

# Nonparametric Deconvolution Models

**Allison J.B. Chaney**  
Princeton University

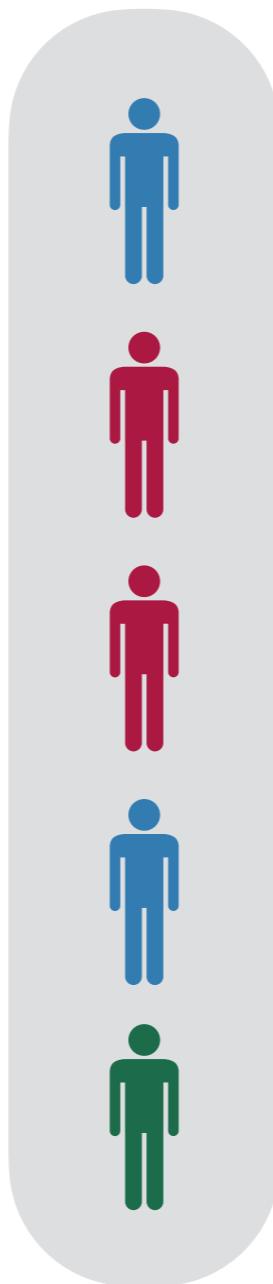
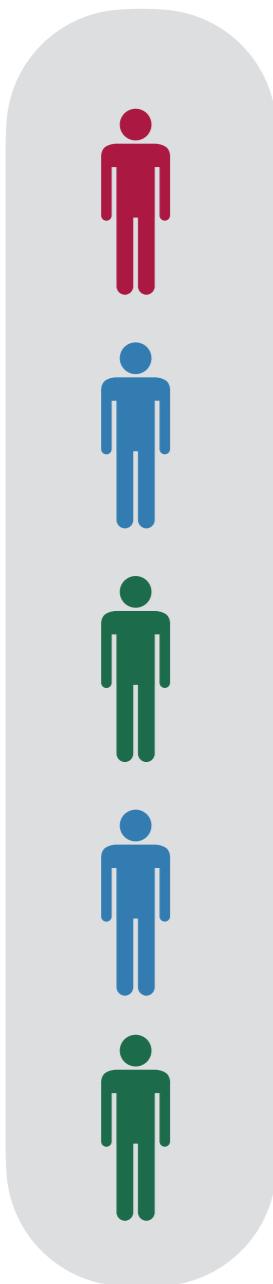
In collaboration with Barbara Engelhardt,  
Archit Verma and Young-Suk Lee

# Objective

Model collections of convolved data points

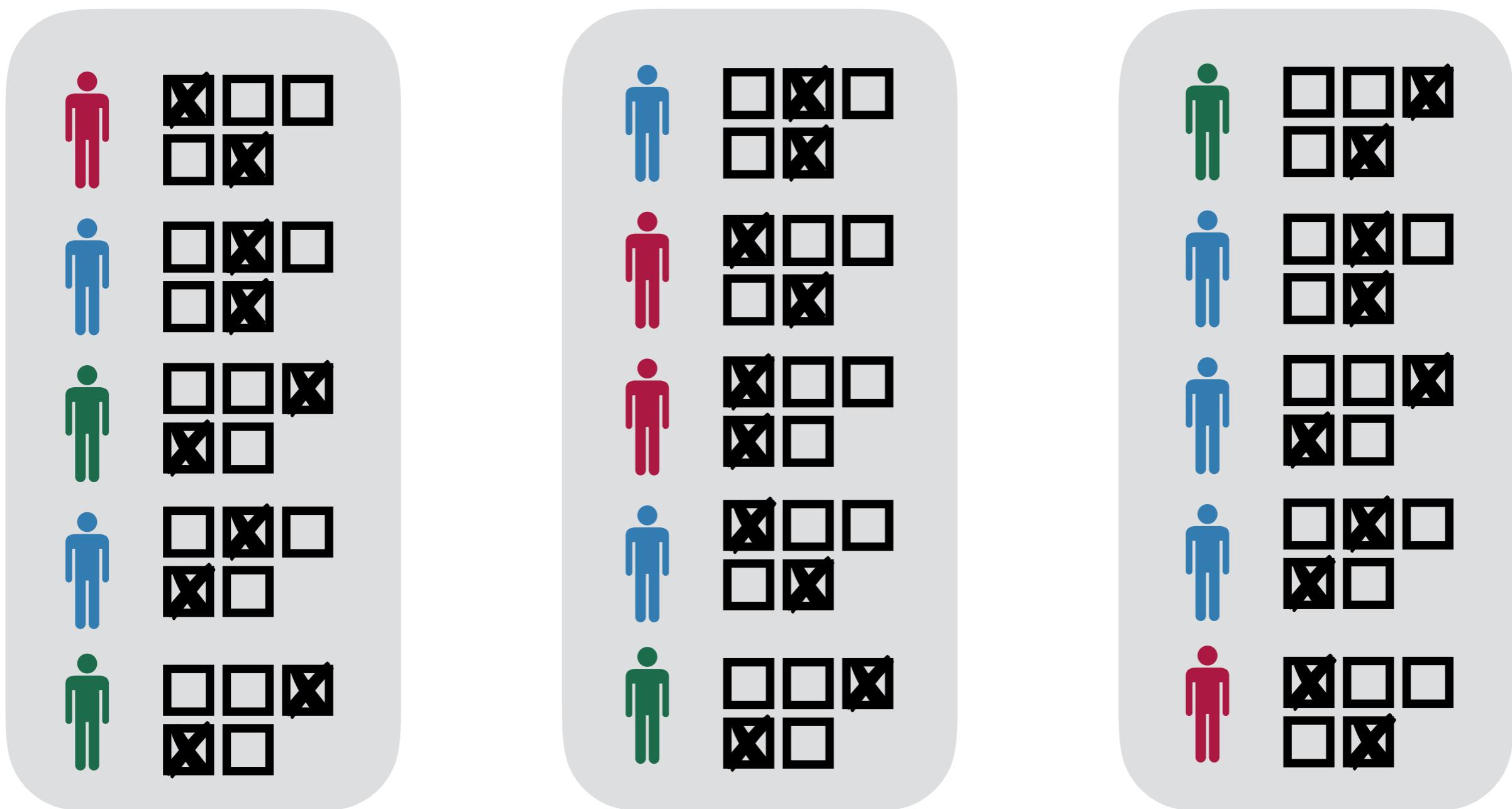
# Objective

Model collections of convolved data points



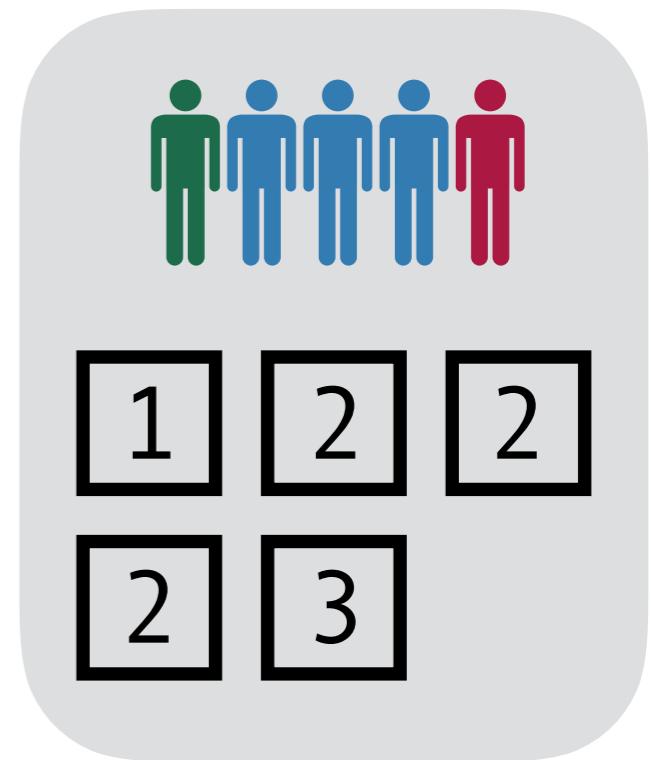
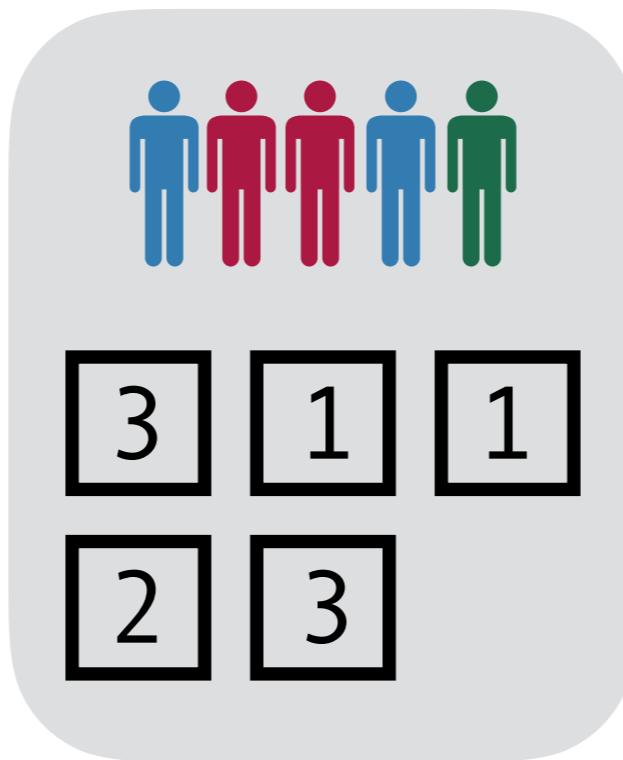
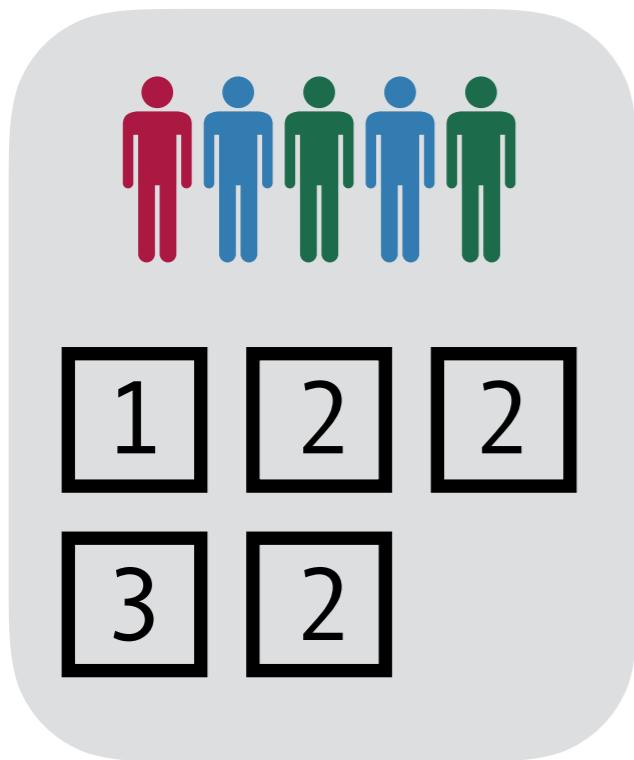
# Objective

# Model collections of convolved data points



# Objective

Model collections of convolved data points



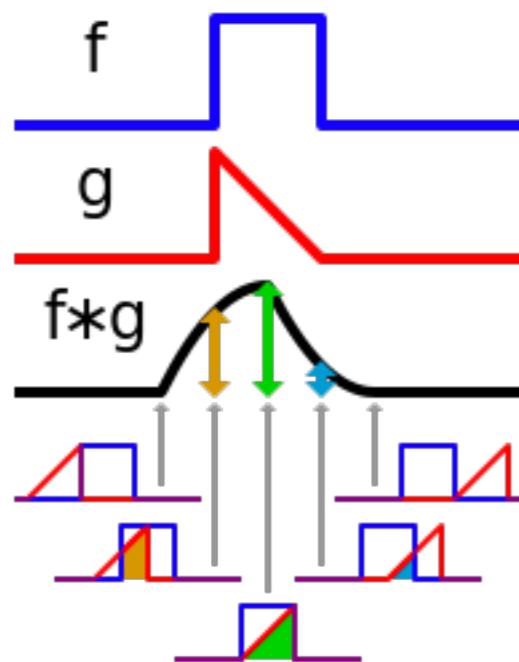
# Objective

Model collections of convolved data points

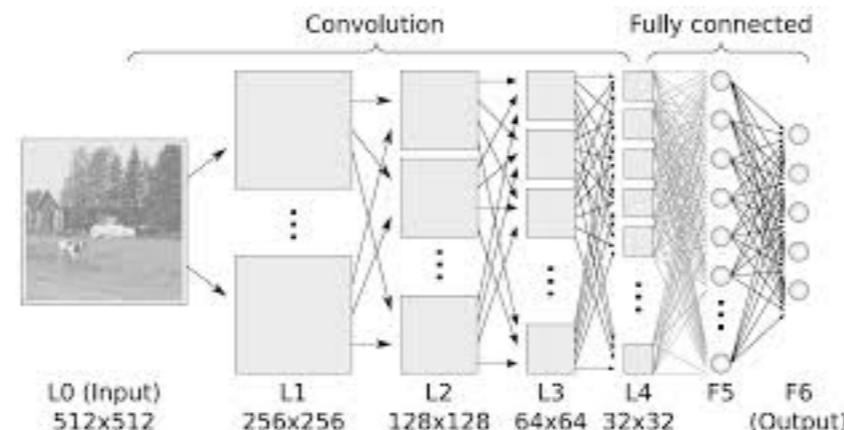
<b>General</b>	<b>Voting</b>	<b>Bulk RNA-seq</b>	<b>Images</b>
observation	district vote tally	sample	image
feature	issue or candidate	gene expression level	pixel
particle	individual voter	one cell	light particle
factor	voting cohort	cell type	visual pattern

