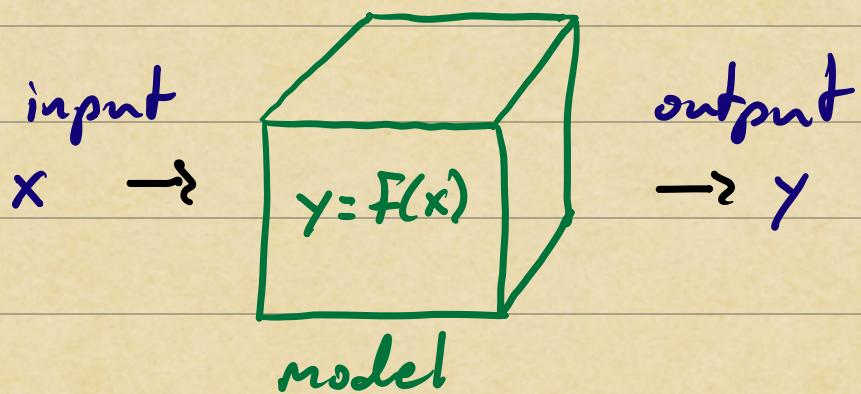


# 1D "Warm Up" - Approximation Theory

Aim: use data to develop mathematical models of complex phenomena.



Idea 1: Model Regression

Q: How well does a model fit data?

Idea 2: Model Accuracy

Q: How well does a model predict new data?

Idea 3: Model Generalization

Q: How accurate is model "far" from data?

# Problem 1. Interpolating "clean" data

Given input-output data from continuous function  $G: [0, 1] \rightarrow \mathbb{R}$ ,

$$y_0 = G(x_0), y_1 = G(x_1), \dots, y_n = G(x_n),$$

construct a degree  $\leq n$  poly. interpolant:

$$F_n(x) = c_0 + c_1 x + \dots + c_n x^n,$$

s.t.  $F_n(x_i) = G(x_i)$  for  $i = 0, \dots, n$ .

Q: How accurate is the interpolant?

"Model Error"  $E_n = \sup_{x \in [0, 1]} |G(x) - F_n(x)|$

$\Rightarrow E_n$  depends on "smoothness" of  $G$  and the distribution of  $\{x_i\}_{i=0}^n$ .

$\Rightarrow$  In practice, also need stable algorithm.

## Algorithm 1. Dictionary Fitting

Let  $\text{span}\{e_0, e_1, \dots, e_n\} = \mathbb{P}_n$ , so that any degree  $n$  polynomial can be written

$$p(x) = a_0 + a_1 x + \dots + a_n x^n = b_0 e_0 + \dots + b_n e_n,$$

for some unique coeffs  $\{b_0, \dots, b_n\}$ .

In particular, there are unique coeffs

$$\text{s.t. } F_n(x) = c'_0 e_0(x) + \dots + c'_n e_n(x),$$

and we can compute them via

$$\begin{bmatrix} e_0(x_0) & \dots & e_n(x_0) \\ e_0(x_1) & \dots & e_n(x_1) \\ \vdots & & \vdots \\ e_0(x_n) & \dots & e_n(x_n) \end{bmatrix} \begin{bmatrix} c'_0 \\ c'_1 \\ \vdots \\ c'_n \end{bmatrix} = \begin{bmatrix} y_0 \\ y_1 \\ \vdots \\ y_n \end{bmatrix}.$$

"Generalized Vandermonde System"

$\Rightarrow$  Sensitivity of solution depends on dict.

$\Rightarrow$  Stability of algorithm depends on dictionary.

See demo01.m on course repository  
for numerical experiments w/ interpolation.

## Analysis of Interpolation

To analyze the accuracy of the interpolant, we follow a strategy that is common in approximation theory.

### Step 1. Best Approximation in $P_n$ .

Q: How well is  $G$  approximated by polynomials in  $P_n$ ?

### Step 2. Suboptimality of $P_n$ -interpolant.

Q: How "far from best" is the interpolant?

This 2-step analysis separates the influence of the ground truth and model from the influence of the data.

## Best Approximation

We want to find  $p_* \in P_n$  that solves

$$(*) \quad p_* = \underset{p \in P_n}{\operatorname{argmin}} \|p - G\|,$$

where  $\|p\| = \sup_{x \in [0,1]} |p(x)|$  is the "sup" norm.

### Key Fact 1. Existence: Uniqueness

If  $G \in C[0,1]$  (continuous on  $[0,1]$ ), then

there is a unique best approximation

$p_* \in P_n$  that satisfies (\*).

pf | Existence: the space  $P_n$  is a complete  $n$ -dimensional vector space and the subset

$$\beta = \{p \in P_n \text{ s.t. } \|p - G\| \leq \|G\|\}$$

is closed! bounded, hence, compact.

The error function  $p \rightarrow \|p - G\|$  is continuous w.r.t.  $p \in \mathcal{P}$  and, therefore, achieves its minimum on  $\mathcal{B}$ .

Uniqueness: Chebyshev Equioscillation Thm.

Key Fact 2. Estimates for Smooth Functions

The error in the best polynomial approximation to  $G$  is tightly linked to the "smoothness" or "regularity" of  $G$ .

Jackson Thm. Let  $G \in C^k[0, 1]$  ( $k \geq 1$ ) and  $n \geq k-1$ . Then,

$$\inf_{p \in P_n} \|p - G\| \leq \left(\frac{\pi}{2}\right)^k \frac{1}{(n+1) \dots (n-k+2)} \|G\|$$

Roughly, the error decreases algebraically

$$\inf_{P \in \mathcal{P}_n} \|P - G\| \leq C_n \frac{\|G\|}{n^{\kappa}}$$