MATH112 FORMULAS

Notation

 $n! = 1 \cdot 2 \cdot 3 \cdot \ldots \cdot (n-1) \cdot n$ is the factorial.

 \mathbb{N} is the set of natural numbers, $\mathbb{N} = \{1, 2, 3, \ldots\}$.

 \mathbb{Z} is the set of integer numbers, $\mathbb{Z} = \{\ldots -3, -2, -1, 0, 1, 2, 3, \ldots\}$. \mathbb{Q} is the set of rational numbers, $\mathbb{Q} = \{\frac{a}{b}, \ a, b \in \mathbb{Z}, b \neq 0\}$.

I is the set of irrational numbers, which cannot be written as a fraction of two integers, for example $\sqrt{2}$, $\pi = 3, 14..., e = 2, 71...$

 \mathbb{R} is the set of real numbers, $\mathbb{R} = \mathbb{Q} \bigcup \mathbb{I}$. The real numbers may be thought of as all points on an infinitely long number line.

A = area, l = arc length, V = volume

ELEMENTARY ALGEBRA 1

1.1 Absolute value

Definition:

$$|a| = \begin{cases} a, & a \ge 0 \\ -a, & a < 0 \end{cases}$$

Properties

1)
$$|-a| = |a|$$

2)
$$\sqrt{a^2} = |a|$$

$$3) |a \cdot b| = |a| \cdot |b|$$

4)
$$||a| - |b|| \le |a + b| \le |a| + |b|$$

5)
$$||a| - |b|| \le |a - b| \le |a| + |b|$$

1.2 Degree property

For any $m, n \in \mathbb{Z}$ or for any a, b > 0 and $m, n \in \mathbb{Q}$:

1)
$$a^0 = 1$$

2)
$$a^{-m} = \frac{1}{a^m} \quad (a \neq 0)$$

$$3) \ a^m a^n = a^{m+n}$$

$$4) \quad \frac{a^m}{a^n} = a^{m-n}$$

$$5) \quad (a^m)^n = a^{mn}$$

$$6) \quad (ab)^m = a^m b^m$$

$$7) \quad \left(\frac{a}{b}\right)^m = \frac{a^m}{b^m} \quad (b \neq 0)$$

For a > 0 and $m, n \in \mathbb{Z}$, $n \neq 0$:

1)
$$a^{\frac{m}{n}} = \sqrt[n]{a^m} = (\sqrt[n]{a})^m$$

2)
$$a^{\frac{1}{n}} = \sqrt[n]{a}$$

1.3 Quadratic propositions

1)
$$(a+b)^2 = a^2 + 2ab + b^2$$

2)
$$(a-b)^2 = a^2 - 2ab + b^2$$

3)
$$(a+b)(a-b) = a^2 - b^2$$

1.4 Quadratic equation

The quadratic equation $ax^2 + bx + c = 0$, $a \neq 0$, has:

• two different roots

$$x_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$
 if the discriminant $D = b^2 - 4ac > 0$,

• one root (with multiplicity 2)

$$x_1 = x_2 = -\frac{b}{2a}$$
 if $D = 0$,

• no real roots if D < 0.

The roots x_1, x_2 of the quadratic equation $ax^2 + bx + c = 0$ satisfy

$$x_1 + x_2 = -\frac{b}{a}, \quad x_1 \ x_2 = \frac{c}{a}.$$

Quadratic factorization

If the equation $ax^2 + bx + c = 0$ has two roots x_1, x_2 then

$$ax^{2} + bx + c = a(x - x_{1})(x - x_{2}).$$

Perfect square

$$ax^{2} + bx + c = a(x + \frac{b}{2a})^{2} + \frac{4ac - b^{2}}{4a}.$$

1.5 Polynomial division

Polynomial division is an algorithm for dividing a polynomial by another polynomial of the same or lower degree.

For any polynomials f(x) and g(x), with g(x) not identical to zero, there exist unique polynomials g(x) and r(x) such that

$$\frac{f(x)}{g(x)} = q(x) + \frac{r(x)}{g(x)}$$

with r(x) having lower degree than g(x).

