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// ===== BOF
// FILE FUNC:  receive a sequence of ASCII characters over the cc2500
//              (at 3-chars per RF packet). Then print them on the host PC
// -----

#include "stdint.h"                // MSP430 data type definitions
#include "msp430x22x4.h"           // Mammoth MSP430-specific macros & defs
#include "wireless-v2.h"           // Mammoth cc2500 setup & function defs

//-----
// Func:  Packet Received ISR:  triggered by falling edge of GD00.
//        Parses pkt & prints entire packet data bytes to the host PC.
// Args:  None
// Retn:  None
//-----
#pragma vector=PORT2_VECTOR        // cc2500 pin GD00 is hardwired to P2.6
__interrupt void PktRxedISR(void)
{
    // Buffer Len for rxPkt = only data bytes;
    // pkt size byte not incl b/c it is stripped off by RFReceivePacket func.
    // IF address check was enabled, THEN would need 1 more byte for device addr

    static uint8_t len = 4;         // Packet Len = 3 bytes (data only)
    uint8_t status[2];             // Buffer to store pkt status bytes
    uint8_t crcOk = 0;             // Flag that pkt was received w/ good CRC

    if(TI_CC_GD00_PxIFG & TI_CC_GD00_PIN) // chk GD00 bit of P2 IFG Reg
    {
        crcOk = RFReceivePacket(rxPkt, &len, status); // Get packet from cc2500
        TI_CC_GD00_PxIFG &= ~TI_CC_GD00_PIN; // Reset GD00 IRQ flag
    }

    if(crcOk) // If RXed pkt is valid
        P1OUT ^= 0x03; // Pkt RXed => Toggle LEDs

    TI_CC_SPIStrobe(TI_CCxxx0_SIDLE); // Set cc2500 to idle mode.
    TI_CC_SPIStrobe(TI_CCxxx0_SRX); // Set cc2500 to RX mode.
    // AutoCal @ IDLE to RX Transition

    __bic_SR_register_on_exit (CPUOFF); // wake CPU on exit so it can print

//-----
// FUNC:  Setup MSP430 Ports & Clocks, reset & config cc2500
// ARGS:  none
// RETN:  none
//-----
void SetupAll(void)
{
    volatile uint16_t delay;

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for(delay=0; delay<650; delay++);    // Empirical: cc2500 Pwr up settle

// set up clock system
BCSCTL1 = CALBC1_8MHZ;                // set DCO = 8MHz
DCOCTL = CALDCO_8MHZ;                // set DCO = 8MHz
BCSCTL2 |= DIVS_3;                    // SMCLK = MCLK/8 = 1MHz

// LED Port config
P1DIR |= 0x03;                        // Set both LED pins to output
P1OUT &= ~0x03;                       // Clear both LEDs

// Wireless Initialization
P2SEL = 0;                            // P2.6, P2.7 = GD00, GD02 (GPIO)
TI_CC_SPISetup();                     // Initialize SPI port
TI_CC_PowerupResetCCxxx();            // Reset cc2500
writeRFSettings();                    // Send RF settings to config regs

TI_CC_GD00_PxIES |= TI_CC_GD00_PIN;   // IRQ on GD00 fall. edge (end of pkt)
TI_CC_GD00_PxIFG &= ~TI_CC_GD00_PIN; // Clear GD00 IRQ flag
TI_CC_GD00_PxIE |= TI_CC_GD00_PIN;    // Enable GD00 IRQ
TI_CC_SPIStrobe(TI_CCxxx0_SRX);        // Init. cc2500 in RX mode.

TI_CC_SPIWriteReg(TI_CCxxx0_CHANNR, 0); // Set Your Own Channel Number
                                         // AFTER writeRFSettings (???)

for(delay=0; delay<650; delay++);    // Empirical: Let cc2500 finish setup

P1OUT = 0x02;                         // Setup done => Turn on green LED
}

// -----
void main()
{
    WDTCTL = WDTPW + WDTHOLD;          // halt watchdog

    volatile uint8_t rxPkt[4];         // Buffer to store received pkt payload
    uint8_t str[8];                    // Buffer to parse payload into ASCII str
    uint8_t i = 0;                     // Index for rxPkt
    uint8_t j = 0;                     // Index for str
    SetupAll();                        // Setup clocks, ports & cc2500 settings
    while (1)
    {
        __bis_SR_register(CPUOFF + GIE); // sleep til Pkt RX
        for (i = 0; i < 4; i++)
        {
            j = i + i;                 // Calc. index of str
            str[j] = rxPkt[i] & 0x0F;   // Get first nybble of byte
            str[j+1] = (rxPkt[i] & 0xF0 >> 4) & 0x0F; // Get second nybble of byte
        }
    }
}

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// Convert hex to corresponding ASCII value
for (j = 0; j < 8; j ++)
{
    if (str[j] < 10) // if the nybble is a number
    {
        str[j] += 0x30; // add 48
    }
    else // if the nybble is a letter
    {
        str[j] += 0x37; // add 55
    }
}

printf ("%c%c%c%c%c%c%c%c\n", str[0], str[1], str[2], str[3],
        str[4], str[5], str[6], str[7]); // print str
}
}

// ===== EOF

```