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QUESTION

Student Name: Ajita Shree Roll Number: 20111262 Date: November 27, 2020

#### Solution

Second Order Optimization for Logistic Regression Logistic Regression model with label  $y_n \in \{0,1\}$  has loss function as  $L(w) = -\sum_{n \in N} (y_n w^T x_n - \log(1 + exp(w^T x_n)))$ 

**Prove:** Second order optimization based update equation  $w^{(t+1)} = w^t - H^{(t)-1}g^{(t)}$ , where H is Hessian and g is gradient, reduces to solving importance weighted regression problem of the form  $w^{(t+1)} = argmin_w \sum_{n \in N} \gamma_n^{(t)} (y_n'^{(t)} - w^T x_n)^2$  where  $\gamma_n$  is the importance of nth training example  $y_n'$  denote modified real valued label.

• Gradient, 
$$\frac{dL(w)}{dw}$$
 can be written as  $-\sum_{n\in N} y_n x_n + \sum_{n\in N} \frac{exp(w^T x_n)x_n}{1 + exp(w^T x_n)}$ 

• Hessian, 
$$\frac{d^2L(w)}{dw^2} = \sum_{n \in N} \frac{exp(w^Tx_n)x_n^Tx_n}{(1 + exp(w^Tx_n))^2}$$

• Substituting the values in the **Update Equation**,

$$w^{(t+1)} = w^t + \sum_{n \in \mathbb{N}} \frac{(1 + exp(w^T x_n))^2}{exp(w^T x_n)} (x_n^T x_n)^{-1} \left\{ y_n x_n - \frac{exp(w^T x_n) x_n}{1 + exp(w^T x_n)} \right\}$$

ullet Taking  $H^{-1}$  term out of the equation

$$w^{(t+1)} = \frac{(1 + exp(w^Tx_n)^2}{exp(w^Tx_n)} (x_n^Tx_n)^{-1} \left\{ \frac{exp(w^Tx_n)}{(1 + exp(w^Tx_n))^2} (x_n^Tx_n)w^t + y_nx_n - \frac{exp(w^Tx_n)x_n}{1 + exp(w^Tx_n)} \right\}$$

• On further simplification,

$$w^{(t+1)} = \frac{(1 + exp(w^T x_n))^2}{exp(w^T x_n)} (x_n^T x_n)^{-1} \left\{ \frac{exp(w^T x_n)}{(1 + exp(w^T x_n))^2} w^{tT}(x_n) + y_n - \frac{exp(w^T x_n)}{1 + exp(w^T x_n)} \right\} x_n$$

• Alternatively, using  $\sigma(w^T x) = \frac{exp(w^T x_n)}{1 + exp(w^T x_n)}$ , we have

$$w^{(t+1)} = \frac{(1 + exp(w^T x_n))}{\sigma(w^T x_n)} (x_n^T x_n)^{-1} \left\{ y_n - \sigma(w^T x_n) \left\{ \frac{w^{tT}(x_n)}{(1 + exp(w^T x_n))} - 1 \right\} \right\} x_n$$
 (1)

- Considering Importance weighted regression problem,
- $w^{(t+1)} = argmin_w \sum_{n \in N} \gamma_n^{(t)} (y_n'^{(t)} w^T x_n)^2$
- Differentiating above equation and equating it to 0, we have

$$w = (\sum_{n \in N} \gamma_n x_n^T x_n)^{-1} (\sum_{n \in N} y_n' x_n)$$
 (2)

- Comparing equation 1 and equation 2, we will get the following values
- $\gamma_n = \frac{\sigma(w^T x_n)}{(1 + exp(w^T x_n))}$ ; Also,can be written as  $\gamma_n = \sigma(w^T x_n)(1 \sigma(w^T x_n))$  (alternatively, called constant term in the Hessian matrix).
- $y' = y_n \sigma(w^T x_n) \{ \frac{w^{tT}(x_n)}{(1 + exp(w^T x_n))} 1 \}$
- The  $\gamma_n$  makes intuitive sense here because
  - We know, in logistic regression,  $\mu_n = \sigma(w^T x)$  and likelihood function for a given point  $x_n$  can be defined by  $Bernoulli(\mu_n)$  with form  $Bernoulli(\mu_n) = \mu_n^{y_n} (1 \mu_n)^{(1-y_n)}$  and  $\gamma$  has a similar form.
  - More likely/important points will get more importance while predicting real-valued y'in the regression problem because of this form of  $\gamma$ .

