frac{1}{3 [\Sigma_t(x) - \Sigma_{s1}(x)]} .$$

This can be generalized to 3-D by making the two **formal** modifications:

1. Replace the 1-D diffusion operator

$$\frac{d}{dx} D \frac{d}{dx}$$

by the 3-D diffusion operator

$$\nabla \cdot D \nabla \equiv \frac{\partial}{\partial x} D \frac{\partial}{\partial x} + \frac{\partial}{\partial y} D \frac{\partial}{\partial y} + \frac{\partial}{\partial z} D \frac{\partial}{\partial z};$$

2. In the boundary conditions, replace the derivative terms

$$\pm \frac{d}{dx}$$

by the outward normal derivative

$$\vec{n} \cdot \nabla$$

Making these formal modifications, we obtain the standard 3-D diffusion (P_1) equations

$$\begin{aligned} -\nabla \cdot D \nabla \phi_0(\vec{r}) + \Sigma_a(\vec{r}) \phi_0(\vec{r}) &= s_0(\vec{r}), \vec{r} \in V, \\ \frac{1}{2} \phi_0(\vec{r}) + D \vec{n} \cdot \nabla \phi_0 &= 2J^-(\vec{r}), \vec{r} \in \partial V. \end{aligned}$$

These equations obviously reduce to the standard 1-D diffusion equations in planar geometry.

We carry out the same procedure for the general SP_N equations. First, for odd values of l' , $\phi_{l'}$ is replaced by a vector:

$$\phi_{l'} \rightarrow \vec{\phi}_{l'} = (\phi_{l'}^x, \phi_{l'}^y, \phi_{l'}^z)^t.$$

Then, in the even l' equations the derivative in x is replaced by a divergence:

$$\frac{d}{dx} \rightarrow \nabla \cdot;$$

and in the odd l' equations the x derivative is changed to a gradient:

$$\frac{d}{dx} \rightarrow \nabla$$

This allows us to write the first-order form of the SP_N equations as

$$\begin{aligned}\nabla \cdot \vec{\phi}_1 + \Sigma_a \phi_0 &= s_0 , \\ \left(\frac{l' + 1}{2l' + 1} \right) \nabla \phi_{l'+1} + \left(\frac{l'}{2l' + 1} \right) \nabla \phi_{l'-1} + \Sigma_t \vec{\phi}_{l'} &= \Sigma_{s l'} \vec{\phi}_{l'} + s_{l'} , & \text{for odd } l' , \\ \left(\frac{l' + 1}{2l' + 1} \right) \nabla \cdot \vec{\phi}_{l'+1} + \left(\frac{l'}{2l' + 1} \right) \nabla \cdot \vec{\phi}_{l'-1} + \Sigma_t \phi_{l'} &= \Sigma_{s l'} \phi_{l'} + s_{l'} , & \text{for even } l' > 0 .\end{aligned}$$

The boundary conditions for the SP_N equations can be obtained from the P_N Marshak boundary conditions by replacing $\phi_{l'}$ with the SP_N unknowns and μ with $\vec{n} \cdot \hat{\Omega}$, where \vec{n} is the unit inward normal to the boundary.

The SP_3 Equations

Assuming an isotropic source, the SP_3 equations in their first-order form are

$$\begin{aligned}\nabla \cdot \vec{\phi}_1 + \Sigma_a \phi_0 &= s_0 , \\ \frac{1}{3} \nabla \phi_0 + \frac{2}{3} \nabla \phi_2 + [\Sigma_t - \Sigma_{s1}] \vec{\phi}_1 &= 0 , \\ \frac{2}{5} \nabla \cdot \vec{\phi}_1 + \frac{3}{5} \nabla \cdot \vec{\phi}_3 + [\Sigma_t - \Sigma_{s2}] \phi_2 &= 0 , \\ \frac{3}{7} \nabla \phi_2 + [\Sigma_t - \Sigma_{s3}] \vec{\phi}_3 &= 0 .\end{aligned}$$

We can rewrite them in their second-order form by using the relation

$$\vec{\phi}_{l'} = -\frac{1}{\Sigma_t - \Sigma_{s l'}} \left(\frac{l'}{2l' + 1} \nabla \phi_{l'-1} + \frac{l' + 1}{2l' + 1} \nabla \phi_{l'+1} \right) ,$$

yielding

$$\begin{aligned}-\nabla \cdot \frac{1}{3[\Sigma_t - \Sigma_{s1}]} \nabla \phi_0 - \nabla \cdot \frac{2}{3[\Sigma_t - \Sigma_{s1}]} \nabla \phi_2 + \Sigma_a \phi_0 &= s_0 , \\ -\nabla \cdot \frac{2}{15[\Sigma_t - \Sigma_{s1}]} \nabla \phi_0 - \nabla \cdot \left(\frac{4}{15[\Sigma_t - \Sigma_{s1}]} + \frac{9}{35[\Sigma_t - \Sigma_{s3}]} \right) \nabla \phi_2 + [\Sigma_t - \Sigma_{s2}] \phi_2 &= 0 .\end{aligned}$$

The second-order form is useful because it makes the SP_N equations look like a set of coupled diffusion equations.

