# Notes on 'Adaptive Non-Parametric Regression With the K-NN Fused Lasso'

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Let  $\mathbf{X} = x_1, \dots, x_n$  be sampled i.i.d from  $\mu$  with density function  $p(\cdot)$  over some subset  $\mathcal{X}$  of Euclidean space, and suppose

$$y_i = f_0(x_i) + \epsilon_i, \quad \epsilon_i \stackrel{i.i.d}{\sim} SG(\sigma^2)$$

holds for some unknown  $f_0$ . Let  $\widehat{\theta}$  be the solution to the fused lasso

$$\widehat{\theta} := \operatorname*{argmin}_{\theta \in \mathbb{R}^n} \left\{ \frac{1}{2} \left\| y - \theta \right\|_2^2 + \lambda \left\| \nabla_G \theta \right\|_1 \right\}$$

where  $\lambda > 0$  is a tuning parameter, and  $\nabla_G$  is an oriented incidence matrix of the graph G.

The K-NN-FL estimator computes the fused lasso over the K-NN graph  $G_K$  of X. The  $\epsilon$ -FL estimator computes the fused lasso over the  $\epsilon$  graph  $G_{\epsilon}$ .

The assumptions required for Theorems 1 and 2 are as follows.

(a) For all  $x \in \mathcal{X}$ 

$$0 < p_{\min} \le p(x) \le p_{\max} < \infty$$

(b) The base measure  $\mu$  in  $\mathcal{X}$  satisfies

$$r^d c_{1,d} \le \mu(B_r(x)) \le c_{2,d} r^d \qquad (\forall x \in \mathcal{X})$$

(c) There exists a homeomorphism (continuous bijection with continuous inverse)  $h: \mathcal{X} \to [0,1]^d$  such that

$$L_{\min} d_{\mathcal{X}}(x, x') \le \|h(x) - h(x')\|_{2} \le L_{\max} d_{\mathcal{X}}(x, x') \qquad (\forall x, x' \in \mathcal{X})$$

(d) The function  $g_0 := f_0 \circ h^{-1}$  has bounded variation, meaning

$$|g_0|_{BV(\Omega)} := \sup \left\{ \int_{\Omega} g_0(x) \operatorname{div}(g)(x) dx; g \in C_c^1(\Omega, \mathbb{R}^d), ||g||_{\infty} \le 1 \right\} < \infty$$

where  $\mathfrak{B}$  is the Borel  $\sigma$ -algebra of  $\Omega = [0,1]^d$ ,  $C_c^1(\Omega,\mathbb{R}^d)$  is the set of  $\mathfrak{B}$ -measurable, continuously differentiable functions into  $\mathbb{R}^d$ , and

$$\|g\|_{\infty} := \left\| \left( \sum_{i=1}^d g_i^2 \right)^{1/2} \right\|_{L_{\infty}(\Omega)}.$$

- (e)  $g_0$  is piecewise Lipschitz<sup>1</sup>, meaning there exists a set  $\mathcal{S} \subset (0,1)^d$  such that
  - (a)  $\nu(S) = 0$ .
  - (b)  $\mu(h^{-1}(S_{\epsilon} \cup ([0,1]^d \setminus \Omega_{\epsilon}))) \leq C_{\mathcal{S}}\epsilon$
  - (c) There exists a positive constant  $L_0$  such that if z and z' belong to the same connected component of  $\Omega_{\epsilon} \setminus B_{\epsilon}(\mathcal{S})$ , then

$$|g(z) - g(z')| \le L_0 ||z - z'||_2$$

where  $\Omega_{\epsilon} = [0,1]^d \setminus B_{\epsilon}(\partial [0,1]^d)$ .

**Theorem 1.** Let  $K \approx \log^{1+2r} n$  for some r > 0, Then under Assumptions 1-3, with an appropriate choice of the tuning parameter  $\lambda$ , the K-NN-FL estimator  $\widehat{\theta}$  satisfies

$$\left\|\widehat{\theta} - \boldsymbol{\theta}^{\star}\right\|_{n}^{2} = O_{\mathbb{P}}\left(\frac{\log^{1+2r} n}{n} + \frac{\log^{1.5+r} n}{n} \left\|\nabla_{G_{K}} \boldsymbol{\theta}^{\star}\right\|_{1}\right)$$

This upper bound also holds for  $\epsilon$ -NN-FL if we replace  $\|\nabla_{G_K}\theta^{\star}\|_1$  with  $\|\nabla_{G_{\epsilon}}\theta^{\star}\|_1$ .

