

Stats Review

EC420 MSU Online

Justin Kirkpatrick

Last updated December 22, 2021

Lectures:

1. Random variables.
 - Sample vs. Population
2. Probability density functions.
 - PDF, PMF, CDF
 - Mean and variance
3. Correlation and independence
4. Types of distributions
5. Statistical inference
 - Hypothesis testing, T-tests, p-values.
6. Useful functions and properties

Random variables

[Back](#)

We are starting with the concept of a *random variable* because most of what we're interested in is not perfectly constant in the real world

- Wage, life expectancy, elasticity

Think about an MSU graduate's wages:

- Solid guess could be \$45k per yr after graduation
- But surely not every graduate makes \$45k per yr
- Maybe econ is \$50k vs. < insert oft-derided degree here > at \$40k
- Even knowing degree, still don't know wage perfectly!

→ **Wage is a random variable when we look across graduates!**

So we can say "Alright, I don't know exactly what a graduate's wage will be, but what can we learn about it?"

Wooldridge defines a random variable as

"...one that takes on numerical values and has an outcome that is determined by an experiment."

When referring to a random variable (RV), we use an upper-case e.g. X

RV's have *realizations* ("...determined by an experiment")

- Like flipping a coin
- Or rolling a die

We label these using lower-case: x

And when we have multiple realizations of a RV, we can label them:

$$\{x_1, x_2, x_3\} = \{5, 3, 4\}$$

And when we have a map of how this RV behaves, we have a **distribution** e.g.

$$X \sim N(0, 1)$$

- E.g. the "normal" distribution.
- One important element of a distribution is the *support*, which is the possible values that the RV can take

As an example, maybe X is a roll of a normal die

- The support of X is $\{1, 2, 3, 4, 5, 6\}$
- The distribution of X is:
 - $Pr(X = 1) = \frac{1}{6}$
 - $Pr(X = 2) = \frac{1}{6}$
 - $Pr(X = 3) = \frac{1}{6} \dots$
- The random variable is not the realizations
 - "The map is not the territory"

Discrete vs. Continuous

A random variable is discrete if it can take on only a finite or countably infinite number of values.

- Bernoulli (coin flip) can take on only two values, $\{0, 1\}$. It is discrete.
- Poisson (count) can take on the values $\{0, 1, 2, \dots\}$, which is countably infinite. It is discrete.
- Normal can take on any value $\in (-\infty, +\infty)^*$
- Whether or not a RV is discrete or continuous is determined by it's support

* \in = "in"

Sample vs. Population

Population

The "population" is what we'd like to learn about.

Let X be a random variable (RV) representing a population

- X could be "hourly wage"
- X could be "age"

There is some feature of the population we are interested in

- The mean hourly wage
- The distribution of age
- This is the "population statistic"

But we cannot collect complete data on the population:

- It may be too expensive or it just isn't possible

So we have to take a *sample*

For example:

When we do national Presidential polling, we are *trying* to measure the national vote. The RV here is "voting preference"

- Call the true fraction of all people who intend on voting for Candidate A the "population statistic"
- But we do not get to call every person in America
- Even if we had infinite phones and infinite interns, the *population* we're interested in might not be that easy to figure out
 - "Likely voters"
- So we instead settle for getting as close to the population statistic as we can. We use a sample.

Population Effect

- In econometrics, we're often going to be concerned about a population *effect*:
 - Effect of a drug on a health outcome
 - Effect of a work training program
- Just as there is a population statistic we can call "average vote", there is a "population effect" of a drug or work training program.
 - Just as we can't call everyone in the country about their vote, we can't test everyone in the country for a drug's effect
- We don't observe the whole population, so we cannot directly calculate the population statistic we're interested in.

Sample

The sample is what we observe.

It is always taken from the population. We use N (or n) to denote it's size.

And under certain conditions^{*} the sample tells us about the population

Population statistics will **always get a greek letter**. Sample statistics don't.

- μ is the population mean
- σ^2 is the population variance
- \bar{x} is the sample mean
- s^2 is the sample variance

^{*} We will learn a lot about these conditions this semester.

For any *population statistic* we are interested in, there will be a *sample statistic* that will tell us something about the *population statistic*.

- In the voting example, our sample poll tells us *something* about the population

The sample statistic will never be exactly the population statistic

But it will be close

The statistical applications of econometrics are all about quantifying "how close"

In everything we do for the first half, we will use the concept of "population" and "sample" heavily.

Please make sure you are comfortable with the difference.

Probability Density Functions

[Back](#)

Probability density function

The *probability density function* (pdf) of X summarizes the information concerning the possible outcomes of X and the corresponding probabilities in the population

$$f_X(x) = \begin{cases} p_j & \text{if } x = x_j \\ 0 & \text{otherwise} \end{cases}$$

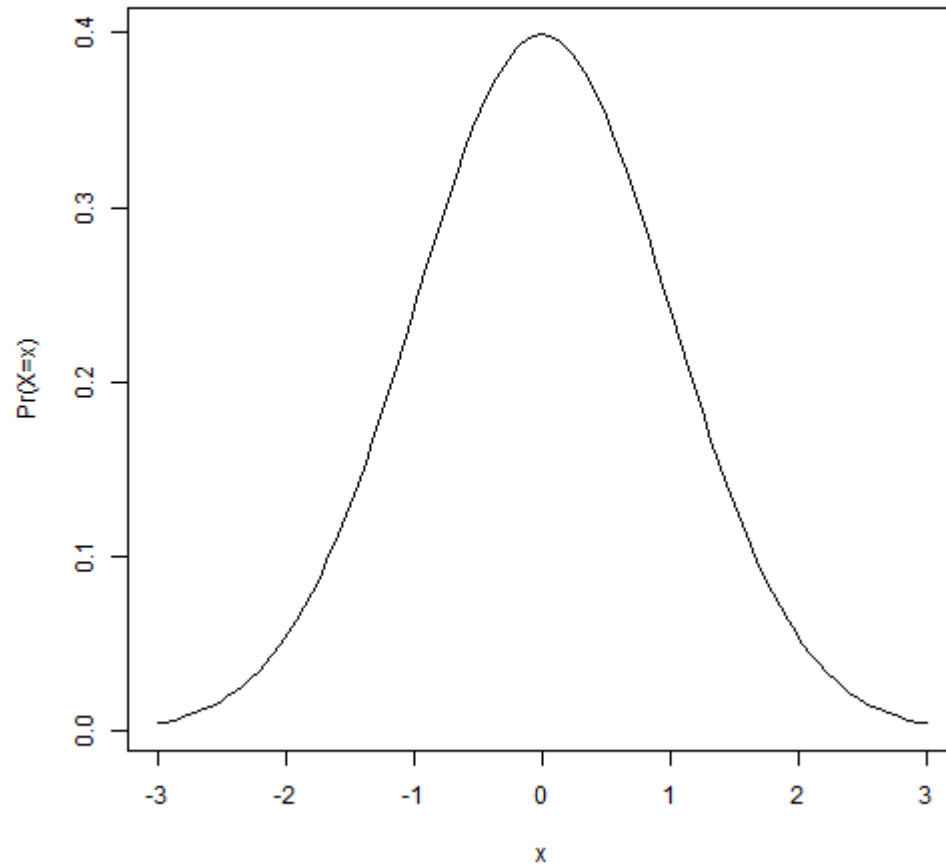
The *pdf* tells us the probability of realizing any value within a very small window around the value. If we know the distribution, including the parameters, then we can plug in any value.

In a Normal $X \sim N(\mu, \sigma^2)$, then $f_X(t) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(t-\mu)^2}{2\sigma^2}}$

- Just note that the pdf pertains to a RV, X , and some number you want to plug in, here labeled t .

A *pdf* must **always sum (discrete) or integrate (continuous) to one**

A PDF



The *cumulative density function*, or *cdf*:

The *cdf* tells us the probability of a RV realization being less than some value:

$$Pr(X \leq t) = F_X(t) = \int_{-\infty}^t f_X(s) ds$$

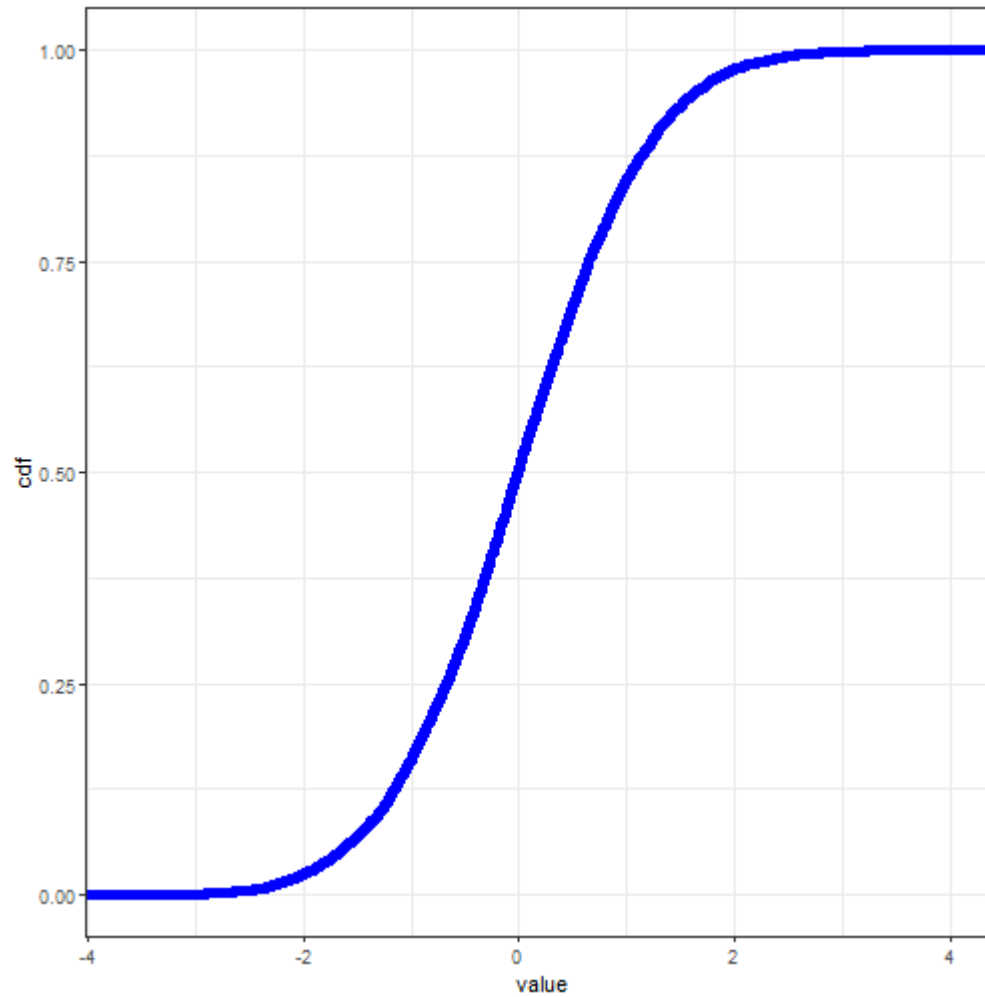
The *cdf* has a few useful properties:

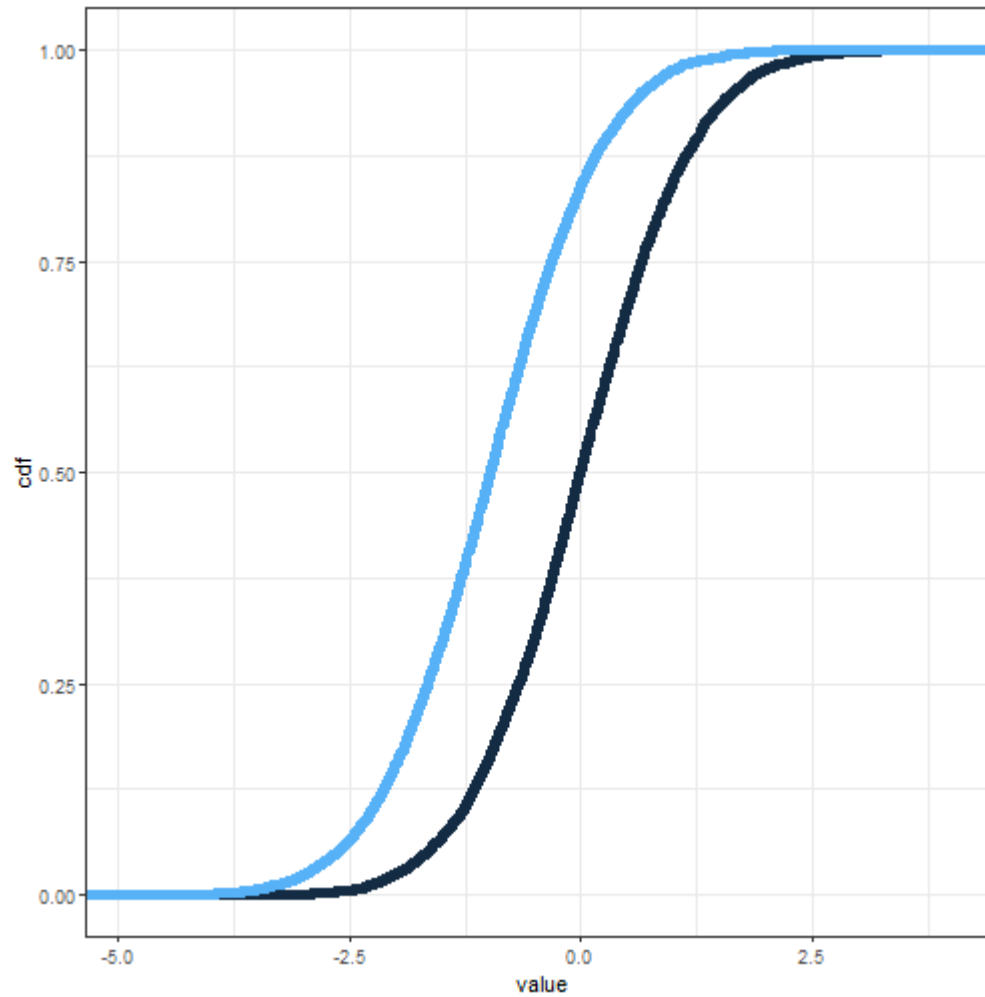
The probability of a RV X being **greater than** some value t is $1 - F_X(t)$

The derivative of the *cdf* at any value t is the *pdf* at t

The *cdf* is always $\in [0, 1]$

The *cdf* is denoted as F , while the PDF is f .





The PDF and the CDF describe the RV. Therefore, they are statements about the population.

- They are also not directly observed
- We may say that $X \sim N(0, 1)$
 - "X is distributed Normal with a mean of 0 and a variance of 1"
 - But we never get to know this for sure in practice

A probability distribution (and thus an RV described by a distribution), has "moments"

- Mean
- Variance
- And more!

Let's look at those. But first, we'll define their sample equivalents.

Sample mean

It should surprise nobody in this room that the *sample mean* is calculated as:

$$\bar{x} = \frac{x_1 + x_2 + \dots + x_n}{N} = \frac{1}{N} \sum_{n=1}^N x_n$$

Note that N is the sample size, n is the index, and x_n are the realizations of X

\bar{x} is a *sample statistic* and a *descriptive statistic* (it describes the sample x_1, \dots, x_n). We will also see that it is an *estimate* of the population mean, μ_X . Let's hold off on this for now.

Property of the sample mean (and summation operator)

Remember that multiplying the sample by a constant means you can take the constant out:

$$\frac{1}{N} \sum_{n=1}^N c x_n = c \bar{x}$$

But you cannot do this with the product of two RVs

$$\frac{1}{N} \sum_{n=1}^N x_n y_n \neq \bar{x} \bar{y}$$

You can move the addition or subtraction of a constant in or out:

$$\frac{1}{N} \sum_{n=1}^N (x_n - c) = \bar{x} - \frac{1}{N} Nc = \bar{x} - c$$

Just as we cannot say that the mean of the product of two RV's is the product of the means, we cannot say that the mean of one RV squared is the mean squared

$$\frac{1}{N} \sum_{n=1}^N x_n^2 \neq \bar{x}^2$$

That is, the average of the square of a sample is **not** the square of the average

If we had a sample from X of $\{1, 2, 6\}$, then $\bar{x} = \frac{1+2+6}{3} = 3$

But $\frac{1+4+36}{3} = 13.6667$ which is **not** 3^2 .

The *sample average*, \bar{x} , can be treated like a constant since it is the realization from a sample.

This is important as we will be working with deviations from the mean a lot:

$$\frac{1}{N} \sum_{n=1}^N x_n - \bar{x}$$

ClassID	Score
a	4
b	5
c	3
d	5
e	5
f	2
Avg	4

One particularly important property is revealed here: the sum of all deviations from the *sample mean* is zero.

$$(4 - 4) + (5 - 4) + (3 - 4) + (5 - 4) + (5 - 4) + (2 - 4) = 0$$

$$\frac{1}{N} \sum_{n=1}^N x_n - \bar{x} = \bar{x} - \bar{x} = 0$$

Expected value

The expected value is a very similar concept to the mean. When referring to an RV, "mean" and "expected value" are interchangeable.

Expected value is a population concept, while the sample mean exists only for any set of *realizations* of a RV.

The *expected value* of a RV is the "measure of central tendency"

- A fancy way of saying "tells us about the middle"
- Sometimes called the "first moment"

It is represented by the E operator and is read as "the expectation of X ". In a discrete RV, the Expectation is defined by:

$$E(X) = x_1 f(x_1) + x_2 f(x_2) + \dots + x_n f(x_n)$$

Remember, f is the pdf, and is a population concept

For continuous RVs:

$$E(X) = \int_{-\infty}^{+\infty} x_s f(x_s) ds$$

This is the integral over all possible values of x , weighted by the pdf at that value.

Note that we don't use a sample to calculate this - we need to know the support (the values X can take) and the pdf, $f(x)$.

Expectation operator

$E(X)$ has some useful properties (similar to the mean), where c is a constant (not a RV):

- $E(cX) = cE(X)$
- $E(cX + b) = b + cE(X)$

That is, you can add and multiply constants in and out of the expectation

In general:

- $E(XY) \neq E(X)E(Y)$ (in general)
 - This **will** be true in certain cases, which will be **very** useful to us!
- $E(X^2) \neq [E(X)]^2$

Conditional Expectation

In an upcoming lecture, we will think about conditional expectations:

- $E(X|Y = y)$ is the expectation of X *conditional on* Y taking the value y

We will work a lot more with the expected value in this class

Expected value continued...

The *expected value* will also be the best guess of a realization of a RV

- "best" as in "minimizes the sum of differences between realizations and the guess"
- If I have to pay \$1 for every unit off I am from a realization of a RV, I am best-off by guessing the expected value
- This applies for any monotonically increasing loss function
 - Loss function is any way of calculating a penalty
 - For example, it could be the square of the difference
 - Or, the absolute value of the difference
 - "Increasing" means its result increases with the input
 - This excludes *The Price Is Right* pricing

Expected value and (population mean) are essentially interchangeable

$$E(X) = \mu_X$$

Both are population concepts, so these are not observed

- Thus, the greek letter for μ
- The extra X in μ_X just clarifies what RV's population mean we're referring to

Variance

variance is a "measure of diffusion"

- A fancy way of saying "how spread out are the likely values"
- Sometimes called the "second moment"
- Not all RVs have a finite variance; some are ∞
 - All samples do - you can always calculate the variance from a finite number of draws
 - ...but not all RVs have a finite variance

Most important, two RVs or two samples of two RVs can have the same mean but different variance

- The mean is still the "best guess"
- The variance tells us how far off your "best guess" will be on average
- Higher variance = more spread = further off

Variance, in a sample, is calculated by summing the squared differences between the realizations of \mathbf{X} and the mean of \mathbf{X} . The concept of variance can refer to the population (population variance) **or** the sample (sample variance)

It is written as $Var(\mathbf{X})$ or σ_X^2 (or s^2 for sample variance)

If we know the whole population and the population mean, we would use:

$$Var(\mathbf{X}) = \sigma_X^2 = \frac{1}{N} \sum_{n=1}^N (x_n - \mu)^2$$

But we rarely know μ or observe the whole population.

But we do have a good sample analog using \bar{x} !

Sample variance

So, we can get a **sample variance**, s^2 , by first calculating \bar{x} , taking it as a constant, and calculating:

$$s^2 = \frac{1}{N - 1} \sum_{n=1}^N (x_i - \bar{x})^2$$

Note the $N - 1$ in the denominator! This corrects for the fact that \bar{x} is an estimate

We can write the variance using expectations as well:

(Note that I'm using the population variance here)

$$\begin{aligned}\frac{1}{N} \sum_{n=1}^N (x_n - \mu)^2 &= \frac{1}{N} \sum_{n=1}^N [x_n^2 - 2x_n\mu + \mu^2] \text{ (Expand polynomial)} \\ &= \frac{1}{N} \sum_{n=1}^N x_n^2 - \frac{1}{N} \sum_{n=1}^N 2\mu x_n + \frac{1}{N} \sum_{n=1}^N \mu^2 \text{ (Distribute the sum)} \\ &= \frac{1}{N} \sum_{n=1}^N x_n^2 - 2\mu \frac{1}{N} \sum_{n=1}^N x_n + \frac{1}{N} N\mu^2 \text{ (Move constants out)} \\ &= E(X^2) - 2\mu E(X) + \mu^2 \\ &= E(X^2) - 2E(X)E(X) + [E(X)]^2 \\ &= E(X^2) - [E(X)]^2\end{aligned}$$

Operations on Variance where a and b are constants differ from the Expected Value operations:

$$\text{Var}(aX + b) = a^2 \text{Var}(X) + 0$$

- Constants have zero variance.
- Scaling X by a scales variance by a^2 .
- This **will** be important in this class.