The SP_3 equations can be manipulated into a form that resembles a two group diffusion equation

by defining $\hat{\phi}_0 = \phi_0 + 2\phi_2$. Using this new variable, we can write

$$\begin{aligned} -\nabla \cdot \frac{1}{3[\Sigma_t - \Sigma_{s1}]} \nabla \hat{\phi}_0 + \Sigma_a \hat{\phi}_0 &= 2\Sigma_a \phi_2 + s_0, \\ -\nabla \cdot \frac{9}{35[\Sigma_t - \Sigma_{s3}]} \nabla \phi_2 + \left([\Sigma_t - \Sigma_{s2}] + \frac{4}{5}\Sigma_a \right) \phi_2 &= \frac{2}{5} [\Sigma_a \hat{\phi}_0 - s_0]. \end{aligned}$$

These equations can be solved with a two-group diffusion code by properly setting the diffusion coefficients and cross-sections or with a one-group diffusion code utilizing an iteration strategy for the coupling terms (FLIP).

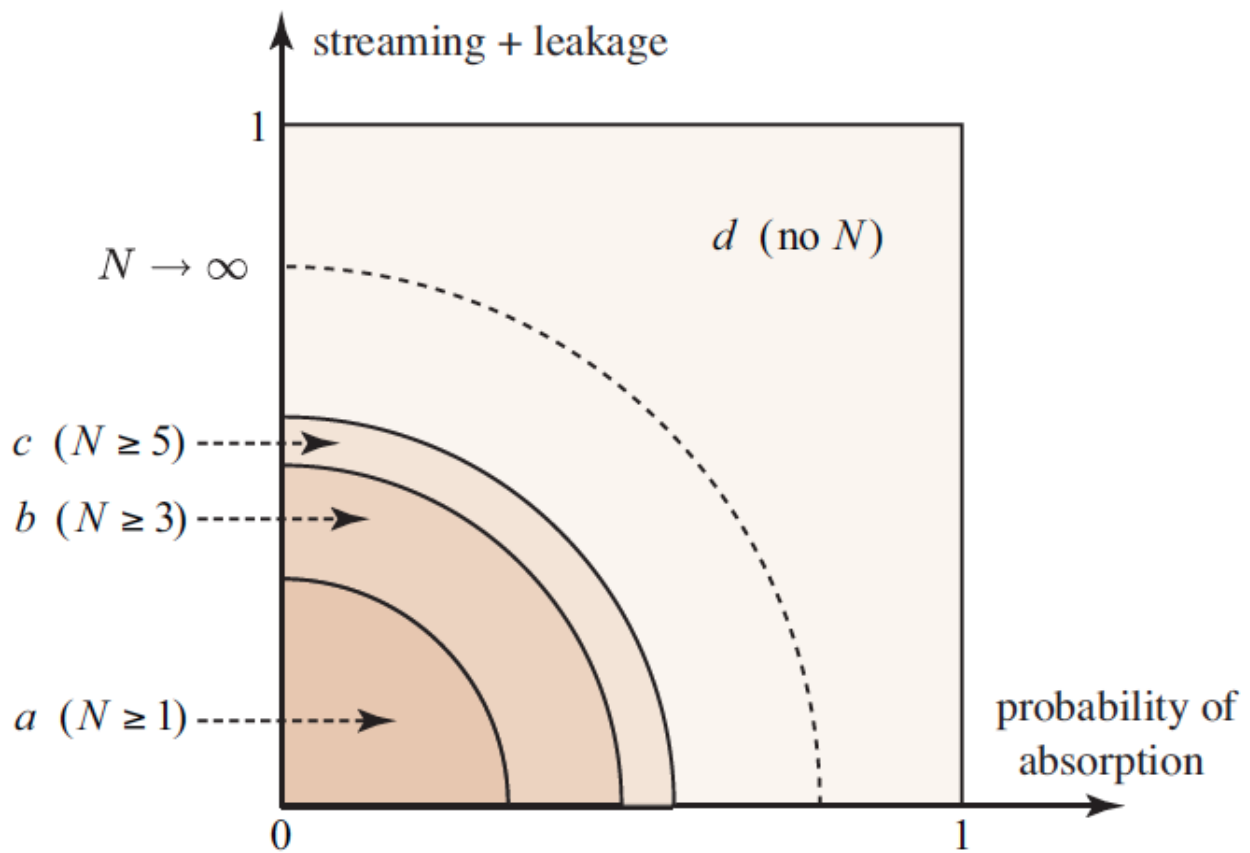
General Properties of the SP_N Equations

