

Introduction to (Mathematical) Optimization

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Optimization

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Mathematical Optimization

Optimization introducing a **change** to a **system** to achieve a **better (or best) outcome**

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Mathematical Optimization

Optimization introducing a **change** to a **system** to achieve a **better (or best) outcome**

Optimized there does not exist a **(known) change** to a **system** to achieve a **better outcome**

- ▶ **system**: mathematical model
- ▶ **change**: change to input variables (parameters)
- ▶ **outcome**: a measure of performance of the model, objective function

The Raptor Problem

See other slides

Optimization in one variable

$$\text{minimize } f(x) \in C^2 : \mathbf{R} \rightarrow \mathbf{R}$$

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- ▶ Local optimization: look for a point x^* such that $f(x^*) \leq f(x)$ for all points x near x^*

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- ▶ Global optimization: look for a point x^* such that $f(x^*) \leq f(x)$ for all points x in domain of interest

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- ▶ Local optimization: look for a point x^* such that $f(x^*) \leq f(x)$ for all points x near x^*
- ▶ Global optimization: look for a point x^* such that $f(x^*) \leq f(x)$ for all points x in domain of interest
- ▶ When $f(x)$ is twice continuously differentiable, then local optimization involves finding a point x^* such that $f'(x^*) = 0$ and $f''(x^*) > 0$

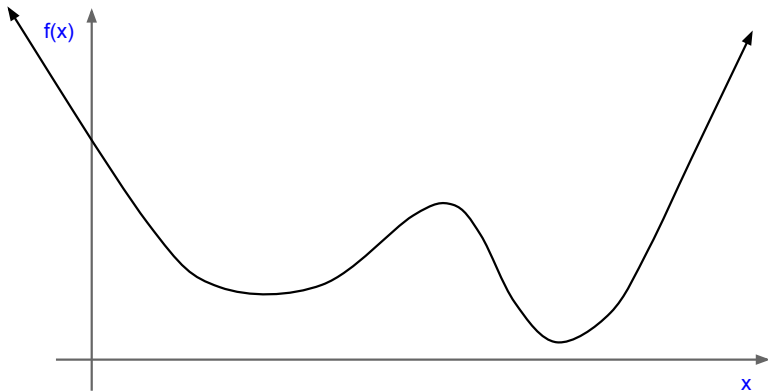
Optimization in one variable: axis



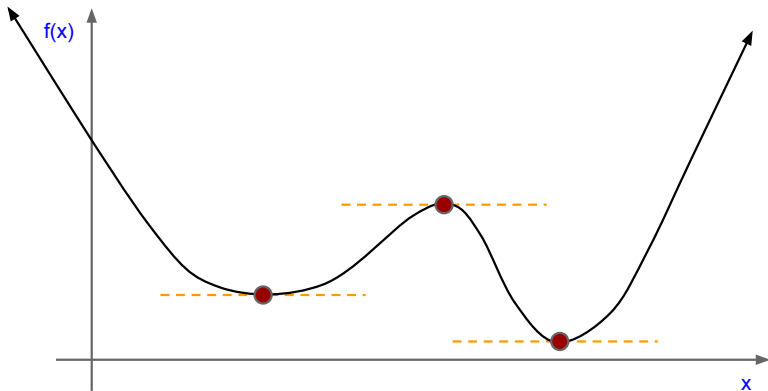
Optimization in one variable: definitions



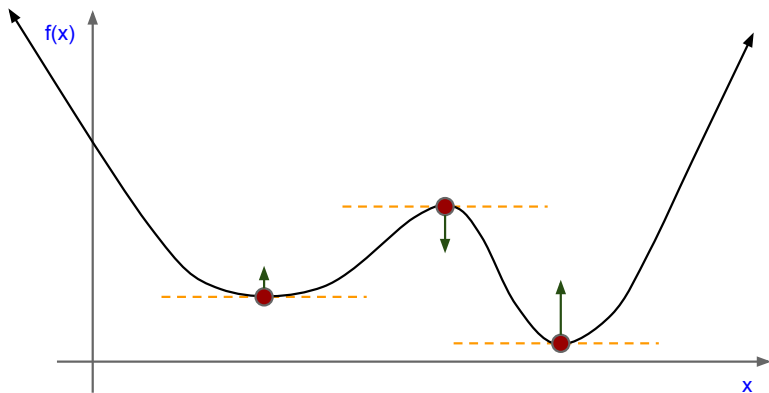
Optimization in one variable: example objective function