If we have an RV, and we know its population mean and variance: μ and σ^2

We can standardize X by subtracting the mean and dividing by the standard deviation:

$$Z = \frac{X - \mu}{\sigma}$$

Write a as $\frac{1}{\sigma}$ and b as $-\frac{\mu}{\sigma}$. Then

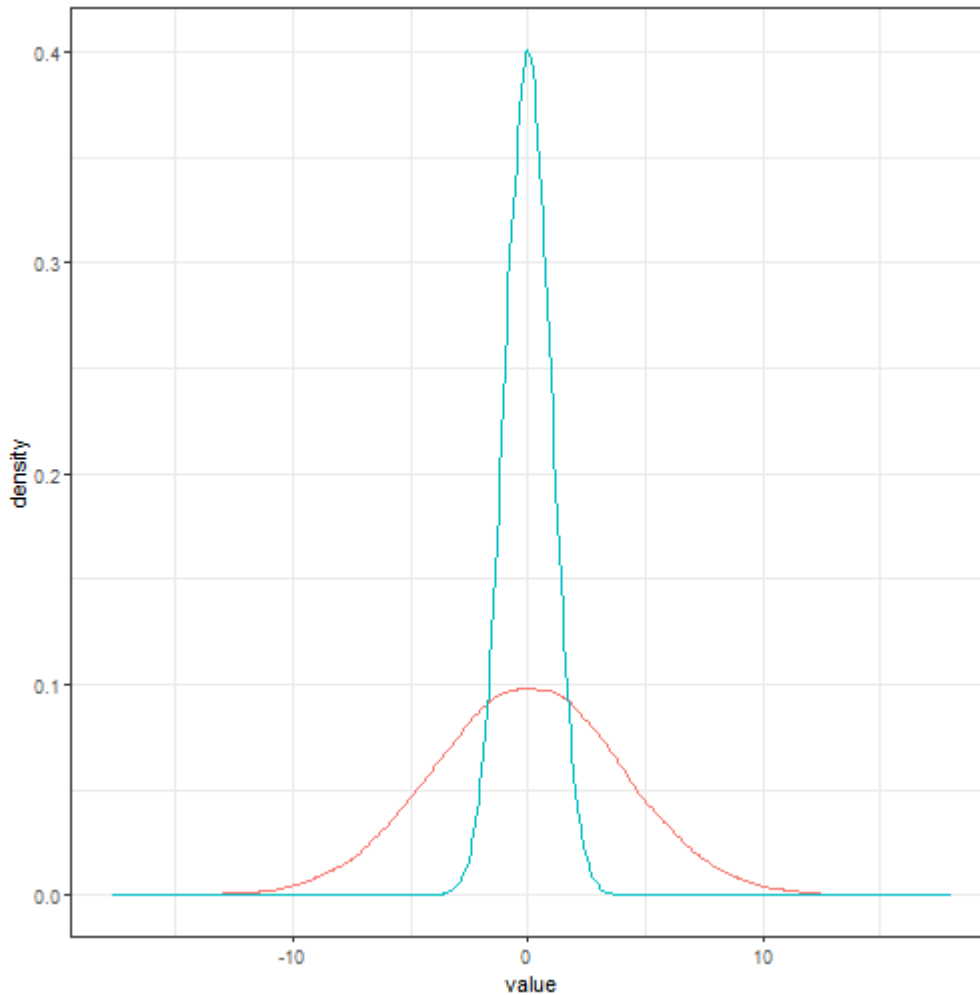
$$Z = \frac{1}{\sigma}X + -\frac{\mu}{\sigma} = aX + b$$

$$E(Z) = aE(X) + b = \frac{\mu}{\sigma} - \left(\frac{\mu}{\sigma}\right) = 0$$

$$Var(Z) = a^2Var(X) + 0 = \frac{1}{\sigma^2}\sigma^2 = 1$$

We used the operations for variance and mean to show the (familiar) result of standardization.

Low variance is $\sigma^2 = 1$; high variance is $\sigma^2 = 16$. Both means are zero.



Correlation and independence

[Back](#)

We may be interested in how **two random variables** behave together.

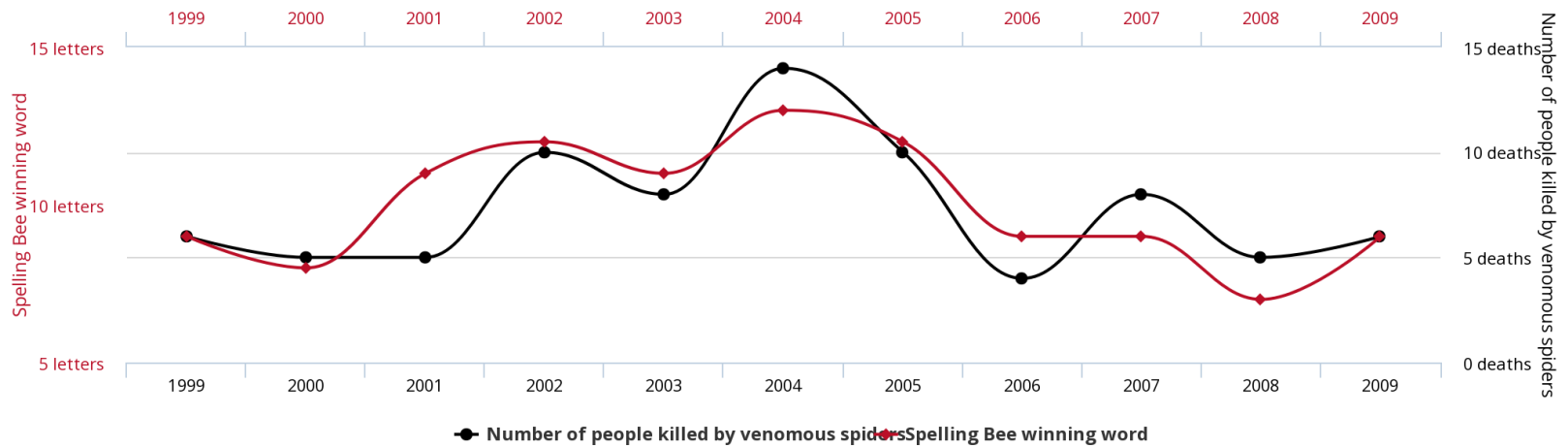
- Income and age
- Wage and education
- Corn yields and fertilizer
- Snowfall and traffic fatalities
- "Letters in Winning Word in Scripps National Spelling Bee" and "Deaths from Venemous Spiders"

Each of these are *pairs* of RV's.

Just as we have measures of central tendency and dispersion, we will have a measure of this association between RV's: **covariance**.

And we can also express the relationship between the PDF's of the RV's.

Letters in Winning Word of Scripps National Spelling Bee
correlates with
Number of people killed by venomous spiders



tylervigen.com

Let's define **Covariance** between X and Y

$$\text{Cov}(X, Y) = \frac{1}{N} \sum_{n=1}^N (x_n - \mu_X)(y_n - \mu_Y)$$

Note that we are *summing the pairwise deviations from the mean*.

Note that this is a population concept (which will have a sample analog)

Covariance will be:

-**higher** if x is above the mean when y is also above the mean

-**lower** if x is below the mean when y is also below the mean

-**zero** if x is randomly above/below the mean when y is above/below the mean

Covariance is a measure of how closely two RV's track each other.

With some algebra, we can also write covariance as:

$$\text{Cov}(X, Y) = \frac{1}{N} \sum_{n=1}^N (x_n - \mu_X)(y_n - \mu_Y) = E(XY) - \mu_X \mu_Y$$

Just as $E(X)$ was important to the *measure of central tendency* and $E(X^2)$ was important to the *measure of dispersion* (variance), $E(XY)$ is important to the covariance, a *measure of association*.

We can also scale the covariance so that it is between -1 and 1:

$$\frac{Cov(X, Y)}{\sqrt{Var(X)Var(Y)}} = \rho \in [-1, 1]$$

We will use ρ for the *correlation coefficient*, though you'll frequently see ρ used for other purposes as well.

With regards to the elements of $\rho : Cov(X, Y), Var(X), Var(Y)$, in what case would:

- $\rho = 1$?
- $\rho = -1$?
- $\rho = 0$

When we have two RV's added to each other

$$\text{Var}(X + Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

When two RVs are added to each other, their covariance must be included when calculating the variance of the sum.

- Intuitively, imagine a perfectly correlated X and Y - picture how big the variance would be if, when X is large, Y were also large.
- It would be much larger than the case where X and Y were perfectly negatively correlated.

For constants a and b and RVs X and Y :

$$\text{Cov}(aX, bY) = ab\text{Cov}(X, Y)$$

and therefore:

$$\text{Var}(aX + bY) = a^2\text{Var}(X) + b^2\text{Var}(Y) + 2ab\text{Cov}(X, Y)$$

When a RV is multiplied by a constant, the variance is multiplied by the *square* of the constant.

When two RVs are added to each other, their covariance must be included when calculating the variance of the sum.

Now that we've looked at covariance using the $Cov(X, Y)$ notation, what about in probability distribution function?

The *joint PDF* tells us the probability of seeing a pair of values for X and Y :

$$f_{X,Y}(x, y) = Pr(X = x, Y = y)$$

Note the subscript on f has both X and Y in it, and the joint pdf takes *two* values as inputs.

So in the joint pdf, you'll see both x and y .

- It would be strange to have X and Y correlated and not have a pdf that includes x and y

This bring us to **independence** of random variables, which will be extra-important in this class.

Two RVs are independent if and only if their joint pdf is equal to the product of the marginal pdfs

$$X \perp Y \iff f_{X,Y}(x,y) = f_X(x)f_Y(y)$$

- \perp is read as "independent"
- Sometimes you'll see $\perp\!\!\!\perp$
- The symbol \iff means "if and only if"
 - This will be common in future courses
 - It means that when one side holds true, the other side will always hold true.
- $f_X(x)$ is the pdf of X , just as we used it before.
 - This will be called the *marginal pdf of X*.

Independence is *defined* in this way, but it has many implications.