# “convolution”

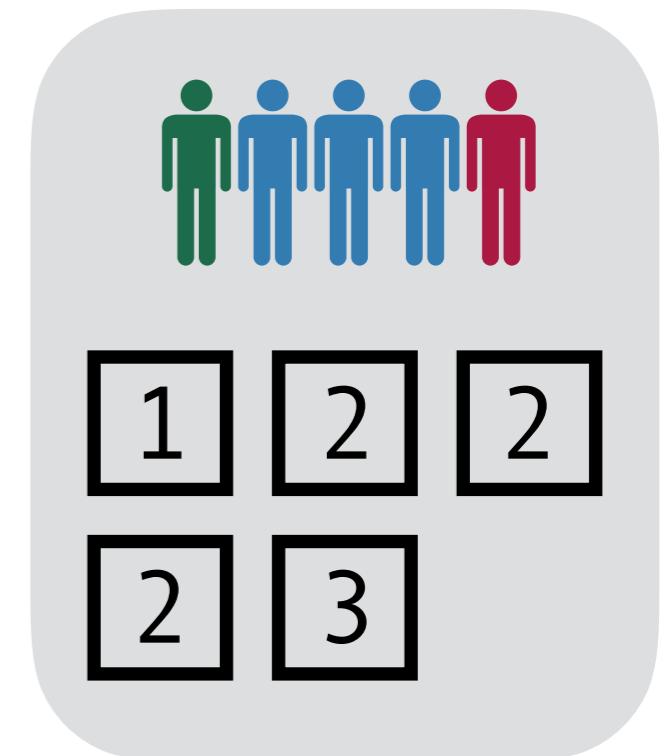
signal  
progressing



convolutional  
neural nets

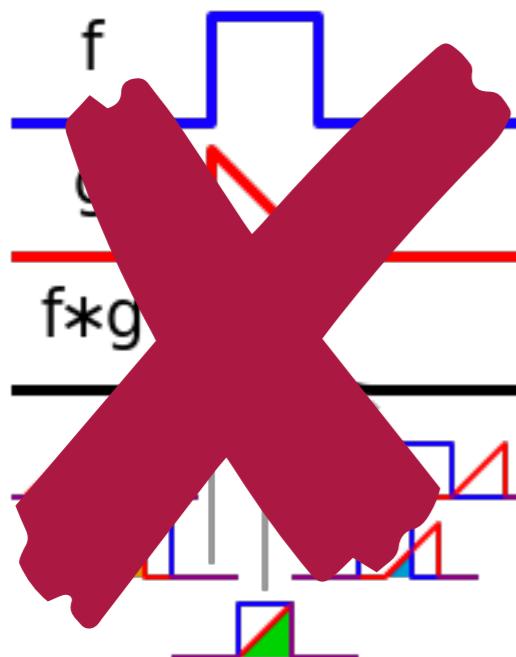


individual particles  
observed together

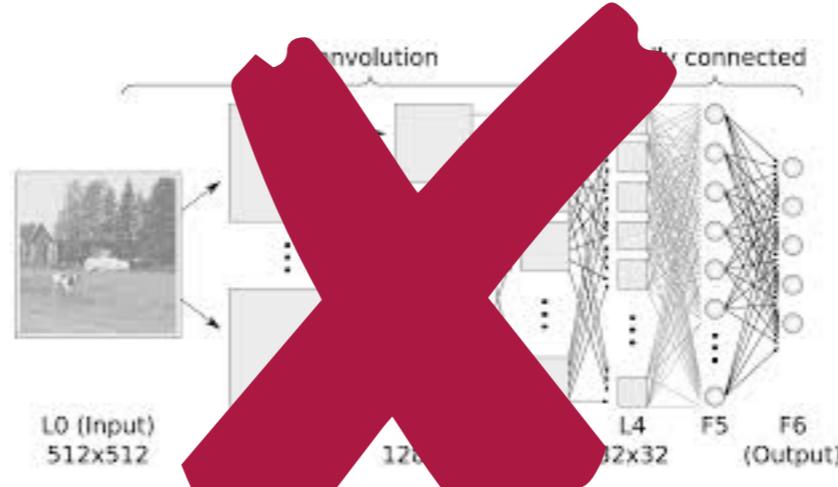


# “convolution”

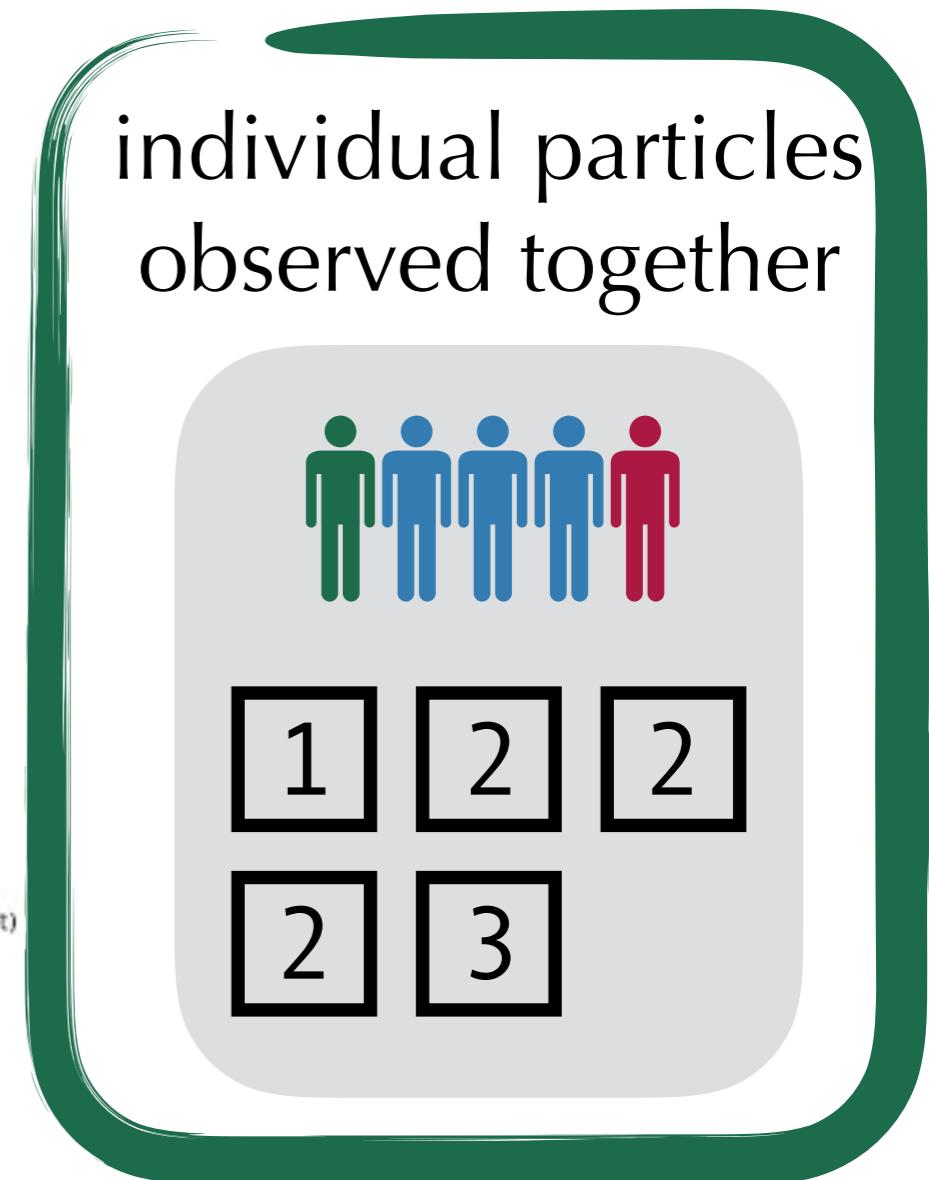
signal  
progressing



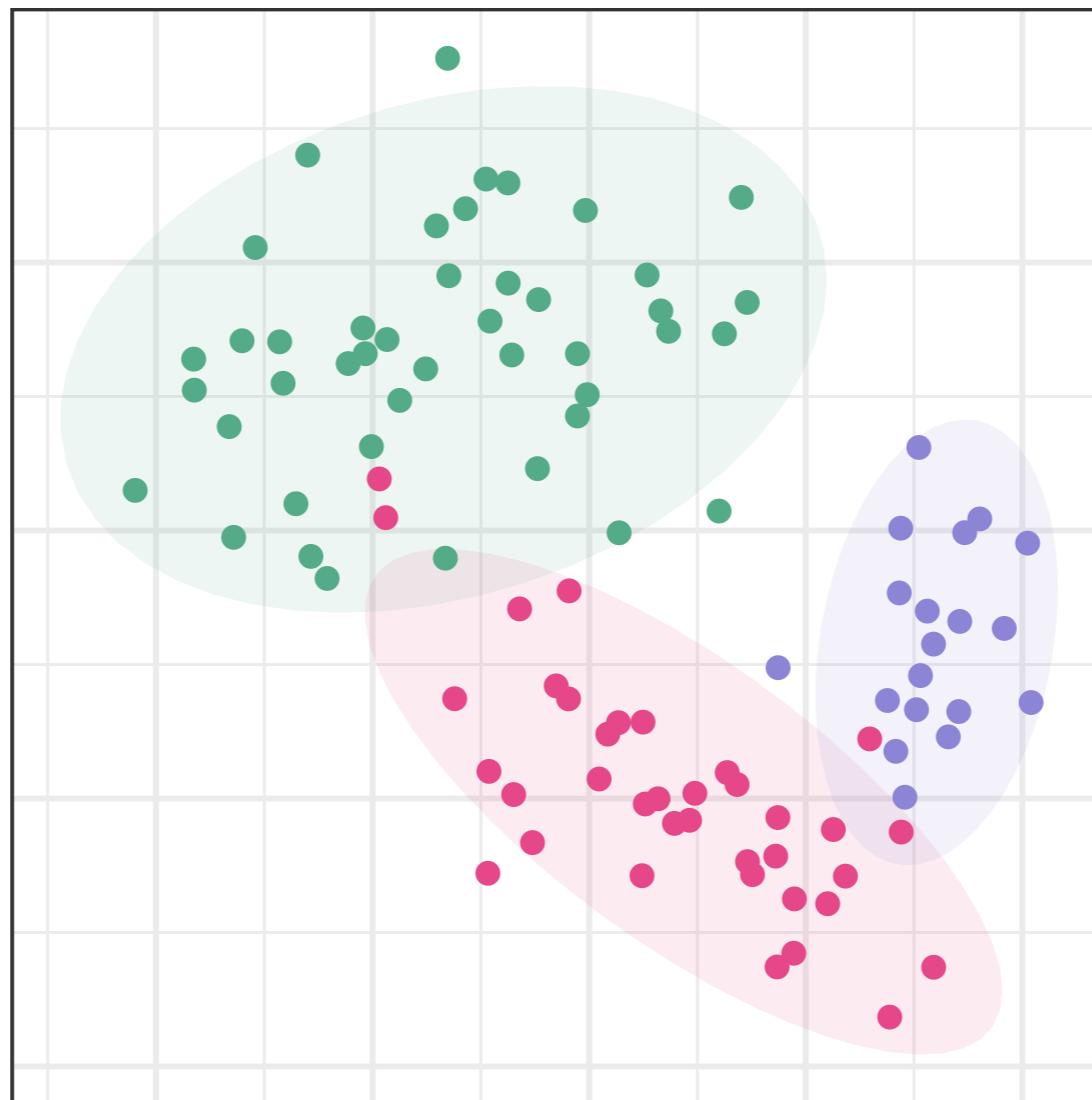
convolutional  
neural nets



individual particles  
observed together

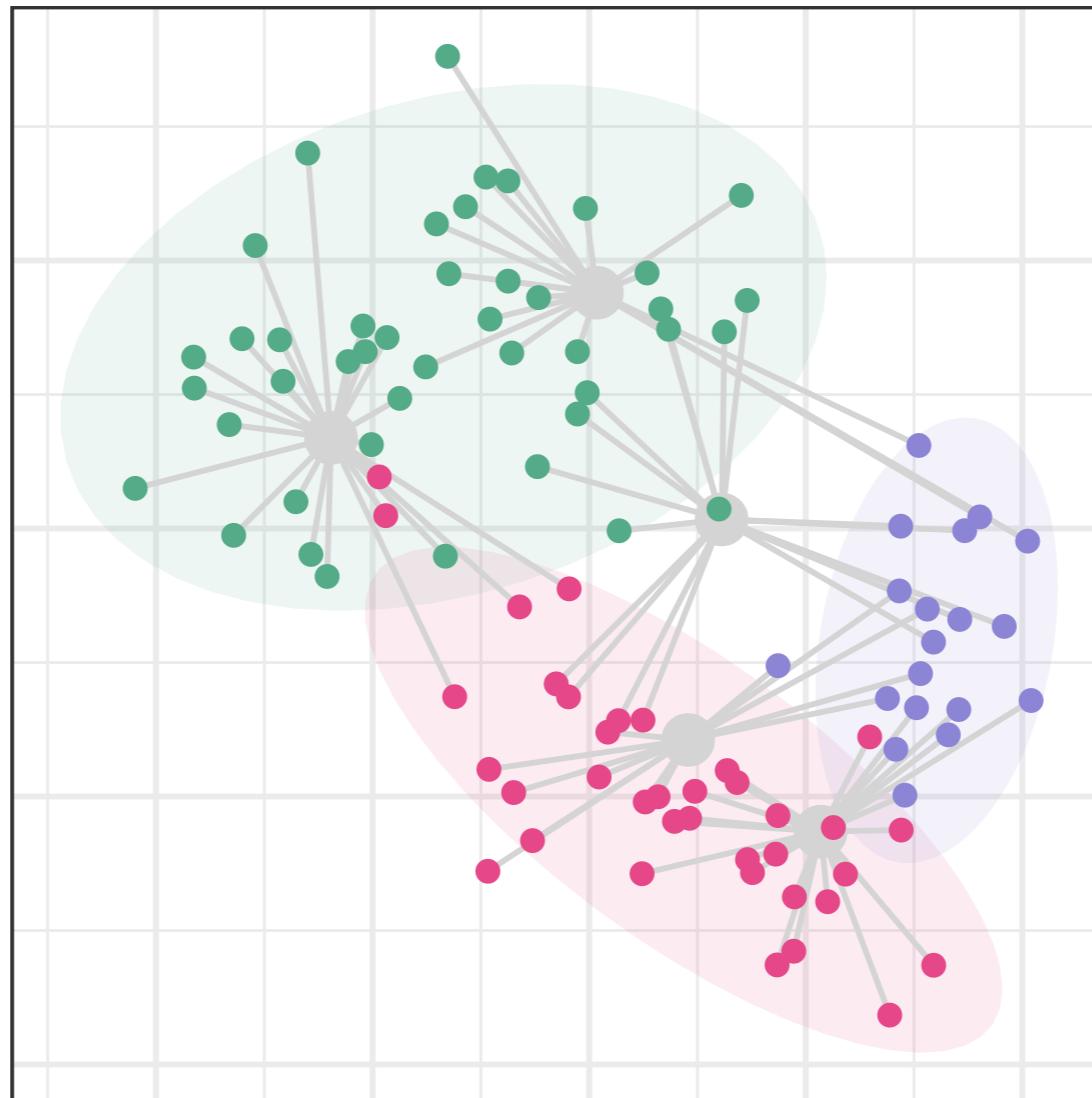


# Related Models



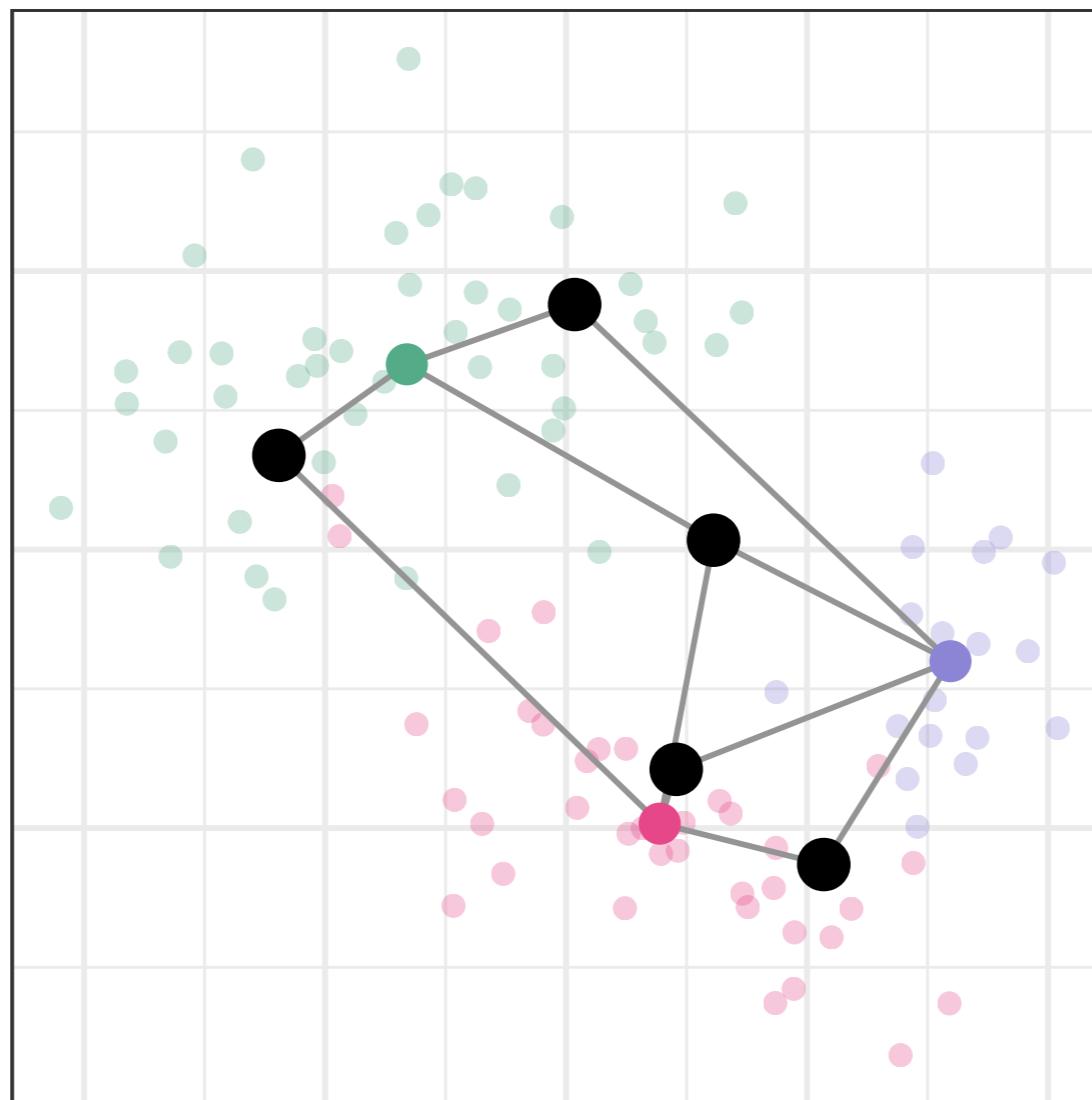
**Mixture models** assign each observation to one of  $K$  clusters, or factors.

# Related Models



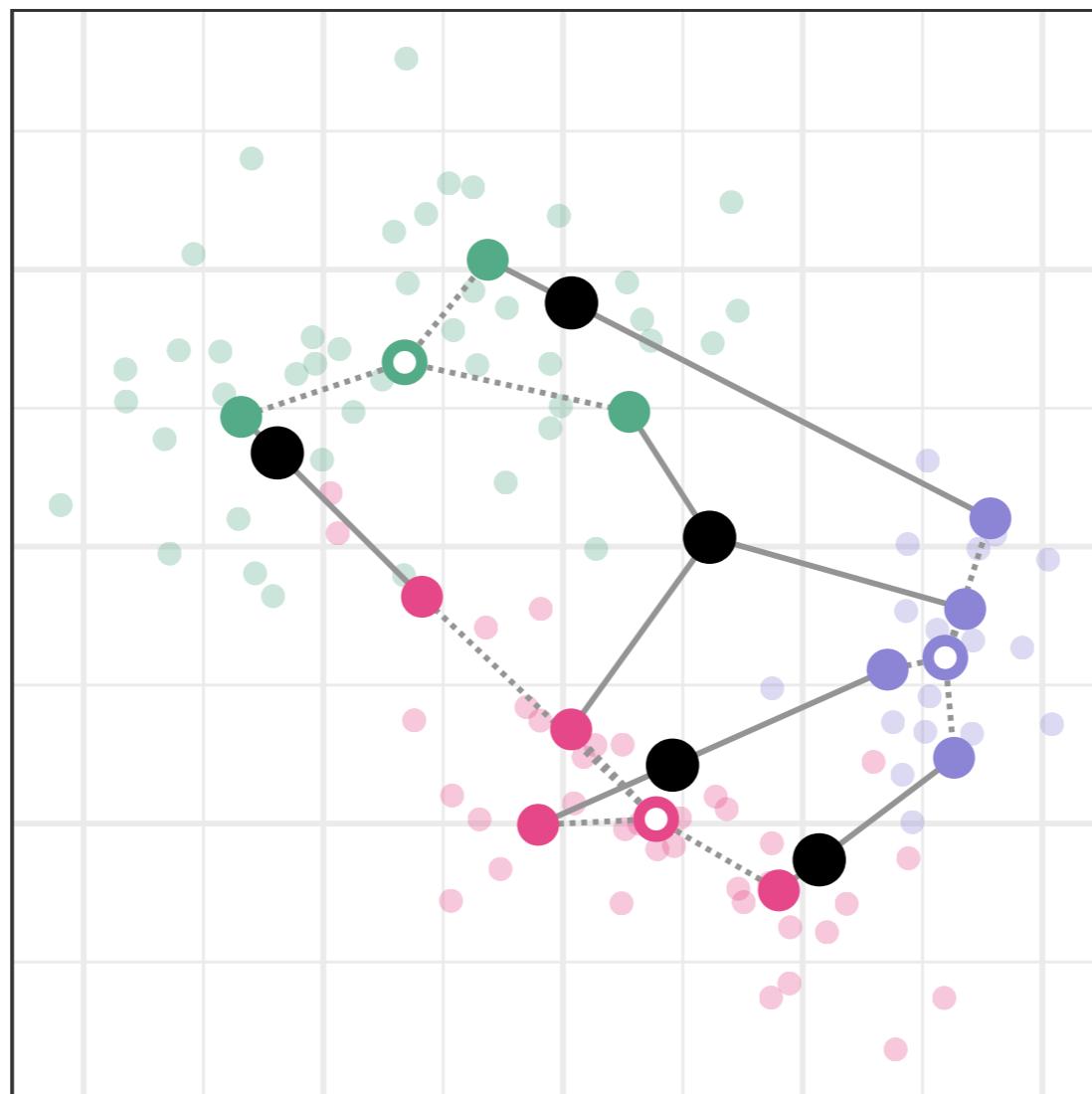
**Admixture models** represent groups of observations, each with its own mixture of  $K$  shared factors.

# Related Models

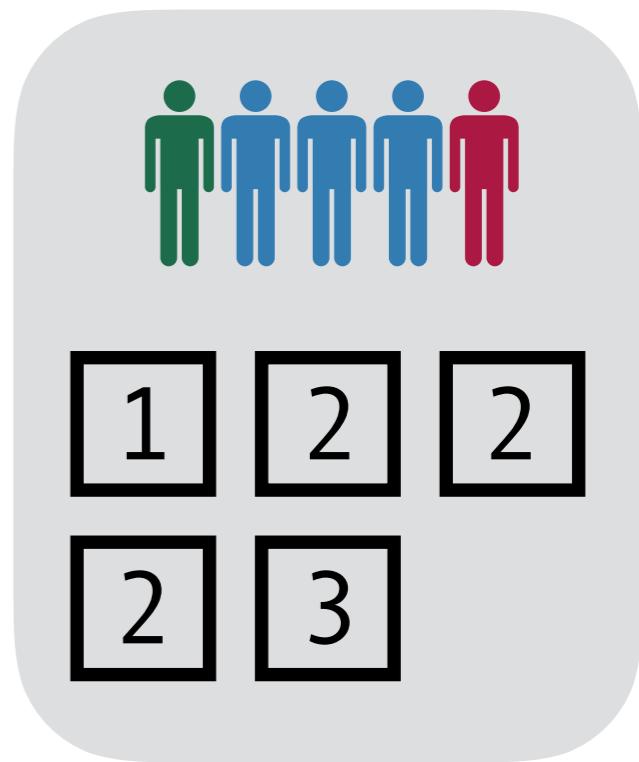
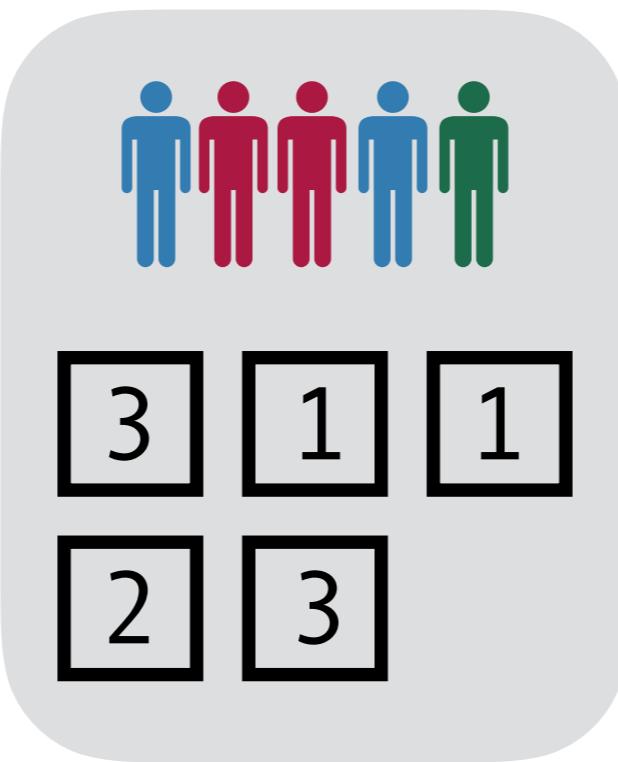
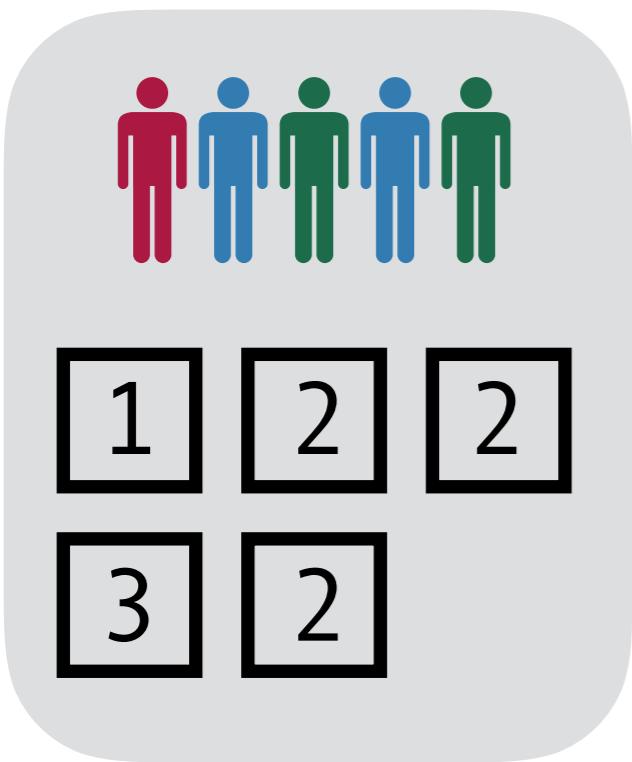


**Decomposition models**  
decompose observations into  
constituent parts by representing  
observations as a product between  
group representations and factor  
features.

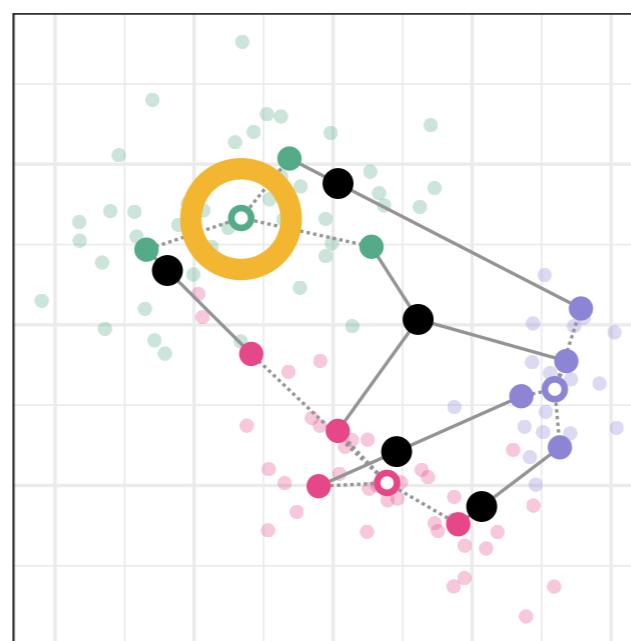
# Our Model

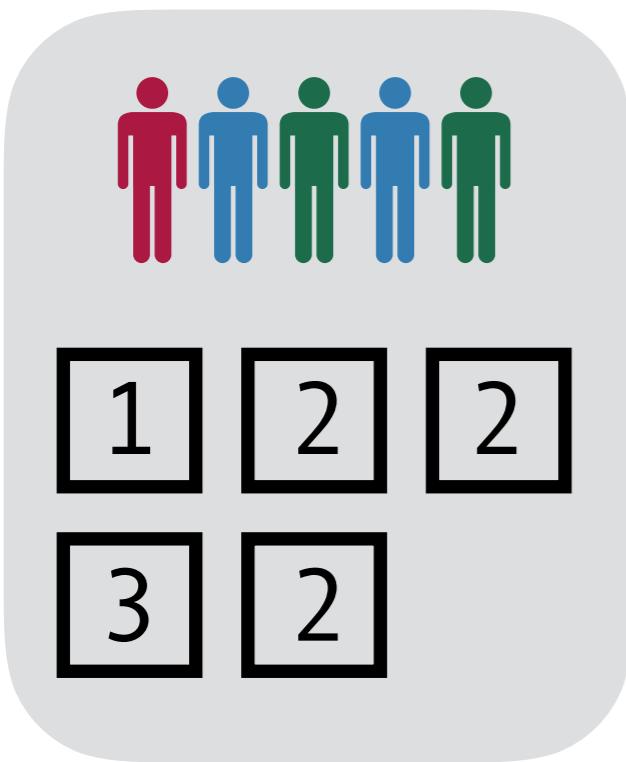
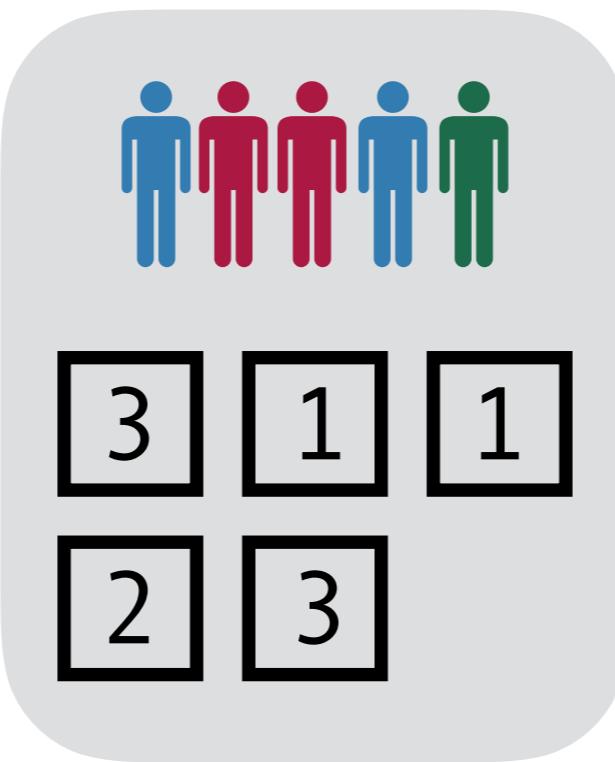
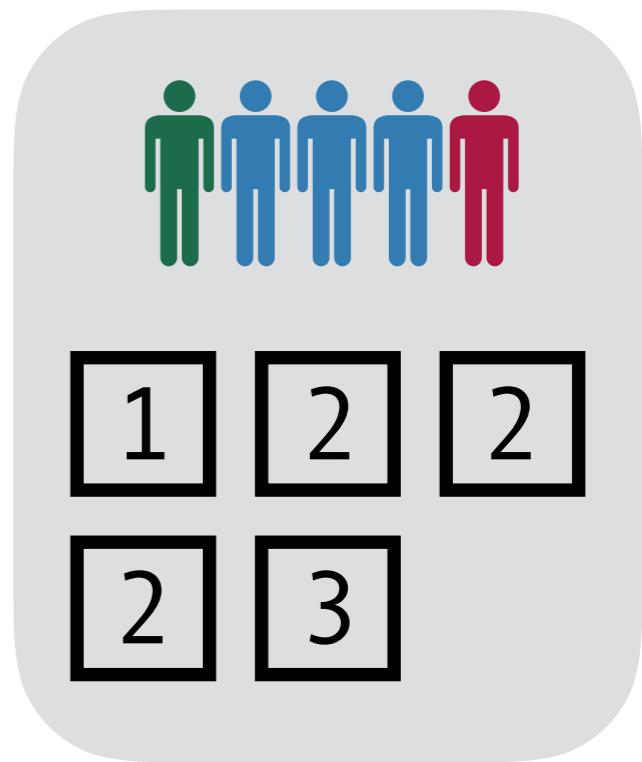


**Deconvolution models** (this work) similarly decompose, or deconvolve, observations into constituent parts, but also capture group-specific (or local) fluctuations in factor features.

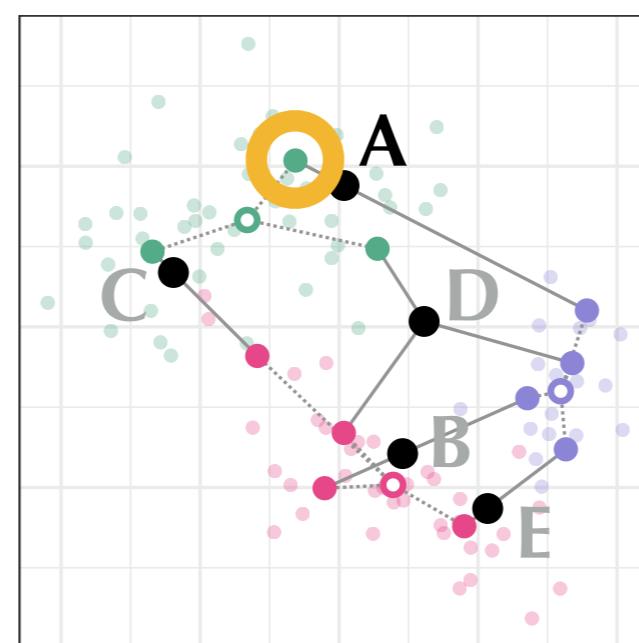


How do usually vote?

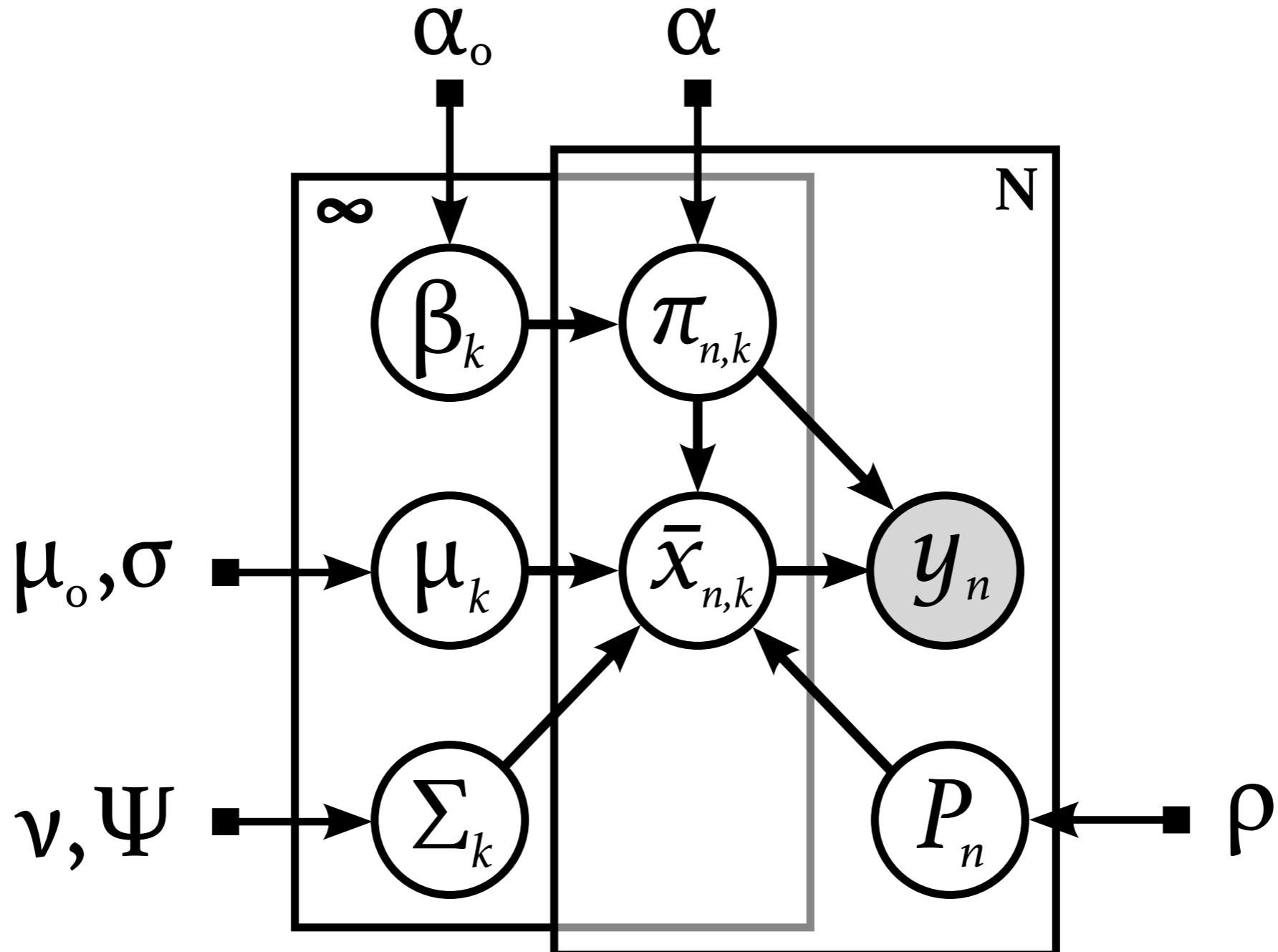


**A****B****C**

How do vote in district A?

