### $\label{eq:parallel} Parallel\ QuickSort\ -\ with\ MPI$

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Abstract

Implement Quick Sort Algorithm Using Parallel Processing with MPI

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### 1 Algorithm Description

- 1. We are given a problem of size N, which is N integers, to be sorted using the quick sort algorithm on P processors
- 2. The algorithm is implemented as below
- 3. Initially we begin with all P processors being in the same communicator group
- 4. The same seeded random number on each processor picks a pivot index  $p_i$  in the range from  $0 \to N 1$ .
- 5. The processor that has the  $p_i^{th}$  element will now broadcast its value  $p_v$  it to all the P processors using MPI\_Bcast, which is of complexity  $\mathcal{O}(\tau + \mu) \log p$
- 6. Each of the processors in that communicator group will then go over its array elements and determine the two groups of elements, one less than or equal to the pivot  $p_v$  and the second that are greater than the pivot  $p_v$ . This is a computation step and of complexity  $\mathcal{O}(\frac{n}{p})$
- 7. Next each processor will communicate to every other processor in its communicator group the count of the elements in the two groups mentioned above. This can be performed with a MPI\_AllGather call. This is of  $\mathcal{O}(\tau \log p + \mu p)$
- 8. With this information, each processor can make decide the following
  - (a) The total number of elements in all processors that are less than or equal to the pivot  $p_v$ , and the total number of elements that are greater than the pivot  $p_v$
  - (b) The number of processors that should be allocated to further sort each group. ( we have to make sure that in the worst case there is at least 1 processor in each group)
  - (c) Which elements from the current processor should be sent to which processors in each of those groups
  - (d) To which group will the current processor belong (If its rank < number of processors in group 1 which will hold elements < pivot  $p_v$ , then it belongs to that new group)
  - (e) How many elements it should receive from each of the other processors in tis group
- 9. With this knowledge at each processor we can now construct a MPI\_Alltoallv for all processors in the group. The count array and displacement arrays to specify the variable number of elements that should go to different processors and as well as the variable number of elements that each processor should receive from other processors

- in the group. Assuming the worst case of all elements need to be moved, we can say the run time complexity of this step is  $\mathcal{O}(\tau \log p + \mu N)$
- 10. Now we split the original communicator group into two smaller communicator groups corresponding to the two groups discussed above, one for processors which have values less than pivot and one for those that have values greater than pivot. This can be done by setting the color depending on if the rank of the processor in the earlier group is less than number of processors in group which will hold elements < pivot  $p_v$  and vice versa
- 11. We keep doing these steps in a loop, where each new group will choose a pivot as described above based on the number of elements in that group
- 12. The loop is broken for a processor, if a processor is in a group of size 1, or in a group where there is only one element
- 13. Once the processor exits the loop, it will perform a sort of its local elements. This can be implemented using iterative quick sort using a stack and is of best case complexity  $\mathcal{O}(\frac{n}{p}\log\frac{n}{p})$  and worst case complexity of  $\mathcal{O}(\frac{n^2}{p^2})$
- 14. Once all the processors have reached this step (ensured using MPI\_Barrier), we have re balance the elements among the processors to make sure that each processor has either  $\lfloor \frac{n}{p} \rfloor$  or  $\lceil \frac{n}{p} \rceil$  elements and we have to ensure that the sort order is retained after re balancing
- 15. This can again be done as described earlier in the MPI\_Alltoallv step
- 16. Each processor will communicate to every other processor in the group the count of the elements with it. This can be performed with a MPI\_AllGather call. This is of  $\mathcal{O}(\tau \log p + \mu p)$
- 17. With this information, each processor can make decide the following
  - (a) The global index of its elements
  - (b) Which elements from the current processor should be sent to which processors in ordinal fashion
  - (c) How many elements should the current processor receive from each of the other processors in ordinal fashion
- 18. With this knowledge at each processor we can now construct a MPI\_Alltoallv for all processors. The count array and displacement arrays are used to specify the variable number of elements that should go to different processors and as well the variable number of elements that this processor should receive from each other processors in the group. Assuming the worst case of all elements requiring moving, we can say the run time complexity of this step is  $\mathcal{O}(\tau \log p + \mu N)$

	6	

19. With this operation the elements are sorted and their count is balanced in all the

processors in the group

#### 2 Performance Plots

The algorithm was executed for the following parameters

- size N = 1000, 10000, 15000, 35000, 50000, 75000, 100000, 200000, 250000, 500000, 1000000, 2000000, 3000000, 5000000, 10000000
- Number of parallel processors P=3,4,5,8,10,16,18,20,22,24,25,30

#### 2.1 Runtime Performance Plots

The following are the run time plots

## 2.1.1 Runtime Performance Vs N (1,000-10,000,000) for fixed number of processors P

The following is the plot of run time performance in seconds Vs N the problem size ranging from  $N \in 1,000...10,000,000$ , for a fixed number of parallel processors P. Each curve plotted is for a constant number of Processors P ranging from  $P \in 3...30$ .