Example

$$f(x) = x^4 + 5x^3 + 6x^2 - 4x + 11, \quad g(x) = x^2 - 3x + 1.$$

Applying the algorithm

we get
$$q(x) = x^2 + 8x + 29$$
, $r(x) = 75x - 18$.

$$\frac{x^4 + 5x^3 + 6x^2 - 4x + 11}{x^2 - 3x + 1} = x^2 + 8x + 29 + \frac{75x - 18}{x^2 - 3x + 1}$$

1.6 Simple fractions

The rational expression $\frac{P_n(x)}{Q_m(x)}$, n < m, where $P_n(x)$, $Q_m(x)$ are polynomials of degrees n and m, respectively, can be represented as the finite sum of the simple fractions of following types:

$$\frac{A}{(x-a)^s}$$
, $s \in \mathbb{N}$, $A, a \in \mathbb{R}$

$$\frac{Bx+C}{(x^2+px+q)^r}, \quad r\in \mathbb{N}, \quad B,C,p,q\in \mathbb{R},$$

where $x^2 + px + q$ is an irreducible quadratic polynomial, i.e. its discriminant D < 0.

Examples

1)
$$\frac{P_k(x)}{(x-a)(x-b)} = \frac{A}{x-a} + \frac{B}{x-b}, \quad k \in \{0,1\}$$

2)
$$\frac{P_l}{(x-a)(x^2+px+q)} = \frac{A}{x-a} + \frac{Bx+C}{x^2+px+q}, \quad l \in \{0,1,2\}$$

3)
$$\frac{P_m}{(x-a)^2(x^2+px+q)} = \frac{A_1}{x-a} + \frac{A_2}{(x-a)^2} + \frac{Bx+C}{x^2+px+q}, \quad m \in \{0,1,2,3\}$$

4)
$$\frac{P_n}{(x-a)(x^2+px+q)^2} = \frac{A}{x-a} + \frac{B_1x + C_1}{x^2+px+q} + \frac{B_2x + C_2}{(x^2+px+q)^2}, \quad n \in \{0, 1, 2, 3, 4\}$$

1.7 The logarithm

Definition: The *logarithm* of x to the *base* a is the power to which one needs to raise a in order to get x. Symbolically, if $x = a^b$ then $\log_a(x) = b$, x > 0, a > 0, $a \ne 1$.

The logarithm to the base e is called the *natural logarithm* and denoted by $\ln(x)$. The logarithm to the base 10 is called the *common logarithm* and denoted by $\log(x)$.

Properties of logarithm

$$1) \quad a^{\log_a(x)} = x$$

$$2) \quad \log_a(a) = 1$$

$$3) \quad \log_a(1) = 0$$

4)
$$\log_a(xy) = \log_a(x) + \log_a(y)$$

5)
$$\log_a(\frac{x}{y}) = \log_a(x) - \log_a(y)$$

6)
$$\log_a(x^k) = k \log_a(x)$$

7)
$$\log_a(x) < \log_a(y) \Leftrightarrow \begin{cases} x < y & \text{if } a > 1, \\ x > y & \text{if } 0 < a < 1 \end{cases}$$

1.8 Arithmetical and Geometrical series

Arithmetical series

1)
$$a_n = a_{n-1} + d = a_1 + (n-1) d$$
, $d = \text{difference}$

2)
$$\sum_{k=1}^{n} a_k = \frac{a_1 + a_n}{2} n = \frac{2a_1 + d(n-1)}{2} n$$

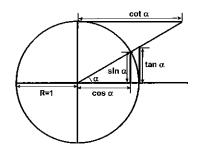
Geometrical series

1)
$$b_n = b_{n-1} \cdot q = b_0 q^n$$
, $q = \text{quotient}$

2)
$$\sum_{k=0}^{n-1} b_k = \frac{b_n q - b_0}{q - 1} = b_0 \frac{1 - q^n}{1 - q}, \quad q \neq 1$$

3)
$$\sum_{k=0}^{\infty} b_k = \frac{b_0}{1-q}, \quad -1 < q < 1$$

1.9 Trigonometry



Sign of trigonometric functions in each quadrant

	sin	cos	tan	cot
I	+	+	+	+
П	+	-	1	
III	1	-	+	+
IV		+	_	_

1) $y = \cos(x)$ is the even 2π -periodic function, i.e.