Intuitively, it means that **knowing a realized value of X tells us nothing at all about the realized value of Y .**

Think about flipping a coin X and rolling a die Y

- If X lands on "heads", what do you think the die roll will be?
- The die roll would have the same probability of each number $\{1, \dots, 6\}$, regardless of how coin X landed!
- If we were to write the pdf of the die roll Y , *it would not have the realization of the first in it.*

$$f_Y(y) = \frac{1}{6} \quad \text{for any } y \in \{1, \dots, 6\}$$

- See - no "X" in there at all! $Y \perp X$
- $f_{Y|X}(y|x) = f_Y(y)$ is another way of saying this

If X and Y are independent:

$$f_X = \frac{f_{X,Y}(x, y)}{f_Y(y)}$$

Because $E(X)$ and $E(Y)$ are defined by their pdf's, $X \perp Y$ implies that the expectations can be separated:

$$E(XY) = E(X)E(Y)$$

And this means that $X \perp Y$ implies that:

$$X \perp Y \Rightarrow \overbrace{Cov(X, Y) = E(XY) - E(X)E(Y)}^{\text{defined before}} = \overbrace{E(X)E(Y) - E(X)E(Y)}^{\text{because } X \perp Y} = 0$$

If X has no information about Y , then we would expect $Cov(X, Y)$ to be zero!

When X and Y are *not* independent (\nsubseteq), we can use the *conditional pdf* for X and Y . The conditional pdf is written as: $f_{X|Y}(x|y)$

- The symbol '|' is read as "conditional"
- In a discrete RV, $f_{X|Y}(x|y) = Pr(X = x|Y = y)$

Example:

Let X be life expectancy and let Y be smoking status ($Y = 1$ if a smoker).

- $f_X(x)$ is the marginal pdf of life expectancy (ignoring smoking status)
- $f_Y(y)$ is the marginal pdf of smoking status (ignoring any data we may have on life expectancy)
- $f_{X|Y}$ has a different result when we learn about a realization's smoking status.
- $f_{X|Y}(x|y = 1)$ will have higher probabilities on lower values of x here

We are pretty sure that *knowing about a random draw's smoking status* tells us something about the distribution of their life expectancy.

Of course, there is an Expectation equivalent: the *conditional expectation*:

$$E(X|Y) = \int_{-\infty}^{+\infty} x_s f_{X|Y}(x_s|Y = y) ds$$

That is, the weighted sum/integral of the *conditional pdf* of X

If X and Y are independent, then:

$$E(X|Y) = E(X)$$

This property does not always imply independence (it is not \iff).

- We call this property *mean independence*, meaning the *mean* of X is not affected by realizations of Y .
- This property will be crucial in the next unit.

Remember, that mean independence does not imply independence!

iid

You will see "iid" frequently - it means "independent and identically distributed". It refers to collections of random draws from random variables that are:

- *independent* - the realization of one draw does not give any information about the realization of any other draws
- *identically distributed* - each draw is from a RV that has the same pdf

When we have iid random variables, we can say something about the distribution they all share.

Since they all have the same mean (same distribution), then we can say something about the mean.

Example: **rolls of a fair die are iid**

- The outcome of one roll tells us nothing about the value of the next roll
- The values are drawn from the same distribution

Types of distributions

[Back](#)

Bernoulli

The *Bernoulli* distribution is a very simple distribution, best known as the "coin flip" distribution.

It is for a binary 0/1 outcome variable and has only one "parameter", θ .

For a coin flip, $\theta = .5$

The full distribution is:

$$f_X(x) = \begin{cases} \theta & \text{if } x = 1 \\ 1 - \theta & \text{if } x = 0 \\ 0 & \text{otherwise} \end{cases}$$

This is a distribution because it sums to 1 and it covers every possible value in the domain of X .

Normal

Also known as *gaussian*, the normal is very useful. It is written as $N(\mu, \sigma^2)$

It has two parameters:

- μ is the "location" parameter
- σ^2 is the "scale" parameter
- $E(X) = \mu$ and $Var(X) = \sigma^2$

$$f_X(x) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x - \mu)^2}{2\sigma^2}\right)$$

The normal has support for all real numbers. That is, *every real number* has a non-zero probability of being realized.

Standardization of the Normal

Standardizing the normal to Z :

$$Z = \frac{X - \mu}{\sigma} \sim N(0, 1)$$

The \sim is read as "is distributed as"

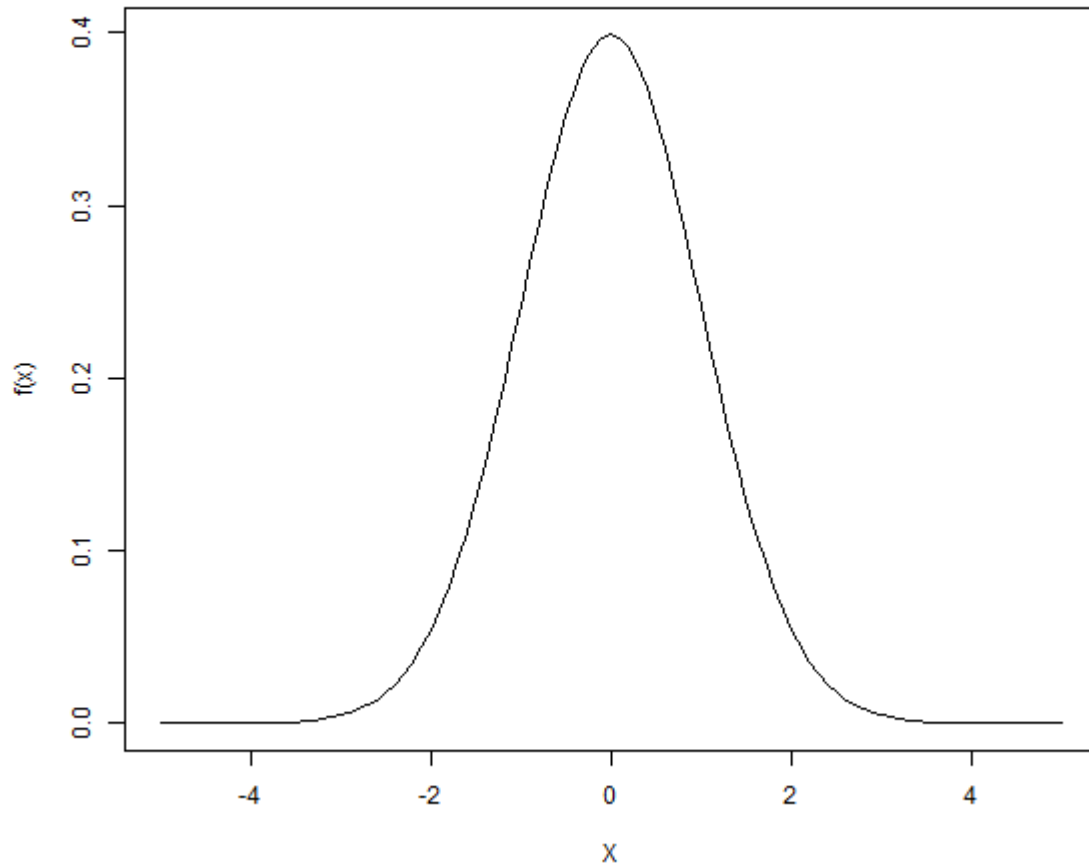
Subtracting the (population) mean and dividing by (population) standard deviation results in a normal RV with mean 0 and variance of 1.

The pdf of the standard normal is $\phi(z) = \frac{1}{\sqrt{2\pi}} \exp\left[-\frac{z^2}{2}\right]$

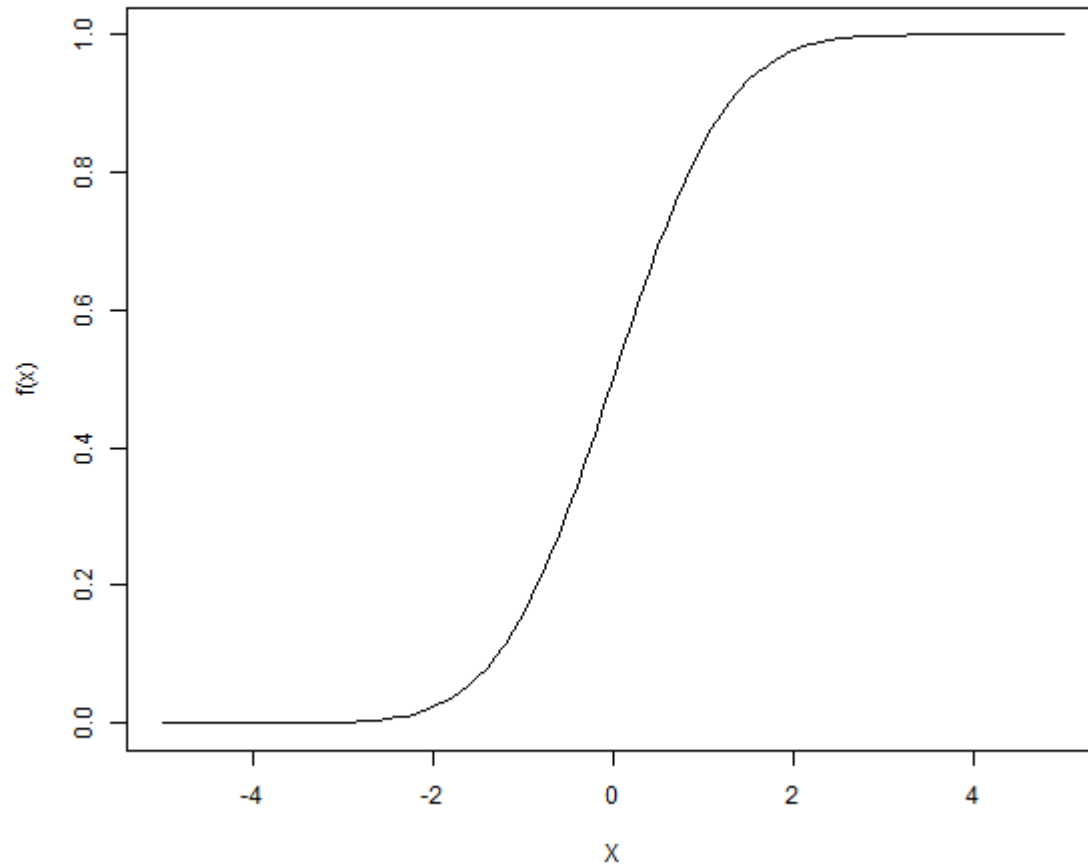
The standard normal is very useful, so it appears in a lot of texts. Thus, it gets its own notation:

- The standard normal pdf is written as $\phi(z)$.
- The standard normal cdf is written as $\Phi(z)$.