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#### Solution

**Perceptron with Kernels** Perceptron updates have the form  $w = w + y_n x_n$ , the weight learned by perceptron can be written as  $w = \sum_{n \in \mathbb{N}} \alpha_n y_n x_n$  where  $\alpha_n$  is the number of times perceptron makes a mistake on example  $x_n$ 

Goal Enable perceptron to learn non-linear boundaries, using kernel k with feature map  $\phi$ . Give the kernalized variant of perceptron algorithm.

Kernel perceptron algorithm is stochastic gradient descent on the perceptron kernel loss.Let  $\phi$  defines the kernel mapping for data point x and kernel function  $K(x_m, x_n) = \phi(x_m)^T \phi(x_n)$  that is guaranteed to be always in the finite dimension.

- Step 1: Initialization: Initialize  $w = \sum_{n \in N} \alpha_n y_n x_n$  and  $\alpha_m = 0 \forall m \in N$ .
- Step 2: Pick a point  $(x_m, y_m)$  at random
- Step 3: Mistake Condition:  $y_m w^{(t)T} \phi(x_m) < 0$

$$-\sum_{n\in N} (y_m \alpha_n y_n \phi^T(x_n) \phi(x_m)) < 0$$
  
$$-\sum_{n\in N} (y_m \alpha_n y_n K(x_n, x_m) < 0$$

- Step 4: Update Equation  $\alpha_m + = 1$  if mistake condition holds true.
- Step 5: Go to step 2 until no converged.

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# QUESTION 3

#### Solution

**SVM with unequal class importance** The primal formulation of SVM with unequal class importance is given by the following equation

$$min_{w,b,\zeta} \frac{||w||^2}{2} + \sum_{n \in N} C_{y_n} \zeta_n$$
$$s.t.y_n(w^T x_n + b) >= 1 - \zeta_n$$
$$\zeta_n >= 0, \forall n$$

• Lagrangian Problem of this modified SVM is

$$\min_{w,b,\zeta} \max_{\alpha > =0,\beta > =0} L(w,b,\zeta,\alpha,\beta)$$

$$= \frac{||w||^2}{2} + \sum_{n \in N} C_{y_n} \zeta_n + \sum_{n \in N} \alpha_n (1 - y_n (w^T x_n + b) - \zeta_n) - \sum_{n \in N} \beta_n \zeta_n$$

• Differentiating w.r.t. w, b,  $\zeta_n$ ,  $C_{y_n}$ , we get

- setting 
$$\frac{dL}{dw}=0$$
, we get  $\mathbf{w}=\sum_{n\in N}\alpha_ny_nx_n$   
- setting  $\frac{dL}{db}=0$ , we get  $\sum_{n\in N}\alpha_ny_n=0$   
- setting  $\frac{dL}{d\zeta_n}=0$ , we get  $C_{y_n}-\alpha_n-\beta_n=0$  and we know that  $\beta_n>=0$ . We will have  $\alpha_n<=C_{y_n}$   
- setting  $\frac{dL}{dC_{y_n}}=0$ , we get  $\zeta_n=0$ 

• Substituting all the values in the Lagrangian equation, we get

$$\begin{split} 1/2\sum_{m,n\in N}\alpha_{m}\alpha_{n}y_{m}y_{n}(x_{m}^{T}x_{n}) + \sum_{n\in N}(\alpha_{n}\zeta_{n} + \beta_{n}\zeta_{n}) + \sum_{n\in N}\alpha_{n} - \sum_{m,n\in N}\alpha_{m}\alpha_{n}y_{m}y_{n}(x_{m}^{T}x_{n}) \\ + \sum_{n\in N}\alpha_{n}y_{n}b - \sum_{n\in N}\alpha_{n}\zeta_{n} - \sum_{n\in N}\beta_{n}\zeta_{n} \end{split}$$