$$\cos(-x) = \cos(x)$$
$$\cos(x + 2\pi n) = \cos(x), \ n \in \mathbb{Z}$$

2) $y = \sin(x)$ is the odd 2π -periodic function, i.e.

$$\sin(-x) = -\sin(x)$$

$$\sin(x + 2\pi n) = \sin(x), n \in \mathbb{Z}$$

3) $y = \tan(x)$ is the odd π -periodic function, i.e.

$$\tan(-x) = -\tan(x)$$

$$\tan(x + \pi n) = \tan(x), \ x \neq \pi k, \ n, k \in \mathbb{Z}$$

4) $y = \cot(x)$ is the odd π -periodic function, i.e.

$$\cot(-x) = -\cot(x)$$
$$\cot(x + \pi n) = \cot(x), \ x \neq \frac{(2k+1)\pi}{2}, \ n, k \in \mathbb{Z}$$

Trigonometric identities

$$1) \quad \cos^2 \alpha + \sin^2 \alpha = 1$$

2)
$$\tan \alpha \cot \alpha = 1 \quad (\alpha \neq \frac{\pi n}{2}, n \in \mathbb{Z})$$

3)
$$\tan^2 \alpha = \frac{1}{\cos^2 \alpha} - 1 \quad (\alpha \neq \frac{\pi(2n+1)}{2}, n \in \mathbb{Z})$$

4)
$$\cot^2 \alpha = \frac{1}{\sin^2 \alpha} - 1 \quad (\alpha \neq \frac{\pi n}{2}, n \in \mathbb{Z})$$

Angle-addition and substraction formulas

1)
$$\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$$

2)
$$\cos(\alpha \pm \beta) = \cos \alpha \cos \beta \mp \sin \alpha \sin \beta$$

3)
$$\tan(\alpha \pm \beta) = \frac{\tan \alpha \pm \tan \beta}{1 \mp \tan \alpha \tan \beta}$$

4) $\cot(\alpha \pm \beta) = \frac{\cot \alpha \cot \beta \mp 1}{\cot \beta \pm \cot \alpha}$

4)
$$\cot(\alpha \pm \beta) = \frac{\cot \alpha \cot \beta \mp 1}{\cot \beta \pm \cot \alpha}$$

Some values of trigonometric functions ${\bf r}$

α°	$arc(\alpha)$	\sin	cos	tan	cot
0°	0	0	1	0	×
30°	$\frac{\pi}{6}$	$\frac{1}{2}$	$\frac{\sqrt{3}}{2}$	<u>√3</u> 3	$\sqrt{3}$
45°	π 4	$\frac{\sqrt{2}}{2}$	$\frac{\sqrt{2}}{2}$	1	1
60°	$\frac{\pi}{3}$	$\frac{\sqrt{3}}{2}$	$\frac{1}{2}$	$\sqrt{3}$	$\frac{\sqrt{3}}{3}$
90°	$\frac{\pi}{2}$	1	0	×	0
180°	π	0	-1	0	×
270°	$\frac{3\pi}{2}$	-1	0	×	0
360°	2π	0	1	0	×

Shift and periodicity formulas

	sin	cos	tan	cot
$-\alpha$	$-\sin \alpha$	$\cos \alpha$	- an lpha	$-\cot \alpha$
$\frac{\pi}{2} \pm \alpha$	$\cos \alpha$	$\mp\sinlpha$	$\mp \tan \alpha$	$\mp\cotlpha$
$\pi \pm \alpha$	$\mp\sinlpha$	$-\cos \alpha$	$\pm \tan \alpha$	$\pm \cot \alpha$
$\frac{3\pi}{2} \pm \alpha$	$-\cos\alpha$	$\pm \sin \alpha$	$\mp \cot \alpha$	$\mp \tan \alpha$
$2\pi \pm \alpha$	$\pm \sin \alpha$	$\cos \alpha$	$\pm \tan \alpha$	$\pm \cot \alpha$