Standard normal pdf:



Standard normal cdf:



Properties of the Normal Distribution

- If $X \sim N(\mu, \sigma^2)$, then $Y = aX + b \sim N(a\mu + b, a^2\sigma^2)$
 - This is not true for other distributions.
- If X and Y are jointly normally distributed, then they are independent if and only if $Cov(X, Y) = 0$

Any linear combination of independent, identically distributed (iid) normal random variables has a normal distribution:

- Given $X \sim N(\mu_X, \sigma_X^2)$ and $Y \sim N(\mu_Y, \sigma_Y^2)$
$$\Rightarrow X + Y \sim N(\mu_X + \mu_Y, \sigma_X^2 + \sigma_Y^2 + 2\rho\sigma_X\sigma_Y)$$

The Chi-Square Distribution, χ^2

If $Z_i, i=1, \dots, n$ is iid standard normal $N(0, 1)$, then the sum of these variables squared:

$$X = \sum_{i=1}^n Z_i^2 \sim \chi_n^2$$

is distributed Chi-squared with n degrees of freedom

The t-distribution:

If $Z \sim N(0, 1)$ and $X \sim \chi_n^2$ and Z and X are independent, then:

$$T = \frac{Z}{\sqrt{\frac{X}{n}}} \sim t_n$$

T is distributed t with n degrees of freedom.

Statistical inference

[Back](#)

Our goal is to learn something about a *population* given the availability of a *sample* from that population.

- We will spend a lot of time making the connection between a sample and the population
- We have already done this when we introduced the sample mean and compared it to the (unknown) population mean

If X_1, X_2, \dots, X_n are independent random variables all drawn from a common pdf, $f(x; \theta)$, then X_1, X_2, \dots, X_n is said to be a *random sample* from $f(x; \theta)$.

- Here, the θ parameterizes the distribution.
- θ might be $\theta = \{\mu, \sigma^2\}$

The realization would be denoted by x_1, x_2, \dots, x_n .

If we know (or will assume) a specific distribution for X but do not know the specific values of the parameters of that distribution, then we **estimate** the parameter(s) from the available sample

Estimator

The *estimator* of θ is a rule that assigns to each possible outcome of the sample a value of θ

- It is specified before any sampling. It does not depend on the sample.

For example, we may be interested in the *population mean* μ . The sample average is an *estimator* of μ .

$$\bar{Y} = \frac{1}{N} \sum_{n=1}^N Y_n$$

But \mathbf{Y} is a random variable - it changes every time we take a sample. We can calculate an *estimate*:

$$\bar{y} = \frac{1}{N} \sum_{n=1}^N y_n$$

The *estimate* pertains to the realized sample. An *estimator* is a mapping (e.g. a "plan") for learning about the unknown parameters of the distribution.

Now, relate these to our earlier discussion on mean and variance:

- \bar{Y} is an estimator of the population mean $E(Y) = \mu_Y$
- The *sample variance*, s^2 from earlier is an estimator of $Var(Y) = \sigma^2$

$$s^2 = \frac{1}{N-1} \sum_{n=1}^N (Y_i - \bar{Y})^2$$

If \bar{Y} is an *estimator*, a function of multiple RV's, then \bar{Y} **is a Random Variable itself**

And it has a mean and variance.

- The mean of \bar{Y} is the mean of the distribution of Y
- The variance of \bar{Y} is related to N and σ_Y

If we assume that $Y \sim N(\mu, \sigma_Y^2)$:

$$\begin{aligned} \text{Var}(\bar{Y}) &= \text{Var}\left(\frac{1}{N} \sum y_i\right) \quad (\text{by def of average}) \\ &= \frac{1}{N^2} \text{Var}\left(\sum y_i\right) \quad (\text{By operation of variance}) \\ &= \frac{1}{N^2} N \sigma_Y^2 \quad (\text{Sum of iid } y_i) \\ &= \frac{\sigma_Y^2}{N} \quad (\text{Cancel } N) \end{aligned}$$

That gives us a *sampling distribution* for \bar{Y}

So if $Y \sim N(\mu, \sigma_Y^2)$, then the sampling distribution of $\bar{Y} \sim N(\mu, \frac{\sigma_Y^2}{N})$

This is a very important link because it tells us:

- $E[\bar{Y}] = \mu$, the population statistic of interest
- $Var(\bar{Y})$, so we know how much dispersion there is around μ .
 - **IF** we know σ_Y^2 .
 - Remember, $Var(Y) = \sigma_Y^2$ and $Var(\bar{Y}) = \frac{\sigma_Y^2}{N}$ are different

Central Limit Theorem (CLT)

The CLT is what tells us that \bar{Y} is **normally** distributed.

In fact, it says that *any* normalized sum of iid variables is distributed normally

- "Normalized" here means "divided by N "
- **Even** when those iid variables are from a non-normal distribution
 - This is **amazing**.

Let's look at an example

Let's take a random variable, X , that is definitely not normally distributed.

We'll draw a sample of size $N = 5$ and calculate the average, \bar{x} .

Then, we'll do the same thing again, drawing $N = 5$ new realizations and calculating the average. And again. And again. $R = 100$ times.

Despite the fact that X is not normally distributed, if we plot all 100 values of \bar{x}_r calculated from the 100 draws of $N = 5$, **it is going to look like a normal distribution!**

Even more notable, it will have a variance equal to the population variance of X divided by N .

So what do we do with this?

Even if we just have *one* \bar{y} from *one* draw of size N , we we can learn alot about the population mean, μ .

Law of Large Numbers

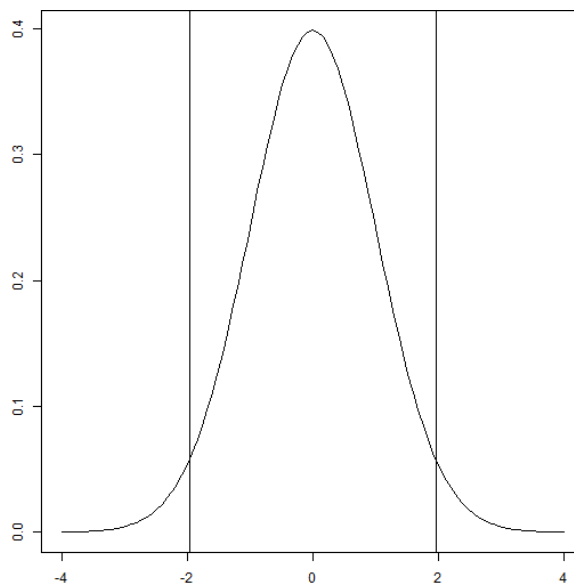
$$\bar{y}_n = \frac{1}{n} \sum_{i=1}^n y_i \rightarrow E[Y] = \mu_Y \quad \text{when } n \rightarrow \infty$$

Thus, we know that $E[\bar{Y}] = \mu_Y$

Now, that we have a distribution for our estimate, we can standardize it:

$$Z = \frac{\bar{Y} - \mu}{\sqrt{\sigma_Y^2/N}} \sim N(0, 1)$$

Which implies that the now-standardized distribution of \bar{Y} , Z , looks like:



The vertical lines are where $F(z) = \{.025, .975\}$. The area under the curve between the lines is .95

Thus, we can get our 95% CI

$$\begin{aligned} .95 &= Pr\left(-1.96 < \frac{\bar{Y} - \mu}{\frac{\sigma_Y}{\sqrt{N}}} < 1.96\right) \\ &= Pr\left(\bar{Y} - 1.96 \frac{\sigma_Y}{\sqrt{N}} < \mu < \bar{Y} + 1.96 \frac{\sigma_Y}{\sqrt{N}}\right) \end{aligned}$$

± 1.96 is the *critical value* for a Normal with a 95% confidence interval.

- You can find this in the Z-tables in any statistics text, including Wooldridge

Confidence intervals (CI)

- We know the sampling distribution of \bar{Y} .
- We know the 95% CI

Question:

- If I draw a new sample from Y , will the 95% CI on \bar{Y} change?
- Will the population parameter we're interested in change?

So which is correct:

A. "there is a 95 percent probability that the true value of μ falls in the estimated confidence interval."

B. "for 95% of all random samples, the constructed CI will contain μ ."

B is correct.

TABLE C.2 Simulated Confidence Intervals from a Normal($\mu, 1$) Distribution with $\mu = 2$			
Replication	\bar{y}	95% Interval	Contains μ ?
1	1.98	(1.36, 2.60)	Yes
2	1.43	(0.81, 2.05)	Yes
3	1.65	(1.03, 2.27)	Yes
4	1.88	(1.26, 2.50)	Yes
5	2.34	(1.72, 2.96)	Yes
6	2.58	(1.96, 3.20)	Yes
7	1.58	(.96, 2.20)	Yes
8	2.23	(1.61, 2.85)	Yes
9	1.96	(1.34, 2.58)	Yes
10	2.11	(1.49, 2.73)	Yes
11	2.15	(1.53, 2.77)	Yes
12	1.93	(1.31, 2.55)	Yes
13	2.02	(1.40, 2.64)	Yes
14	2.10	(1.48, 2.72)	Yes
15	2.18	(1.56, 2.80)	Yes
16	2.10	(1.48, 2.72)	Yes
17	1.94	(1.32, 2.56)	Yes
18	2.21	(1.59, 2.83)	Yes
19	1.16	(.54, 1.78)	No
20	1.75	(1.13, 2.37)	Yes

© Cengage Learning, 2013

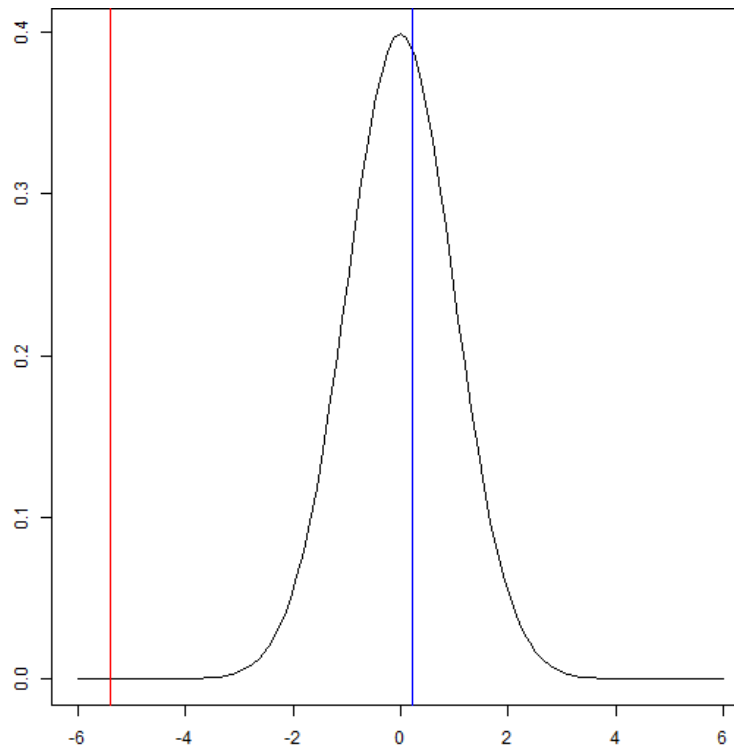
The resulting standardized distribution tells us what we would expect to see **if μ is the true population mean.**

Remember, we acted as if we knew what μ was.