- 1.  $N \in \{1,000...10,000,000\}$  graph 1
- 2.  $N \in \{1,000...200,000\}$  graph 2

As can be see from this plot, the run time increases as the problem size N is increased from 1000...10,0000,000. It can also be seen that as the number of processors goes over P > 24, the run time for any given fixed same problem size N increases substantially. This is because the higher number of processors will increase the communication cost, making this cost dominate over the well divided computational cost of the parallel algorithm

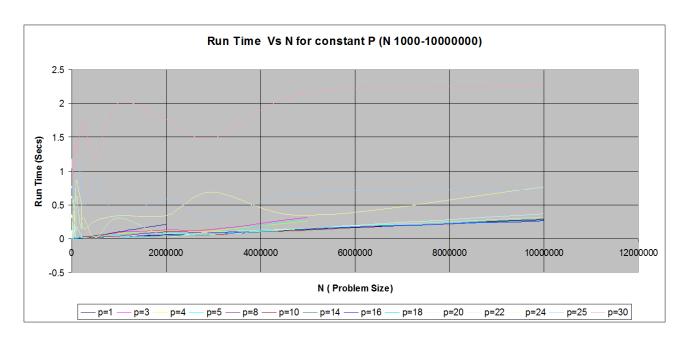


Figure 1: Runtime Vs N (1,000-10,000,000) for fixed number of processors P

# 2.1.2 Runtime Performance Vs N (1000-200,000) for fixed number of processors P

This plot is the same as the earlier except that it focuses on the range of  $N \in 1,000...200,000$ 

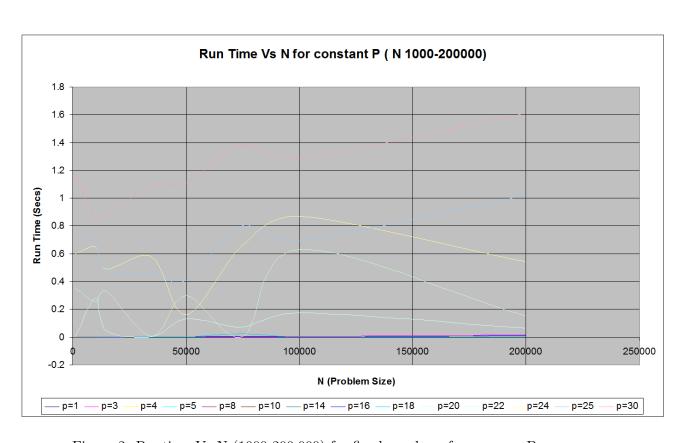


Figure 2: Runtime Vs N (1000-200,000) for fixed number of processors P

### 2.1.3 Runtime Performance - Plot of Run Time Vs P for fixed problem size N

The following is the performance plot of Runtime Vs P the number of parallel processors ranging from  $P \in 3...30$  for a fixed problem size N. Each curve is for a fixed problem size N, ranging from  $N \in 1000...10,000,000$ .

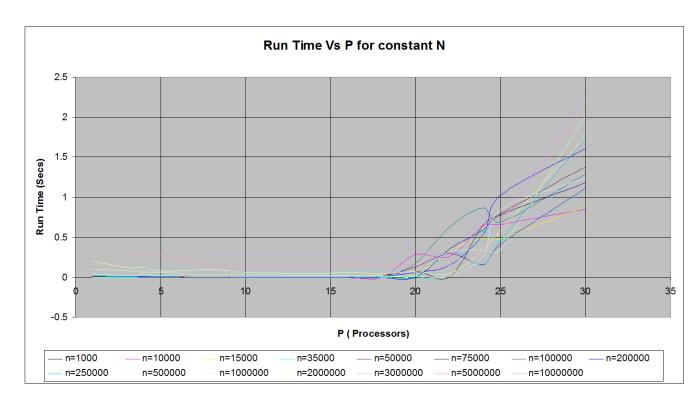


Figure 3: Run Time Vs P for fixed N

As can be seen from this plot, for any problem size the run time is fairly constant till we reach a certain number of processors. Beyond that point the run time increases dramatically. As the problem size N increases, the number of processors at which the run time increases dramatically goes up slightly. From the graphs it can be seen that for  $N \in 1000...10,0000,000$ , run time increases dramatically as the number of processors P in increased beyond the range of  $P > 20 \rightarrow 22$ 

