PIC Microcontroller - 3

PIC Instruction Set (I)

Review: Data Memory Organization

- Made up of SFRs and GFRs
- Banking: 7Fh (128) bytes chunks
- Addressing Modes
 - Direct addressing:
 - 7 bit address (within bank)
 - RP1:RP0 selects bank
 - Indirect addressing:
 - Access to INDF causes indirect addressing
 - Actual memory address in IRP+FSR
- Special Function Registers
 - W, PC (PCL+PCLATH), FSR, INDF, STATUS
 - I/O Ports



- 35 instructions
- Each instruction is 1 word long (14 bits)
- Byte-oriented OPCODE f, F(W)
 - Source f: name of a SFR or a RAM variable
 - Destination F(W):
 - F if the destination is to be the same as the source register
 - W if the destination is to be the working register
- Bit-oriented OPCODE f, b
 - Bit address b (0≤b≤7)
- Literal and control OPCODE k
 - Literal value k

Byte-oriented file register operations

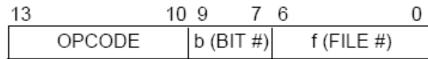
13 8 7 6 0 OPCODE d f (FILE #)

d = 0 for destination W

d = 1 for destination f

f = 7-bit file register address

Bit-oriented file register operations

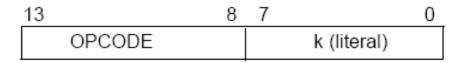


b = 3-bit bit address

f = 7-bit file register address

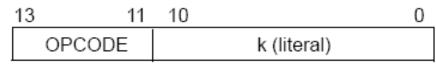
Literal and control operations

General



k = 8-bit immediate value

CALL and GOTO instructions only



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k = 11-bit immediate value

TABLE 13-2: PIC16F87X INSTRUCTION SET

Mnemonic, Operands		Description	Cycles	14-Bit Opcode				Status	Notes
				MSb			LSb	Affected	Notes
BYTE-ORIENTED FILE REGISTER OPERATIONS									
ADDWF	f, d	Add W and f	1	0.0	0111	dfff	ffff	C,DC,Z	1,2
ANDWF	f, d	AND W with f	1	0.0	0101	dfff	ffff	Z	1,2
CLRF	f	Clear f	1	0.0	0001	lfff	ffff	Z	2
CLRW	-	Clear W	1	0.0	0001	0xxx	xxxx	Z	
COMF	f, d	Complement f	1	0.0	1001	dfff	ffff	Z	1,2
DECF	f, d	Decrement f	1	0.0	0011	dfff	ffff	Z	1,2
DECFSZ	f, d	Decrement f, Skip if 0	1(2)	0.0	1011	dfff	ffff		1,2,3
INCF	f, d	Increment f	1	0.0	1010	dfff	ffff	Z	1,2
INCFSZ	f, d	Increment f, Skip if 0	1(2)	0.0	1111	dfff	ffff		1,2,3
IORWF	f, d	Inclusive OR W with f	1	0.0	0100	dfff	ffff	Z	1,2
MOVF	f, d	Move f	1	0.0	1000	dfff	ffff	Z	1,2
MOVWF	f	Move W to f	1	0.0	0000	lfff	ffff		
NOP	-	No Operation	1	0.0	0000	0xx0	0000		
RLF	f, d	Rotate Left f through Carry	1	0.0	1101	dfff	ffff	С	1,2
RRF	f, d	Rotate Right f through Carry	1	0.0	1100	dfff	ffff	С	1,2
SUBWF	f, d	Subtract W from f	1	0.0	0010	dfff	ffff	C,DC,Z	1,2
SWAPF	f, d	Swap nibbles in f	1	0.0	1110	dfff	ffff		1,2
XORWF	f, d	Exclusive OR W with f	1	0.0	0110	dfff	ffff	Z	1,2
BIT-ORIENTED FILE REGISTER OPERATIONS									
BCF	f, b	Bit Clear f	1	01	0 0bb	bfff	ffff		1,2
BSF	f, b	Bit Set f	1	01	01bb	bfff	ffff		1,2
BTFSC	f, b	Bit Test f, Skip if Clear	1 (2)	01	10bb	bfff	ffff		3
BTFSS	f, b	Bit Test f, Skip if Set	1 (2)	01	11bb	bfff	ffff		3
LITERAL AND CONTROL OPERATIONS									
ADDLW	k	Add literal and W	1	11	111x	kkkk	kkkk	C,DC,Z	
ANDLW	k	AND literal with W	1	11	1001	kkkk	kkkk	Z	
CALL	k	Call subroutine	2	10	0kkk	kkkk	kkkk		
CLRWDT	-	Clear Watchdog Timer	1	0.0	0000	0110	0100	TO,PD	
GOTO	k	Go to address	2	10	1kkk	kkkk	kkkk		
IORLW	k	Inclusive OR literal with W	1	11	1000	kkkk	kkkk	Z	
MOVLW	k	Move literal to W	1	11	00xx	kkkk	kkkk		
RETFIE	-	Return from interrupt	2	0.0	0000	0000	1001		
RETLW	k	Return with literal in W	2	11	01xx	kkkk	kkkk		
RETURN	-	Return from Subroutine	2	0.0	0000	0000	1000		
SLEEP	-	Go into standby mode	1	0.0	0000	0110	0011	TO,PD	
SUBLW	k	Subtract W from literal	1	11	110x	kkkk	kkkk	C,DC,Z	
XORLW	k	Exclusive OR literal with W	1	11	1010	kkkk	kkkk	Z	