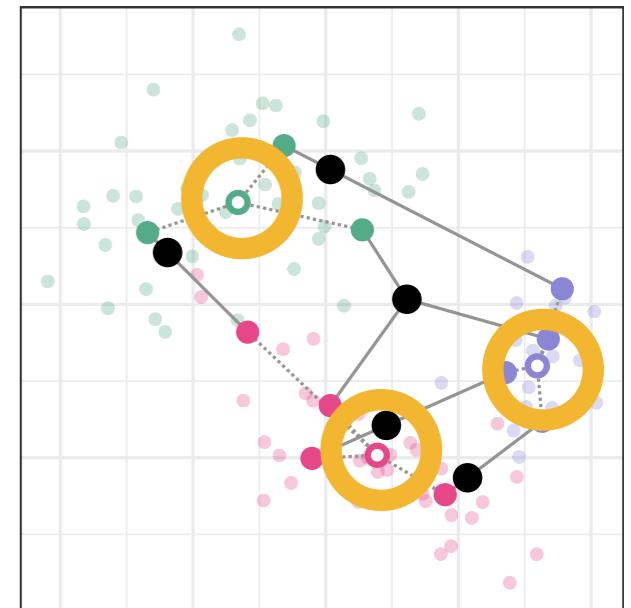
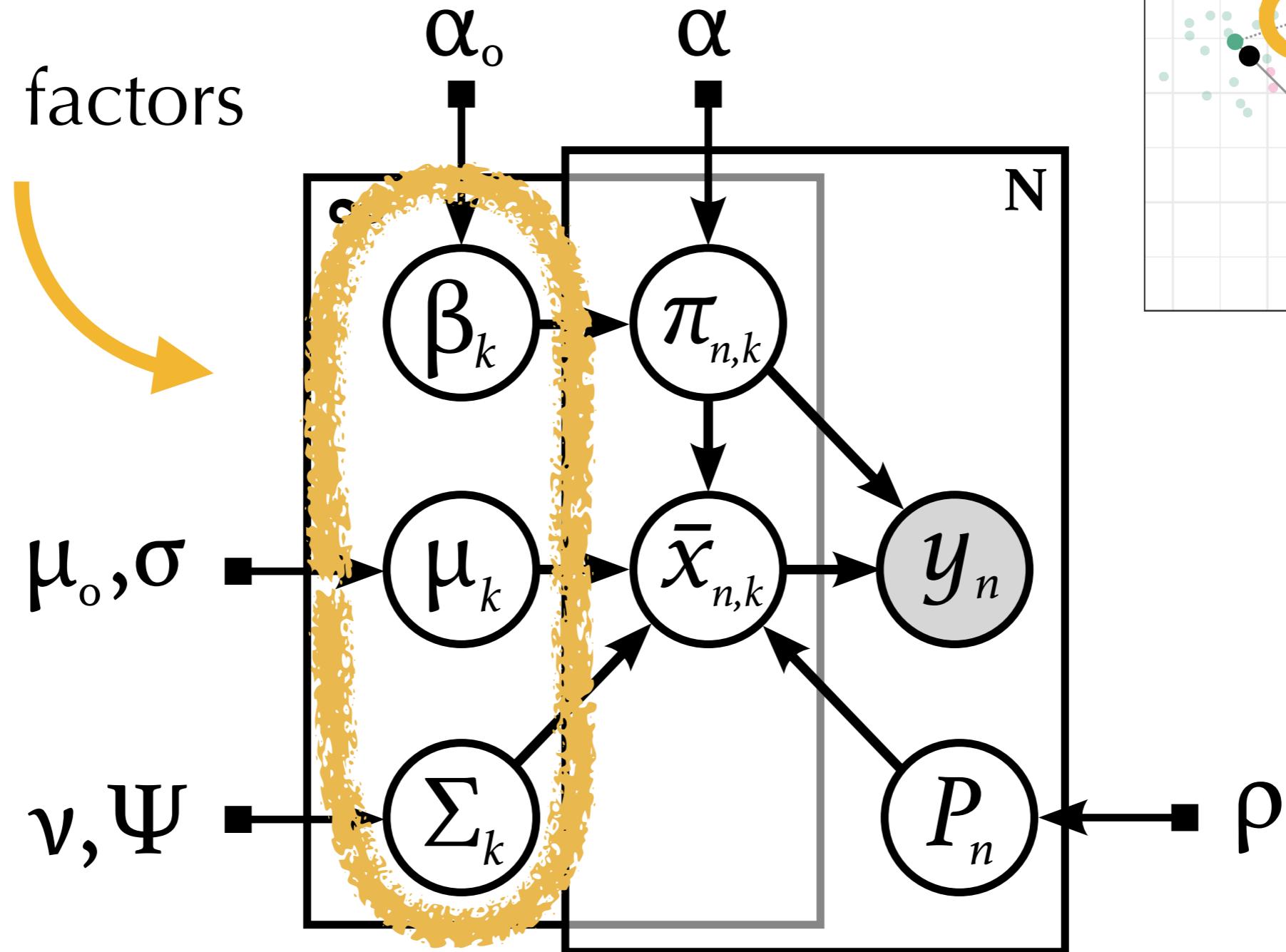


# Our Model

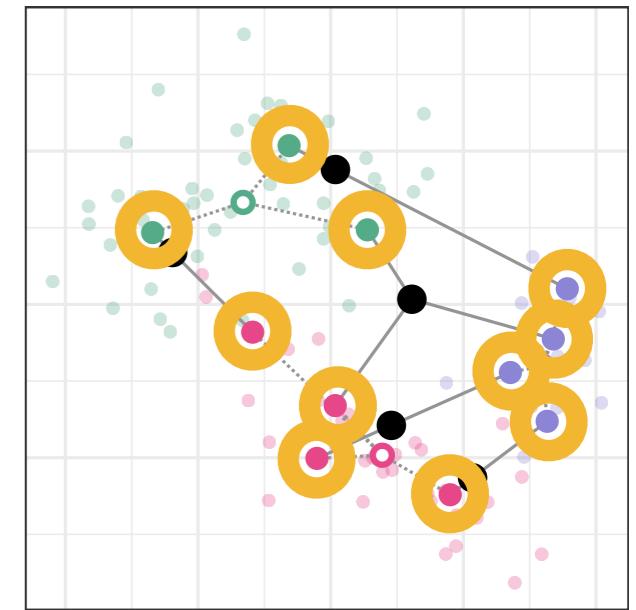
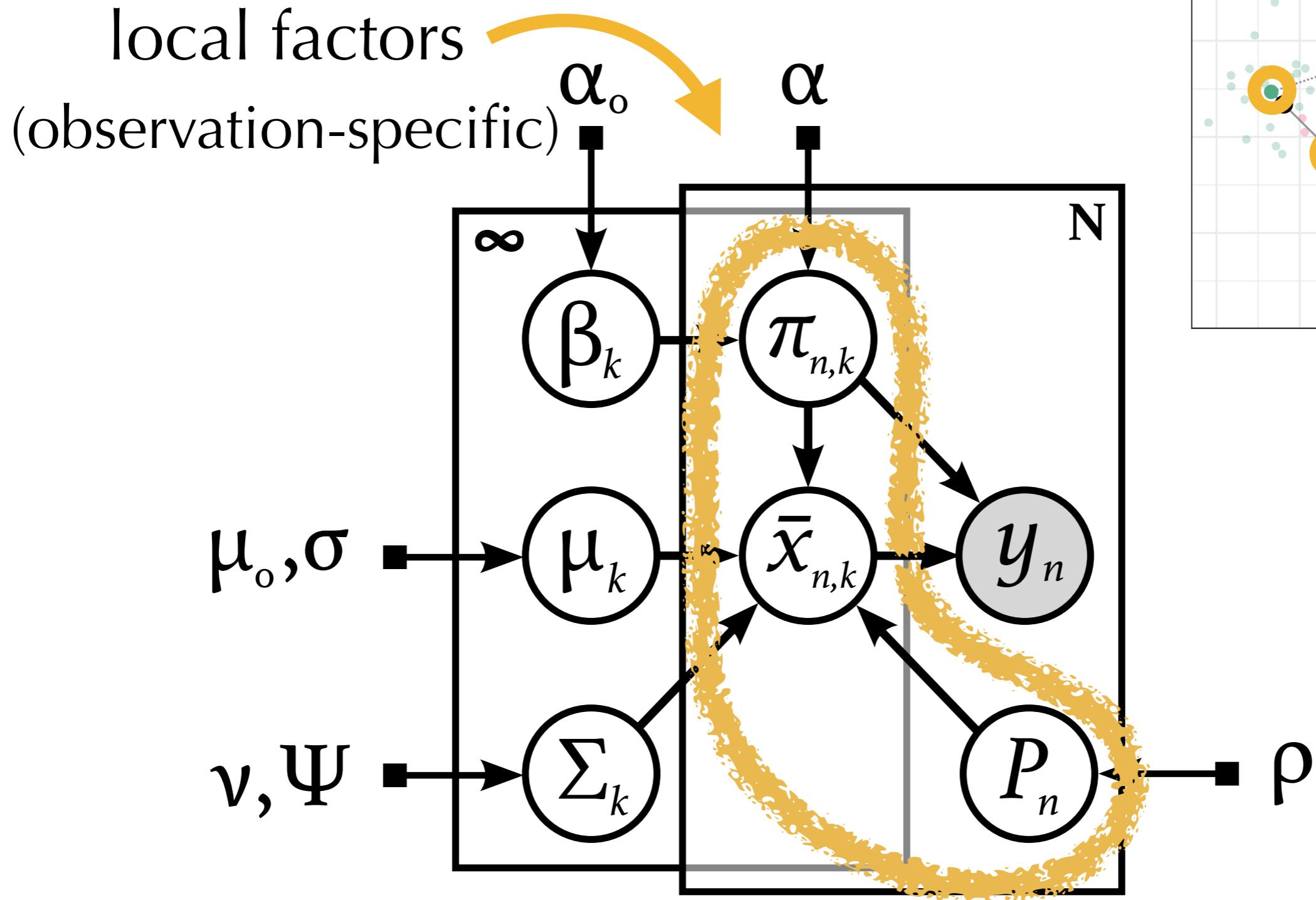