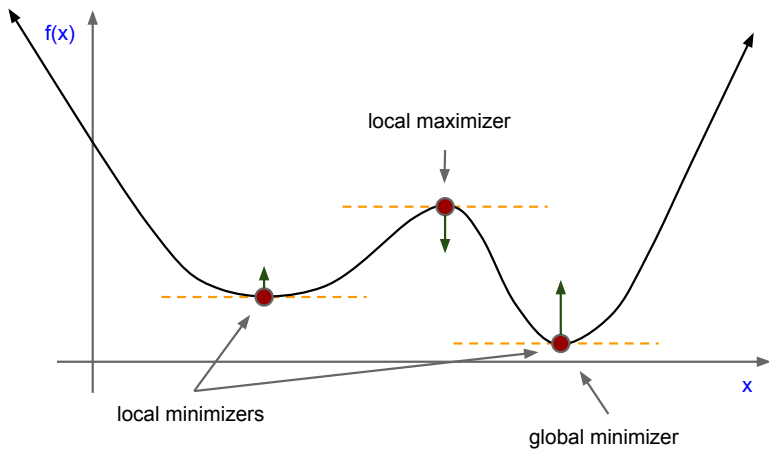
Optimization in one variable: critical points, $f'(x) = 0$



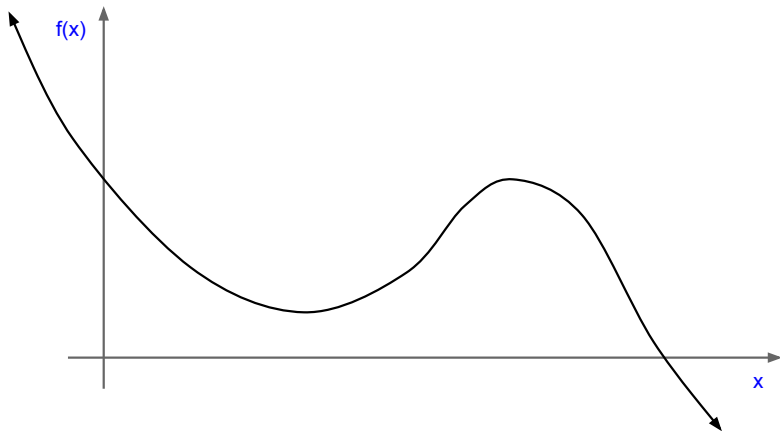
Optimization in one variable: local optima



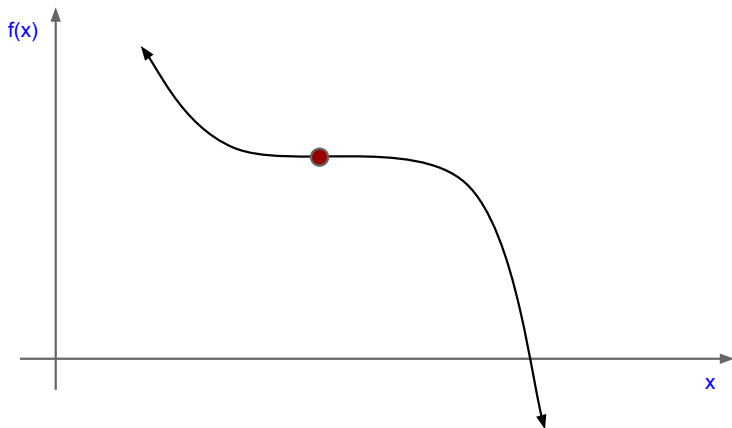
Optimization in one variable: local optima, $f''(x) = ?$



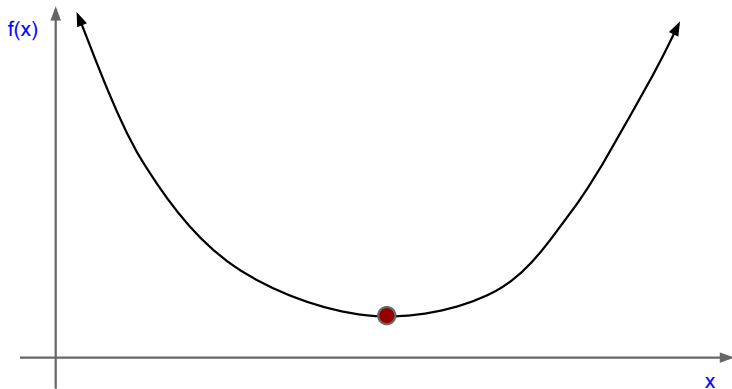
Optimization in one variable: unbounded below