Although we know that $E[\bar{Y}] = \mu$, our realization of the sample mean, \bar{y} , is not exactly equal to μ .

If we plug in any guess for the real μ , we can take our sample estimate of \bar{y} , subtract our hypothesized μ , divide by σ/\sqrt{N} and plot it on the distribution.

Let's call our hypothesized population mean μ_0 . It is the *null hypothesis*.



- If the null hypothesis is correct, the black curve is the pdf ("what we'd expect to see")
- If our statistic $\frac{\bar{y} - \mu_0}{\sigma/\sqrt{N}}$ is the red line, do we think we have the distribution right?
- What about for the blue?

Another problem:

We can hypothesize about μ_0 , but what about σ^2 ? We don't know σ^2 . If we did, we'd be in great shape.

But we have the **sample variance** estimator from before:

$$s^2 = \frac{1}{N-1} \sum_{n=1}^N (y_i - \bar{y})^2$$

But because we have an estimate of σ_Y^2 , our standardized statistic is no longer $\sim N(\mu_Y, \frac{\sigma_Y^2}{N})$. Now it is:

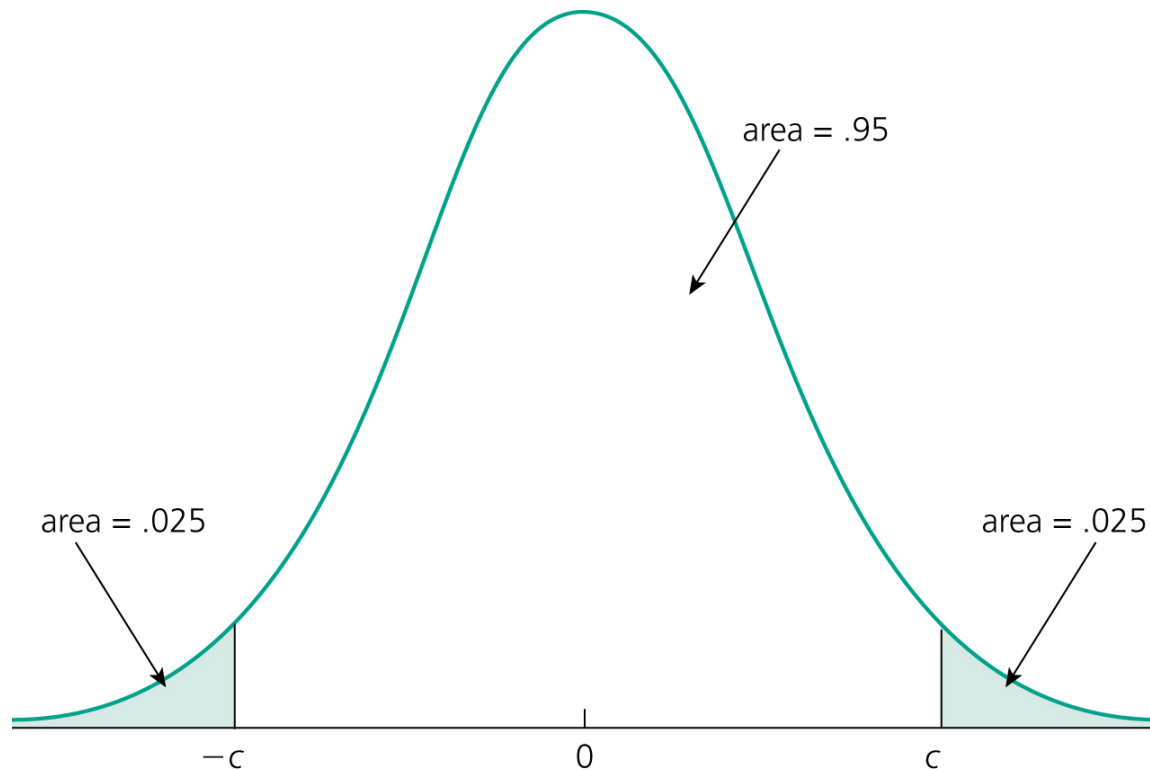
$$\frac{\bar{Y} - \mu_Y}{\sqrt{\frac{s^2}{N}}} \sim t_{N-1}$$

It is distributed t with $N - 1$ degrees of freedom.

- The t-distribution is also given in your book (Table G-2)
- So we can look up the 95% critical values
- Note that the critical values will change as $N - 1$ changes
- And that they get closer to the values for a Standard Normal as N gets large.

Critical values

By standardizing, we are relating the distribution of our **estimate** to a known distribution.



Wooldridge Figure C-4

TABLE G.2 Critical Values of the t Distribution					
Significance Level					
1-Tailed:	.10	.05	.025	.01	.005
2-Tailed:	.20	.10	.05	.02	.01
Degrees of freedom	1	3.078	6.314	12.706	31.821
	2	1.886	2.920	4.303	6.965
	3	1.638	2.353	3.182	4.541
	4	1.533	2.132	2.776	3.747
	5	1.476	2.015	2.571	3.365
	6	1.440	1.943	2.447	3.143
	7	1.415	1.895	2.365	2.998
	8	1.397	1.860	2.306	2.896
	9	1.383	1.833	2.262	2.821
	10	1.372	1.812	2.228	2.764
	11	1.363	1.796	2.201	2.718
	12	1.356	1.782	2.179	2.681
	13	1.350	1.771	2.160	2.650
	14	1.345	1.761	2.145	2.624
	15	1.341	1.753	2.131	2.602
	16	1.337	1.746	2.120	2.583
	17	1.333	1.740	2.110	2.567
	18	1.330	1.734	2.101	2.552
	19	1.328	1.729	2.093	2.539
	20	1.325	1.725	2.086	2.528
	21	1.323	1.721	2.080	2.518
	22	1.321	1.717	2.074	2.508
	23	1.319	1.714	2.069	2.500
	24	1.318	1.711	2.064	2.492
	25	1.316	1.708	2.060	2.485
	26	1.315	1.706	2.056	2.479
	27	1.314	1.703	2.052	2.473
	28	1.313	1.701	2.048	2.467
	29	1.311	1.699	2.045	2.462
	30	1.310	1.697	2.042	2.457
	40	1.303	1.684	2.021	2.423
	60	1.296	1.671	2.000	2.390
	90	1.291	1.662	1.987	2.368
	120	1.289	1.658	1.980	2.358
	∞	1.282	1.645	1.960	2.326

© Cengage Learning, 2013

Examples: The 1% critical value for a one-tailed test with 25 *df* is 2.485. The 5% critical value for a two-tailed test with large (> 120) *df* is 1.96.

Source: This table was generated using the Stata® function invttail.

Wooldridge Figure G-2

An example: years to complete a PhD

Years
9.0
6.5
4.0
7.5
5.5
4.5
1.5
5.5

Calculate \bar{x} and s^2

$$N = 8$$

$$\bar{x} = 5.5$$

$$s^2 = 5.214$$

$$\sqrt{\frac{s^2}{N}} = 0.807$$

So once we standardize our \bar{x} , it is distributed t_{8-1}

The critical values, which we'll call t_{crit} for t_{8-1} are:

$$\pm 2.365$$

So the 95% confidence interval is $\bar{x} \pm t_{crit} \sqrt{\frac{s^2}{N}}$:

$$5.5 \pm 2.365 \times 0.807$$

Which is **[3.638, 7.362]**

For 95% of random samples, this confidence interval will include the true parameter.

What if we want to ask the question "does the average Ph.D. take 5 years?"

Often, we are interested in these *population* questions

- E.g.: does the average person obtain more education when college is subsidized?
- Similarly, we can ask "Does a MSU Ph.D. take five years on average?".

We call the **null hypothesis** H_0 .

It is what we can test and either **reject** or **fail to reject**

- We do not ever **accept** or **confirm** a null hypothesis
- H_0 is always a point estimate (=)

We call the alternative the **alternative hypothesis**, H_1 .

- H_1 is always an inequality ($>$ or $<$) or \neq
 - When H_1 takes the form \neq , it is a 2-tailed test.

Hypothesis testing

There are two types of mistakes we can make in testing a hypothesis:

- Type I error: Rejecting the null hypothesis, H_0 , when it is true
 - The *significance level of a test*, α , is the *probability of a Type I error*.
 - Mathematically, $\alpha = \Pr(\text{Reject } H_0 \mid H_0 \text{ is true})$
- Type II error: Failing to reject the null hypothesis when it is false

Let's call our test statistic T

- So far, in all of our examples, our test statistic has been the population mean
 - But not always!
- The realized value (mapped from the sample to the estimate) we'll call t
- Given the test statistic, we can define a *rejection rule* which will tell us the values of t for which H_0 is rejected.
 - Think of H_0 as the "guess"
 - The rejection regions are the values which rule out that guess

For example: if our test statistic, T is "average miles driven per day" and our H_0 is something reasonable, then the rejection region will tell us the *realized* values t that would make H_0 unlikely.

- If our H_0 is "5 miles per day" and we *realize* a value $t = 100$, then we would be pretty convinced that the true value is not "5 miles per day".
- But if $t = 5.1$, then we wouldn't have any evidence against our H_0

The rejection region depends on the alternative hypothesis:

- $H_1 : \mu \neq \mu_0$ (where μ_0 is the hypothesized value)
- $H_1 : \mu > \mu_0$
- $H_1 : \mu < \mu_0$

In a two sided case ($H_1 : \mu \neq \mu_0$), we reject the null hypothesis if the test statistic (e.g. sample average) differs too much from the hypothesized value in either direction.

- This is most common, especially when we are testing for "has zero effect".

In a one-sided case ($H_1 : \mu > \mu_0$ or $H_1 : \mu < \mu_0$), we reject the null hypothesis if the test statistic is far above (below) the hypothesized value.

- On a right-tailed test where $H_1 : \mu > \mu_0$, a test statistic that is very *low* does not reject the null hypothesis.

Simply comparing a realization of a test statistic t to a hypothesized value, $H_0 : \mu_0 = 5$ (for example) doesn't tell us everything we need to know.

- What if $t = 5.1$?
- What if $t = 1000$?

We need to know how varied T is in the first place.

- If it's highly dispersed (high variance), then a realization of $t = 1000$ might be perfectly reasonable under the null hypothesis that $\mu_0 = 5$.