**Theorem 2.** Under Assumptions 1-5, with an appropriate choice of the tuning parameter  $\lambda$ , the K-NN-FL estimator  $\hat{\theta}$  satisfies

$$\left\|\widehat{\theta} - {\theta^{\star}}\right\|_{n}^{2} = \widetilde{O}_{\mathbb{P}}\left(\frac{1}{n^{1/d}}\right).$$

## 1 Proof of Theorem 1

To ease proofs, we will assume  $\mathcal{X} = [0, 1]^d$ .

Construct  $G_{lat} = (V_{lat}, E_{lat})$  a lattice graph with equal side lengths in  $[0, 1]^d$ , where

$$V_{lat} = P_{lat}(N) := \left\{ \left( \frac{i_1}{N} - \frac{1}{2N}, \dots, \frac{i_d}{N} - \frac{1}{2N} \right) : i_1, \dots, i_d \in \{1, \dots, N\} \right\}$$

$$(z, z') \in E_{lat} \text{ if and only if } ||z - z'|| \le \frac{1}{N}$$

<sup>&</sup>lt;sup>1</sup>Technically, the requirement is slightly weaker than piecewise Lipschitz.

where z and  $z' \in P_{lat}(N)$ .

Denoting  $I = P_{lat}$ , we define

$$P_I(x) = \operatorname{argmin} \{ \|x - z'\|_{\infty}, z' \in P_{lat}(N) \}$$

Then, let  $C(z) = \{x \in [0,1]^d : z = P_I(x)\}$  be the collection of cells associated with the mesh  $P_{lat}(N)$ , noting that  $\{C(z) : z \in P_{lat}(N)\}$  defines a partition over  $[0,1]^d$ .

**Quantization.** For a given  $\theta \in \mathbb{R}^n$ , the quantization  $\theta_I \in \mathbb{R}^n$ 

$$(\theta_I)_i := \theta_j$$
, where  $x_j = \underset{x_l, l \in [n]}{\operatorname{argmin}} \|P_I(x_i) - x_l\|_{\infty}$ 

is constant over every cell C(z). We now induce a signal in  $\mathbb{R}^{N^d}$  corresponding to the elements in I. Let  $\{z_1, \ldots, z_{N^d}\} = I$ . Then we write

$$I_k = \{i \in [n] : P_I(x_i) = z_k\}$$

for  $k = 1, ..., N^d$ . Define  $\theta^I \in \mathbb{R}^{N^d}$  by

$$(\theta^I)_k := \begin{cases} (\theta_I)_i, x_i \in I_k \\ 0, I_k = \emptyset \end{cases}$$

where we note that  $(\theta^I)$  is well-defined since  $(\theta_I)_i = (\theta_I)_j$  if  $x_i$  and  $x_j$  are both in  $I_k$ .

### 1.1 Controlling counts of mesh

Define the event  $\Omega$  as: "If  $x_i \in C(z_k)$  and  $x_i \in C(z_l)$  for  $z_k, z_l \in I$  with  $||z_k - z_l||_2 \leq \frac{1}{N}$ , then  $x_i$  and  $x_j$  are connected in the K-NN graph." Then,

**Lemma 1.** Take Assumptions 1-3, and additionally assume that N in the construction of  $G_{lat}(N)$  is chosen as

$$N \ge \left\lceil \frac{3\sqrt{d}(2c_{2,d}p_{\max})^{1/d}n^{1/d}}{L_{\min}K^{1/d}} \right\rceil. \tag{1}$$

Then,

$$\mathbb{P}(\Omega) \ge 1 - n \exp(-K/3).$$

#### 1.2 Bounding Empirical Process

#### Lemma 2.

## 1.3 Mesh embedding for K-NN graph

**Lemma 3.** Fix N to satisfy (1), and let us assume that the event  $\Omega$  from Lemma 1 holds. Denote  $I = P_{lat}(N)$  to be the mesh. Then, for all  $e \in \mathbb{R}^n$ , it holds that

$$\left| e^{T} (\theta - \theta_{I}) \right| \leq 2 \left\| e \right\|_{\infty} \left\| \nabla_{G_{K}} \theta \right\|_{1}, \qquad (\forall \theta \in \mathbb{R}^{n})$$

Moreover,

$$\|D\theta^I\|_1 \le \|\nabla_{G_K}\theta\|_1,$$
  $(\forall \theta \in \mathbb{R}^n)$ 

where D is the incidence matrix of  $G_{lat}$ .