ADVANCED TOPICS IN MICROECONOMETRICS: MATCHING MODELS AND THEIR APPLICATIONS

Alfred Galichon (NYU and ScPo)

Spring 2018 Lecture 9. Demand models

IMPORTANT ANNOUCEMENT REGARDING NEXT LECTURES

- ► Mar 5, 2018: class from 8am to 12noon
- ► Mar 12, 2018: regular schedule
- ▶ Mar 19, 2018: class from 8am to 12noon
- ► Mar 26, 2018: regular schedule
- ► April 2, 2018: no class (holiday)
- ► April 9, 2018: class cancelled and replaced
- ► April 16, 2018: class cancelled and replaced
- ► April 23, 2018: class cancelled and replaced
- ► April 30, 2018: regular schedule
- ► May 7, 2018: exam 10am-12noon

LEARNING OBJECTIVES: LECTURE 9

- ▶ Beyond GEV: the pure characteristics models, the random coefficient logit model, the probit model
- ► Simulation methods: AR, GHK, and SARS
- ► The inversion theorem

REFERENCES FOR LECTURE 9

- ► [OTME], Ch. 9.2
- ► McFadden (1981). "Econometric Models of Probabilistic Choice," in C.F. Manski and D. McFadden (eds.), Structural analysis of discrete data with econometric applications, MIT Press.
- ▶ Berry, Levinsohn, and Pakes (1995). "Automobile Prices in Market Equilibrium," *Econometrica*.
- ► Berry and Pakes (2007). The pure characteristics demand model".

 International Economic Review
- ► Train (2009). *Discrete Choice Methods with Simulation*. 2nd Edition. Cambridge University Press.
- ► G, Salanié (2017). "Cupids invisible hand". Working paper.
- ► Bonnet, G and Shum (2017). "Yogurts choose consumers? Identification of Random Utility Models via Two-Sided Matching". Working paper.

Section 1

THEORY

I. CHOICE MODELS BEYOND GEV

- ▶ The GEV models are convenient analytically, but not very flexible.
 - ► The logit model imposes zero correlation across alternatives
 - The nested logit allows for nonzero correlation, but in a very rigid way (needs to define nests).
- ▶ A good example is the probit model, where ε is a Gaussian vector. For this model, there is no close-form solution neither for G nor for G^* .
- More recently, a number of modern models don't have closed-form either. These models require simulation methods in order to approximate them by discrete models.

THE PURE CHARACTERISTICS MODEL: MOTIVATION

- ► The pure characteristics model (Berry and Pakes, 2007) can be motivated as follows. Assume *y* stands for the number of bedrooms. The logit model would assume that the random utility associated with a 2-BR is uncorrelated with a 3-BR, which is not realistic.
- Let ξ_y is the typical size of a bedroom of size y, one may introduce ϵ as the valuation of size; in which case the utility shock associated with y should be $\epsilon_y = \epsilon \xi_y$. More generally, the characteristics ξ_y is a d-dimensional (deterministic) vector, and $\epsilon \sim \mathbf{P}_{\epsilon}$ is a (random) vector of the same size standing for the valuations of the respective dimensions, so that

$$\varepsilon_y = \epsilon^{\mathsf{T}} \xi_y$$
.

▶ For example, if each alternative y stands for a model of car, the first component of ξ_y may be the price of car y; the other components may be other characteristics such as number of seats, fuel efficiency, size, etc. In that case, for a given dimension $y \in \mathcal{Y}_0$, ϵ_y is the (random) valuation of this dimension by the consumer with taste vector ϵ .

THE PURE CHARACTERISTICS MODEL: DEFINITION

- Assume without loss of generality that $\varepsilon_y = 0$, that is $\xi_0 = 0$ as we can always reduce the setting to this case by replacing ξ_V by $\xi_V \xi_0$.
- ▶ Letting Z be the $|\mathcal{Y}| \times d$ matrix of (y, k)-term ξ_y^k , this rewrites as

$$\varepsilon = Z\epsilon$$
.