• The final form of the equation is:

$$\max_{\alpha_n < =Cy_n: \forall n \in N} \sum_{n \in N} \alpha_n - 1/2 \sum_{m,n \in N} \alpha_m \alpha_n y_m y_n (x_m^T x_n)$$
$$s.t. \sum_{n \in N} \alpha_n y_n = 0$$
$$\zeta_n = 0, \forall n \in N$$

- Intuitively, the key difference between this SVM and standard SVM is as follows:
  - The dual formulation of this SVM has an additional constraint on  $\zeta_n$  i.e.  $\zeta_n = 0$  which is making this formulation similar to that of hard margin SVM conceptually.
  - However, the dual formulation is exactly matching with soft margin SVM Only difference is that here nth term of  $\alpha$  is constraint by the respective  $C_{y_n}$  where as in standard SVM all  $\alpha$  terms are upper bounded by constant c
  - Intuitvely, if nth example is +, only possible prediction are and +. + would be correct prediction and would fall under the category of mis-classification of positive examples. Hence, it makes more sense if  $\alpha_n$  is bounded the  $C_+$ . Same logic applied for class.

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#### Solution

**SGD for k-means objective** The kmeans objective is given by  $\sum_{n \in N} \sum_{k \in K} z_{nk} ||x_n - \mu_k||^2$ . Assume  $\mu_{k \in K}$  are initialized randomly at the beginning of the algorithm. K-means can be made online by using following steps: 1) Taking random example  $x_n$  at a time and greedily assign it to best cluster.2) Updating the cluster means using SGD on objective L.

#### • How to solve step 1?

- Randomly select point  $x_{n'}$  from the data points (It can be a point that is not assigned to any cluster or in case of no new data points, it can be any point that is already being assigned to a cluster)
- Select the cluster greedily k' for  $x_{n'}$  which is the closest i.e.  $k' = \min_k ||x_{n'} \mu_k||^2$
- Update z matrix for  $x_{n'}$
- What will be the SGD based cluster mean update equations for step 2? Intuitively, why does the update make sense.
  - SGD for updating the mean  $\mu_{k'}$

$$\frac{dL}{d\mu_{k'}} = \frac{d\sum_{n \in N} z_{nk'} ||x_n - \mu_{k'}||^2}{d\mu_{k'}}$$

$$\frac{dL}{d\mu_{k'}} = -2\sum_{n \in N} z_{nk'}(x_n - \mu_{k'})$$

- Update equation:

$$\mu_{k'+1} = \mu_{k'} + \eta_{k'} 2 \sum_{n \in N} z_{nk'} (x_n - \mu_{k'})$$

- The update make sense because the gradient term signifies the sum of euclidean distance of the current assignment of data points to that cluster. Given right  $\eta$  term, it will be exactly equal to the mean formula (typically used in k-means algorithms to compute the mean).
- SGD requires a step size. For your derived SGD update, suggest a good choice of step size (mention why it is a good choice).
  - In each iteration of SGD, cluster assignment of only one point  $x'_n$  is changed as per the algorithm. Hence,  $n_{k'}$  can be selected based on following scenarios.

\* Case 1:  $x_{n'}$  is added to k' cluster

$$\eta_{k'} = \frac{1}{2\sum_{n \in N} z_{nk'}} - \frac{\sum_{n \neq n'} z_{nk'}(x_n - \mu_k')}{2\sum_{n \neq n'} z_{nk'}}$$

First term of the  $\eta_{k'}$  will ensure the mean calculation for the updated assignments and second term will be the mean calculation for previous assignment (will be canceled out by  $\mu_{k'}$  in the update equation). Note that,in case of new data points, previous assignment will automatically not be considered as  $z_n$  vector will be all 0.

\* Case 2:  $x_{n'}$  is removed from k' cluster

$$\eta_{k'} = \frac{1}{2\sum_{n \in N} z_{nk'}} - \frac{\sum_{n} z_{nk'} (x_n - \mu'_k) + (x_{n'} + \mu_{k'})}{2(\sum_{n} z_{nk'} + 1)}$$

First term is similar to case 1 denoting mean of cluster with updated assignment; Second term is the mean of cluster when  $x_{n'}$  was the part of this previous cluster (2 in the denominator is to cancel terms in update equation). Note: This case will arise in case of there are no new data points and some already assigned  $x_n s$  got picked at random in the iterations.