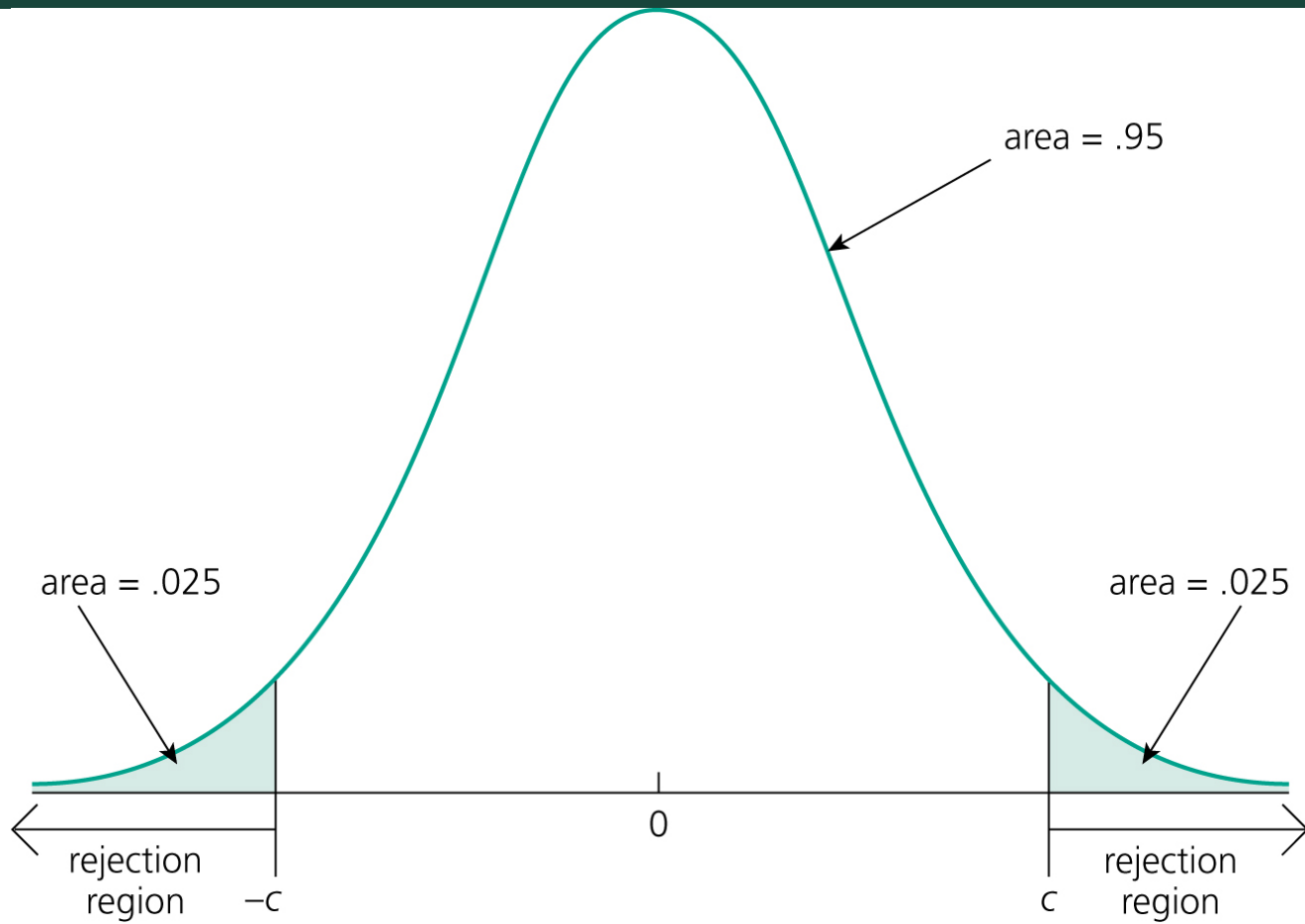
Which is why we want to standardize the test statistic!

$$T = \frac{\bar{Y} - \mu_0}{\frac{s}{\sqrt{N}}} \sim t_{N-1}$$

Which means we do the same with the realization: $t = \frac{\bar{y} - \mu_0}{se(\bar{y})}$, where $se(\bar{y}) = \frac{s}{\sqrt{N}}$

This lets us compare the now-standardized t to critical values of a distribution we know, t_{N-1}

- The size of the rejection region will depend upon how confident we want to be regarding our rejection of the null
- ...or to put it another way, how small we want the probability of a Type I error (significance level) to be
- If we want a significance level to be $100 \times \alpha$, then the critical level is $c_{\frac{\alpha}{2}}$
- This splits the rejection region evenly between \bar{y} being too big and \bar{y} being too small



Wooldridge Figure C-6

Let's go back to our example "Years to completion of a Ph.D."...

Statistic	Value	Note
N	8	Number of observations
\bar{x}	5.5	Sample mean
s^2	5.214	Sample variance
$\frac{s}{\sqrt{N}}$	0.807	Std. error of the mean

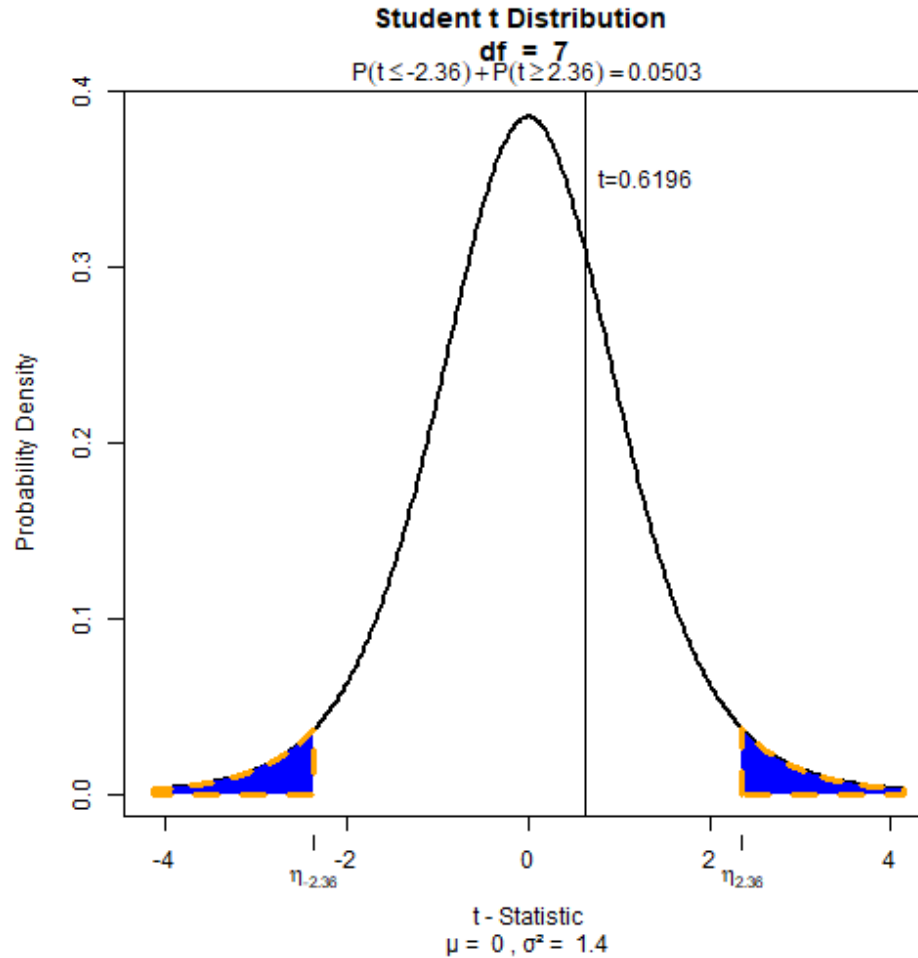
Calculate t from the sample:

$$t = \frac{\bar{y} - \mu_0}{se(\bar{y})} = \frac{5.5 - 5}{0.807} = 0.6196$$

Now, does this fall into the rejection region? Is it such an extreme value that it provides evidence against $H_0 : \mu_0 = 5$?

First, we have to define the rejection region:

- For $\alpha = .95$, $\pm c_{\frac{\alpha}{2}} = \pm 2.36$



P-values

- An alternative approach computes the corresponding *p-value* for a test statistic
 - The p-value is the probability of obtaining a result equal to or "more extreme" than what was actually observed **when the null hypothesis is true**
 - "Under the null"

$$\text{p-value} = P(|T| > |t| | H_0)$$

If that probability is small, would it provide evidence *against* the null, or *for* the null?

In our **example**:

$$\begin{aligned}\text{p-value} &= P(|T_{N-1}| > |t| | H_0) \\ &= 2 \times P(T_{N-1} > 0.6196 | H_0) \\ &= 2 \times 0.2775787 \\ &= 0.555\end{aligned}$$

There is a 56% chance of observing a t-statistic as big or bigger than the one found in our current sample.

Some useful examples from Wooldridge

- Example C.4 - p.696: Effect of Enterprise Zones on Business Investment
- Example C.5 - p. 698: Race Discrimination in Hiring
- Example C.8 - p. 700: Effect of Job Training Grants on Worker Productivity
- Example C.9 - p. 702: Effect of Freeway Width on Commute Time

Useful functions and properties

[Back](#)

We will cover:

- Linear functions
- Non-linear functions
 - Polynomials (e.g. $x^3 + 2x^2 + 10x$)
 - Natural log
 - Exponential
- Non-linear functions in equations

This will be geared towards the use of these functions in a regression of the form:

$$y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \cdots + \epsilon$$

Linear functions

A linear function is one where the result is a linear transformation ($ax + b$) of the inputs.

$$y = \beta_0 + \beta_1 x$$

Where β_0 is the *intercept* and β_1 is the slope (which forms a straight line).