► Hence, we have

$$G(U) = \mathbb{E}\left[\max\left\{U + Z\epsilon, 0\right\}\right].$$

and

$$\sigma_{y}\left(U\right) = \Pr\left(U_{y} - U_{z} \geq \left(Z\epsilon\right)_{y} - \left(Z\epsilon\right)_{z} \ \forall z \in \mathcal{Y}_{0} \setminus \left\{y\right\}\right).$$

THE PURE CHARACTERISTICS MODEL IN DIMENSION 1

▶ When d=1 (scalar characteristics), one has $\sigma_{y}\left(U\right)=\Pr\left(U_{y}-U_{z}\geq\left(\xi_{y}-\xi_{z}\right)\varepsilon\;\forall z\in\mathcal{Y}_{0}\backslash\left\{ y\right\} \right)$, and thus

$$\sigma_{y}\left(U\right) = \Pr\left(\max_{z: \xi_{y} > \xi_{z}} \left\{\frac{U_{y} - U_{z}}{\xi_{y} - \xi_{z}}\right\} \leq \epsilon \leq \min_{z: \xi_{y} < \xi_{z}} \left\{\frac{U_{y} - U_{z}}{\xi_{y} - \xi_{z}}\right\}\right)$$

with the understanding that $\max_{z \in \emptyset} f_z = -\infty$ and $\min_{z \in \emptyset} f_z = +\infty$.

▶ Therefore, letting \mathbf{F}_{ϵ} be the c.d.f. associated with the distribution of ϵ , one has a closed-form expression for $\sigma_{\mathbf{v}}$:

$$\sigma_{y}\left(U\right) = \mathbf{F}_{\epsilon}\left(\left[\max_{z:\xi_{y}>\xi_{z}}\left\{\frac{U_{y}-U_{z}}{\xi_{y}-\xi_{z}}\right\}, \min_{z:\xi_{y}<\xi_{z}}\left\{\frac{U_{y}-U_{z}}{\xi_{y}-\xi_{z}}\right\}\right]\right)$$

THE PROBIT MODEL

▶ When \mathbf{P}_{ϵ} is the $\mathcal{N}\left(0,S\right)$ distribution, then the pure characteristics model is called a Probit model; in this case,

$$\varepsilon \sim \mathcal{N}\left(0,\Sigma\right) \text{ where } \Sigma = \textit{ZSZ}^\intercal.$$

- ▶ Note the distribution ε will not have full support unless $d \ge |\mathcal{Y}|$ and Z is of full rank.
- ightharpoonup Computing σ in the Probit model thus implies computing the mass assigned by the Gaussian distribution to rectangles of the type

$$[I_y, u_y]$$
.

When Σ is diagonal (random utility terms are i.i.d. across alternatives), this is numerically easy. However, this is computationally difficult in general (more on this later).

THE RANDOM COEFFICIENT LOGIT MODEL (1)

► The random coefficient logit model (Berry, Levinsohn and Pakes, 1995) may be viewed as an interpolant between the random characteristics model and the logit model. In this case,

$$\varepsilon = (1 - \lambda) Z\epsilon + \lambda \eta$$

where $\epsilon \sim \mathbf{P}_{\epsilon}$, η is an EV1 distribution independent from the previous term, and λ is a interpolation parameter ($\lambda = 1$ is the logit model, and $\lambda = 0$ is the pure characteristics model).

▶ In this case, one may compute the Emax operator as

$$\begin{split} G\left(U\right) &= \mathbb{E}\left[\max_{y \in \mathcal{Y}_0} \left\{U_y + \left(1 - \lambda\right) \left(Z\epsilon\right)_y + \lambda \eta_y\right\}\right] \\ &= \mathbb{E}\left[\mathbb{E}\left[\max_{y \in \mathcal{Y}_0} \left\{U_y + \left(1 - \lambda\right) \left(Z\epsilon\right)_y + \lambda \eta_y\right\} | \epsilon\right]\right] \\ &= \mathbb{E}\left[\lambda \log \sum_{y \in \mathcal{Y}_0} \exp\left(\frac{U_y + \left(1 - \lambda\right) \left(Z\epsilon\right)_y}{\lambda}\right)\right] \end{split}$$

THE RANDOM COEFFICIENT LOGIT MODEL (2)