The trigonometric functions in terms of the other functions

	$\sin lpha$	$\cos lpha$	an lpha	$\cot lpha$
$\sin \alpha$		$\pm\sqrt{1-\cos^2\alpha}$	$\frac{\tan\alpha}{\pm\sqrt{1+\tan^2\alpha}}$	$\frac{1}{\pm\sqrt{1+\cot^2\alpha}}$
$\cos \alpha$	$\pm\sqrt{1-\sin^2\alpha}$		$\frac{1}{\pm\sqrt{1+\tan^2\alpha}}$	$\frac{\cot\alpha}{\pm\sqrt{1+\cot^2\alpha}}$
$\tan \alpha$	$\frac{\sin\alpha}{\pm\sqrt{1-\sin^2\alpha}}$	$\frac{\pm\sqrt{1-\cos^2\alpha}}{\cos\alpha}$		$\frac{1}{\cot \alpha}$
$\cot \alpha$	$\frac{\pm\sqrt{1-\sin^2\alpha}}{\sin\alpha}$	$\frac{\cos\alpha}{\pm\sqrt{1-\cos^2\alpha}}$	$rac{1}{ an lpha}$	

Sum-to-product identities

1)
$$\sin \alpha + \sin \beta = 2 \sin \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

2)
$$\sin \alpha - \sin \beta = 2 \cos \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$

3)
$$\cos \alpha + \cos \beta = 2 \cos \frac{\alpha + \beta}{2} \cos \frac{\alpha - \beta}{2}$$

4)
$$\cos \alpha - \cos \beta = -2 \sin \frac{\alpha + \beta}{2} \sin \frac{\alpha - \beta}{2}$$

5)
$$\cos \alpha \pm \sin \beta = 2 \sin(\frac{\pi}{4} - \frac{\alpha \mp \beta}{2}) \sin(\frac{\pi}{4} + \frac{\alpha \pm \beta}{2})$$

6)
$$\cot \alpha \pm \tan \beta = \frac{\cos(\alpha \mp \beta)}{\sin \alpha \cos \beta}$$

Linear combination

1) $a \cos \alpha + b \sin \alpha = \sqrt{a^2 + b^2} \cos(\alpha - \varphi)$, $a^2 + b^2 \neq 0$, where $\cos \varphi = \frac{a}{\sqrt{a^2 + b^2}}$, $\sin\varphi = \tfrac{b}{\sqrt{a^2 + b^2}}$

2) $a \cos \alpha + b \sin \alpha = \sqrt{a^2 + b^2} \sin(\alpha + \psi)$, $a^2 + b^2 \neq 0$, where $\cos \psi = \frac{b}{\sqrt{a^2 + b^2}}$ $\sin \psi = \frac{a}{\sqrt{a^2 + b^2}}$

Double and half-angle formulas

1)
$$\sin(2\alpha) = 2\sin\alpha \cos\alpha = \frac{2\tan\alpha}{1+\tan^2\alpha}$$

2)
$$\cos(2\alpha) = \cos^2 \alpha - \sin^2 \alpha = \frac{1 - \tan^2 \alpha}{1 + \tan^2 \alpha}$$

3)
$$\tan(2\alpha) = \frac{2 \tan \alpha}{1 - \tan^2 \alpha}$$

4)
$$\cot(2\alpha) = \frac{\cot^2 \alpha - 1}{2 \cot \alpha}$$

5) $\sin^2 \frac{\alpha}{2} = \frac{1 - \cos \alpha}{2}$

$$5) \quad \sin^2 \frac{\alpha}{2} = \frac{1 - \cos \alpha}{2}$$

$$6) \quad \cos^2\frac{\alpha}{2} = \frac{1+\cos\alpha}{2}$$

7)
$$\tan \frac{\alpha}{2} = \frac{\sin \alpha}{1 + \cos \alpha} = \frac{1 - \cos \alpha}{\sin \alpha}$$

8) $\cot \frac{\alpha}{2} = \frac{\sin \alpha}{1 - \cos \alpha} = \frac{1 + \cos \alpha}{\sin \alpha}$

8)
$$\cot \frac{\alpha}{2} = \frac{\sin \alpha}{1 - \cos \alpha} = \frac{1 + \cos \alpha}{\sin \alpha}$$

Product-to-sum identities

1)
$$\sin \alpha \sin \beta = \frac{1}{2}(\cos(\alpha - \beta) - \cos(\alpha + \beta))$$

2)
$$\cos \alpha \cos \beta = \frac{1}{2}(\cos(\alpha - \beta) + \cos(\alpha + \beta))$$