#### 2.2 Speed Up Plots

The following are the speed up ratio plots

#### 2.2.1 Speed Up Vs N (1000-2,000,000) for fixed number of processors P

The following is the plot of speed up Vs N the problem size from  $N \in 1000...2,000,000$  for a fixed number of processors. Each curve plotted is for a fixed number of Processors P ranging from  $P \in 3...30$ . Speed up plots could not be plotted for N > 2,000,000 as the serial algorithm ran out of memory resource while loading the input.

- 1. Speed Up Vs N (1000-2,000,000) graph 4
- 2. Speed Up Vs N (1000-50,000) graph 5

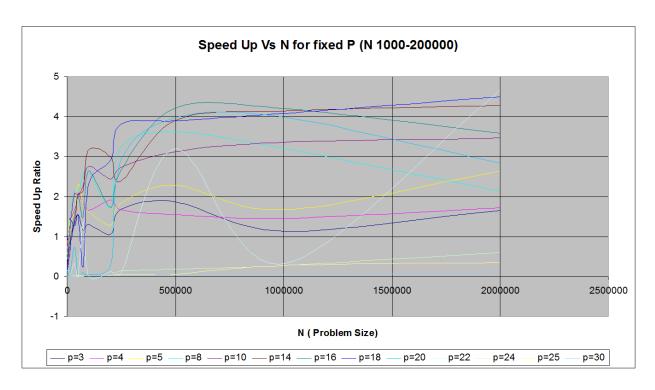


Figure 4: Speed Up Vs N (1000-2,000,000) for fixed number of processors P

From this speed up plot it can be observed that the best speed up of over 4 is achieved when the problem size N is in the range of  $N \in 500,000...2,000,000$  and the number of processors used P are in the range of  $P \in 15...20$ 

### 2.2.2 Speed Up Vs N (1000-50,000) for fixed number of processors P

This plot is the same as the earlier except that it focuses on the range of  $N \in 1,000...50,000$ 



Figure 5: Speed Up Vs N (1000-50,000) for fixed number of processors P

#### 2.2.3 Speed Up - Plot of Speed Up Vs P for fixed problem size N

The following is the plot of speed up Vs P the number of parallel processors ranging from  $P \in 3...30$  for a fixed problem size N. Each curve is for a fixed problem size N, ranging from  $N \in 1000...2,000,000$ .

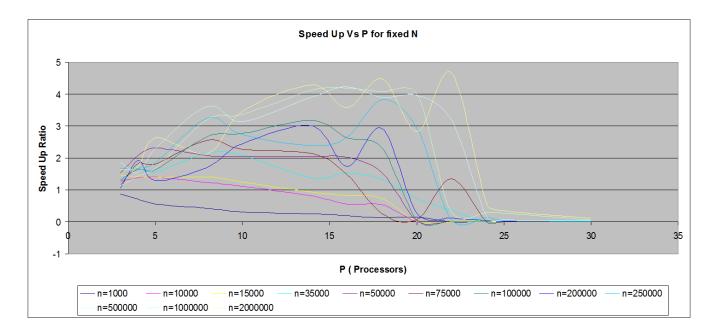


Figure 6: Speed Up Vs P for fixed N

This plot clearly shows that the best performance in terms of speed up, is achieved with P is in the range of  $P \in 15 \dots 20$ , The performance falls outside this range of processors, with a steep fall as the number of processors is increased beyond this range. It can also be seen that for any fixed number of processors in this best performance range of  $P \in 15 \dots 20$ , a increase in the problem size N from  $N \in 15,000 \rightarrow 2,000,000$ , increased performance in terms of speed up from  $< 1 \rightarrow > 4$ 

### 3 Conclusions

• The worst case serial runtime of the algorithm is of the order of

$$T(n,1) = \mathcal{O}(n^2) \tag{1}$$

The best serial runtime of the algorithm is of the order of

$$T(n,1) = \mathcal{O}(n\log n) \tag{2}$$

• From the algorithm description, we can take that the parallel algorithm has a worst case complexity of

$$T(n,p) = iterations * [\mathcal{O}(\tau + \mu) \log p + \mathcal{O}(\frac{n}{p}) + \mathcal{O}(\tau \log p + \mu p) + \mathcal{O}(\tau \log p + \mu N)] + \dots \mathcal{O}(\frac{n^2}{p^2}) + \mathcal{O}(\tau \log p + \mu p) + \mathcal{O}(\tau \log p + \mu N)$$