► Recall

$$G\left(U\right) = \mathbb{E}\left[\lambda\log\sum_{y\in\mathcal{Y}_{0}}\exp\left(\frac{U_{y}+\left(1-\lambda\right)\left(Z\epsilon\right)_{y}}{\lambda}\right)\right].$$

► The demand map in the random coefficients logit model is obtained by derivation of the expression of the Emax, i.e.

$$\sigma_{y}\left(U\right) = \mathbb{E}\left[\frac{\exp\left(\frac{U_{y} + (1 - \lambda)(Z\epsilon)_{y}}{\lambda}\right)}{\sum_{y' \in \mathcal{Y}_{0}} \exp\left(\frac{U_{y'} + (1 - \lambda)(Z\epsilon)_{y'}}{\lambda}\right)}\right].$$

II. SIMULATION METHODS

- ▶ In a number of cases, one cannot compute the choice probabilities $\sigma\left(U\right)$ using a closed-form expression. In this case, we need to resort to simulation to compute G, G^* , σ and σ^{-1} .
- ► The idea is that:
 - ► one is able to compute G and G* for discrete distributions (more on this later)
 - ▶ the sampled versions of G, G^* , σ and σ^{-1} converge to the populations objects when the sample size is large.

ACCEPT-REJECT SIMULATOR

▶ One simulates N points $\varepsilon^i \sim P$. The Emax operator associated with the empirical sample distribution P_N is

$$G_N = N^{-1} \sum_{i=1}^{N} \max_{y \in \mathcal{Y}} \left\{ U_y + \varepsilon_y^i \right\}$$

and the demand map is given by

$$\sigma_{N,y}\left(U\right) = N^{-1} \sum_{i=1}^{N} 1\left\{U_{y} + \varepsilon_{y}^{i} \geq U_{z} + \varepsilon_{z}^{i} \ \forall z \in \mathcal{Y}_{0}\right\}$$

▶ In the literature, σ_N is called the *accept-reject simulator*.

THE GHK ESTIMATOR: DESCRIPTION (1)

- ► GHK simulator (Geweke, Hajivassiliou and Keane) improves on the AR simulator.
- \blacktriangleright Without loss of generality, we shall focus on the market share of y=0, and label the elements of \mathcal{Y} as $\mathcal{Y} = \{1, ..., M\}$ where $M = |\mathcal{Y}|$. Then if \mathbf{F}_{η} is the c.d.f. of the random vector η valued in $\mathbb{R}^{\mathcal{Y}}$ defined by $\eta_{v} := \varepsilon_{v} - \varepsilon_{0}$ for $z \in \mathcal{Y}$, then

$$\mu_{0}=1-1_{\mathcal{Y}}^{\prime}\nabla G\left(U\right)=\mathbf{F}_{\eta}\left(z\right),$$

where $z_v = -U_v$, for all $y \in \mathcal{Y}$.

▶ Note that $\mathbf{F}_{\eta}(z) = \Pr(\eta_1 \leq z_1, ..., \eta_M \leq z_M)$ can be expressed as

$$\mu_0 = \prod_{i=1}^{M} \Pr\left(\eta_i \le z_i | \eta_1 \le z_1, ... \eta_{j-1} \le z_{j-1}\right) \tag{1}$$

with the understanding that the first term in this product (associated with i=1) is simply the unconditional probability distribution $\Pr(\eta_1 < z_1).$

THE GHK ESTIMATOR: DESCRIPTION (2)

- ▶ The fundamental assumption behind the GHK method is that the Rosenblatt quantile associated with the distribution of η is known.
- ▶ Recall from the exercise discussed in the previous lecture that the Rosenblatt quantile is the map T such that $T\#\mu=P$, and such that the Jacobian DT of T is lower triangular with nonnegative diagonal. That is,

$$\begin{cases} \eta_{1} = T_{1}(U_{1}) \\ \eta_{2} = T_{2}(U_{1}, U_{2}) \\ ... \\ \eta_{M} = T_{M}(U_{1}, U_{2}, ..., U_{M}) \end{cases},$$

where $U \sim U([0,1]^d)$, and $T_i(u)$ depends only on $u_1,...,u_i$ and is a nondecreasing function of u_i . In order to evaluate quantity $\mathbf{F}_{\eta}(z)$ in (1), one needs to evaluate $\pi_j = \Pr(\eta_j \leq z_j | \eta_1 \leq z_1,...\eta_{j-1} \leq z_{j-1})$, that is

$$\pi_{j} = \mathbb{E}\left[1\left\{T_{j}\left(U_{1}, U_{2}, ..., U_{j}\right) \leq z_{i}\right\} \middle| T_{1}\left(U_{1}\right) \leq z_{1}, ..., T_{j-1}\left(U_{1}, U_{2}, ..., U_{j-1}\right)\right]$$