2)
$$\cos \alpha \cos \beta = \frac{1}{2}(\cos(\alpha - \beta) + \cos(\alpha + \beta))$$

3) $\sin \alpha \cos \beta = \frac{1}{2}(\sin(\alpha - \beta) + \sin(\alpha + \beta))$

Inverse trigonometric functions 1.10

The inverse trigonometric functions $\arcsin x$, $\arccos x$, $\arctan x$ and $\operatorname{arccot} x$ are defined in the following way:

$$\arcsin x = y \text{ such that } \sin y = x \text{ for } -1 \le x \le 1, \, -\frac{\pi}{2} \le y \le \frac{\pi}{2},$$

$$\arccos x = y$$
 such that $\cos y = x$ for $-1 \le x \le 1$, $0 \le y \le \pi$,

$$\arctan x = y$$
 such that $\tan y = x$ for $-\infty < x < +\infty$, $-\frac{\pi}{2} < y < \frac{\pi}{2}$,

$$\operatorname{arccot} x = y$$
 such that $\cot y = x$ for $-\infty \le x \le \infty$, $0 \le y \le \pi$.

Alternative notation

$$\arcsin x = \sin^{-1} x$$
, $\arccos x = \cos^{-1} x$, $\arctan x = \tan^{-1} x$, $\operatorname{arccot} x = \cot^{-1} x$.

Correspondences between the inverse trigonometric functions

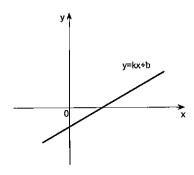
	$\arcsin x$	$\arccos x$	$\arctan x$	$\operatorname{arccot} x$
$\arcsin x$	$-\arcsin(-x)$	$\frac{\pi}{2} - \arccos x$	$\arctan \frac{x}{\sqrt{1-x^2}}$	$\frac{\pi}{2} - \operatorname{arccot} \frac{x}{\sqrt{1-x^2}}$
$\arccos x$	$\frac{\pi}{2} - \arcsin x$	$\pi - \arccos(-x)$	$\frac{\pi}{2} - \arctan \frac{x}{\sqrt{1-x^2}}$	$\operatorname{arccot} \frac{x}{\sqrt{1-x^2}}$
$\arctan x$	$\arcsin(\frac{x}{\sqrt{1+x^2}})$	$\frac{\pi}{2} - \arccos(\frac{x}{\sqrt{1+x^2}})$	$-\arctan(-x)$	$\frac{\pi}{2} - \operatorname{arccot} x$
$\operatorname{arccot} x$	$\frac{\pi}{2} - \arcsin(\frac{x}{\sqrt{1+x^2}})$	$\arccos(\frac{x}{\sqrt{1+x^2}})$	$\frac{\pi}{2} - \arctan x$	$\pi - \operatorname{arccot}(-x)$

Trigonometric equations

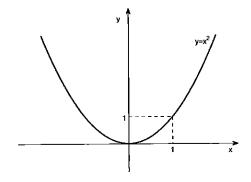
1)
$$\sin x = c$$
, $c \in [-1, 1]$ \Leftrightarrow $x = \begin{cases} \arcsin c + 2\pi k, & k \in \mathbb{Z} \\ (\pi - \arcsin c) + 2\pi k, & k \in \mathbb{Z} \end{cases}$
2) $\cos x = c$, $c \in [-1, 1]$ \Leftrightarrow $x = \begin{cases} \arccos c + 2\pi k, & k \in \mathbb{Z} \\ -\arccos c + 2\pi k, & k \in \mathbb{Z} \end{cases}$
3) $\tan x = c$ \Leftrightarrow $x = \arctan c + \pi k, & k \in \mathbb{Z} \end{cases}$

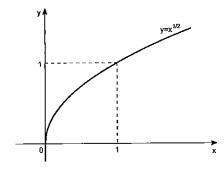
1.11 Graphs of some elementary functions

Linear function y = kx + b

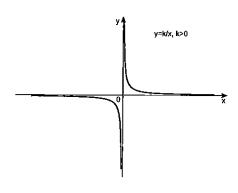


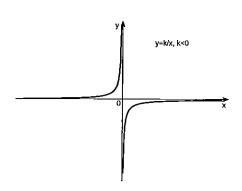
Power function $y = x^n$



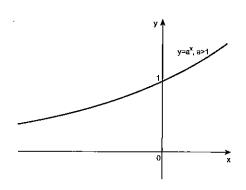


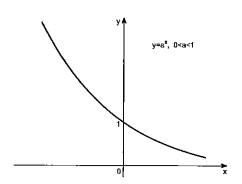
Linear-fractional function $y = \frac{k}{x} \ (k \neq 0, x \neq 0)$