# Our Model

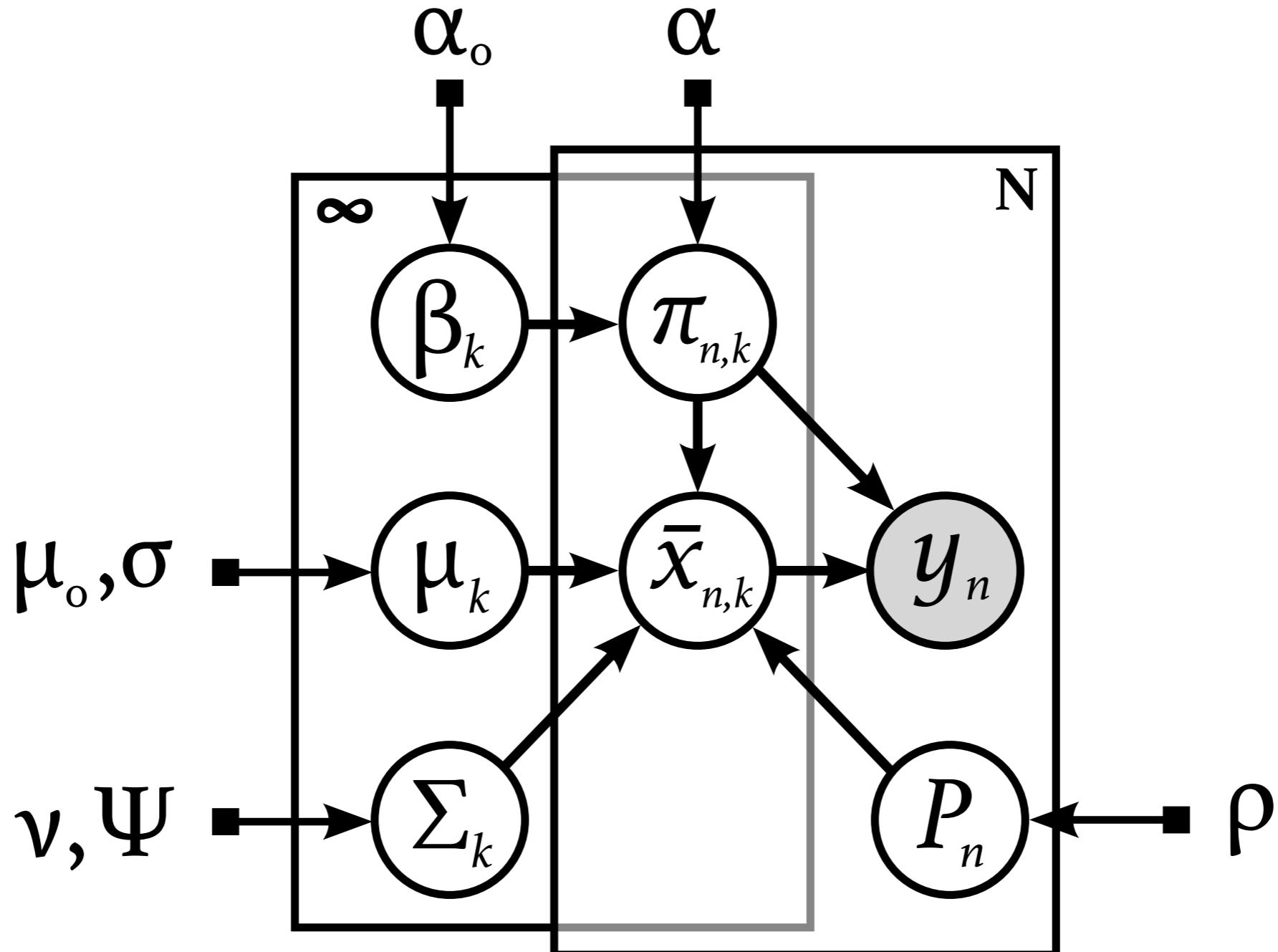
global factors



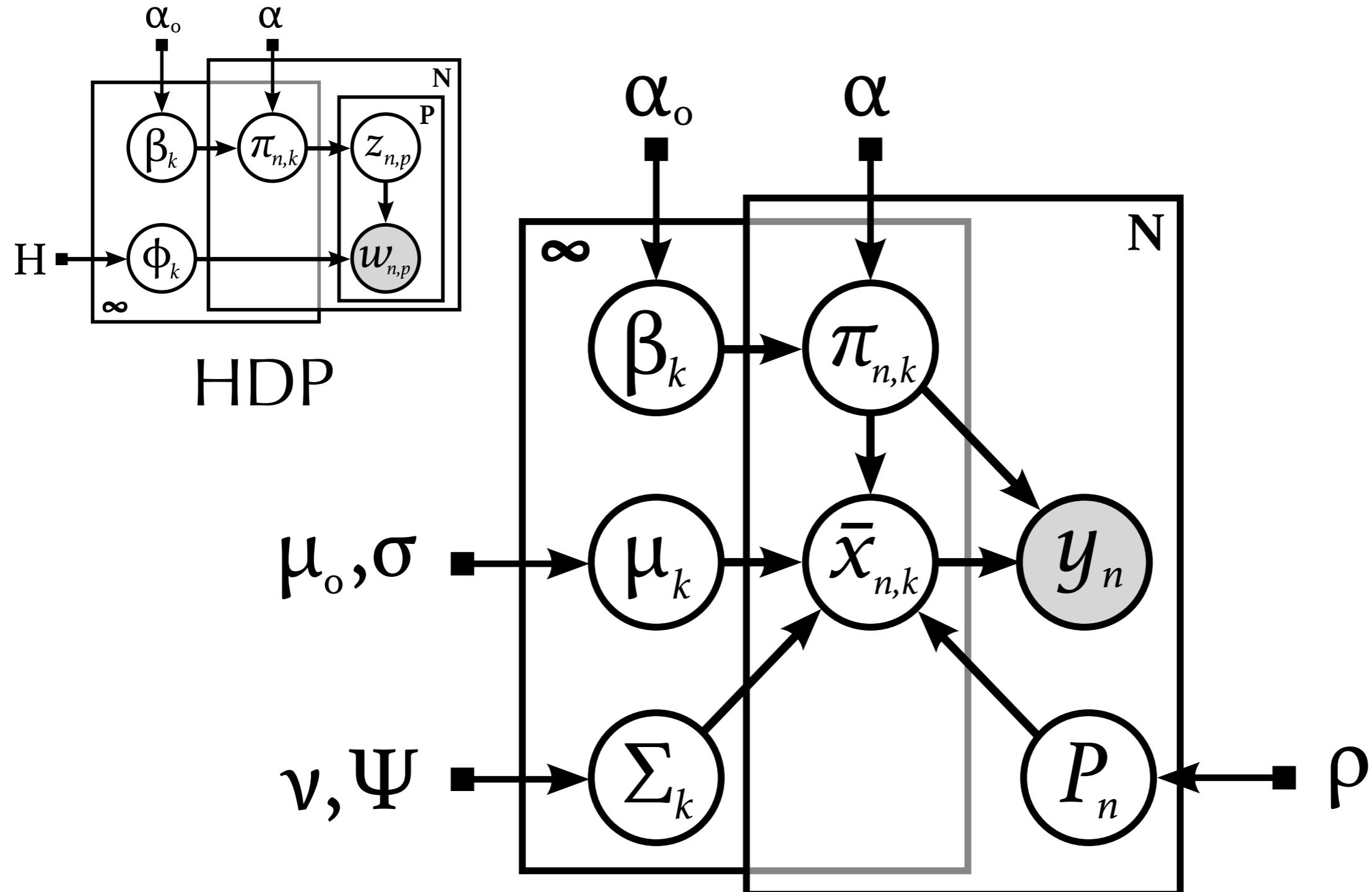
# Our Model



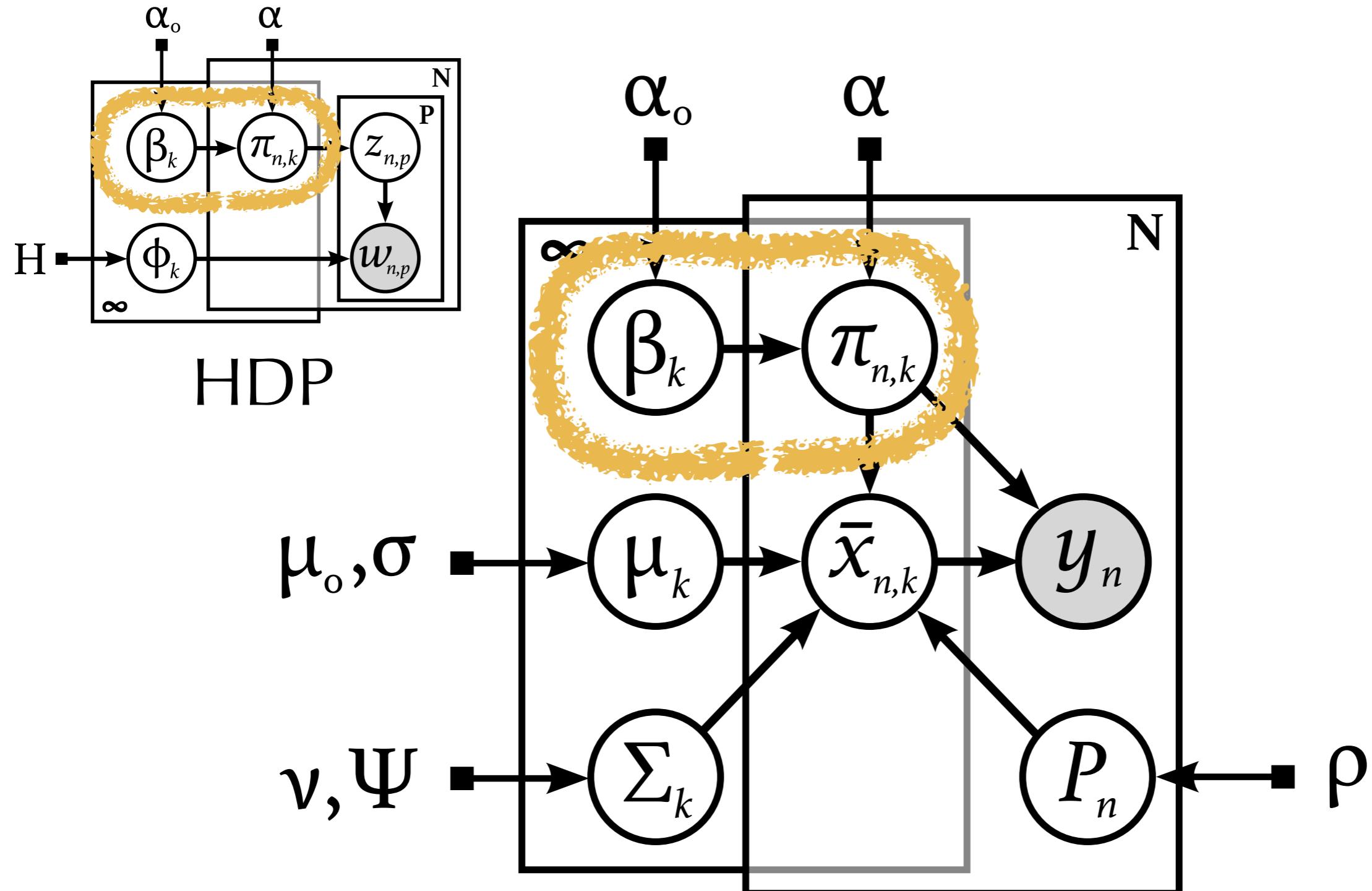
# Our Model



# Our Model

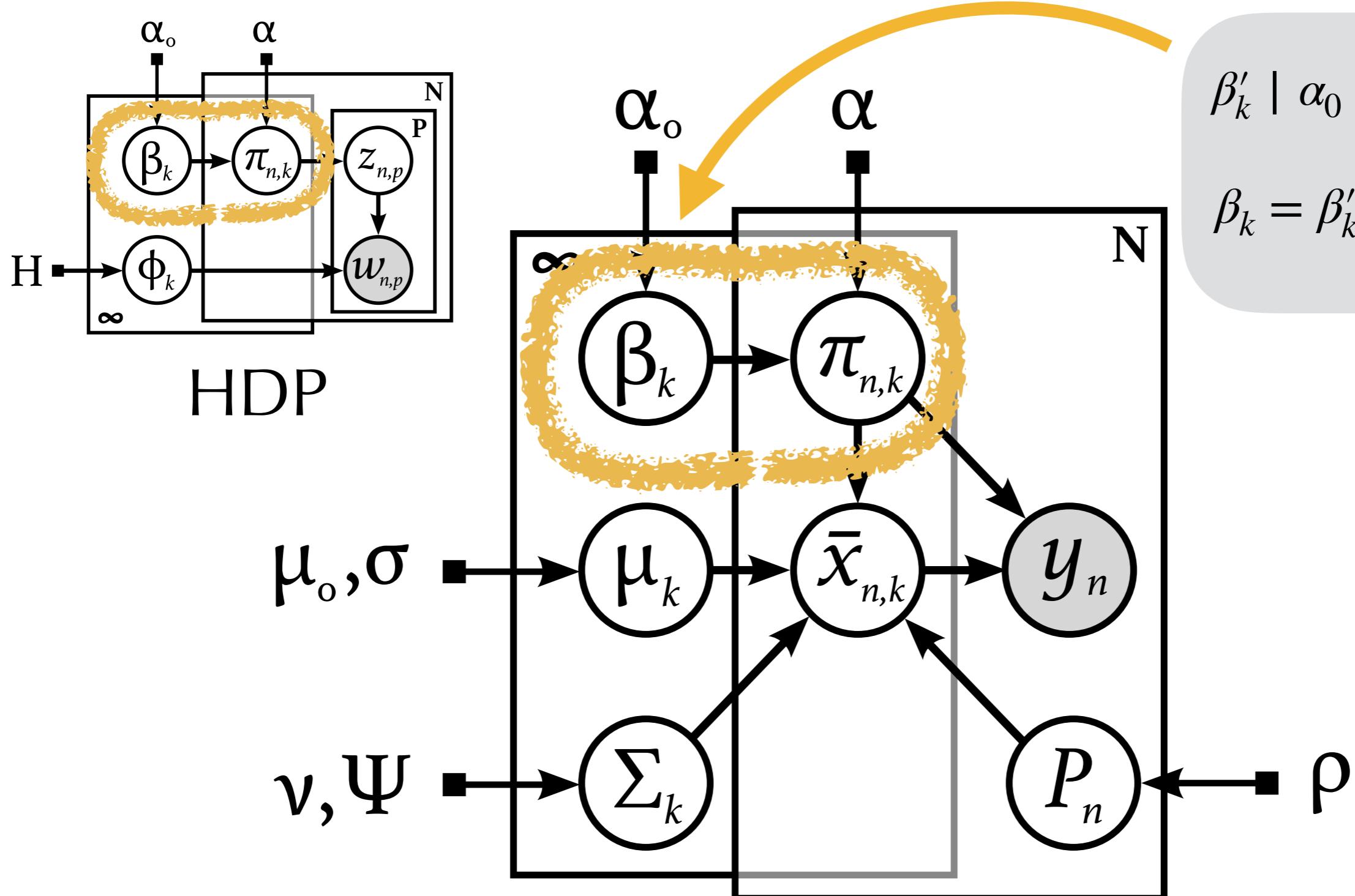


# Our Model



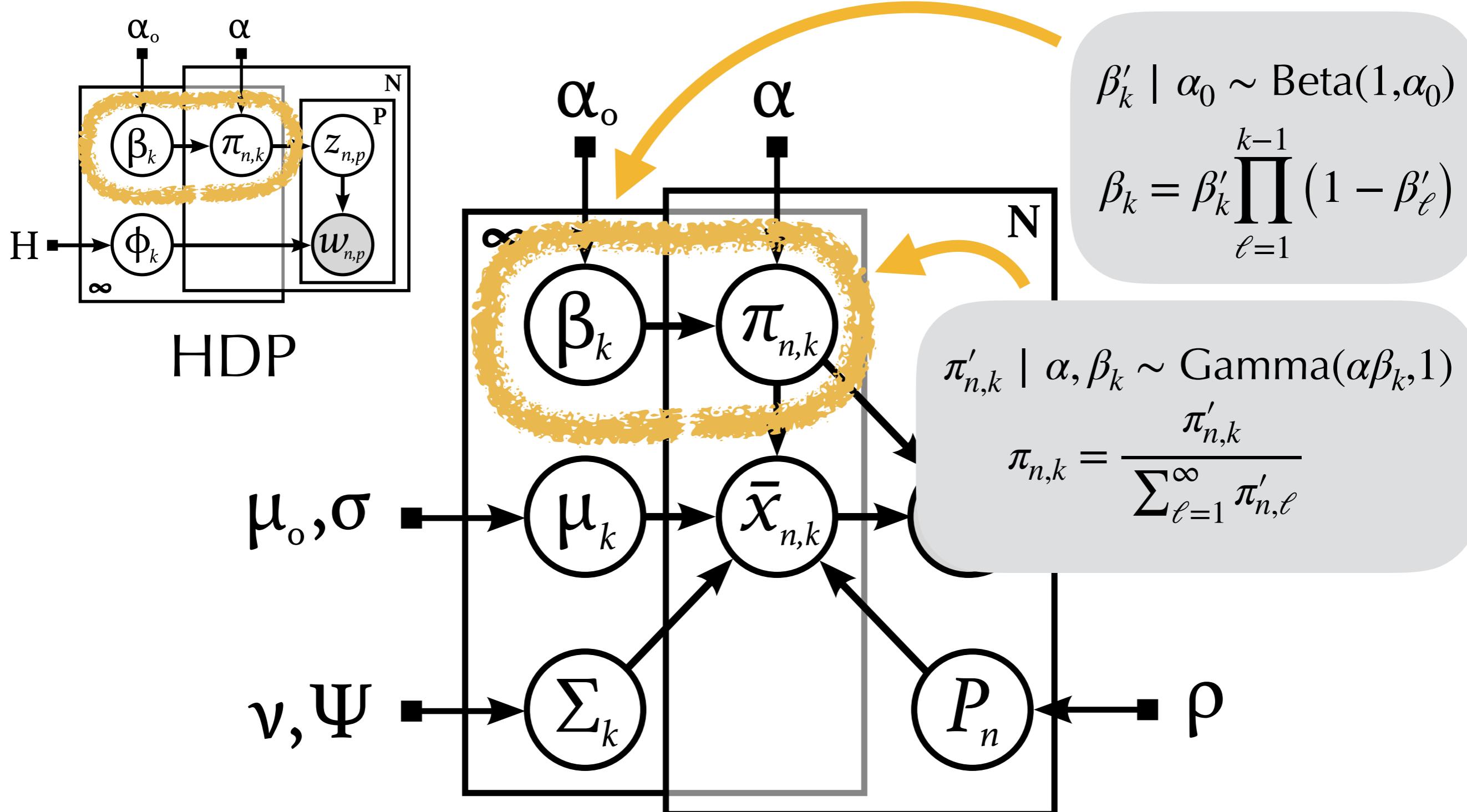
# Our Model

Paisley, 2012



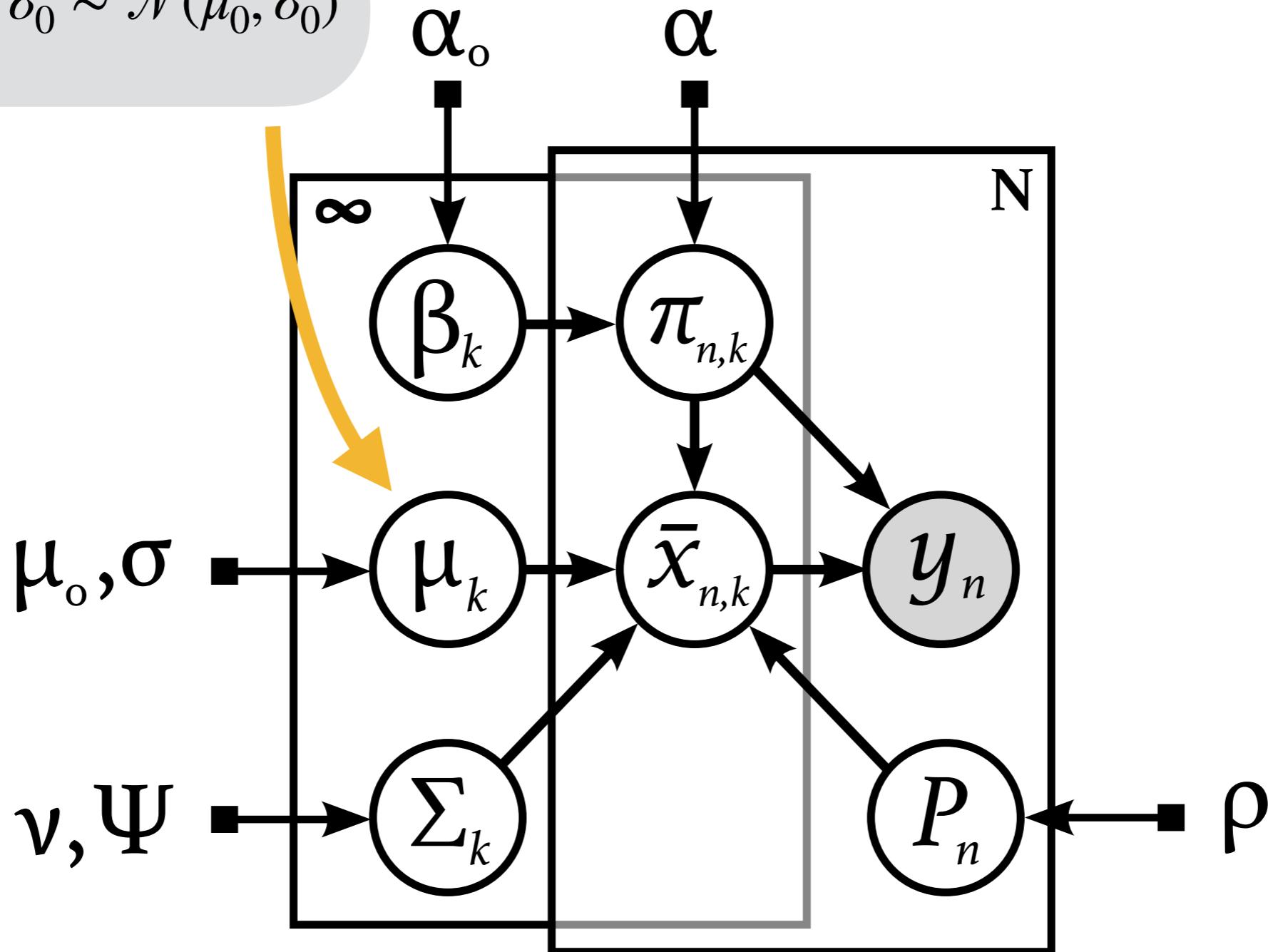
# Our Model

Paisley, 2012

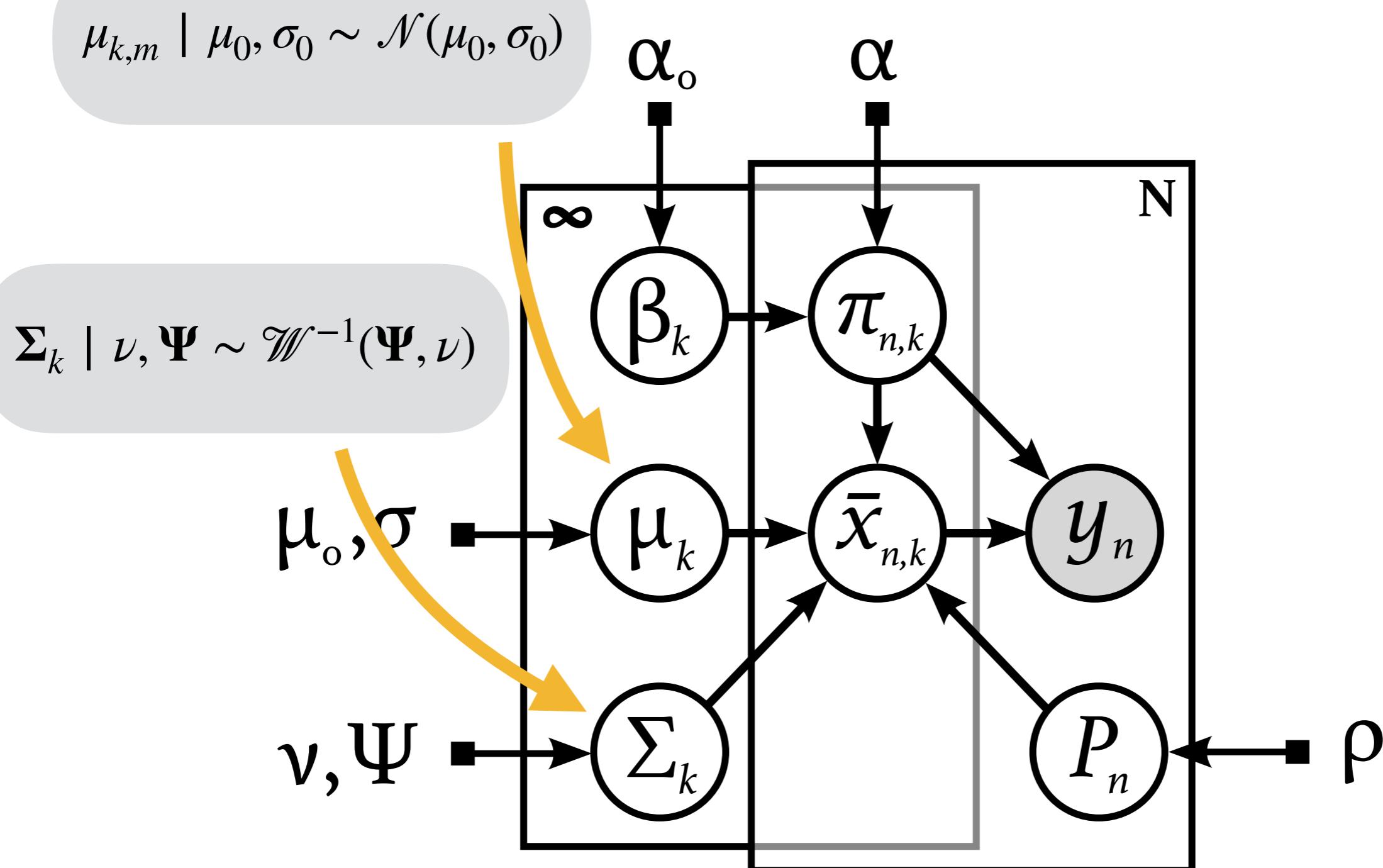


# Our Model

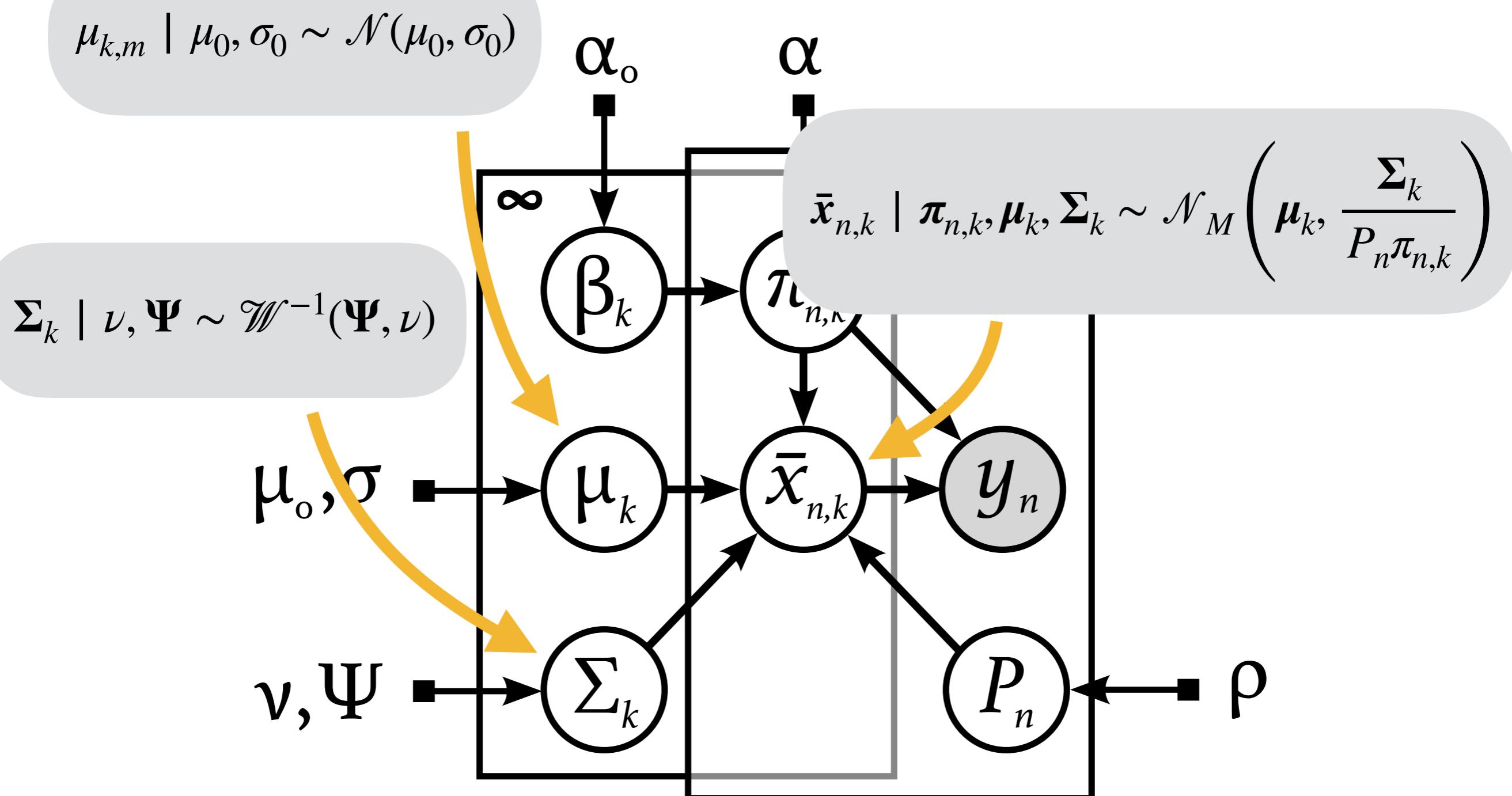
$$\mu_{k,m} \mid \mu_0, \sigma_0 \sim \mathcal{N}(\mu_0, \sigma_0)$$