THE GHK ESTIMATOR: DESCRIPTION (3)

- ▶ Denote $T_i^{-1}(z; u_1, ..., u_{i-1})$ the inverse of $u_i \mapsto T_i^{-1}(u_1, ..., u_{i-1}, u_i)$ for fixed values of $u_1, ..., u_{i-1}$.
- ▶ Then, observe that if $\tilde{U} \sim U([0,1]^d)$, and if

$$\begin{cases}
\hat{U}_{1} = \tilde{U}_{1} T_{1}^{-1} (z_{1}) \\
\hat{U}_{2} = \tilde{U}_{2} T_{2}^{-1} (z_{2}; \hat{U}_{1}) \\
... \\
\hat{U}_{M} = \tilde{U}_{M} T_{M}^{-1} (z_{M}; \hat{U}_{1}, ..., \hat{U}_{M-1})
\end{cases} (3)$$

Then the conditional expectation

$$\pi_{j} = \mathbb{E}\left[1\left\{T_{j}\left(U_{1}, U_{2}, ..., U_{j}\right) \leq z_{i}\right\} \middle| T_{1}\left(U_{1}\right) \leq z_{1}, T_{2} \leq etc.\right]$$

coincides with the unconditional expectation

$$\pi_j = \mathbb{E}\left[T_j^{-1}(z_j; \hat{U}_1, \hat{U}_2, ..., \hat{U}_{j-1})\right].$$
(4)

THE GHK SIMULATOR AND IMPORTANCE SAMPLING

- ► The GHK simulator can be interpreted as an importance sampling simulation procedure.
- ► Indeed, expression

$$\pi_{j} = \mathbb{E}\left[1\left\{T_{j}\left(U_{1}, U_{2}, ..., U_{j}\right) \leq z_{i}\right\} \middle| T_{1}\left(U_{1}\right) \leq z_{1}, T_{2} \leq etc.\right]$$

is a conditional expectation; one may compute it by accept-reject but this is computationally suboptimal, as it leads us to discard a fraction of draws – which can be a significant fraction.

► In contrast, in expression

$$\pi_{j} = \mathbb{E}\left[T_{j}^{-1}\left(z_{j}; \hat{U}_{1}, \hat{U}_{2}, ..., \hat{U}_{j-1}\right)\right].$$

is an unconditional expectation; one shall compute it by drawing K i.i.d. draws of $\tilde{U} \sim U([0,1]^d)$, computing the \hat{U} 's, and averaging over all the values of $T_j^{-1}(\hat{U}_1,\hat{U}_2,...,\hat{U}_{j-1},z_i)$ simulated that way. In the second method, we have not discarded any draws, which is more efficient.

THE GHK ALGORITHM

Algorithm.

For k=1,...K: Draw $\tilde{U}^k \sim \mathcal{U}([0,1]^d)$. Compute $(\hat{U}_1^k,...,\hat{U}_M^k)$ from $(\tilde{U}_1^k,...,\tilde{U}_M^k)$ using transformation (3). Compute $\pi_j^K = K^{-1}\sum_{k=1}^K T_j^{-1}\left(z_j;\hat{U}_1^k,\hat{U}_2^k,...,\hat{U}_{j-1}^k\right)$ for j=1,...,M. Return the GHK simulator

$$\mu_0 = \prod_{j=1}^M \pi_j^K.$$

Remark: The practical difficulty with the implementation of this algorithm is the knowledge of the Rosenblatt quantile in closed form. A leading example where this object is readily available is given by the case when \boldsymbol{P} is Gaussian, which is called the probit model.

