

Best Approx. in Hilbert Space

Question: How to choose c_1, c_2, \dots, c_n so that $f - f_n$ is as "small" as possible?

$$(*) \quad \underbrace{\begin{bmatrix} | \\ f(x) \\ | \end{bmatrix}}_{\underline{f}} \approx \underbrace{\begin{bmatrix} | & | & & | \\ e_1 & e_2 & \dots & e_n \\ | & | & & | \end{bmatrix}}_E \underbrace{\begin{bmatrix} c_1 \\ c_2 \\ \vdots \\ c_n \end{bmatrix}}_{\underline{c}}$$

Idea: Develop "linear algebra for functions" to solve (*) in a "least-squares" sense.

Recall: A real or complex Hilbert space H is a complete inner product space over \mathbb{R} or \mathbb{C} .

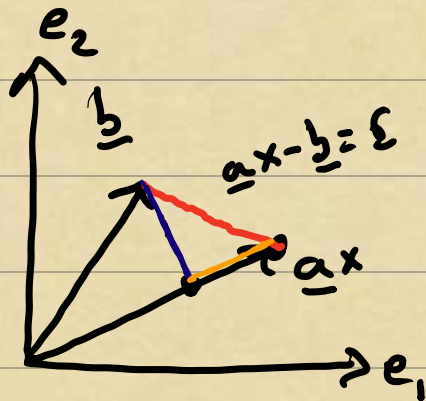
Today: The solution to (*) is obtained by the orthogonal residual condition

$$\underline{f} - E \underline{c} \perp \overbrace{\text{span}\{e_1, e_2, \dots, e_n\}}^{\text{col}(E)},$$

and we can calculate \underline{c} via ONB for $\text{col}(E)$.

Orthogonal Residual Criterion

The basic intuition behind least-squares approximation is captured in a picture:



$$\begin{bmatrix} 1 \\ \underline{a} \\ 1 \end{bmatrix} x = \begin{bmatrix} 1 \\ \underline{b} \\ 1 \end{bmatrix}$$

$$\|r\|^2 = \|\underline{a}x - b\|^2 = \|r_1\|^2 + \|r_2\|^2$$

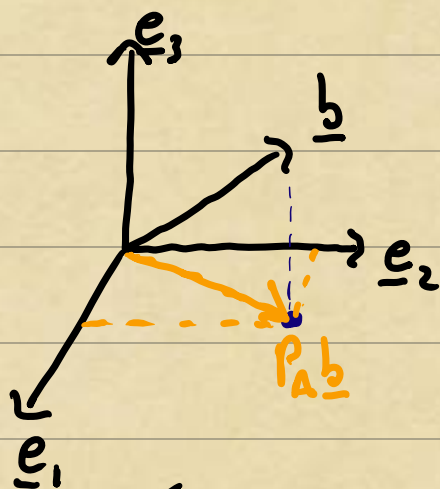
We can choose x to make $r_2 = 0$, but we can never change r_1 by changing x .

$$r_1 = \underline{a} \frac{\underline{a}^T r}{\underline{a}^T \underline{a}} = \frac{\underline{a}}{\underline{a}^T \underline{a}} [\underline{a}^T (\underline{a}x - \underline{b})]$$

So we choose x to make $r_1 = 0$:

$$x = \frac{\underline{a}^T \underline{b}}{\underline{a}^T \underline{a}}$$

The basic picture remains the same in higher, even infinite, dimensions. However, it's useful to formulate the solution via OLS.



$$\min_{\underline{x} \in \mathbb{R}^2} \left\| \begin{bmatrix} 1 & 1 \\ \underline{a}_1 & \underline{a}_2 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} - \begin{bmatrix} 1 \\ \underline{b} \\ 1 \end{bmatrix} \right\|$$

$A \quad \underline{x} \quad - \quad \underline{b}$

Suppose that $\{e_1, e_2\}$ is an ONB for $\text{col}(A)$, i.e.,

$$\Rightarrow \text{span}\{e_1, e_2\} = \text{span}\{\underline{a}_1, \underline{a}_2\}.$$

$$\Rightarrow \langle e_i, e_j \rangle = \begin{cases} 1 & i=j \\ 0 & i \neq j \end{cases}$$

We can solve the least-squares problem by projecting \underline{b} orthogonally onto $\text{col}(A)$ and solving the new linear system for \underline{x} .

$$\text{Project} \Rightarrow P_A \underline{b} = \langle \underline{b}, e_1 \rangle e_1 + \langle \underline{b}, e_2 \rangle e_2$$

$$\text{Solve} \Rightarrow A \underline{x} = P_A \underline{b}$$

We can solve for \underline{x} by expanding the columns of A in the basis $\{e_1, e_2\}$.

$$\underline{a}_1 = c_1^1 e_1 + c_2^1 e_2, \quad \underline{a}_2 = c_1^2 e_1 + c_2^2 e_2$$

$$\Rightarrow \underset{A}{A} \underset{x}{x} = \underset{E}{\begin{bmatrix} 1 & 1 \\ \underline{a}_1 & \underline{a}_2 \\ 1 & 1 \end{bmatrix}} \underset{x}{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}} = \underset{E}{\begin{bmatrix} 1 & 1 \\ e_1 & e_2 \\ 1 & 1 \end{bmatrix}} \underset{C}{\begin{bmatrix} c_1^1 & c_1^2 \\ c_2^1 & c_2^2 \end{bmatrix}} \underset{x}{\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}}$$

Now, to solve $Ax=b$, we multiply both sides by E^T and use orthonormality ($E^T E = I$)

$$A \underline{x} = \underline{b} \quad \Rightarrow \quad E C \underline{x} = E \hat{b} \quad (\hat{b} = \begin{bmatrix} \langle b, e_1 \rangle \\ \langle b, e_2 \rangle \end{bmatrix})$$

$$(**) \quad \Rightarrow \quad C \underline{x} = \hat{b}$$

Note that even if the columns of A and \underline{b} are elements of an abstract Hilbert space (e.g., could be functions instead of vectors in \mathbb{R}^n), working with an ONB for $\text{col}(A) = \text{span}\{\text{cols of } A\}$ allows us to solve $(*)$ by solving a finite linear system $(**)$.