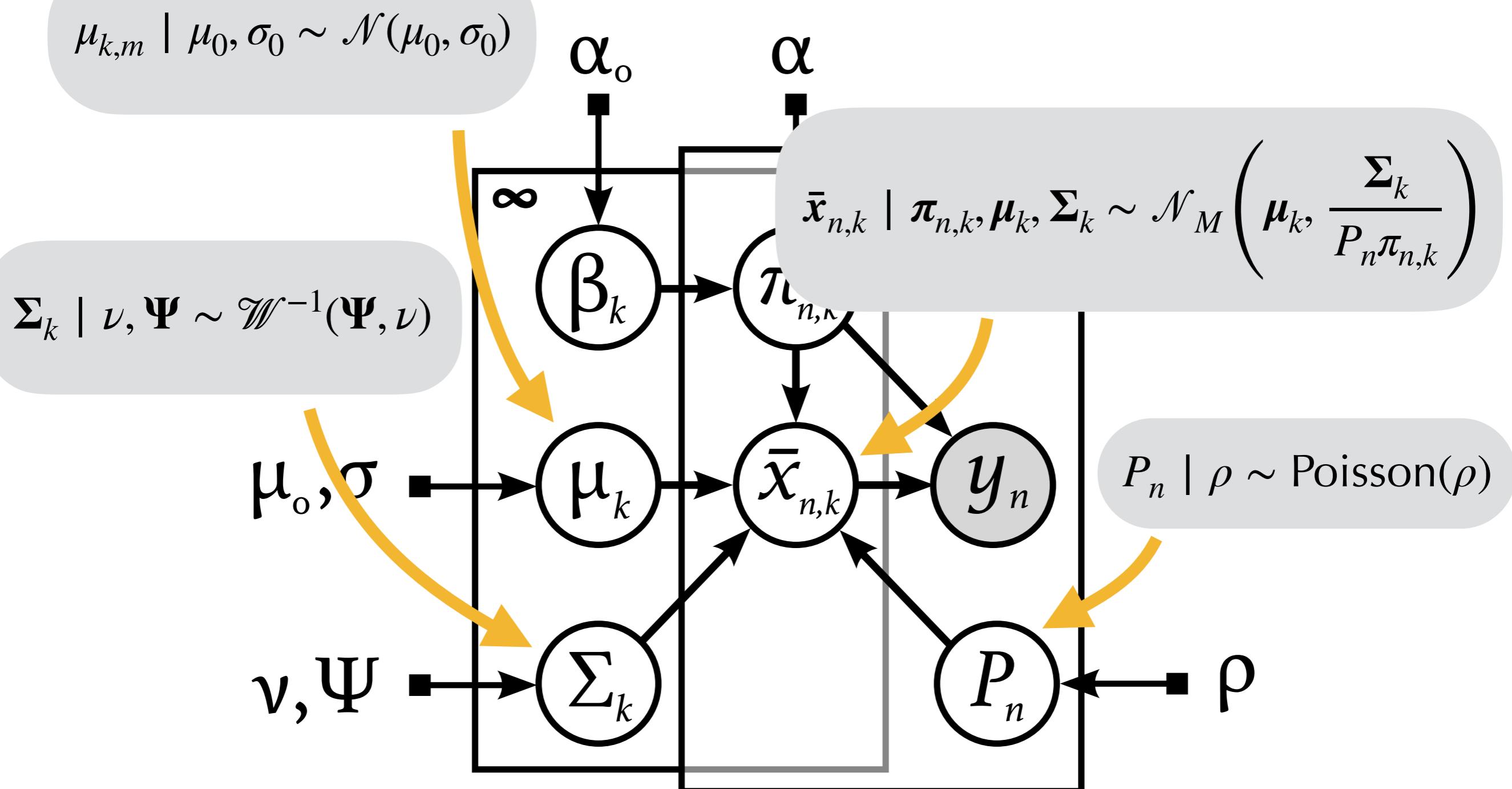
# Our Model



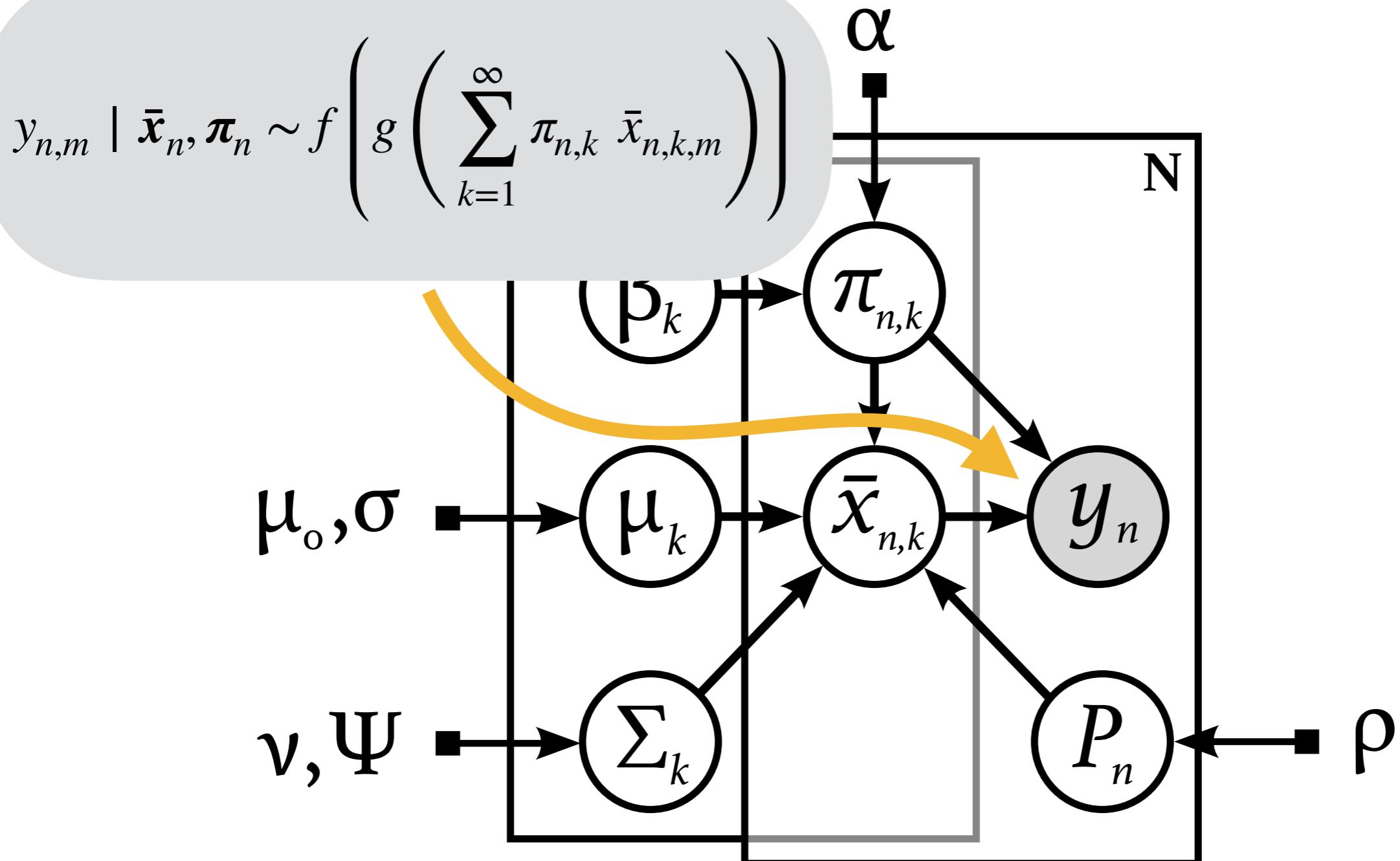
# Our Model



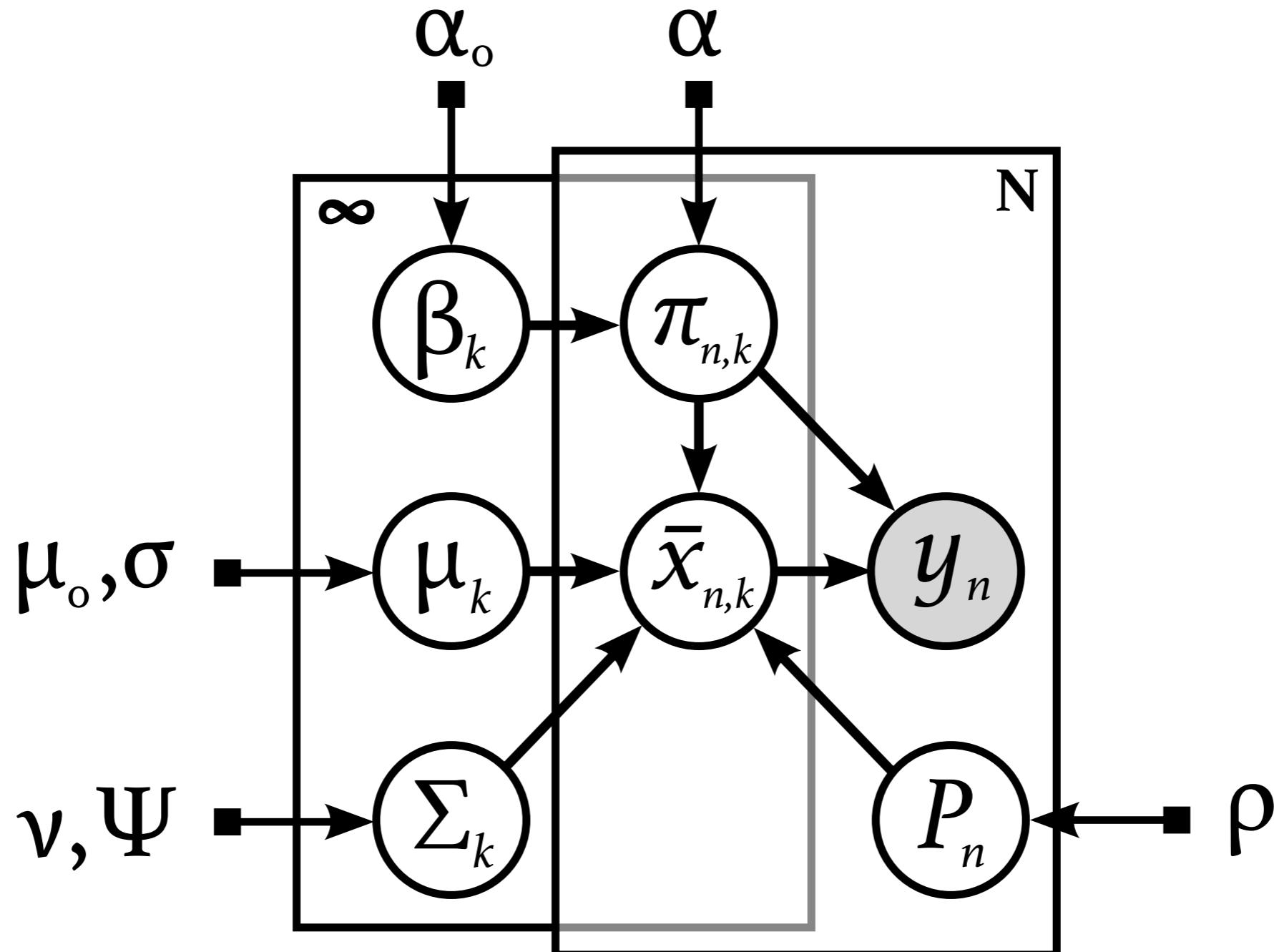
# Our Model



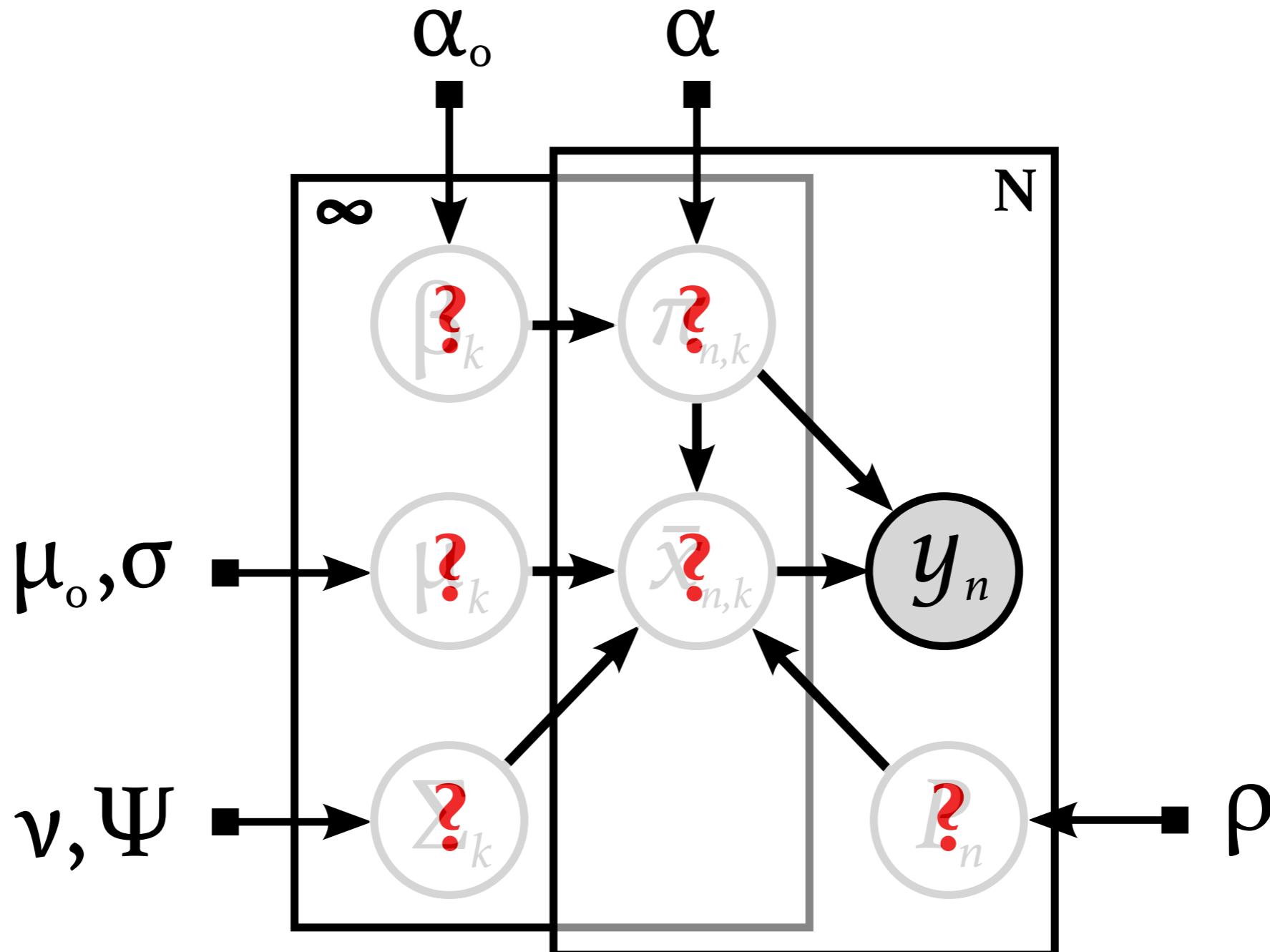
# Our Model



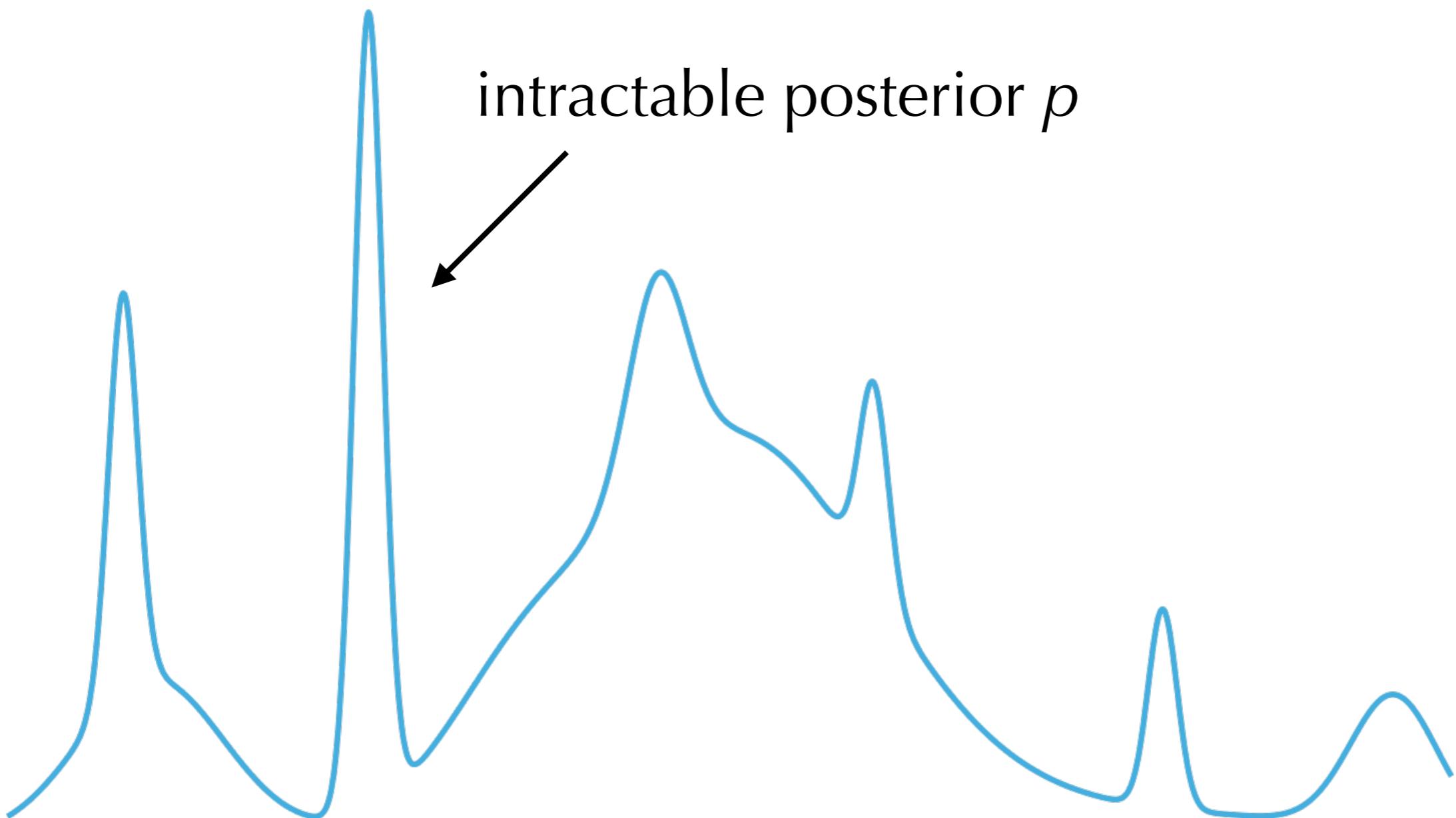
# Inference



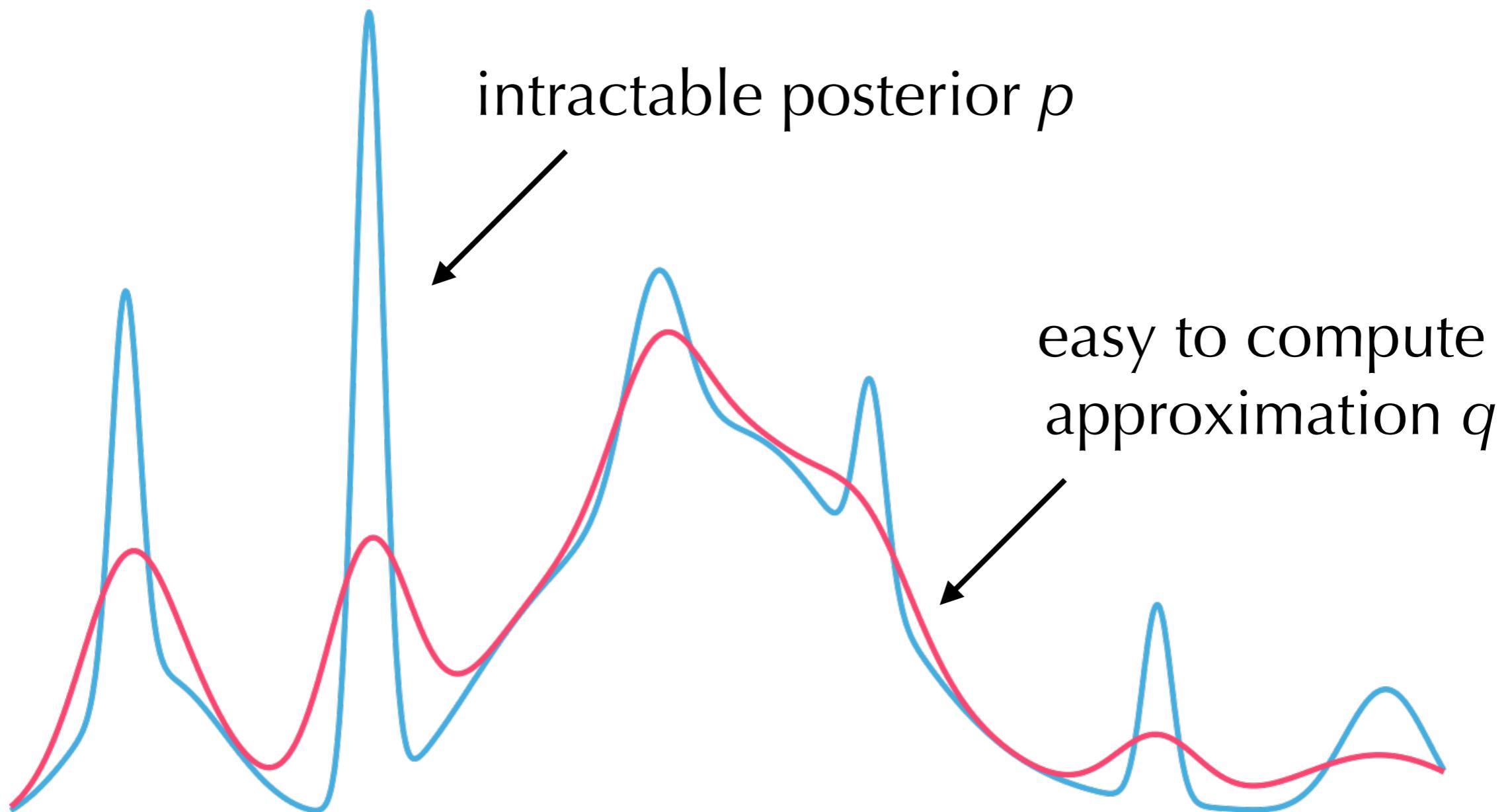
# Inference



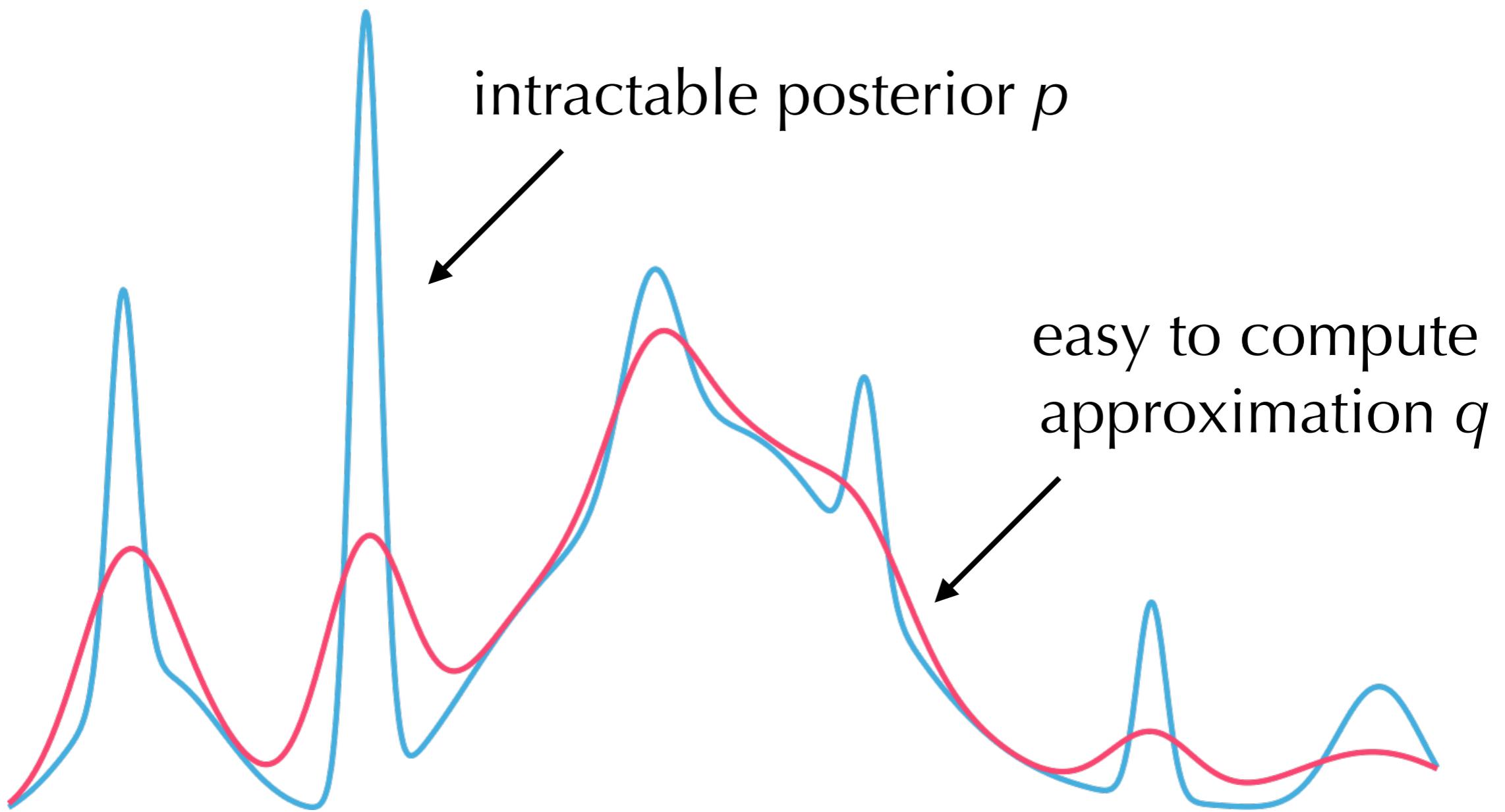
# Variational Inference



# Variational Inference



# Variational Inference



black box variational inference (Ranganath, 2014)  
split-merge procedure (Bryant, 2012) to learn  $K$

# BBVI overview

Ranganath et al., 2014

We want to estimate  $z$



$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

# BBVI overview

Ranganath et al., 2014

We want to estimate  $z$

Which has corresponding variational parameter  $\lambda[z]$

$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

# BBVI overview

Ranganath et al., 2014

$\lambda$  is  
the set of  
all variational  
parameters

We want to estimate  $z$

Which has corresponding  
variational parameter  $\lambda[z]$

$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

# BBVI overview

Ranganath et al., 2014

The gradient of  
the ELBO

We want to estimate  $z$

$\lambda$  is  
the set of  
all variational  
parameters

$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

# BBVI overview

Ranganath et al., 2014

The gradient of  
the ELBO

We want to estimate  $z$

$\lambda$  is  
the set of  
all variational  
parameters

$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

$$\approx \tilde{\nabla}_{\lambda[z]} \mathcal{L}$$

If we can **approximate this gradient**, we can use  
**standard stochastic gradient ascent** to update  $\lambda[z]$

# BBVI overview

Ranganath et al., 2014

The gradient of  
the ELBO

We want to estimate  $z$

$\lambda$  is  
the set of  
all variational  
parameters

$$\nabla_{\lambda[z]} \mathcal{L} = \mathbb{E}_q \left[ \nabla_{\lambda[z]} \log q(z \mid \lambda[z]) (\log p^z(y, z, \dots) - \log q(z \mid \lambda[z])) \right]$$

$$\approx \tilde{\nabla}_{\lambda[z]} \mathcal{L}$$

If we can **approximate this gradient**, we can use  
**standard stochastic gradient ascent** to update  $\lambda[z]$

$$= \frac{1}{S} \sum_{s=1}^S \left[ \nabla_{\lambda[z]} \log q(z[s] \mid \lambda[z]) (\log p^z(y, z[s], \dots) - \log q(z[s] \mid \lambda[z])) \right]$$

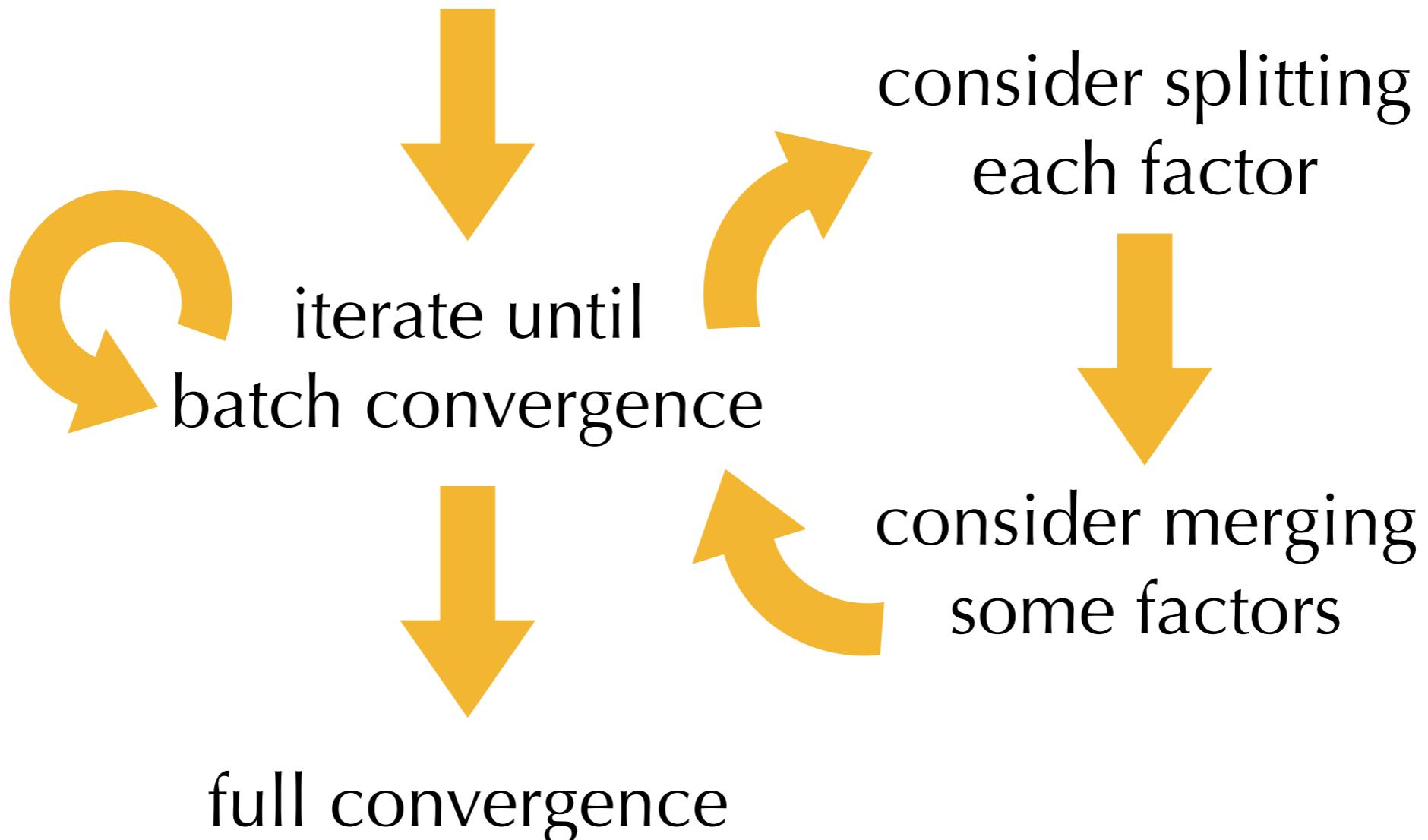
Average over  
 $S$  samples

From the variational distribution  
 $z[s] \sim q(z \mid \lambda[z])$

# split/merge overview

Bryant and Sudderth, 2012

initialize with fixed  $K$



# split/merge overview

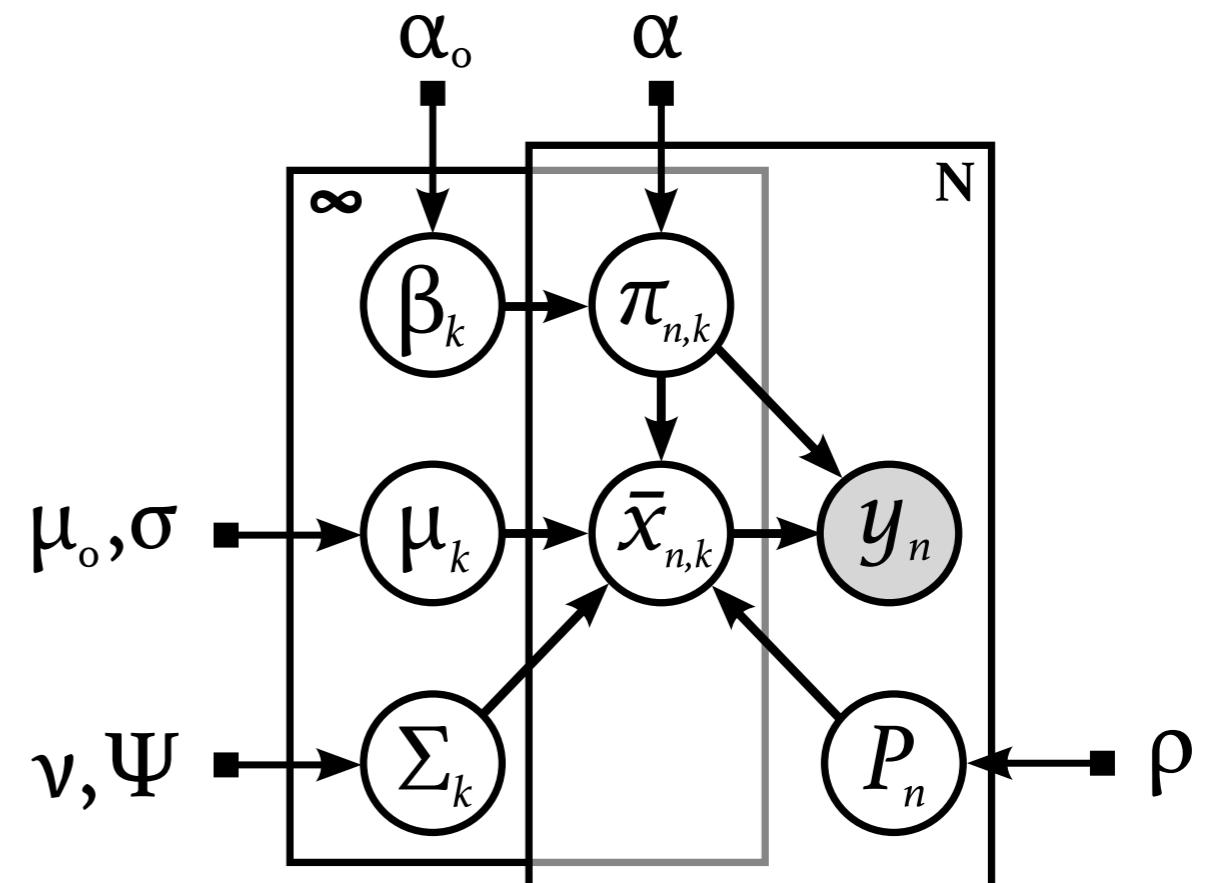
Bryant and Sudderth, 2012

K

consider splitting  
each factor



consider merging  
some factors



# split/merge overview

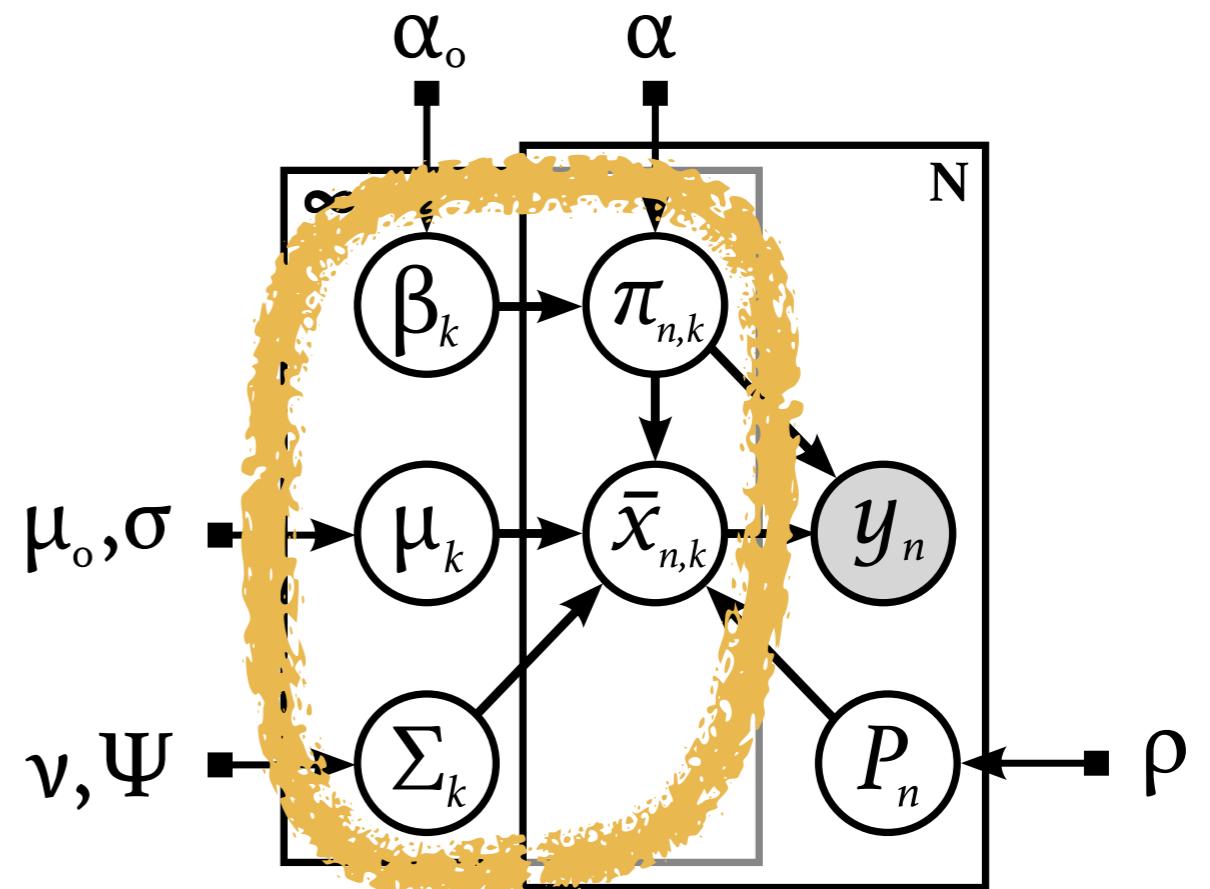
Bryant and Sudderth, 2012

K

consider splitting  
each factor



consider merging  
some factors



# split/merge overview

Bryant and Sudderth, 2012

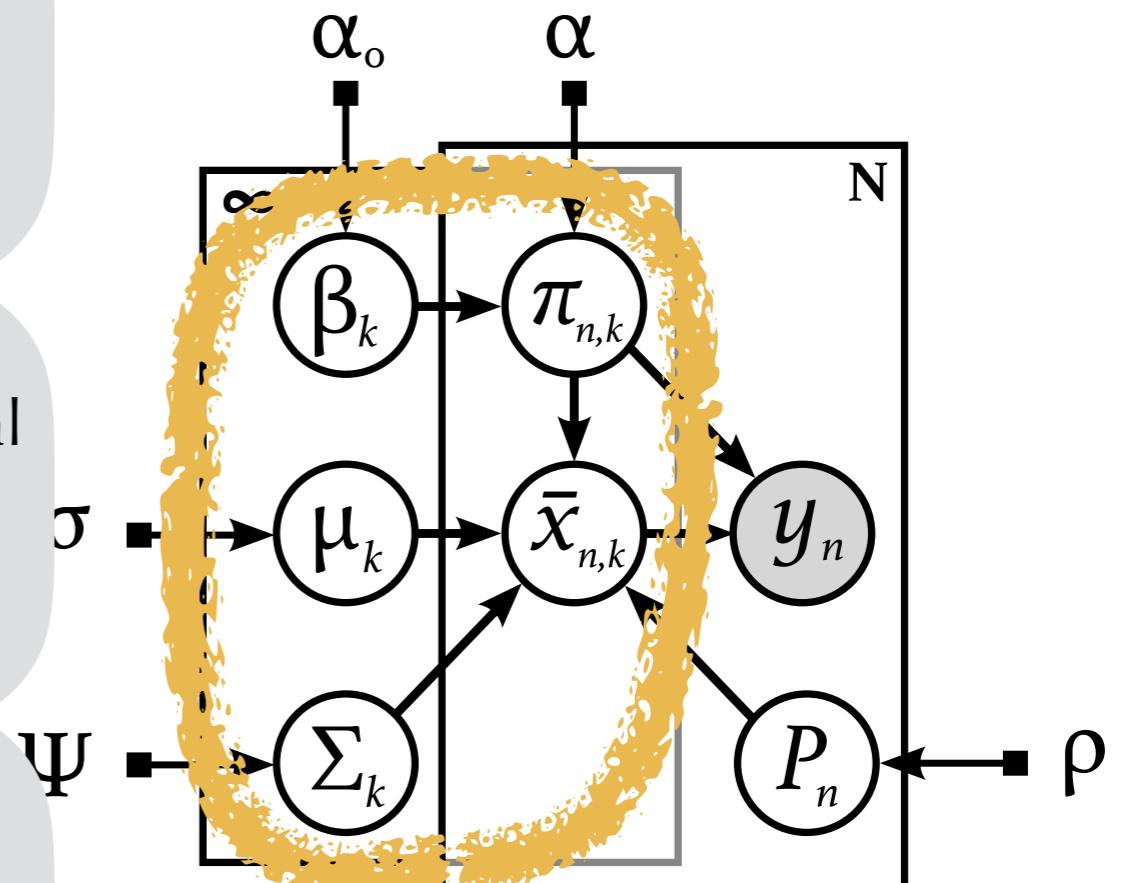
K

consider splitting  
each factor



consider merging  
some factors

- initialize variational parameters
- update variational parameters (one iteration)
- accept / reject based on ELBO