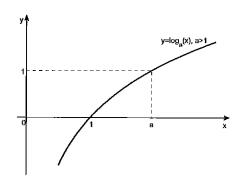


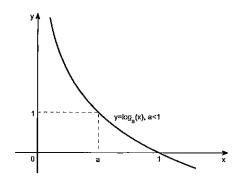
Exponential function $y = a^x \ (a > 0, \ a \neq 1)$



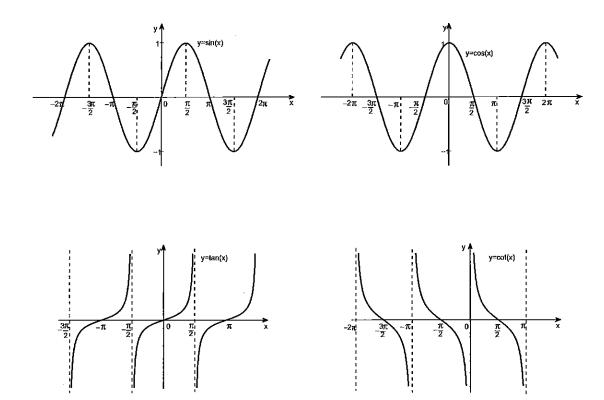


Logarithmic function $y = \log_a(x)$ $(a > 0, a \neq 1, x > 0)$

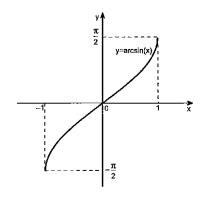


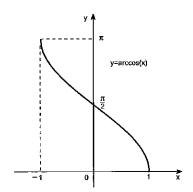


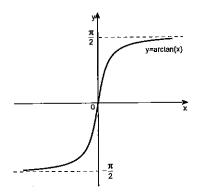
Trigonometric functions

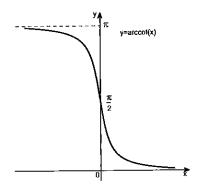


Arc trigonometric functions









2 CALCULUS I

2.1 Limits

Limit laws

Let L, M, c and k be real numbers and $\lim_{x\to c} f(x) = L$, $\lim_{x\to c} g(x) = M$. Then

1)
$$\lim_{x \to c} (f(x) \pm g(x)) = L \pm M$$

2)
$$\lim_{x\to c} kf(x) = kL$$

3)
$$\lim_{x \to c} f(x)g(x) = LM$$

4)
$$\lim_{x \to c} \frac{f(x)}{g(x)} = \frac{L}{M}, M \neq 0$$

5)
$$\lim_{x\to c} (f(x))^q = L^q, q \in \mathbb{Q}$$

6) L'Hospital's rule. Assume that

(i) $g(x) \neq 0$ and f(x), g(x) have continuous derivatives in a deleted neighborhood about c (or ∞)

(ii)
$$f(x), g(x) \to 0$$
 (or ∞) as $x \to c$ (or $x \to \infty$)

then

$$\lim_{egin{array}{c} x
ightarrow c \ (x
ightarrow \infty) \end{array}} rac{f(x)}{g(x)} = \lim_{egin{array}{c} x
ightarrow c \ (x
ightarrow \infty) \end{array}} rac{f'(x)}{g'(x)}$$

if the limit on the right hand side exists.

Useful limits

1)
$$\lim_{\substack{x \to c \\ (x \to \infty)}} k = k$$

$$2) \lim_{x \to \infty} x^n = \infty$$

3)
$$\lim_{x \to -\infty} x^n = \begin{cases} \infty & \text{if } n \text{ is even,} \\ -\infty & \text{if } n \text{ is odd} \end{cases}$$

$$4) \lim_{x\to\infty}\frac{1}{x^n}=0$$

5)
$$\lim_{x \to \infty} \frac{a_m x^m + \dots a_0}{b_n x^n + \dots + b_0} = \begin{cases} 0 & \text{if } m < n, \\ \frac{a_m}{b_n} & \text{if } m = n \\ \infty & \text{if } m > n \end{cases}$$

$$6) \lim_{x \to 0} \frac{\sin x}{x} = 1$$

$$7) \lim_{x \to \infty} \left(1 + \frac{1}{x} \right)^x = e$$

8)
$$\lim_{x \to \infty} x^{1/x} = 1$$
,

where c, k, n, m are constants, n, m > 0 and $a_m, b_n \neq 0$.

