# Joint Track Machine Learning

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#### Outline

Motivation

Background

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# Motivation

#### The Problem

- Joints manifest pain during dynamic activity.
- 20% of patients receiving TKA are dissatisfied.
  - Instability, pain, unnatural [1, 3, 9].
- No reliable method of clinically assessing and quantifying joint dynamics.
  - Too much human supervision, too time consuming



### Our Proposition

Orthopaedic surgeons and clinicians would readily adopt a practical and inexpensive technology that allows them to measure a patient's knee kinematics during activities of daily living.

PICTURE HERE WITH RX OF KNEE MOTION STUDY

#### Constraints

- It must fit within a standard clinical workflow
- The technology must utilize equipment commonly found in hospitals
- There must not be significant human supervision nor interaction to generate an examination report.



# Background

# Projective Geometry

### **Camera Intrinsics**

# Model-Image Registration

**Historical Methods** 

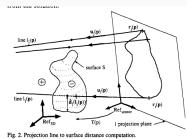
#### Overview

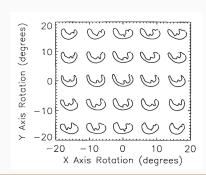
Many different approaches have attempted to solve the model-image registration problem.

- Pre-computed projections
- Skin-mounted motion Capture
- Biplane Imaging
- Iterative Projections

#### **Pre-Computed Projections**

- Saving space and memory by pre-computing as much as possible.
- Pre-computed distance maps [10, 7].
- Pre-computed shape libraries [2]



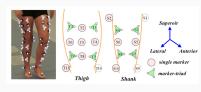


### Limitations of Pre-Computed Projections

- Requires an accurate contour from the input image in order to perform calculations.
  - Human supervision vs. inaccuracy.

# Motion Capture (MoCap)

- Can measure motion of MoCap beads very accurately.
- Skin-mounted [4, 5, 8].
- Bone pins [6] (any volunteers?).





# Biplane Imaging

# **Iterative Projections**

# Model-based Radiostereo Photogrammetry (MBRSA)

# **Aims**

#### **Aims**

Aims 1/2 Joint Track Machine Learning and Overcoming Single-Plane Limitations

Aim 3/4
Pilot Trials and
Standardized
Kinematics Exam

Aim 5 Joint Track Auto Toolkit

#### **Aims**

Aim(s)	Goal
1/2	Joint Track Machine Learning and Overcoming Single-Plane Lin
3/4	Pilot Trials and Standardized Kinematics Exam
5	Joint Track Auto Toolkit: An Open Source Toolkit for Model-In

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