$$= iterations * [\mathcal{O}(\frac{n}{p}) + \mathcal{O}(\tau \log p + \mu N)] + \mathcal{O}(\frac{n^2}{p^2}) + \mathcal{O}(\tau \log p + \mu N)$$
(3)

$$T_{computation}(n,p) = iterations * [\mathcal{O}(\frac{n}{p})] + \mathcal{O}(\frac{n^2}{p^2})$$
 (4)

$$T_{communication}(n, p) = iterations * [\mathcal{O}(\tau \log p + \mu N)] + \mathcal{O}(\tau \log p + \mu N)$$
$$= iterations * [\mathcal{O}(\tau \log p + \mu N)]$$
(5)

- As can be seen from (2), (4) and (5), the computational part of the cost of the parallel quick sort algorithm gets reduced nicely depending on the number of processors P when compared to the worst case cost of the serial algorithm for quicksort. However as seen in (5), there is a communication cost involved with moving elements across processors, which in the worst cast can be all N elements. This communication cost takes away from the performance of the parallel quick sort algorithm. The latency part of the communication cost  $\mathcal{O}(\tau \log p)$  is always going to remain while the bandwidth/congestion part of the cost  $\mathcal{O}(\mu N)$  depends on the distribution of the input data, and in the worst case when all elements need to be moved from their current processor to another processor, then we need to move N elements
- So for this algorithm, all other things being fixed its performance depends on the number of elements that need to be moved
- From the performance graphs especially the Speed up performance graph 6 it can be seen that speed up improves as the number of processors P is increased from a small starting value. The speed up reaches a peak value and then there is an inflexion and the speed up falls precipitously

- The speed up plots for all sizes of N show this same pattern. This indicates that as we increase the number of processors for a given data set N, beyond a certain point the communication cost of latency and bandwidth shown in (5) begins to dominate over the computation cost of (4) causing the performance to fall
- Initially however as the number of processors increase from a small value of P=3 and reach the peak we see an improvement in performance, as the lower computational cost in (4) when compared to the serial computational cost is dominant over the communication cost in (5), thus giving a improving performance and speed up in that range.
- It can be observed from the speed up plots, that if we increase the number of processors P the beyond the number of processors which give the best performance there is a inflexion in the curve with performance falling. The number of processors P at which the there is a inflexion in the performance increases as the problem size N increases.
- ullet So the number of processors P at which we get the best performance increases with the problem size N
- For the range of N from  $N \in 15,000...2,000,000$  that was considered here for speed up plots, the value of P at which we get the peak performance increased from 8 to 20 as N increased from  $15,000 \rightarrow 2,000,000$ . The larger number of processors giving better performance for larger size of the problem of the problem N. This is in line with the run time performance equation in (3), where a larger N would mean that the better performing computational part of the cost (in comparison with the cost of the serial algorithm) is dominating over the communication cast in a larger range of the number of processors P, before the other communication costs start to take overshadow the computation cost
- In general for problems of size N in the range of  $N \in 100,000...10,000,000$ ), processors in the range of  $P \in 16...22$  gave the best performance. Beyond P > 23...24 processors the performance precipitously falls off
- It can also be seen from the Speed up performance graph 6 that in the range of processors P which give peak performance range, if we take a fixed number of processors, say P=16, a speed up of over 4 is achieved with a problem size N=200,000 compared to a speed Up of 2 achieved with N=50,000 and a speed up of just under 1 achieved for N=15,000
- So for a given number of processors, with the number processors P in the range of peak performance, an increase in the problem size N while keeping the number of processors fixed substantially increases the speed up achieved. This is again as

expected from the performance equation (3), where a larger N for the same P will let the computational cost dominate over the communication cost, and since computational cost is well divided between the processors when compared to the serial computation cost, we achieve a better speed up

- Thus we can say that for a given problem size N, there is a optimum number of processors P at which we get the best performance, going beyond this value of P causes a fall in performance
- Larger the problem size N, larger the optimum number of processors P at which we can get the peak performance
- ullet For a fixed number of processors P, in the peak performance range of the plots, a better speed up is achieved if we increase the problem size N while keeping the number of processors fixed
- For the range of  $N \in (15,000...10,000,000)$  the best performance is seen with processors in the range  $P \in (16...22)$
- In this range of processors, if we pick say P=16, a speed up of over 4 is achieved with a problem size N=200,000 compared to a speed Up of 2 achieved with N=50,000 and a speed up of just under 1 achieved for N=15,000