Single Bit Manipulation

bcf f,b

Operation: Clear bit b of register f, where b=0 to 7

STATUS bits:

none

bsf f,b

Operation: Set bit b of register f, where b=0 to 7

Examples:

bcf PORTB, 0 ;Clear bit 0 off PORTB

bsf STATUS, C ;Set the Carry bit

bcf STATUS, RP1 ;

bsf STATUS, RP0 ;Select Bank 1

Clear/Move

```
clrw
                           ; Clear W register
                                                       STATUS bits:
 clrf f
                                                       clrw, clrf, movf: Z
                           ; Clear f register
                                                       movlw, movwf, swapf: none
 movlw k
                           ; move literal value k to W
 movwf f
                           ; move W to f
 movf f, f(W)
                                    : move f to F or W
 swapf f, F(W)
                                    ; swap nibbles of f, putting result in F or
Examples:
   clrf TEMP1
                          :Clear variable TEMP1
   movlw 5
                          ;load 5 into W
   movwf TEMP1
                          :move W into TEMP1
                          :Incorrect Syntax
   movwf TEMP1, F
                          :move TEMP1 into W
   movf TEMP1, W
          TEMP1, TEMP2
   movf
                          Incorrect Syntax
   swapf
         TEMP1, F
                          ;Swap 4-bit nibbles of TEMP1
   swapf
         TEMP1, W
                          ;Move TEMP1 to W, swap nibbles, leave TEMP1 unchanged
```

Increment/Decrement/Complement

```
incf f, F(W)
or W
decf f, F(W)
comf f, F(W)

Examples:
incf TEMP1, F
incf TEMP1, W
```

decf TEMP1, F

comf TEMP1, F

```
; increment f, putting result in F
;decrement f, putting result in F or W
;complement f, putting resultsing valids:

Z
;Increment TEMP1
;W <- TEMP1+1; TEMP1 unchanged
;Decrement TEMP1
;Change 0s and 1s to 1s and 0s
```



Multi-bit Manipulation

```
andlw
                        : AND literal value k into W
andwf f, F(W)
                        ; AND W with F, putting result in F or W
iorlw
         k
                        ; Inclusive-OR literal value k into W
iorwf f, F(W)
                        ; Inclusive-OR W with F, putting result in F or W
xorlw
         k
                        Exclusive-OR literal value k into W
         f, F(W)
xorwf
                        ; Exclusive-OR W with F, putting result in F or W
                                                            STATUS bits:
    Examples:
       andlw
              B'00000111'
                            ;force upper 5 bits of W to zero
       andwf TEMP1, F
                            :TEMP1 <- TEMP1 AND W
       andwf TEMP1, W
                            :W <- TEMP1 AND W
              B'00000111'
                            :force lower 3 bits of W to one
       iorlw
       iorwf TEMP1. F
                            ;TEMP1 <- TEMP1 OR W
              B'00000111'
                            ;complement lower 3 bits of W
       xorlw
              TEMP1, W
                            ;W <- TEMP1 XOR W
       xorwf
```