Linear functions tell us something about *changes*. Specifically, the relationship between Δx and Δy , where Δ is the change ($\Delta x = x^1 - x^0$)

- Here, x^1 is the "after change x " and x^0 is the "before change"
 - They are not exponents!

$$y^1 = \beta_0 + \beta_1 x^1$$

$$y^0 = \beta_0 + \beta_1 x^0$$

$$y^1 - y^0 = \beta_1 (x^1 - x^0)$$

$$\Delta y = \beta_1 \Delta x$$

The previous result can be written as:

$$\frac{\Delta y}{\Delta x} = \beta_1$$

Which is read as "the change in y resulting from a change in x "

Note that this is the same as taking the derivative:

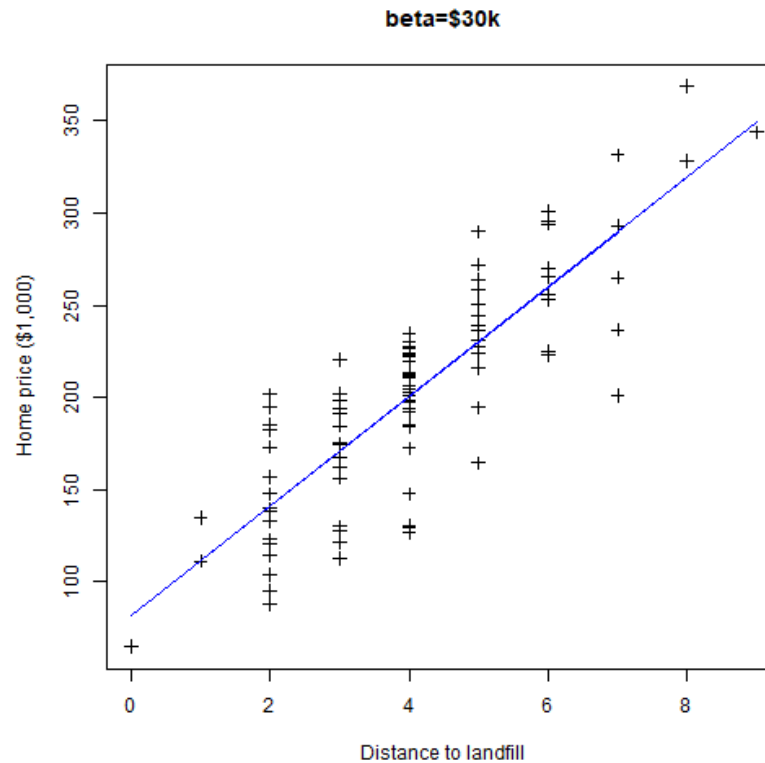
$$\frac{\partial y}{\partial x} = \beta_1$$

It is the slope of a line (rise over run)

In a linear equation relating x to y , it is the **marginal effect** of x .

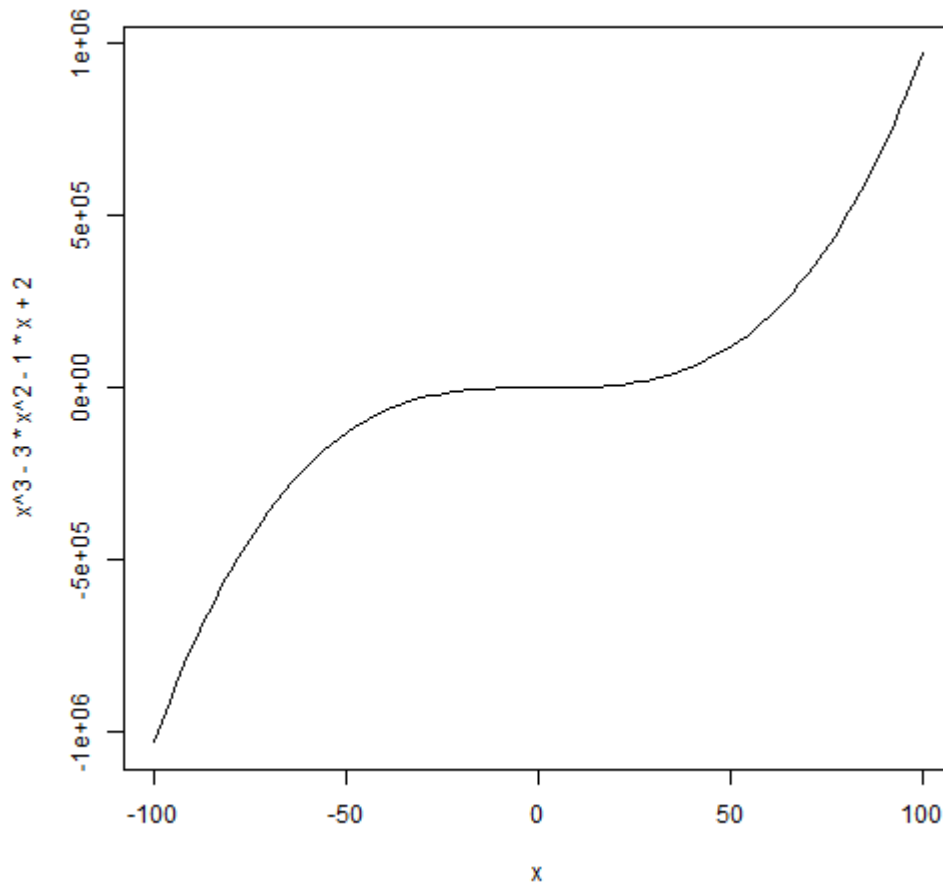
$$\text{home price} = \beta_0 + \beta_1 \times \text{distance to landfill} + \epsilon$$

$$\text{home price} = 82 + 30 \times \text{distance to landfill} + \epsilon$$



Non-linear functions: Polynomials

Polynomials take the form $ax^3 + bx^2 + cx + d$



In a linear function, the change in x (or derivative w.r.t x) is expressed only in terms of β .

In a non-linear function, the change in x depends on the value of x .

- x remains in the derivative

$$\frac{d}{dx}(ax^3 + bx^2 + cx + d) = 3ax^2 + 2bx + c$$

- The slope of the line clearly changes depending on the value of x
- The *marginal effect* is not constant across x

So a regression equation may take the form of:

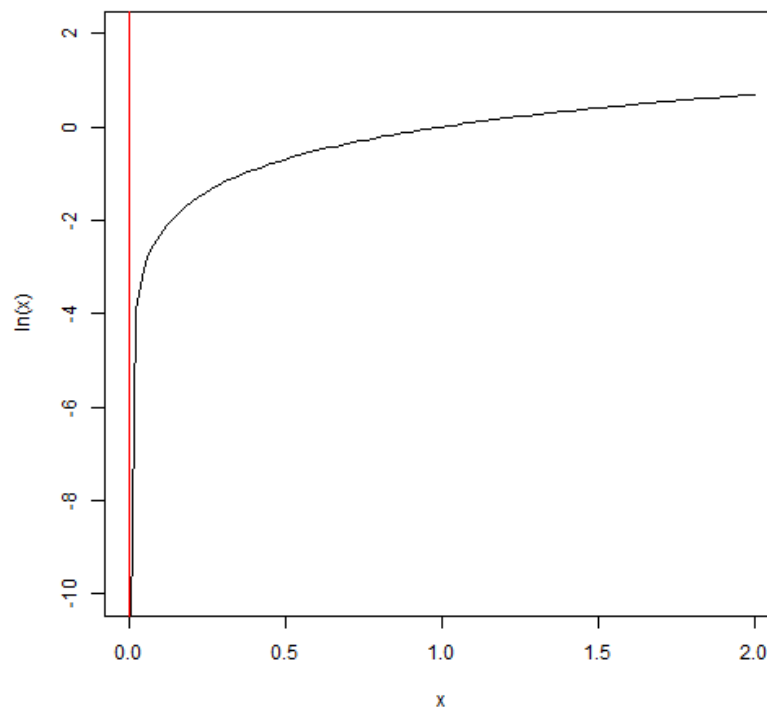
$$y = \beta_0 + \beta_1 x + \beta_2 x^2 + e$$

We can still refer to this as a linear model as it is linear in the parameters!

$$\frac{dy}{dx} \approx \beta_1 + 2\beta_2 x \quad \text{When } dx \text{ is small}$$

The natural log, $\ln(x)$

- Increasing in x
- Domain is $x > 0$
- Makes really big numbers small
- $\ln(xy) = \ln(x) + \ln(y)$
- Range is $(-\infty, +\infty)$
- In economics, "log" almost always means "natural log"



The natural log, $\ln(x)$

The natural log is particularly useful because of the following:

$$\ln(1 + x) \approx x \quad \text{when} \quad x \approx 0$$

$$\Delta \ln(x) = \ln(x^1) - \ln(x^0) = \ln\left(\frac{x^1}{x^0}\right) = \ln\left(\frac{x^0 + \Delta x}{x^0}\right) =$$

$$\ln\left(1 + \frac{\Delta x}{x^0}\right) \approx \frac{\Delta x}{x^0}$$

- This is the percent change in x : $\frac{\Delta x}{x}$
- $100 \times \Delta(\ln(x)) = 100 \times [\ln(x^1) - \ln(x^0)] \approx \% \Delta x$

The natural log, $\ln(x)$

If we have the relationship:

$$\ln(y) = \beta_0 + \beta_1 \ln(x)$$

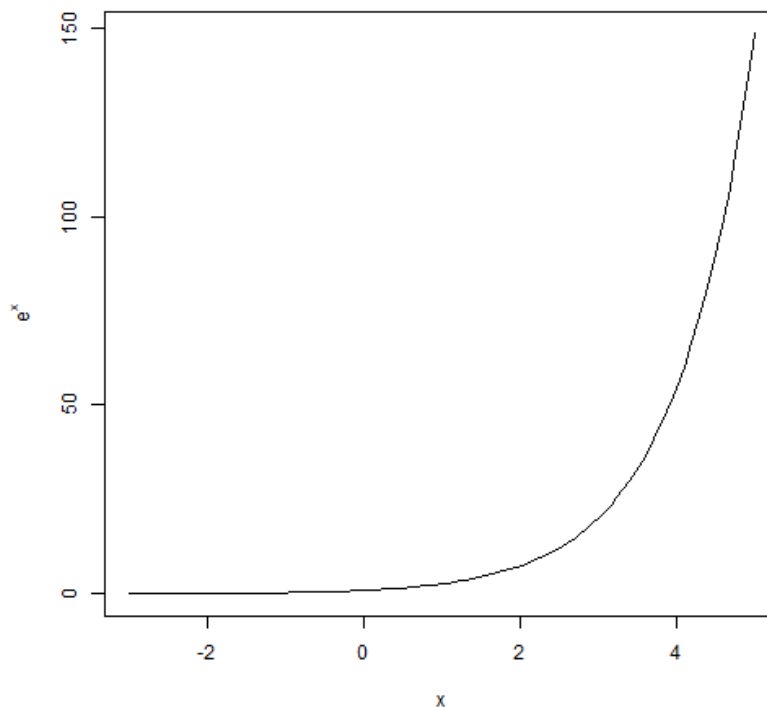
Then $\beta_1 = \frac{\Delta \ln(y)}{\Delta \ln(x)} = \frac{\% \Delta y}{\% \Delta x}$

And of course, the "percent change in y per 1 percent change in x " has a special name in economics:

It is the elasticity. $\epsilon = \beta_1$.

Exponential function: e^x

- Increasing in x
- $\frac{d}{dx}e^x = e^x$
- Domain is $(-\infty, +\infty)$
- Range is $(0, \infty)$
- $\ln(e^x) = x$
- $e^x \times e^y = e^{x+y}$
- $\frac{e^x}{e^y} = e^{x-y}$
- Explodes quickly with large x



We made it!

Now is the time to ask questions. Now is the time to say where you got lost.

Now is the time to visit instructor office hours. Some, maybe even a majority, can be perplexing - this is normal and expected.

Come to office hours and we can work through them until you're comfortable.