The SP_N equations can be understood as a “super” diffusion theory. The structure of the SP_N equations is that of a coupled system of diffusion equations, and the class of problems for which the SP_N equations are accurate encompasses the class of problems for which diffusion theory is accurate.

1. In 1-D planar geometry, SP_N and P_N are identical
2. In multidimensional problems, SP_N form a system of $(N + 1)$ equations; P_N form a much larger system of $(N + 1)^2$ equations
3. The SP_N equations have the same “diffusion” (elliptic) structure as the P_1 equations; the P_N equations have a more complicated (hyperbolic) mathematical structure.
4. The above derivation of the SP_N equations assumes as its starting point a 1-group transport problem. However, applying the same procedures to a multigroup transport problem is straightforward. The only complication is that the diffusion coefficients can become non-diagonal matrices. Thus, unlike standard multigroup diffusion theory (but like standard multigroup P_1 theory), the multigroup SP_N equations generally have non-diagonal matrix diffusion coefficients.
5. In principle, the 2-D or 3-D SP_N equations can be implemented in a 2-D or 3-D diffusion code without fundamentally rewriting the code. This is not the case for the P_N equations.
6. The SP_N equations contain more “transport physics” than the diffusion equations. For this reason, solutions of the SP_N equations can contain boundary layers that are not present in P_1 solutions. In order to properly resolve these boundary layers, it may be necessary to use a finer spatial grid for the SP_N equations than for the diffusion equation. Alternatively, the

use of nodal methods with extra expansion terms capable of expressing the boundary layer effects may be required.

7. The multigroup SP_3 equations are about twice as costly to solve as the multigroup P_1 equations. However, SP_3 solutions are usually much more accurate (transport-like) than P_1 solutions.
8. In the limit as $N \rightarrow \infty$, the P_N solutions converge to the transport solution.
9. In the limit as $N \rightarrow \infty$, the SP_N solutions do not generally converge to the transport solution—unless the underlying problem is 1-D. Therefore, high-order SP_N equations cannot be used to obtain arbitrarily accurate solutions of neutron transport problems in 2 or 3 dimensions.
10. For 3-D problems, the system of P_N equations is much more complicated in structure and greater in number than the system of SP_N equations. Also, for problems having 1-D symmetry, the P_N and SP_N equations become identical. For these reasons, it is widely believed that the 3-D SP_N equations can be derived by discarding the proper terms (and equations) from the 3-D P_N equations. However, this has never been shown. In fact, the precise relationship between the 3-D P_N and the 3-D SP_N equations is not known.
11. For problems in which the P_1 solution is accurate, the SP_3 solution is generally much more accurate. As problems become less “diffusive” (absorption, streaming, or leakage become increasingly important), the P_1 and SP_3 solutions both degrade in accuracy. However, the P_1 solutions degrade more rapidly, and the SP_3 solutions can remain accurate well into the range in which P_1 solutions are not accurate. When the problem becomes sufficiently “difficult”, the P_1 and SP_N solutions both become inaccurate (see figure in the next page).



This figure shows the (qualitative) range of validity of the SP_N equations. The amounts of absorption and streaming/leakage are indicated on arbitrary scales ranging from 0 to 1. In region *a*, where streaming, leakage, and absorption are weak, the P_1 and all SP_N solutions are accurate. As absorption or streaming increase (region *b*), P_1 becomes inaccurate but SP_N with $N \geq 3$ is still accurate. As absorption or streaming increase further (region *c*), P_1 and SP_3 are inaccurate but SP_N with $N \geq 5$ is still accurate. In region *d*, no SP_N solution is accurate.

These notes are derived from Edward Larsen's class notes for NE 644 at the University of Michigan, and from Ryan McClarren's review paper on the SP_N equations: "Theoretical Aspects of the Simplified P_n Equations", *Transport Theory and Statistical Physics* 39: 73–109, 2011.