sublw 5

Addition/Subtraction

subwf TEMP1, F ; TEMP1 <= TEMP1 - W

```
addlw k
                    ;add literal value k into W
addwf f, F(W)
                    ;add w and f, putting result in F or W
sublw
                    ;subtract W from literal value k, putting
                    result in W
subwf
      f, F(W)
                    ;subtract W from f, putting result in F or
  W
                                                 STATUS bits:
  Examples:
                                                  C, DC, Z
     addlw 5
                      : W <= 5+W
    addwf
          TEMP1, F ; TEMP1 <- TEMP1+W
```

; W <= 5-W (not W <= W-5)

Rotate

```
rlf f, F(W) ; copy f into F or W; rotate F or W left through ; the carry bit
rrf f, F(W) ; copy f into F or W; rotate F or W right
through ; the carry bit C
```

Examples:

```
    rlf TEMP1, F ; C <- TEMP1.bit(7), TEMP1.bit(i+1) <- TEMP1.bit(i) ; TEMP1.bit(0) <- C</li>
    rrf TEMP1, W ; Copy TEMP1 to W and rotate W right through C ; TEMP1 unchanged
```

Goto/Call/Retrun/Return from

aterrupt

goto label call label return k

retfie

; Go to labeled instruction

; Call labeled subroutine

; Return from subroutine

; Return from subroutine, putting literal

; value in W

; Return from interrupt service routine;

; re-enable interrupts

Examples:

goto There

call Task1

return

retlw 5

retfie

; Next instruction to be executed is labeled "There"

; Push return address; Next instruction to be

; executed is labeled "Task1"

; Pop return address off of stack

; Pop return address; W <- 5

; Pop return address; re-enable interrupts

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none



Miscellaneous

```
STATUS bits:
clrwwdt, sleep:
NOT_TO, NOT_PD
nop: none
```

Examples:

clrwdt ; if watchdog timer is enabled, this instruction will reset

; it (before it resets the CPU)

sleep; Stop clock; reduce power; wait for watchdog timer or

; external signal to begin program execution again

nop ; Do nothing; wait one clock cycle

Comparing The Old and The

New

```
.model small
        .data
        db
                0A4h
var1
        db
                22h
var2
var3
        db
        .code
        .8086
start:
                ax, @data
                                  ;set data segment
        mov
                 ds, ax
        mov
                al, var1
                                  set AL to 0A4h
        mov
                                 ; set BL to 22h
                 bl, var2
        mov
                al, bl
                                  ; AL<- AL + BL
        add
                                  ; mov sun to memory location var3
                var3, al
        mov
                 stop
stop:
        jmp
        end
                 start
```

An Equivalent PIC Program

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```
C Processor Example
     include p16f877.inc ;Include file for register definitions
Bank0Ram equ
                          0x20 ;Equates mean the same as before!
cblock Bank0Ram
             ; 0x20 locations used for variables
    var1
     var2
             ; 0x21
     var3
             ; 0x22 temp location used for counter
     endc
             0x000
                          ; Set origin at memory address 000
     org
             Mainline
     goto
     org
             0x004
             iStop
iStop goto
Mainline
     bcf
             STATUS,RP0 ; go to BANK 0 by setting
     bcf
             STATUS, RP1 ; RP1:RP0 to 0 0.
     movlw
             0xA4
                          ; Move literal A4h into W.
     movwf
            var1
                          ; Move from W to var1 (initialize var1)
             0x22
                          : Move literal 22h into W.
    movlw
     movwf
            var2
                          ; Move from W to var2 (initialize var2)
     movf
             var1,W
                          ; Get data from var1 into W.
             var2.W
                          : Calculate W = var1 + var2.
     addwf
     movwf
            var3
                          : Store result in var3.
stop goto
             stop
     End
                                         PIC Microcontroller
```



Acknowledgement

The slides are revised based on lecture notes used in WPI ECE 2801