THE GHK ESTIMATOR FOR THE PROBIT MODEL

▶ The Probit model is characterized by $P = \mathcal{N}\left(0, \Sigma\right)$, with Σ is a $M \times M$ symmetric semidefinite positive matrix, hence $cov\left(\varepsilon_{y}, \varepsilon_{y'}\right) = \Sigma_{yy'}$. In this case, the Rosenblatt quantile is known. Let $\Sigma = LL^{\mathsf{T}}$ be the Choleski decomposition of Σ , where L is lower triangular with a positive diagonal. Then the Rosenblatt quantile T is such that

$$\begin{cases} T_{1}\left(u\right) = L_{11}\Phi^{-1}\left(u_{1}\right) \\ T_{2}\left(u\right) = L_{21}\Phi^{-1}\left(u_{1}\right) + L_{22}\Phi^{-1}\left(u_{2}\right) \\ \dots \\ T_{M}\left(u\right) = L_{M1}\Phi^{-1}\left(u_{1}\right) + \dots + L_{MM}\Phi^{-1}\left(u_{M}\right) \end{cases}$$

where Φ is the c.d.f. of the standard normal (univariate) distribution. In this case, \hat{U} is obtained from $U \sim \mathcal{U}\left(\left[0,1\right]^{M}\right)$ by

$$\begin{cases} \hat{U}_{1} = \tilde{U}_{1}\Phi\left(\frac{z_{1}}{L_{11}}\right) \\ \hat{U}_{2} = \tilde{U}_{2}\Phi\left(\frac{z_{2}-L_{21}\Phi^{-1}(\hat{U}_{1})}{L_{22}}\right) \\ \dots \\ \hat{U}_{M} = \tilde{U}_{M}\Phi\left(\frac{z_{M}-L_{M1}\Phi^{-1}(\hat{U}_{1})\dots-L_{M(M-1)}\Phi^{-1}(\hat{U}_{M-1})}{L_{MM}}\right) \end{cases}$$

McFadden's SARS

▶ McFadden's smoothed accept-reject simulator (SARS) consists in sampling $\varepsilon \sim P$: $\varepsilon^1, ..., \varepsilon^N$, and replacing the max by the smooth-max

$$\sigma_{N,T,y}\left(U\right) = \sum_{i=1}^{N} \frac{1}{N} \frac{\exp\left(\left(U_{y} + \varepsilon_{y}^{i}\right)/T\right)}{\sum_{z} \exp\left(\left(U_{z} + \varepsilon_{z}^{i}\right)/T\right)}$$

▶ One seeks *U* so that the induced choice probabilities are *s*, that is

$$s_y = \sum_{i=1}^{N} \frac{1}{N} \frac{\exp\left(\left(U_y + \varepsilon_y^i\right)/T\right)}{\sum_z \exp\left(\left(U_z + \varepsilon_z^i\right)/T\right)}.$$

► The associated Emax operator is

$$G_{N,T}(U) = \mathbb{E}_{\mathbf{P}_{N}}\left[G_{\text{logit}}\left(U + \varepsilon^{i}\right)\right]$$

so the underlying random utility structure is a random coefficient logit.

III. THE INVERSION THEOREM

THEOREM (G AND SALANIÉ)

Consider a solution $(u(\varepsilon), v_y)$ to the dual Monge-Kantorovich problem with cost $\Phi(\varepsilon, y) = \varepsilon_y$, that is:

$$\min_{u,v} \int u(\varepsilon) d\mathbf{P}(\varepsilon) + \sum_{y \in \mathcal{Y}_0} v_y s_y$$

$$s.t. \ u(\varepsilon) + v_v \ge \Phi(\varepsilon, y)$$
(5)

Then:

(i)
$$U = \sigma^{-1}(s)$$
 is given by $U_y = v_0 - v_y$.

(ii) The value of Problem (5) is $-G^*(s)$.

THE INVERSION THEOREM: PROOF

PROOF.

 $\sigma^{-1}(s) = \arg\max_{U:U_0=0} \left\{ \sum_{y \in \mathcal{Y}} s_y U_y - G(U) \right\}$, thus, letting v = -U, v is the solution of

$$\min_{v:v_0=0} \left\{ \sum_{y\in\mathcal{Y}_0} s_y v_y + G(-v) \right\}$$

which is exactly problem (5).