# split/merge overview

Bryant and Sudderth, 2012

K

consider splitting  
each factor

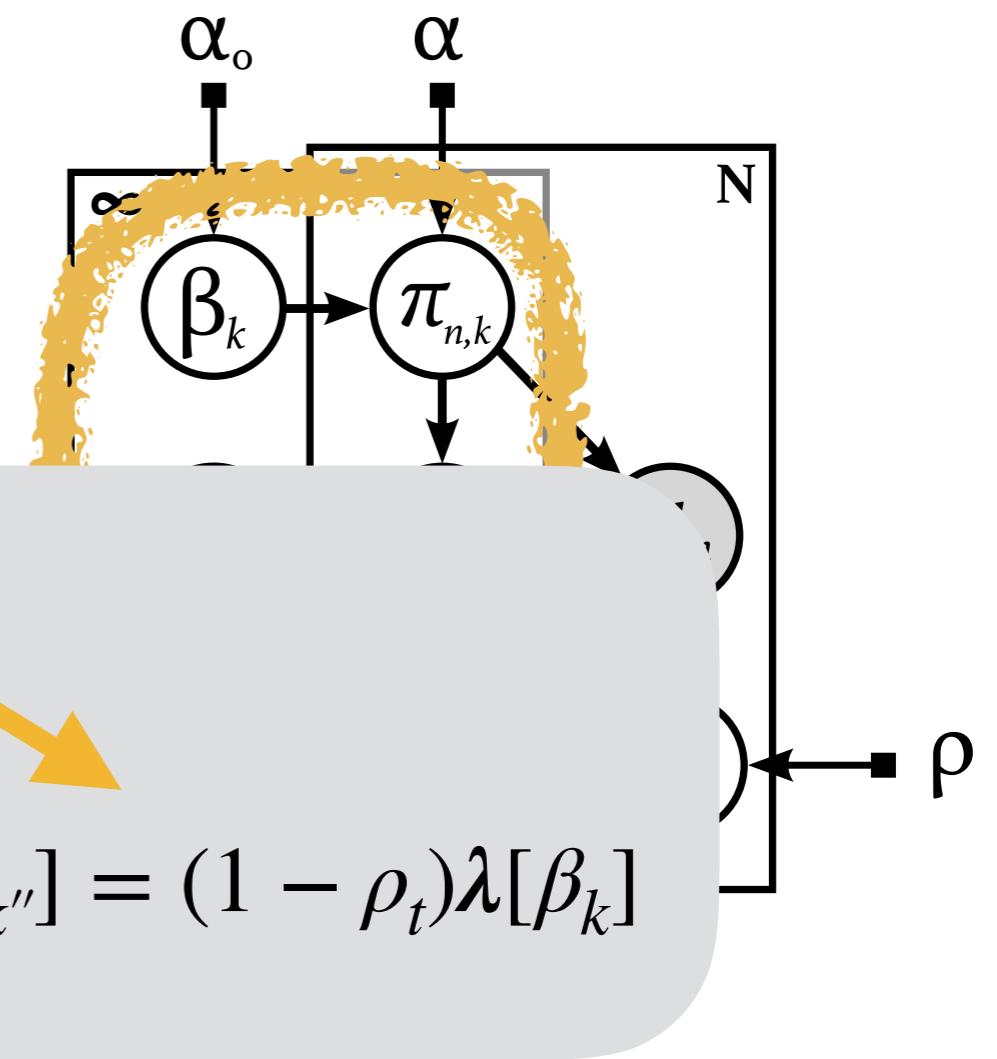


consider  
some

$$\lambda^S[\beta_{k'}] = \rho_t \lambda[\beta_k]$$

$$\lambda[\beta_k]$$

$$\lambda^S[\beta_{k''}] = (1 - \rho_t) \lambda[\beta_k]$$



# split/merge overview

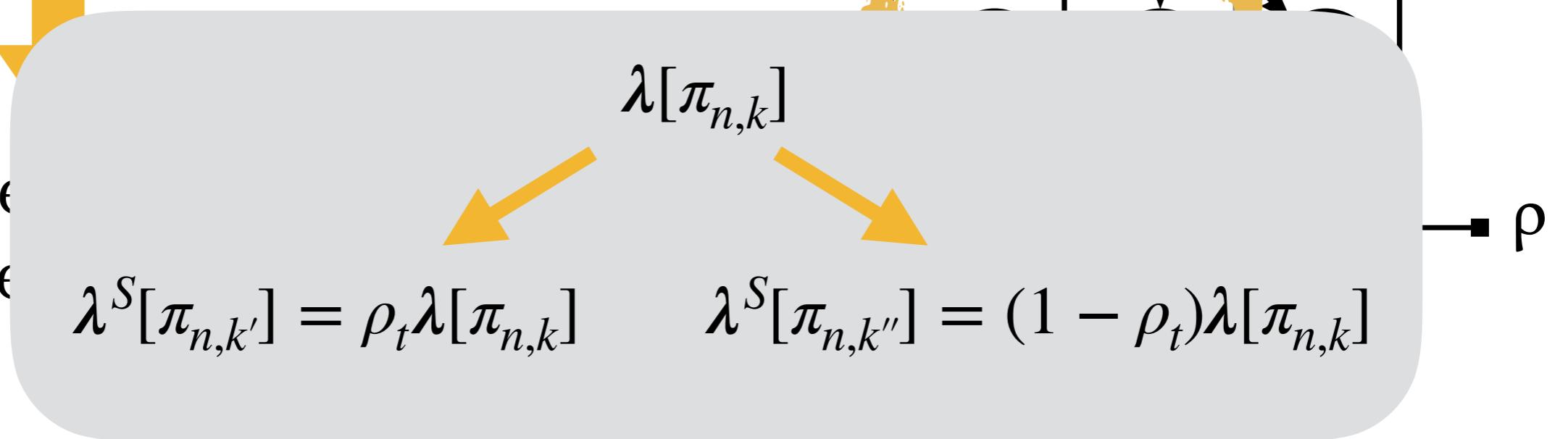
Bryant and Sudderth, 2012

K

consider splitting  
each factor



consider  
some



$$\lambda[\pi_{n,k}] \rightarrow \lambda^S[\pi_{n,k'}] = \rho_t \lambda[\pi_{n,k}]$$

$$\lambda[\pi_{n,k}] \rightarrow \lambda^S[\pi_{n,k''}] = (1 - \rho_t) \lambda[\pi_{n,k}]$$

→  $\rho$

# split/merge overview

Bryant and Sudderth, 2012

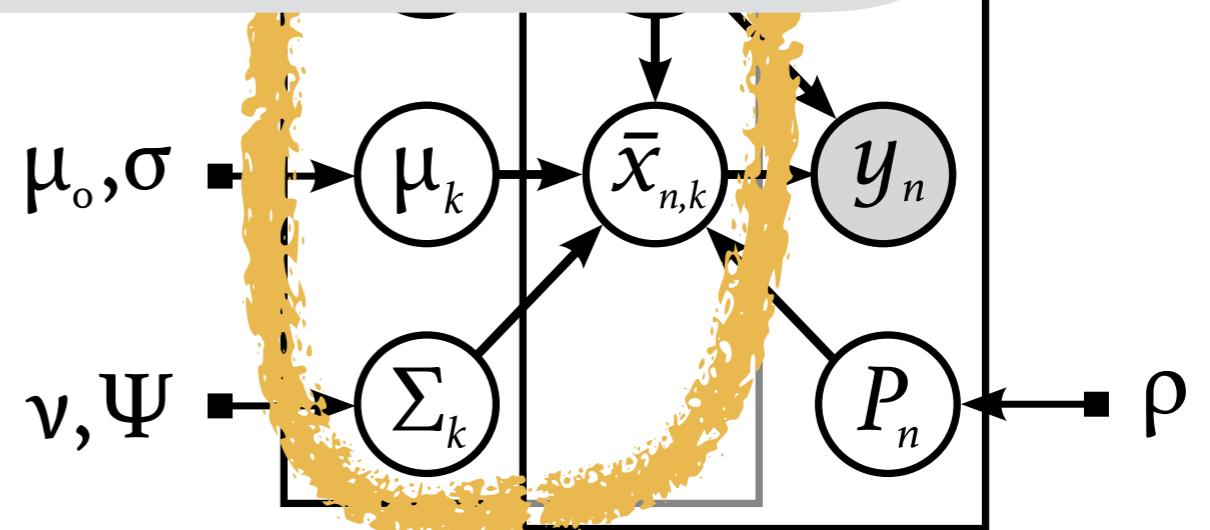
$K$

consider each

$$\lambda^S[\mu_{k'}] = \lambda[\mu_k]$$
$$\lambda^S[\mu_{k''}] = \lambda[\mu_k] + \epsilon$$

$\lambda[\mu_k]$

consider merging some factors



# split/merge overview

Bryant and Sudderth, 2012

$K$

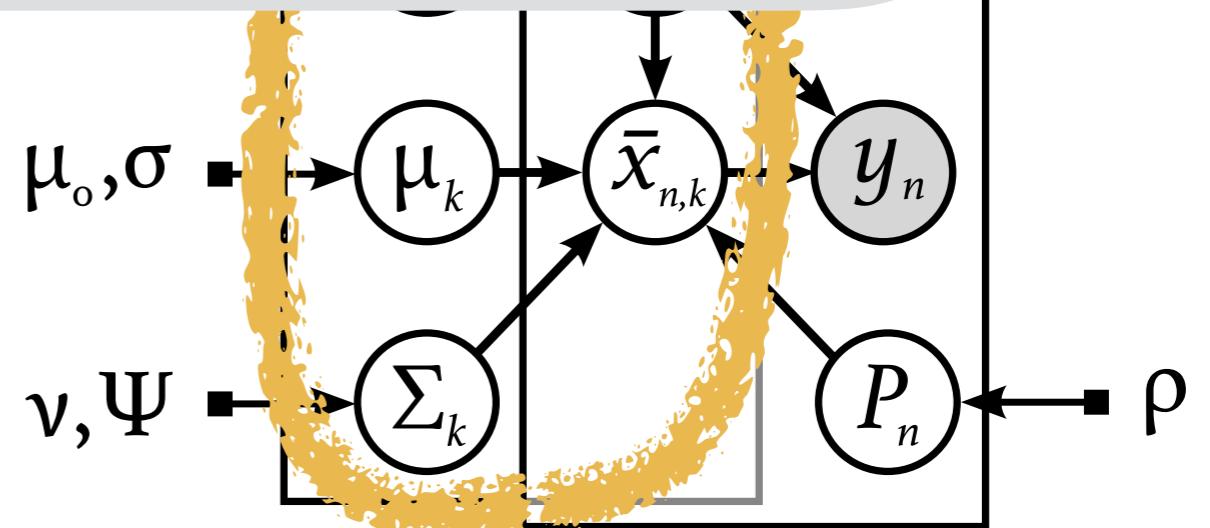
consider each

$$\lambda[\Sigma_k]$$

$$\lambda^S[\Sigma_{k'}] = \lambda[\Sigma_k]$$

$$\lambda^S[\Sigma_{k''}] = \lambda[\Sigma_k]$$

consider merging some factors



# split/merge overview

Bryant and Sudderth, 2012

$K$

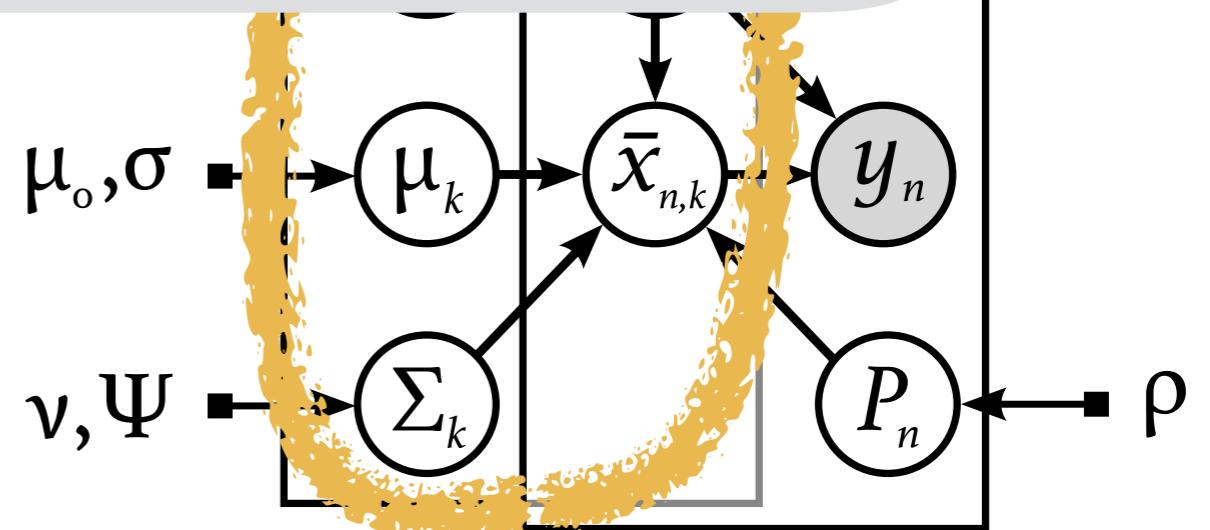
consider each

$$\lambda^S[x_{n,k'}] = \lambda[x_{n,k}]$$

$$\lambda[x_{n,k}]$$

$$\lambda^S[x_{n,k''}] = \lambda[x_{n,k}]$$

consider merging some factors



# split/merge overview

Bryant and Sudderth, 2012

$K$

consider  
each

$$\lambda^M[\beta_k] = \lambda[\beta_{k'}] + \lambda[\beta_{k''}]$$

consider  
some

$$\lambda^M[\pi_{n,k}] = \lambda[\pi_{n,k'}] + \lambda[\pi_{n,k''}]$$

$$\lambda^M[\mu_k] = \frac{\lambda[\beta_{k'}]\lambda[\mu_{k'}] + \lambda[\beta_{k''}]\lambda[\mu_{k''}]}{\lambda[\beta_{k'}] + \lambda[\beta_{k''}]}$$

...

ρ

# Algorithm Pseudocode

set K to an initial value

initialize variational parameters

repeat until convergence:

repeat until batch convergence:

update variational parameters for

$\bar{x}, \pi, P, \beta$  using BBVI

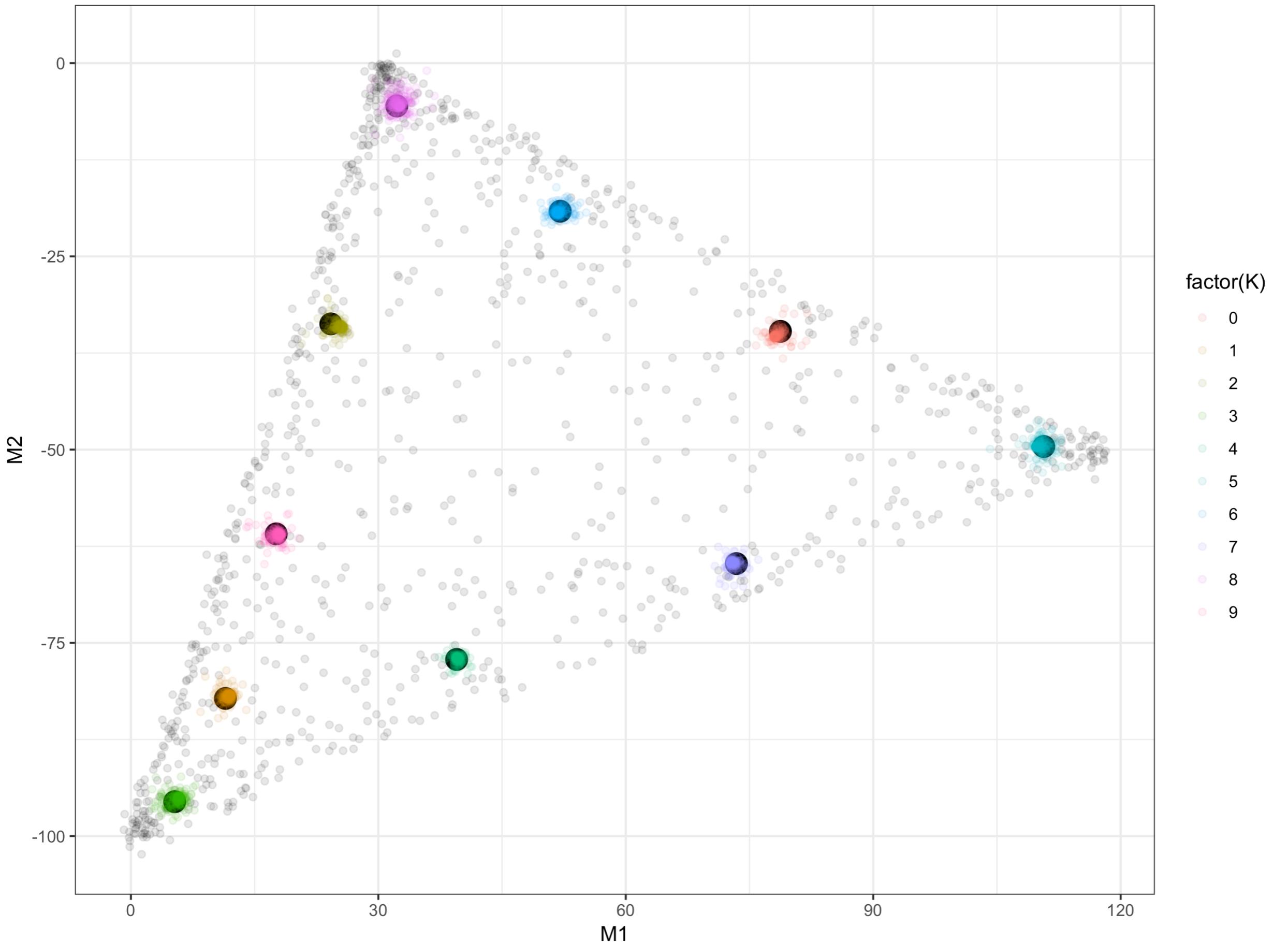
update variational parameters for

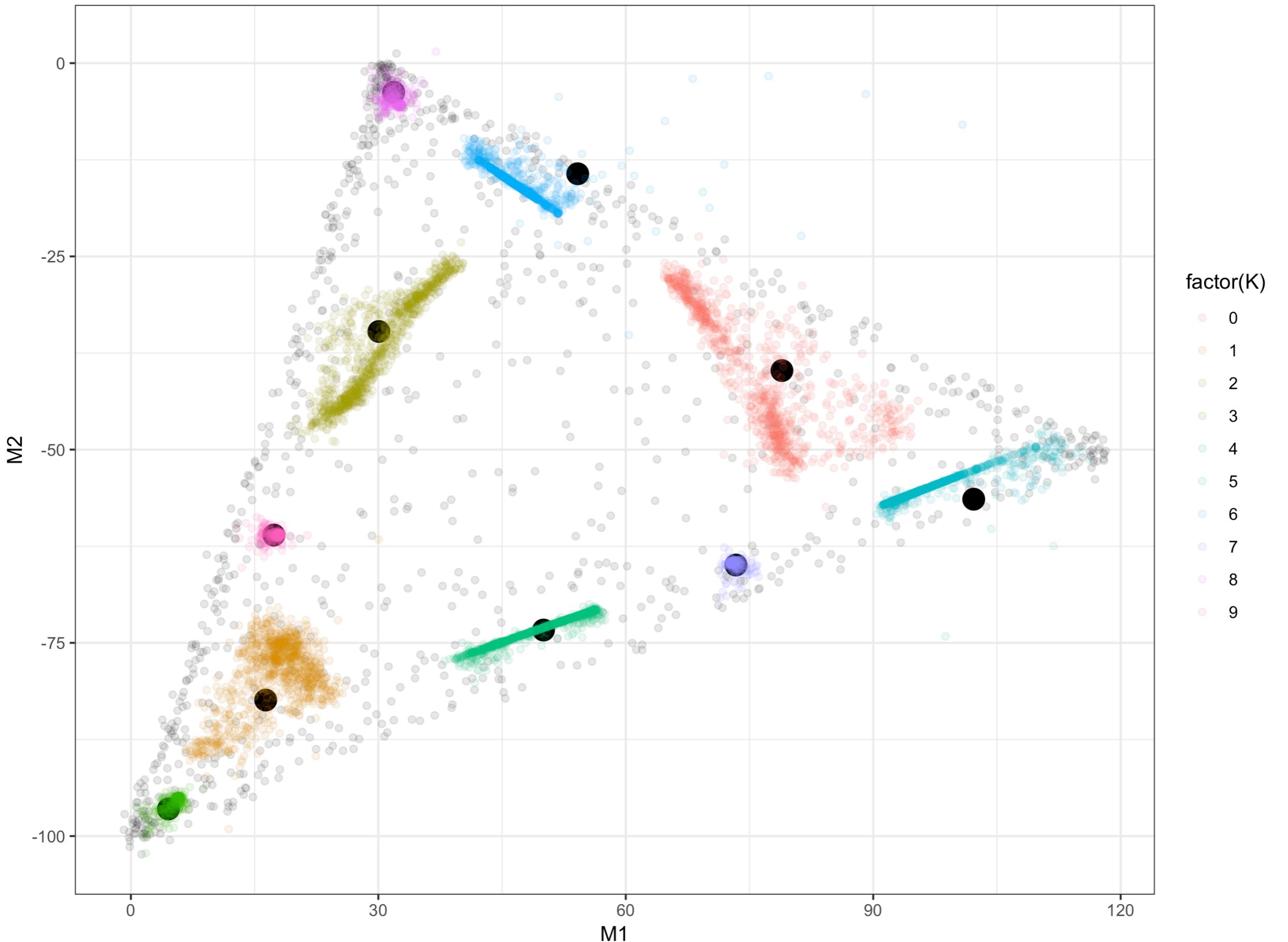
$\mu, \Sigma$  using analytic updates

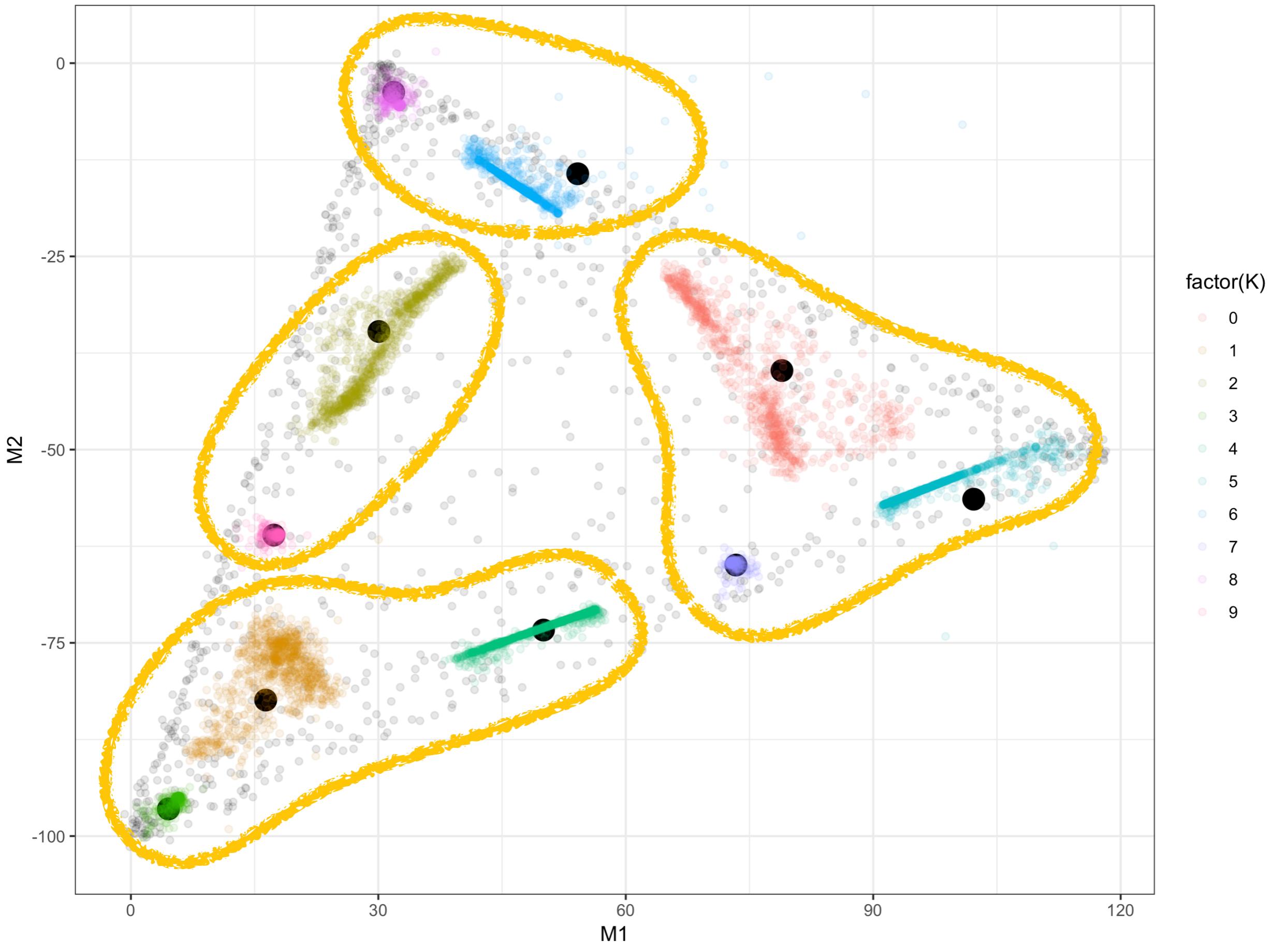
split/merge latent factors, defining new K