\* Case 3: No update needed for cluster k' if the points are neither removed nor added in the cluster

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QUESTION

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#### Solution

**Kernel K-means**: Assume a kernel with infinite dimensional feature map, We can neither store the kernel induced feature set nor can store the cluster means in the kernel induced feature space.

- Sketch the K-means algorithms (initialization, cluster assignment and mean computation)
  - The Loss function for k-means is given by  $\sum_{n \in N} \sum_{k \in K} z_{nk} ||x_n \mu_k||^2$ .
  - The Loss function in the feature induced space can be written as

$$\sum_{n \in N} \sum_{k \in K} z_{nk} ||\phi(x_n) - \phi(\mu_k)||^2$$

On further solving

$$\sum_{n \in N} \sum_{k \in K} z_{nk} (\phi(x_n)^T \phi(x_n) + \phi(\mu_k)^T \phi(\mu_k) - 2\phi(x)\phi(\mu_k))$$

$$\sum_{n \in N} \sum_{k \in K} z_{nk} K(\phi(x_n), \phi(x_n)) + K(\phi(\mu_k), \phi(\mu_k)) - 2K(\phi(x_n), \phi(\mu_k))$$

– Substituting the RBF kernal value,  $K(x,z) = exp[-\gamma ||x-z||^2]$ 

$$\sum_{n \in N} \sum_{k \in K} z_{nk} (exp(-\gamma ||x_n - x_n||^2) + exp(-\gamma ||\mu_k - \mu_k||^2) - 2exp(-\gamma ||x_n - \mu_k||^2))$$

- Loss function for kernal k-means can be written as

$$L(X, Z, \mu) = \sum_{n \in N} \sum_{k \in K} z_{nk}(-2) exp(-\gamma ||x_n - \mu_k||^2))$$

- The initialization , cluster assignments and mean computation will remain same as k-means function using **ALT-OPT technique over** z **and**  $\mu$  to optimize above loss function as follows:
  - \* **Step1:** Fix  $\mu$  as  $\mu'$  find optimal z assignment as  $Z' = argmin_z L(X, Z, \mu')$
  - \* Step 2: Fix z as z' find optimal  $\mu$  as  $\mu' = argmin_{\mu}L(X, Z', \mu)$
  - \* Step 3: Go to step1 until not converged
- What is the difference between how cluster means are stored in kernel k means vs standard k-means

For kernel k means, we need not store kernel induced feature space mean for  $\mu$  as the loss function got reduced to the form with only  $x_n$  and  $\mu_k$ . We need to store  $\mu_k$  for k clusters similar to k-means.

• How does kernel k-means compares with standard k-means in terms of cost of input to cluster mean distance calculations

The cost of computing input to cluster mean distance is same as k-means O(NK). (Reason: Kernal k-means loss function is similar to loss function of k-means in terms of computation).

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## **QUESTION**

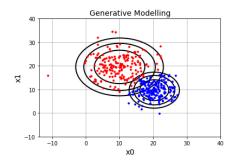
6

#### Solution - Part 1

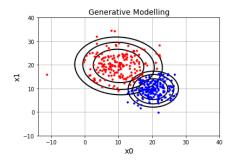
Implement the generative classification model assuming Gaussian class-conditional distributions of positive and negative class examples. Class prior are given as 0.5 in the question and also being verified for the given dataset.

#### Observation on data: binclass.txt

• On the 2-dimensional plane, the examples and the learned decision boundary using class conditionals to be to be  $N(\mu_+, \sigma_+^2 I_2)$  and  $N(\mu_-, \sigma_-^2 I_2)$  are as follows

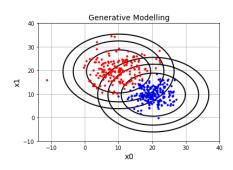


Diagonal Co-variance Matrix

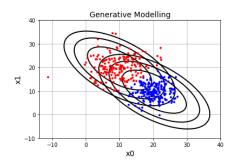


Full Co-variance Matrix

• The Results will be as follows assuming the Gaussian class-conditional distributions of the positive and negative examples to be  $N(\mu_+, \sigma^2 I_2)$  and  $N(\mu_-, \sigma^2 I_2)$ 