INVERSION OF THE PURE CHARACTERISTICS MODEL

- ▶ It follows from the inversion theorem that the problem of demand inversion in the pure characteristics model is a semi-discrete transport problem, a point made in Bonnet, G and Shum (2017).
- ► Indeed, the correspondence is:
 - ▶ an alternative y is a fountain
 - ► the characteristics of an alternative is a fountain location
 - the systematic utility associated with alternative y is minus the price of fountain y
 - ▶ the market share of altenative *y* coindides with the capacity of fountain *y*
 - ullet the random vector ϵ is the location of an inhabitant

McFadden's SARS and regularized OT

► Cf. Bonnet, G. and Shum (2017). Let $u_i = T \log \sum_z \exp \left((U_z + \varepsilon_z^i) / T \right)$. One has

$$\left\{ \begin{array}{l} s_y = \sum_{i=1}^N \frac{1}{N} \exp\left((U_y - u_i + \varepsilon_y^i)/T\right) \\ \frac{1}{N} = \sum_y \frac{1}{N} \exp\left((U_y - u_i + \varepsilon_y^i)/T\right) \end{array} \right. .$$

▶ As a result, (u_i, U_y) are the solution of the regularized OT problem

$$\min_{u,U} \sum_{i=1}^{N} \frac{1}{N} u_i - \sum_{i,y} s_y U_y + \sum_{i,y} \frac{1}{N} \exp\left((U_y - u_i + \varepsilon_y^i) / T \right).$$

BLP'S CONTRACTION MAPPING

► Consider the IPFP algorithm for solving the latter problem:

$$\left\{ \begin{array}{l} \exp\left(u_i^{k+1}/T\right) = \sum_z \exp\left((U_z^k + \varepsilon_z^i)/T\right) \\ \exp U_y^{k+1}/T = \frac{N s_y}{\sum_{i=1}^N \exp\left((-u_i^{k+1} + \varepsilon_y^i)/T\right)} \end{array} \right.$$

► This rewrites as

$$\exp U_y^{k+1}/T = \frac{Ns_y}{\sum_{i=1}^N \frac{\exp(\varepsilon_y^i/T)}{\sum_z \exp((U_z^k + \varepsilon_z^i)/T)}}, \text{ i.e.}$$

$$U_y^{k+1} = T \log s_y - T \log \sum_{i=1}^N \frac{1}{N} \frac{\exp(\varepsilon_y^i/T)}{\sum_z \exp((U_z^k + \varepsilon_z^i)/T)}$$

which is exactly the contraction mapping algorithm of Berry, Levinsohn and Pakes (1995, appendix 1).

Section 2

CODING

- ► We shall code the AR simulator for the probit model and then invert it using the inversion theorem.
- ► Take a vector of systematic utilities: $U_{-V} = c(1.6, 3.2, 1.1, 0)$
- ► Simulate the market shares using the AR simulator:
 epsilon_iy = matrix(rnorm(nbDraws*nbY),ncol=nbY) %*%
 SqrtCovar
 u_iy = t(t(epsilon_iy)+U_y)
 ui = apply(X = u_iy, MARGIN = 1, FUN = max)
 s_y = apply(X = u_iy ui, MARGIN = 2,FUN = function(v)
 (length(which(v==0)))) / nbDraws

INVERTING THE MARKET SHARES

► To invert the market share, simply run the optimal assignment problem:

```
A1 = kronecker(matrix(1,1,nbY),sparseMatrix(1:nbDraws,1:nbDraws))
A2 = kronecker(sparseMatrix(1:nbY,1:nbY),matrix(1,1,nbDraws))
A = rbind2(A1,A2)
result = gurobi (
list(A=A,obj=c(epsilon_iy),modelsense="max",
rhs=c(rep(1/nbDraws,nbDraws),s_y) ,sense="="),
params=list(OutputFlag=0) )
Uhat_y = - result$pi[(1+nbDraws):(nbY+nbDraws)] +
result$pi[(nbY+nbDraws)]
```