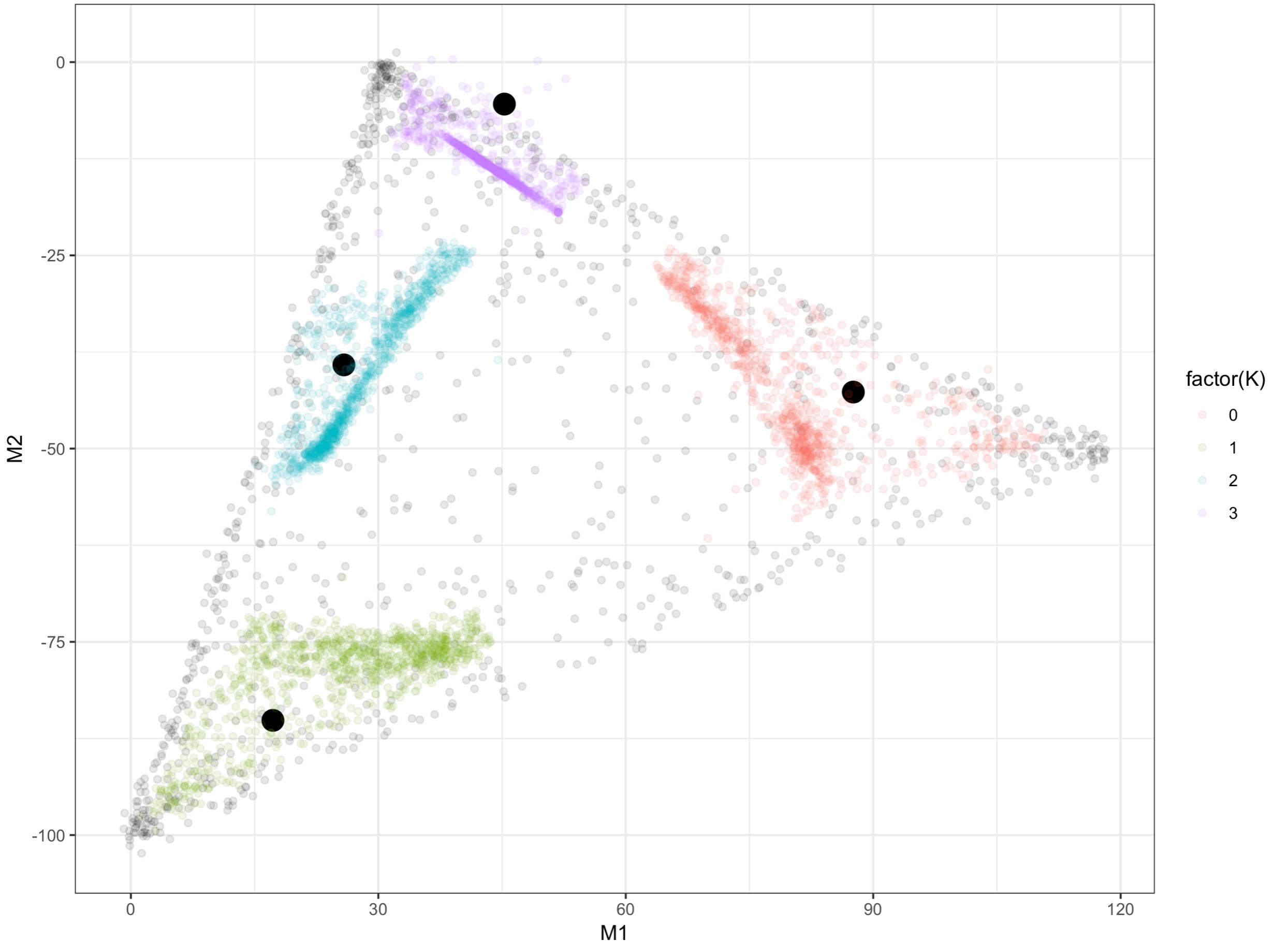
and updating variational parameters

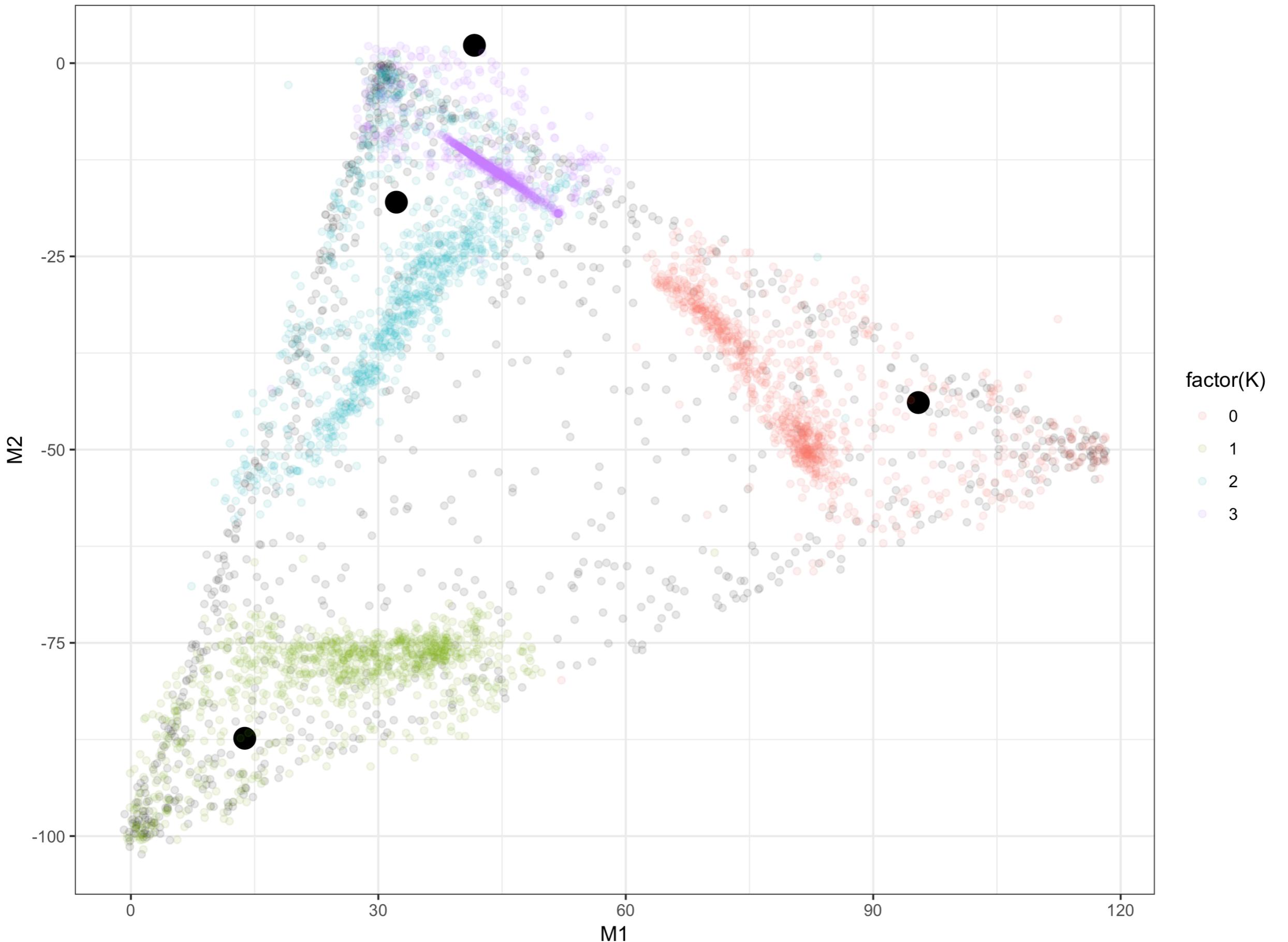
accordingly

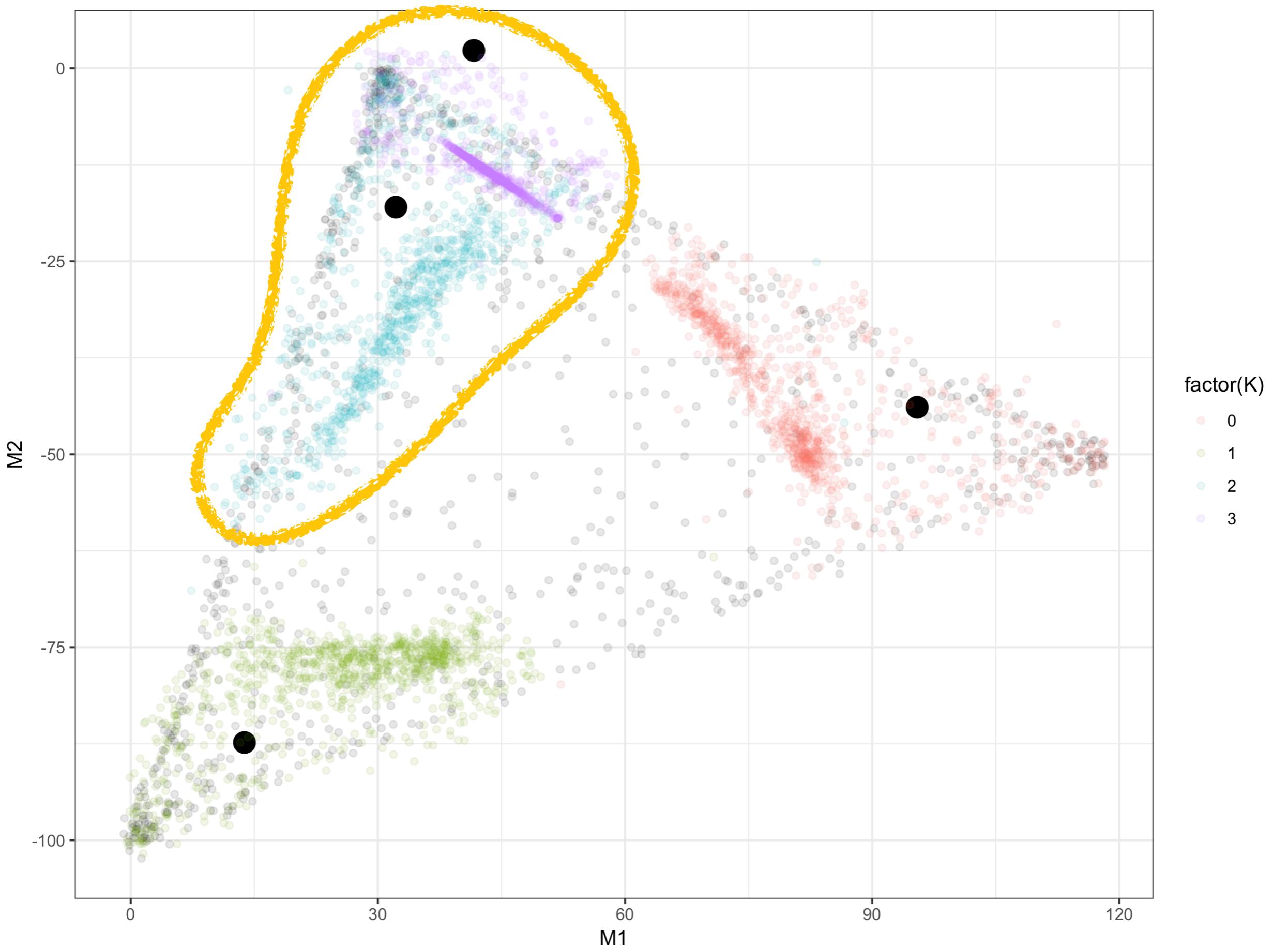


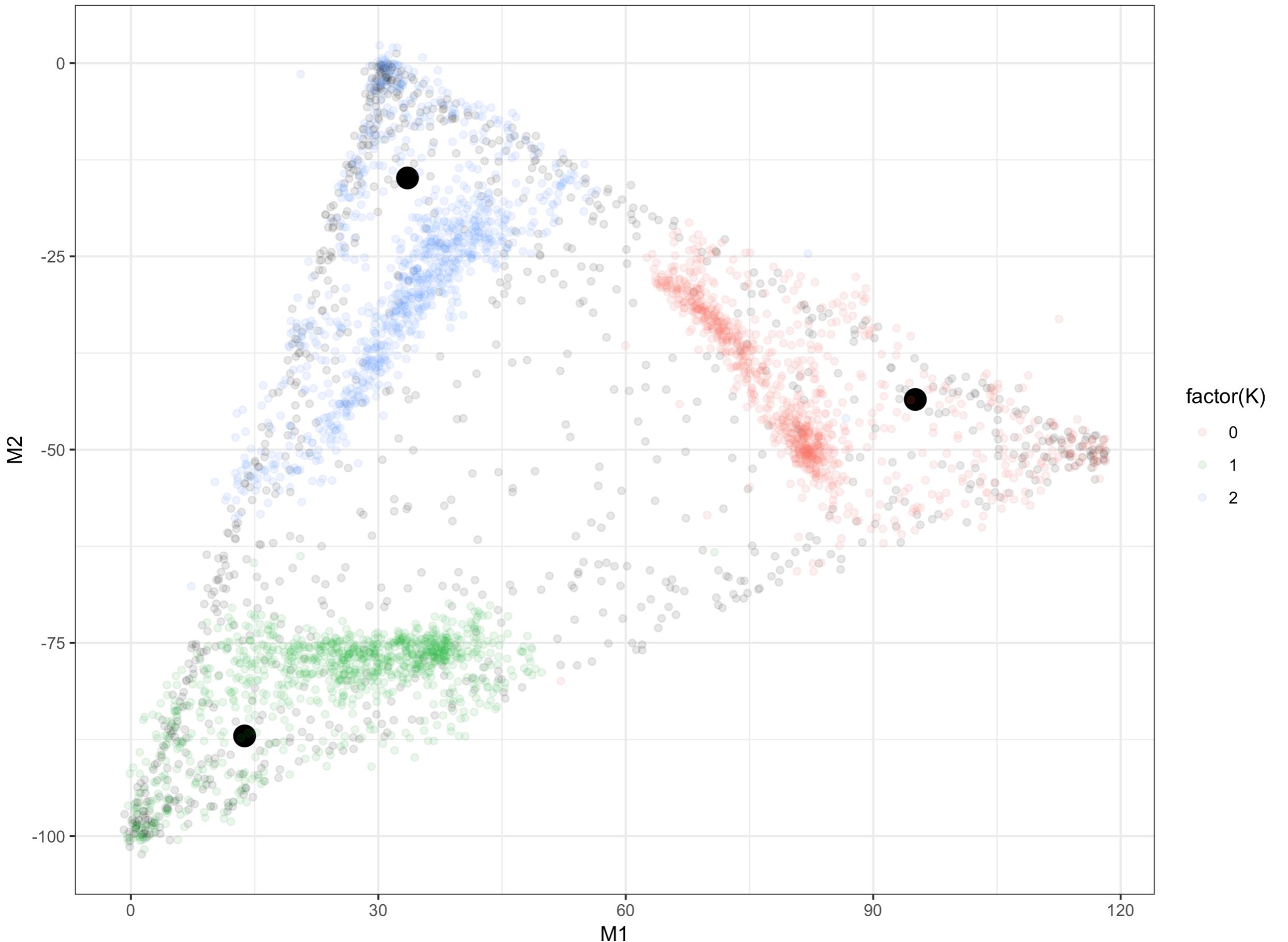




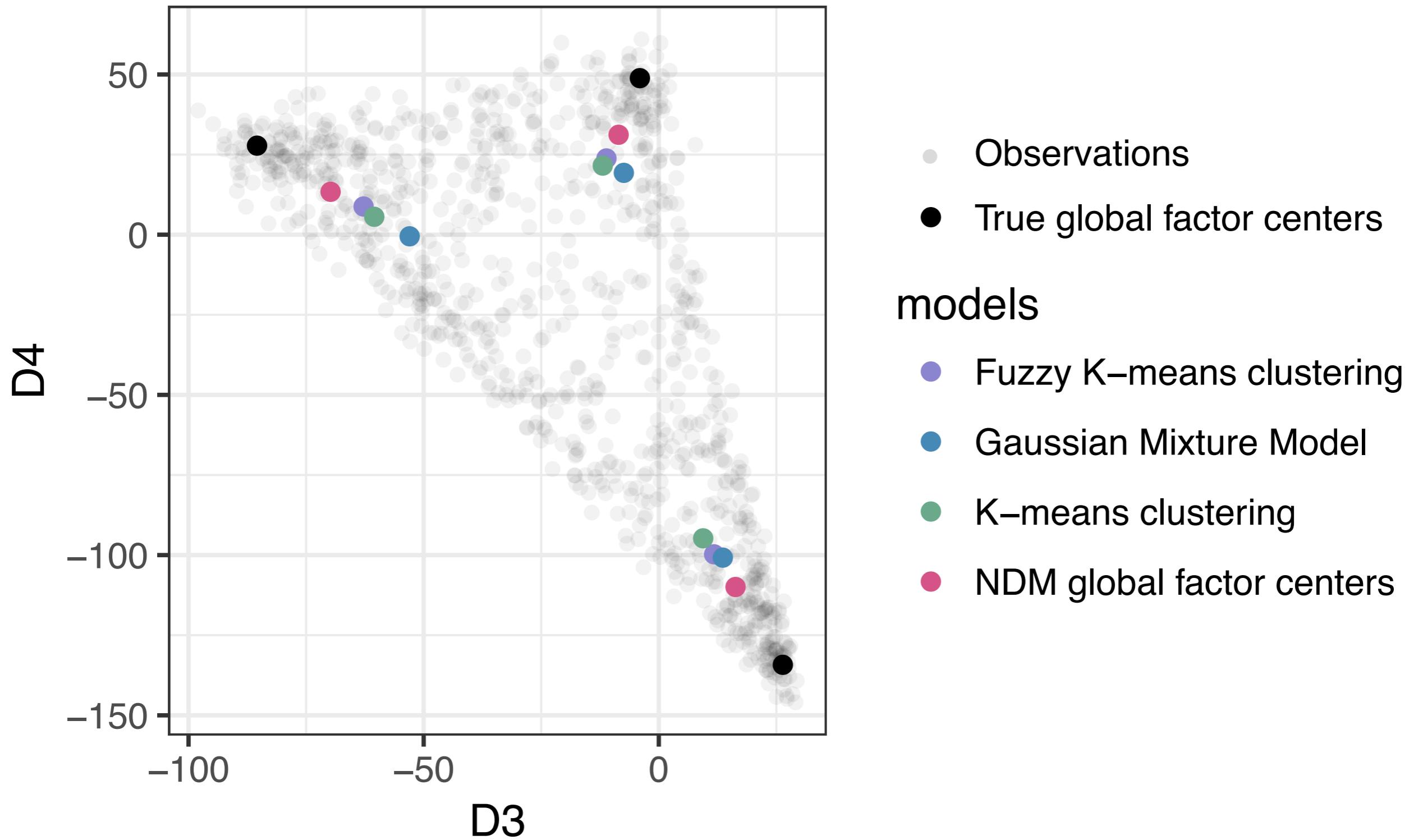




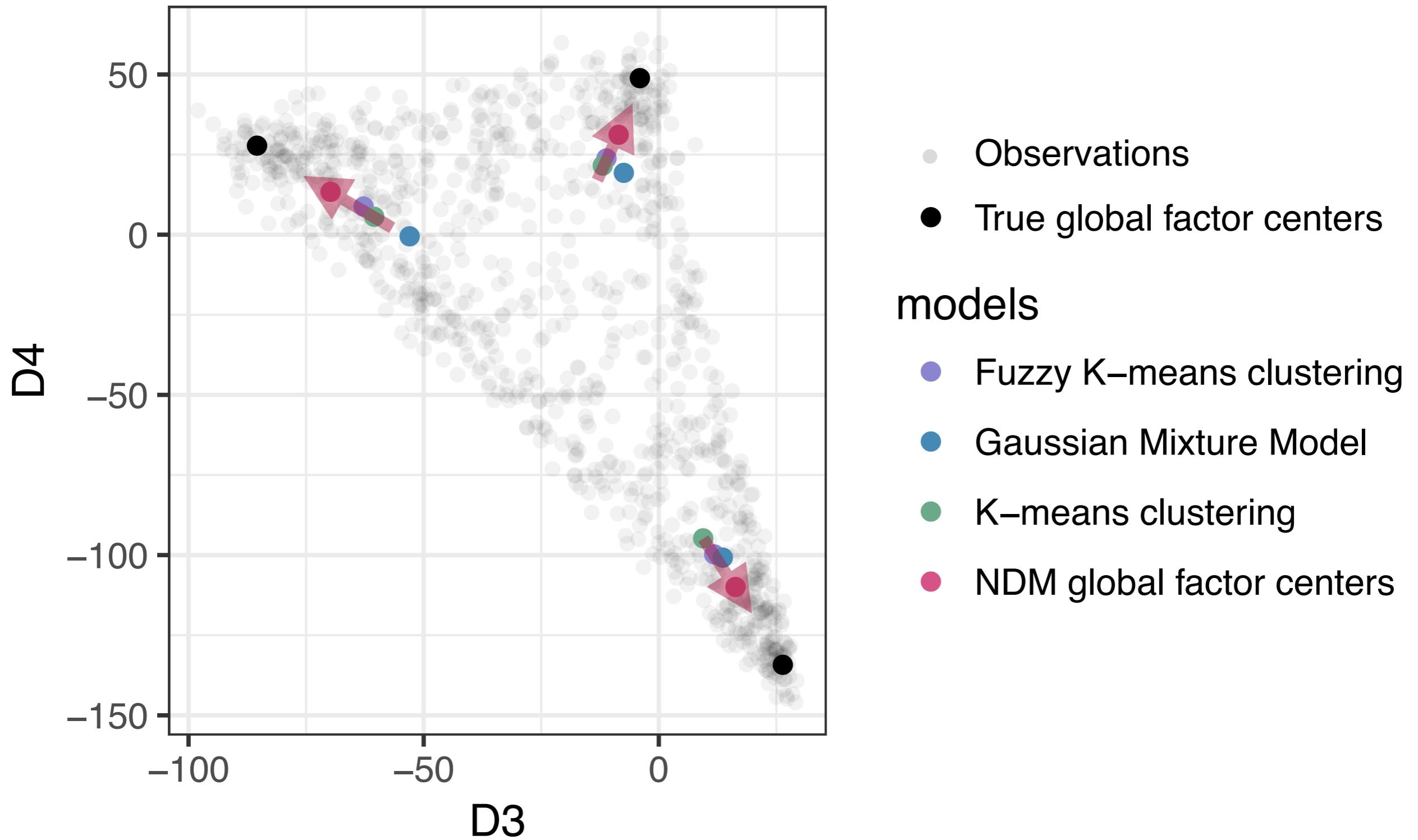




# Results on Simulated Data

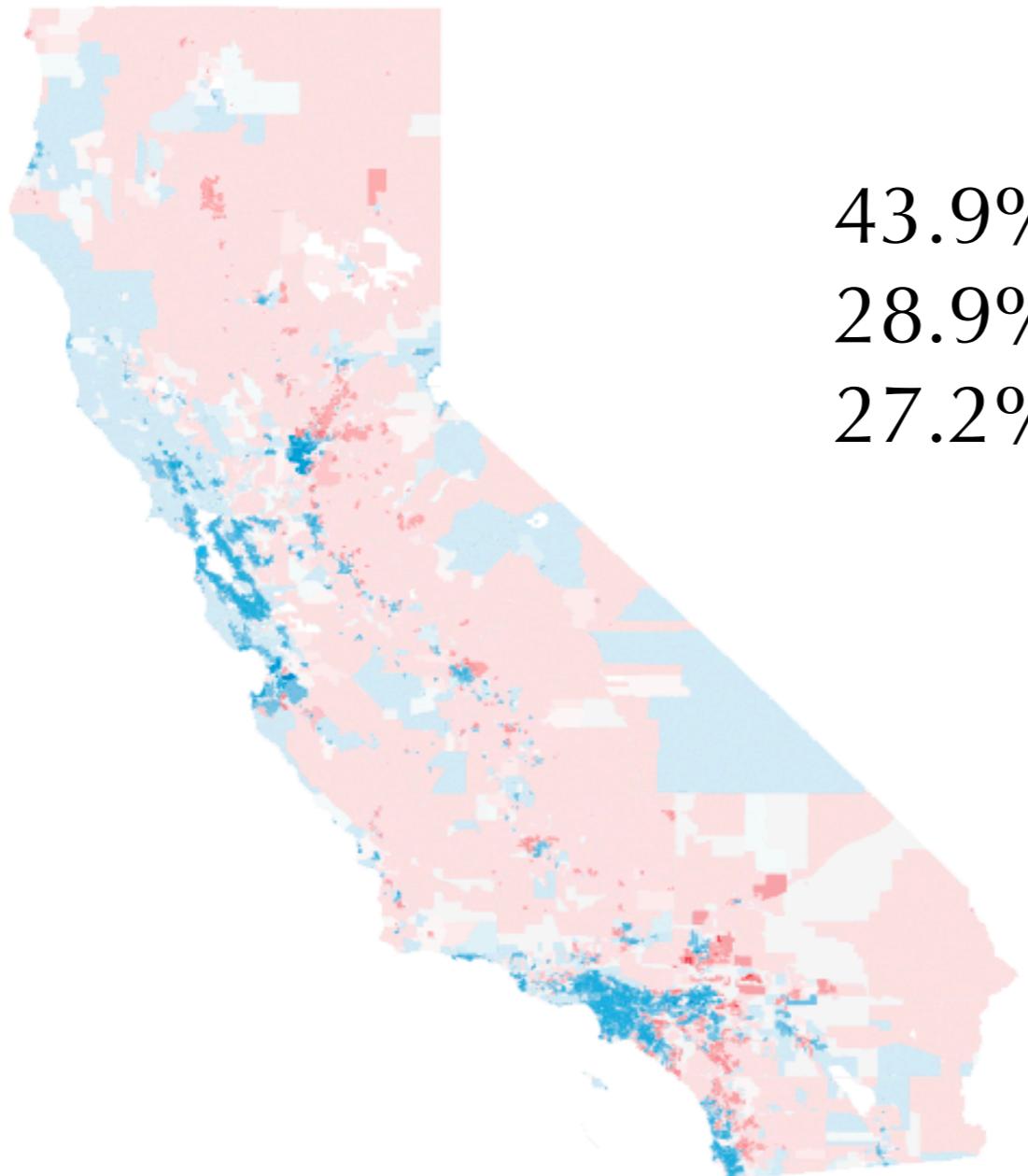


# Results on Simulated Data



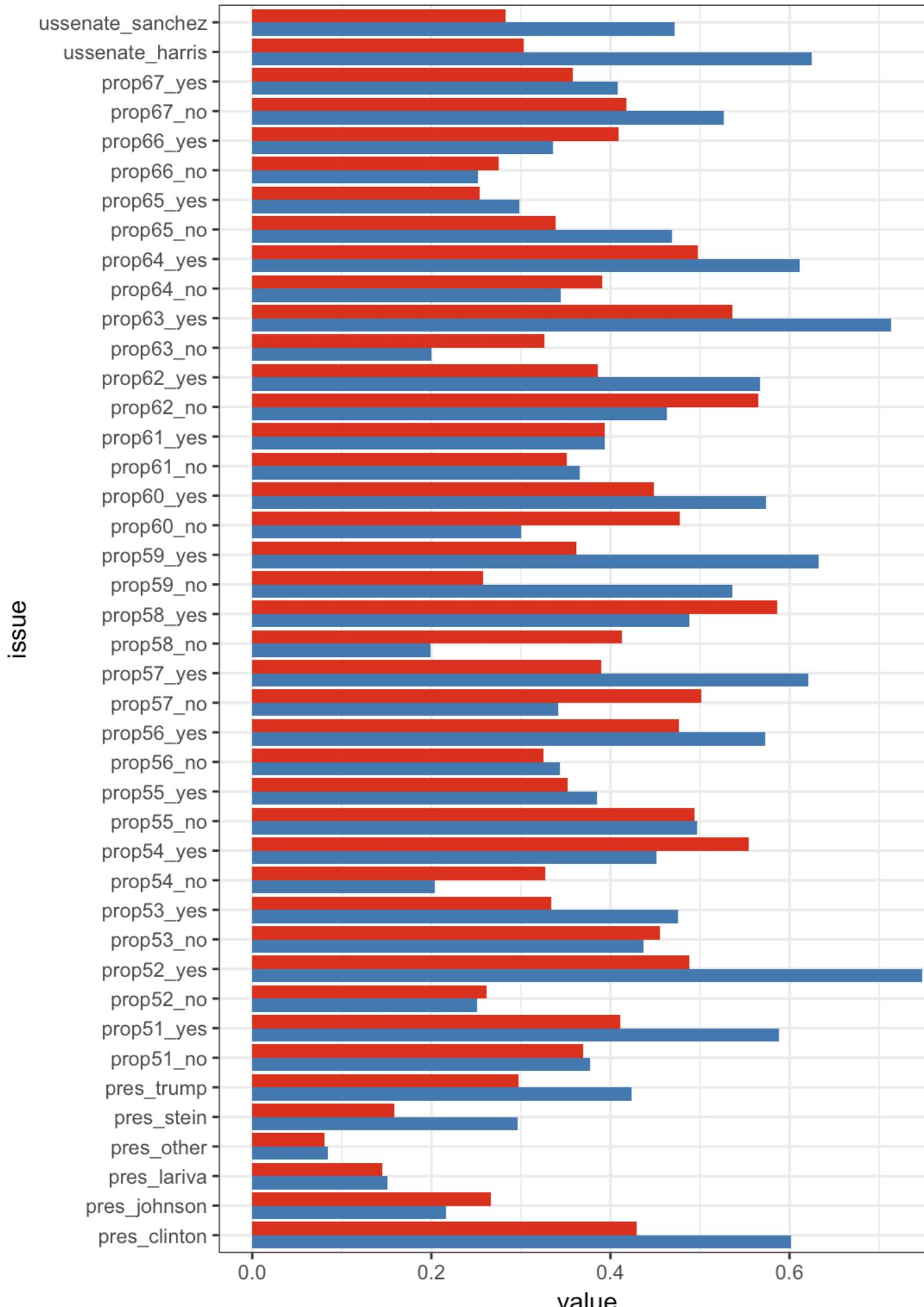
# 2016 Election in California

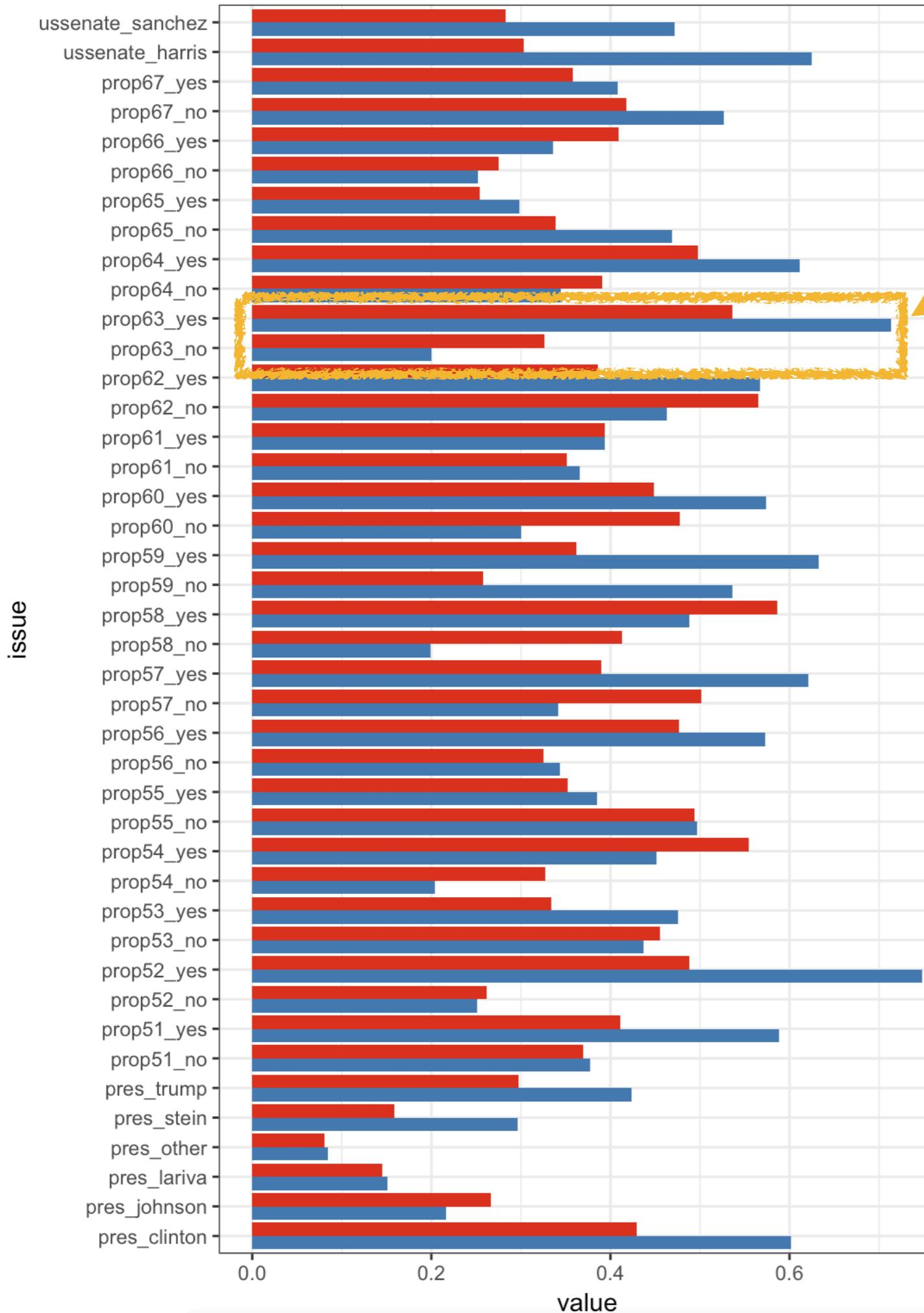
<https://github.com/datadesk/california-2016-election-precinct-maps>



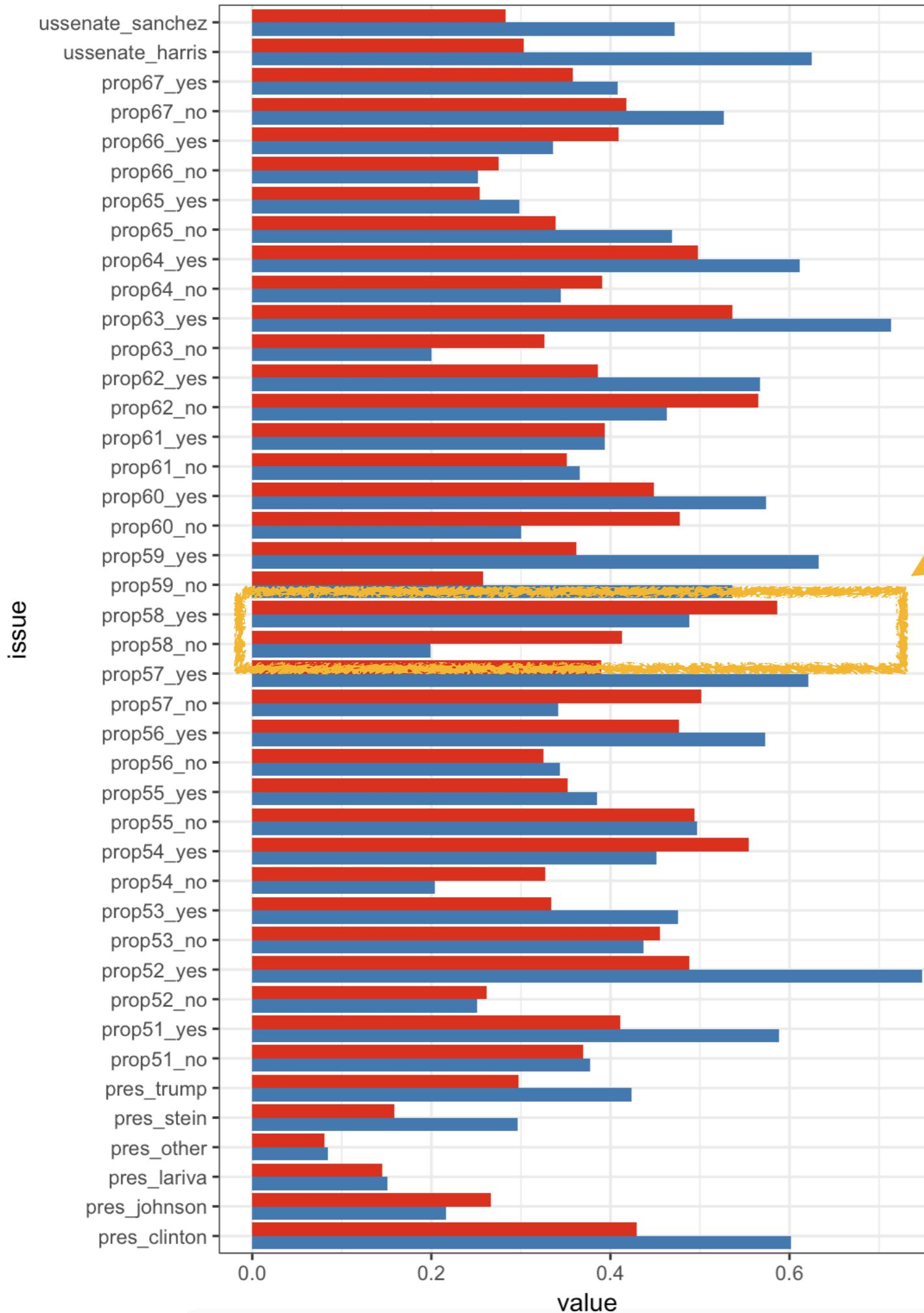
43.9% registered Democrats  
28.9% registered Republicans  
27.2% other parties / unregistered

caveat: these are  
**very** preliminary results

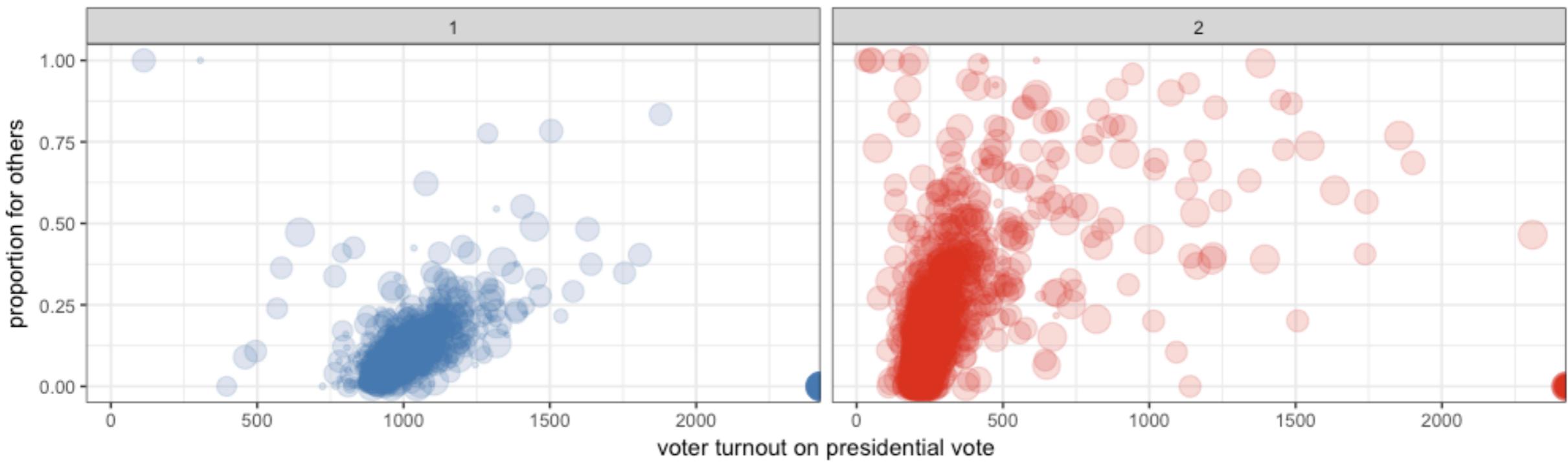