Optimization in one variable: saddle point, $f'(x) = 0$ and $f''(x) = 0$



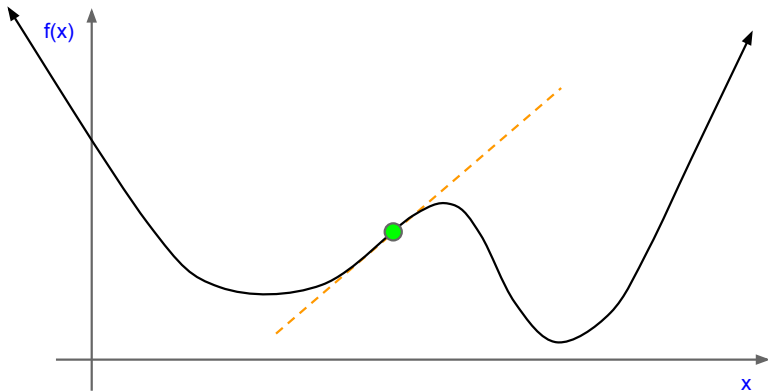
Optimization in one variable: convex objective



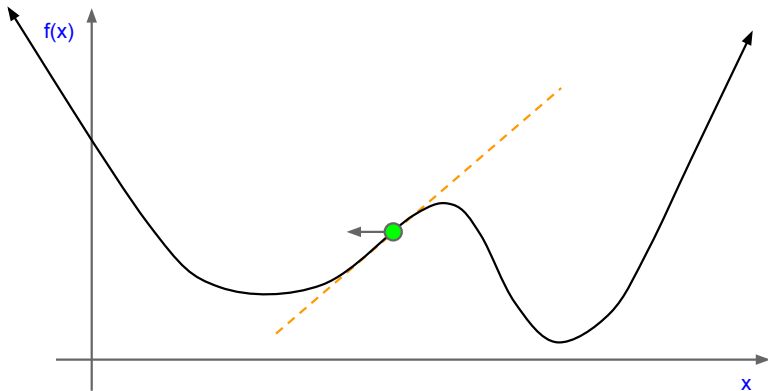
Key definitions

- ▶ *domain*: space for input variable x
- ▶ *range*: space for output of objective function $f(x)$
- ▶ *critical point*: $f'(x) = 0$
- ▶ *local minimizer*: $f'(x) = 0$ and $f''(x) > 0$
- ▶ *local maximizer*: $f'(x) = 0$ and $f''(x) < 0$
- ▶ *saddle point*: $f'(x) = 0$ and $f''(x) = 0$
- ▶ *global minimizer*: x^* such that $f(x^*) \leq f(x)$ for all x in domain

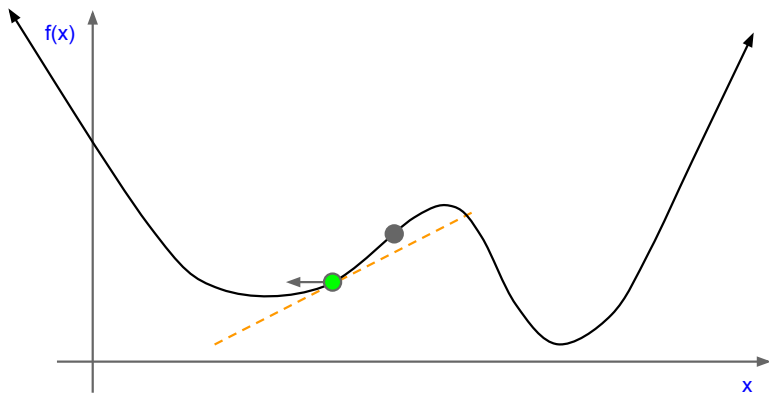
Optimization in one variable: algorithm basics



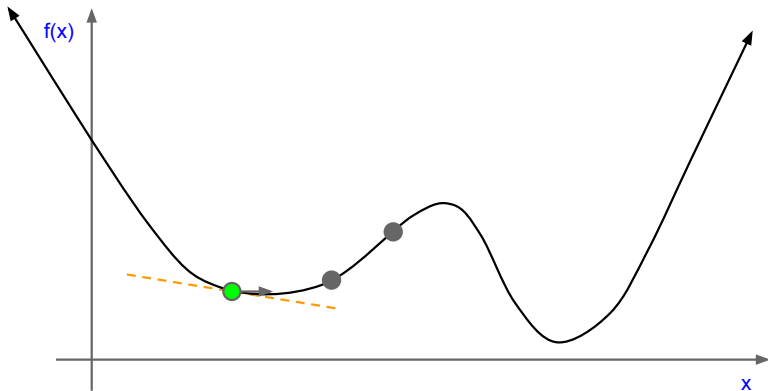
Optimization in one variable: algorithm basics