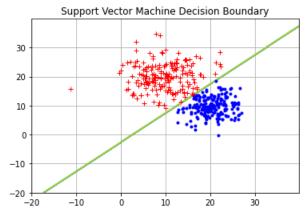


Diagonal Co-variance Matrix



Full Co-variance Matrix

• The decision boundary corresponding to linear SVM ( $svm.LinearSVC(C = 1, max_iter = 5000).fit(X, Y)$  from the sklearn library) is as follows:

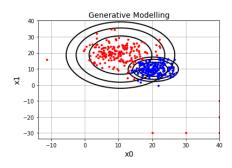


SVM Classifier: Dataset 1

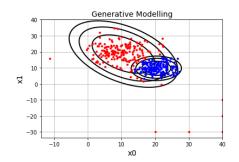
#### Solution - Part 2

#### Observation on data: binclassv2.txt

• On the 2-dimensional plane, the examples and the learned decision boundary using class-conditional to be to be  $N(\mu_+, \sigma_+^2 I_2)$  and  $N(\mu_-, \sigma_-^2 I_2)$  are as follows

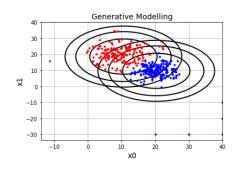


Diagonal Co-variance Matrix

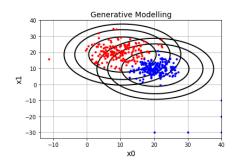


Full Co-variance Matrix

• The Results will be as follows assuming the Gaussian class-conditional distributions of the positive and negative examples to be  $N(\mu_+, \sigma^2 I_2)$  and  $N(\mu_-, \sigma^2 I_2)$ 

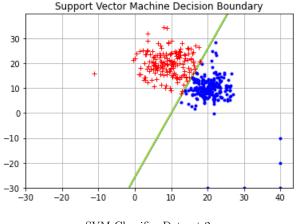


Diagonal Co-variance Matrix



Full Co-variance Matrix

• The decision boundary corresponding to linear SVM ( $svm.LinearSVC(C = 1, max_iter = 5000).fit(X, Y)$  from the sklearn library) is as follows:



SVM Classifier Dataset 2

#### Conclusion: Generative classification vs Linear-SVM

#### • Dataset: binclass.txt

- $-\{\sigma_+,\sigma_-\}$  for both classes: The contours for both the classes are more compact and there is a nice separation between the positive points (red) class versus the negative points (blue class). The shape of contour is similar in both diagonal co-variance matrix and full co-variance matrix. The accuracy achieved is 95.25
- $-\sigma$  for both classes: If  $\sigma$  is learned taking both classes together, the mean differs, the shape and breadth of both the classes matches. The accuracy achieved is 95
- SVM: The linear decision boundary is able to separate the points well. The accuracy achieved is 94.75
- As it can be seen that, the accuracy achieved on the train data for both generative classification as well SVM seems to be same.

#### • Dataset: binclassv2.txt

- $-\{\sigma_+,\sigma_-\}$  for both classes:In this case, significantly smaller contour size is learned for negative samples compared to positive samples. If we take full-co-variance matrix, we can see the diagonal Gaussian is learned for positive class. The best accuracy achieved is 95.5
- $-\sigma$  for both classes: As  $\sigma$  is same for both classes, the spread is similar and similar Gaussian is learnt irrespective of diagonal matrix or full covariance matrix. The best accuracy achieved is 93.75
- SVM: The linear boundary is shown in the diagram above. The accuracy achieved through linear SVM is 93.5.

Observing results on both the data, it can be concluded that generative classification will be slightly better than linear SVM in case of 2 class classification. It is also clearly evident that learning different  $\sigma_+$ , sigma for positive class and  $\sigma_-$ , sigma for negative class is able to learn probability distribution better, specially in the situations when spread of the data is very different.

### Implementation:

- The code will do generative classification and can run for multiple features at the time i.e. D>0
- Co-variance matrices capable of handling any shape of Gaussian i.e. all entries non-zero: Line 50-57 can be un commented to visualize this
- The Code can be easily scaled up for multiple classes at a time.
- Input path and file to be provided (main function).