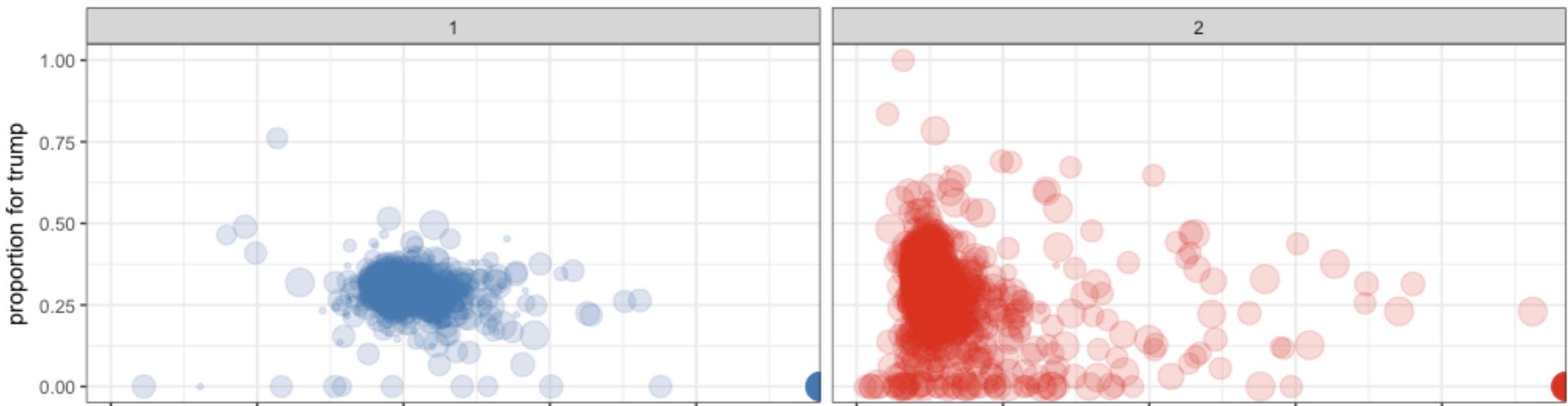
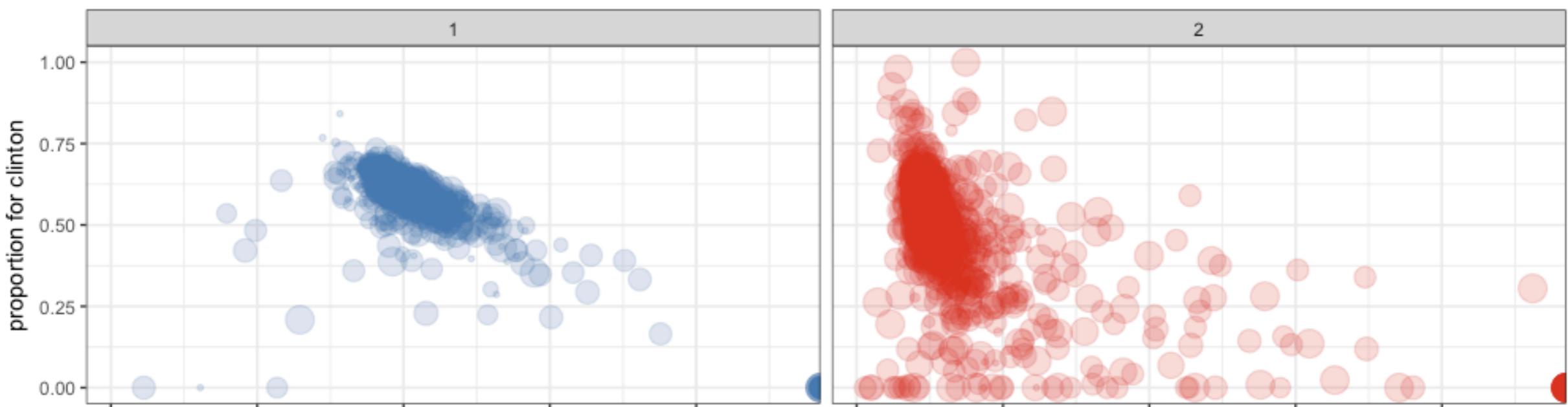


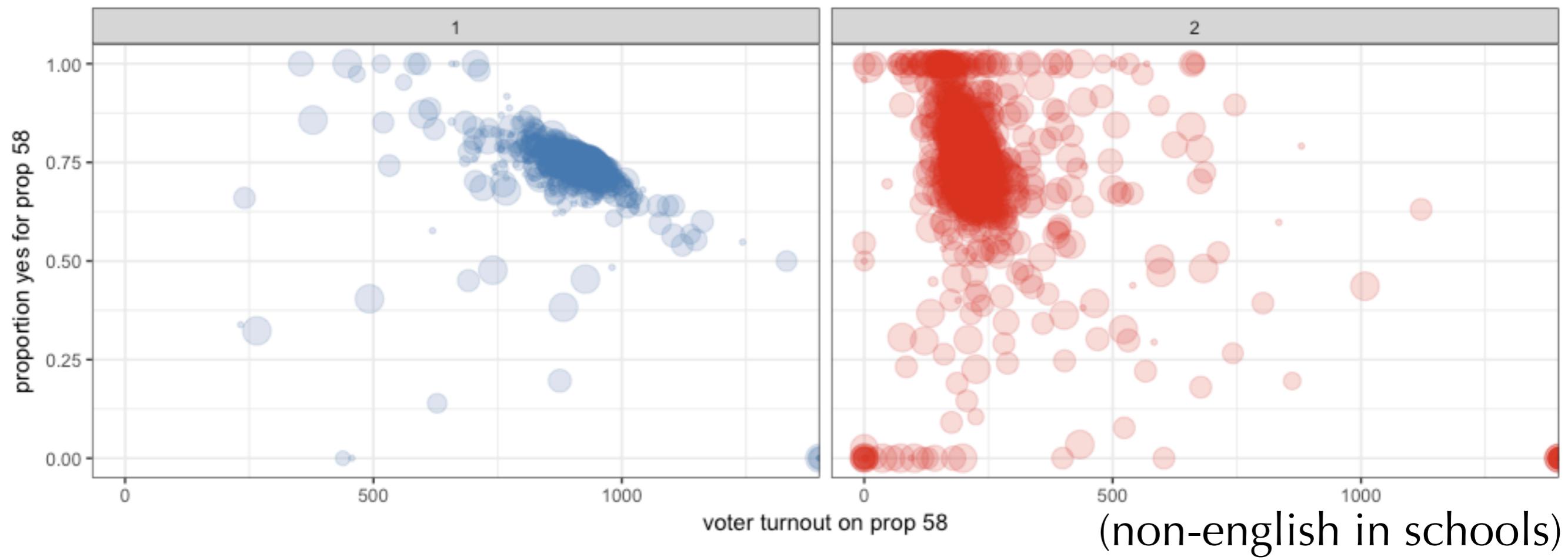
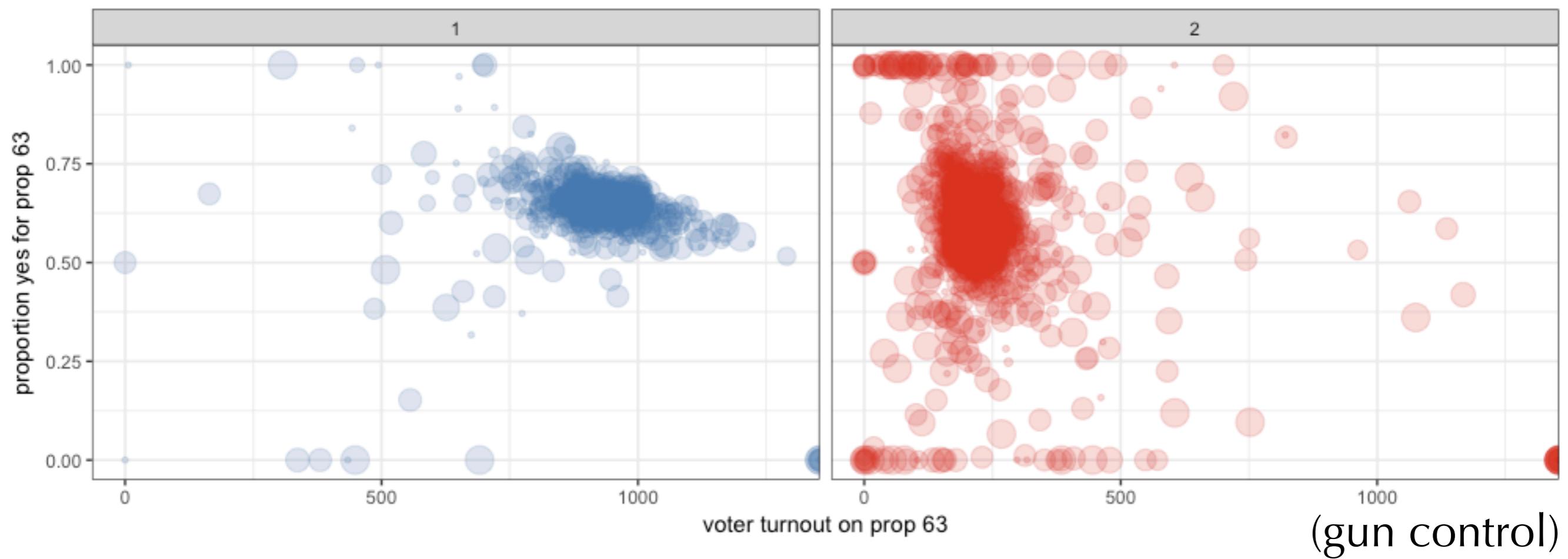


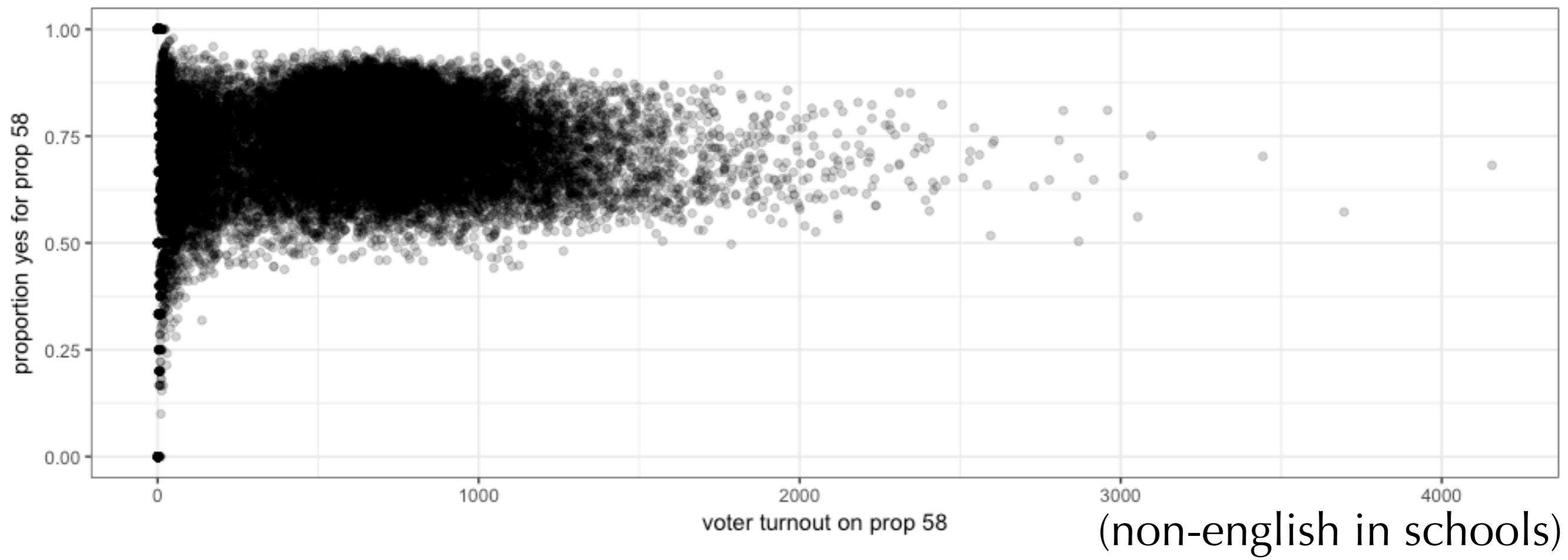
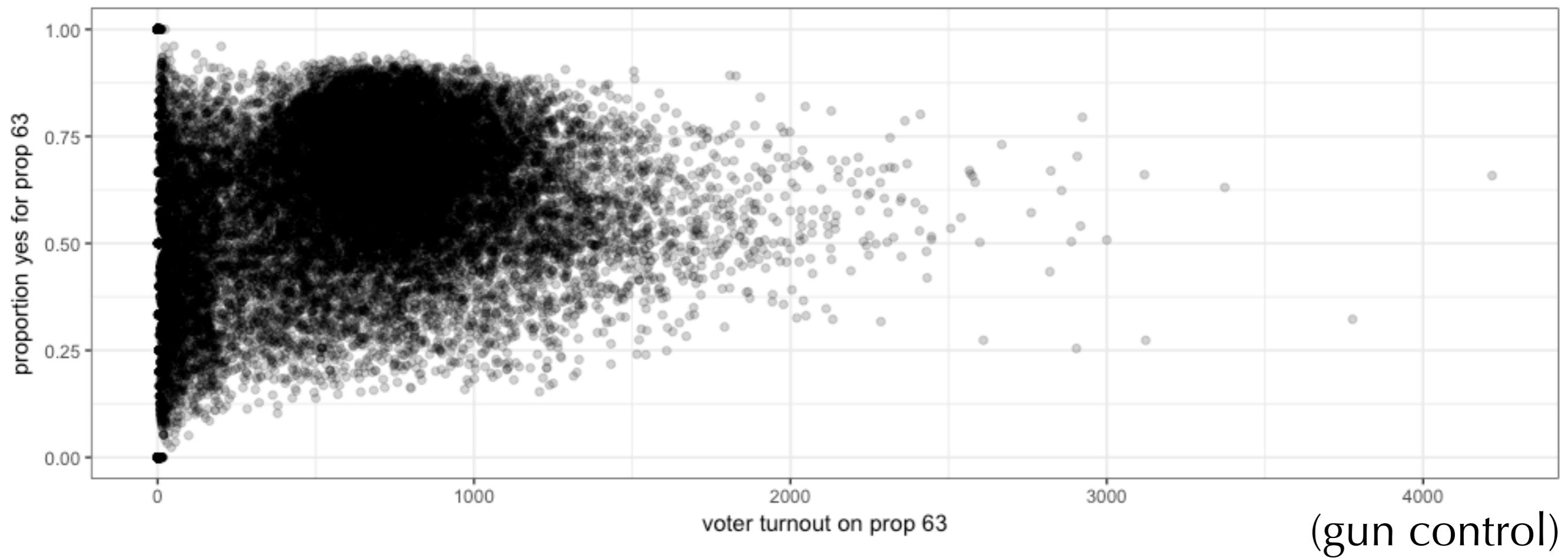
Prop 63: Background Checks for Ammunition Purchases and Large-Capacity Ammunition Magazine Ban



Prop 58: Non-English  
Languages Allowed in  
Public Education







# Thank you!

*This research was supported by an appointment to the Intelligence Community Postdoctoral Research Fellowship Program at Princeton University, administered by Oak Ridge Institute for Science and Education through an interagency agreement between the U.S. Department of Energy and the Office of the Director of National Intelligence.*