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//===== BOF
// FILE FUNC: Generate a sequence of bytes & TRANSMIT them out the cc2500.
//           Subsequent Transmissions are triggered by a roll-over timer.
//-----

#include "msp430x22x4.h"          // chip-specific macros & defs
#include "stdint.h"              // MSP430 data type definitions
#include "wireless-v2.h"         // Wireless setup & function defs

typedef union
{ uint8_t  u8[4];
  uint32_t u32;
} Uint32Payload_t;

//-----
// Func:  Timer A ISR - Just Pull CPU out of sleep mode to retn to next cmd
// Args:  None
// Retn:  None
//-----
#pragma vector=TIMERA0_VECTOR
__interrupt void TimerAISR(void)
{
    __bic_SR_register_on_exit(CPUOFF);    // wake up on exit
} // end function "TimerAISR"

// -----
// Func:  Forms appropriate data packet and uses canned wireless function
//        RFSendPacket to send the data to the CC2500 chip and have it
//        transmit the data.
// Args:  none
// Retn:  none
// -----
void TxRfPacket(void)
{
    P1OUT ^= 0x03;                // Start of TX => toggle LEDs
    static uint8_t pktLen = 5;     // Fix Packet size
    static Uint32Payload_t pld.u32 = 0x0000000F;
    static uint8_t pktData[5] = {0x04,pld.u8[0],pld.u8[1],pld.u8[2],pld.u8[3]};
    // Contents:  pktData[4] = {Pyld leng, data, data, data, data}
    // Note: If addr-mode was enabled, then 2nd byte would be dev. addr, not data

    RFSendPacket(pktData, pktLen); // Activate TX mode & transmit the packet

    // Double the value of the payload until it equals 0xF0000000
    if (pld.u32 == 0xF0000000)
    {
        pld.u32 = 0x0000000F;
    }
}

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    }
    else
    {
        pld.u32 *= 2;
    }

    TI_CC_SPIStrobe(TI_CCxxx0_SIDLE);    // Set cc2500 to IDLE mode.
                                         // TX mode re-activates in RFSendPacket
                                         // w/ AutoCal @ IDLE to TX Transition
}

//-----
// Func:  Setup MSP430 Ports & Clocks, and reset & config cc2500 chip
// Args:  none
// Retn:  none
//-----
void SetupAll(void)
{
    volatile uint16_t delay;

    for(delay=0; delay<650; delay++){    // Empirical: cc2500 Pwr up settle

        // set up clock system
        BCSCTL1 = CALBC1_8MHZ;            // set DCO = 8MHz
        DCOCTL  = CALDCO_8MHZ;            // set DCO = 8MHz
        BCSCTL2 |= DIVS_3;                 // SMCLK = MCLK/8 = 1MHz

        // TimerA config
        TACTL    = TASSEL_2 | ID_3 | MC_1; // TA uses SMCLK/8, in Up mode
        TACCR0   = 60000;                  // ~480 msec @ 1/8 MHz
        TACCTL0  = CCIE;                    // enable TA CCR0 IRQ

        // LED Port config
        P1DIR |= 0x03;                     // Set LED pins to output
        P1OUT &= ~0x03;                     // Clear LEDs

        // Wireless Initialization
        P2SEL = 0;                          // P2.6, P2.7 = GD00, GD02 (GPIO)
        TI_CC_SPISetup();                    // Init SPI port for cc2500
        TI_CC_PowerupResetCCxxx();           // Reset cc2500
        writeRFSettings();                   // Put settings to cc2500 config regs

        TI_CC_SPIWriteReg(TI_CCxxx0_CHANNR, 0); // Set Your Own Channel Number
                                                // only AFTER writeRFSettings

        for(delay=0; delay<650; delay++){    // Empirical: Let cc2500 finish setup

            P1OUT = 0x02;                     // Setup done => Turn on green LED
        }
    }
}

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// -----  
void main()  
{ WDTCTL = WDTPW + WDTHOLD; // halt watchdog  
  SetupAll();                // Setup all ports and wireless settings  
  while(1)                    // Tx one data packet at each timer A IRQ  
  {  
    TxRfPacket();              // Tx one data packet  
    __bis_SR_register(CPUOFF + GIE); // sleep until next timer A IRQ  
  }  
}  
// ===== EOF
```