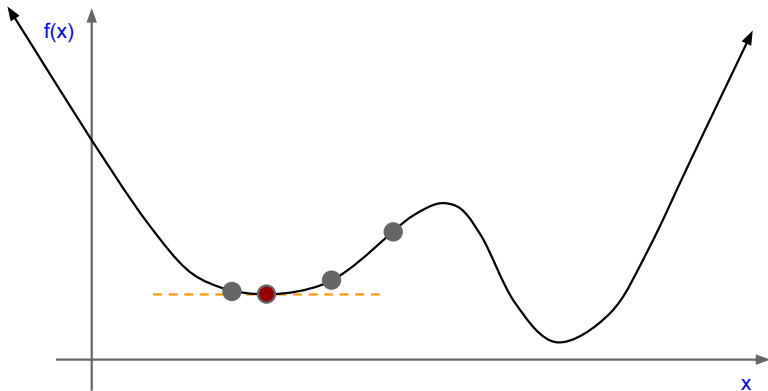
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$$x_0, x_1, x_2, x_3, \dots \rightarrow x^*$$

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- ▶ Notation for sequence and convergence: $\{x_k\} \rightarrow x^*$

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- ▶ Key algorithm property: ***descent condition***

$$f(x_{k+1}) < f(x_k)$$

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$$f(x_{k+1}) < f(x_k)$$

- ▶ Technical algorithm property: ***convergence to solution***

$$|x_{k+1} - x_k| \rightarrow 0 \text{ if and only if } f'(x_k) \rightarrow 0 \text{ and } \lim_{k \rightarrow \infty} f''(x_k) \geq 0$$

Optimization in two variables

$$\text{minimize } f(x) \in C^2 : \mathbf{R}^2 \rightarrow \mathbf{R}$$

- ▶ x is a 2-dimensional vector of real variables
- ▶ $f(x)$ is the objective function
 - ▶ First derivative or gradient of f is written $\nabla f(x)$
 - ▶ Second derivative or Hessian of f is written $\nabla^2 f(x)$
- ▶ We are looking for a point x^* such that $\nabla f(x) = 0$ and $\nabla^2 f(x) \succeq 0$. Note that this is a *local* optimizer

The gradient $\nabla f(x)$

Vector of variables:

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$$

Gradient of f :

$$\nabla f(x) = \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \end{bmatrix}$$

The Hessian $\nabla^2 f(x)$

$$\nabla^2 f(x) = \begin{bmatrix} \frac{\partial^2 f}{\partial x_1^2} & \frac{\partial^2 f}{\partial x_1 \partial x_2} \\ \frac{\partial^2 f}{\partial x_2 \partial x_1} & \frac{\partial^2 f}{\partial x_2^2} \end{bmatrix}$$

Surface plots and contours

- ▶ show local minimizer/maximizer critical point
- ▶ show saddle point

Higher dimensions

- ▶ can't easily visualize
- ▶ need analysis

Algorithms

- ▶ Basic loop
- ▶ Descent condition
- ▶ Gradient descent
- ▶ Newton's method

Show example on rosenbrock function

- ▶ gradient descent vs. newton's method

Two very important optimization problems

- ▶ linear least squares
- ▶ non-linear least squares

Constraints

- ▶ basic idea of constraints
- ▶ work through example from multivariate calculus
- ▶ introduce idea of multipliers
- ▶ equality constraints
- ▶ inequality constraints
- ▶ linear constraints
- ▶ nonlinear constraints

Penalty and barrier methods

- ▶ introduce a penalty into the objective to penalize constraint violation

Linear programming

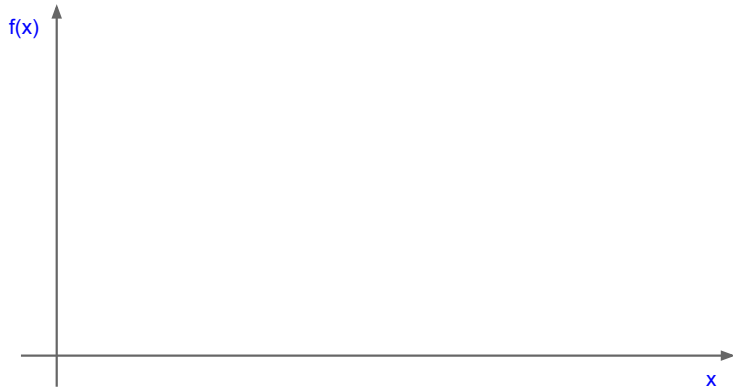
Discrete variables

- ▶ Mixed integer programming
- ▶ Scheduling problems

What's next

- ▶ Nonlinear programming
- ▶ Convex modelling
- ▶ Study of algorithms
- ▶ Modeling languages
- ▶ Automated differentiation

Test image 1



Test image 2