2.2Continuity

Definition: A function y = f(x) is continuous at x_0 if x_0 belongs to the domain of f(x)and $\lim_{x\to x_0} f(x) = f(x_0)$.

A function f is continuous in an interval I if f is continuous at every point of I. We call

f continuous if f is continuous in its domain.

Properties

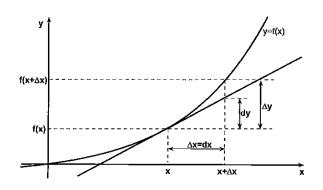
Let f and g be continuous then the following functions are continues (where they are defined)

$$f(x) \pm g(x), \quad f(x)g(x), \quad \frac{f(x)}{g(x)} \ (g(x) \neq 0), \quad f(g(x)).$$

2.3 Differentiation

Definition: The derivative f'(x) of a function y = f(x) is defined by

$$f'(x) = \lim_{\triangle x \to 0} \frac{f(x + \triangle x) - f(x)}{\triangle x} = \lim_{\triangle x \to 0} \frac{\triangle y}{\triangle x}.$$



Alternative notation: $y' = f'(x) = \frac{dy}{dx} = \frac{d}{dx}f(x)$ Second derivative: f''(x) = [f'(x)]'

Differentiation rules

Assume u and v are differentiable functions of x.

1)
$$\frac{d}{dx}(c) = 0$$
, $c = const$

2)
$$\frac{d}{dx}(u \pm v) = \frac{du}{dx} \pm \frac{dv}{dx}$$

3)
$$\frac{d}{dx}(cu) = c \frac{du}{dx}$$
, $c = const$

4)
$$\frac{d}{dx}(uv) = u \frac{dv}{dx} + v \frac{du}{dx}$$

5)
$$\frac{d}{dx}\left(\frac{u}{v}\right) = \frac{\frac{du}{dx}v - u\frac{dv}{dx}}{v^2}$$

6) Chain rule:
$$\frac{d}{dx}(f(g(x))) = f'(g(x)) \cdot g'(x)$$

Useful derivatives

1)
$$\frac{d}{dx}(c) = 0$$
, $c = \text{const}$

1)
$$\frac{d}{dx}(c) = 0$$
, $c = \text{const}$ 8) $\frac{d}{dx}(\cos x) = -\sin x$

$$2) \, \frac{d}{dx}(x^r) = rx^{r-1}$$

2)
$$\frac{d}{dx}(x^r) = rx^{r-1}$$
 9) $\frac{d}{dx}(\tan x) = \frac{1}{\cos^2 x}$

$$3) \frac{d}{dx}(e^x) = e^x$$

3)
$$\frac{d}{dx}(e^x) = e^x$$
 10)
$$\frac{d}{dx}(\cot x) = \frac{-1}{\sin^2 x}$$

$$4) \frac{d}{dx}(a^x) = a^x \ln a$$

4)
$$\frac{d}{dx}(a^x) = a^x \ln a$$
 11) $\frac{d}{dx}(\arcsin x) = \frac{1}{\sqrt{1-x^2}}$

$$5) \frac{d}{dx}(\ln x) = \frac{1}{x}$$

5)
$$\frac{d}{dx}(\ln x) = \frac{1}{x}$$
 12) $\frac{d}{dx}(\arccos x) = \frac{-1}{\sqrt{1-x^2}}$

6)
$$\frac{d}{dx}(\log_a x) = \frac{1}{x \ln a}$$

6)
$$\frac{d}{dx}(\log_a x) = \frac{1}{x \ln a}$$
 13) $\frac{d}{dx}(\arctan x) = \frac{1}{1+x^2}$

$$7) \frac{d}{dx}(\sin x) = \cos x$$

7)
$$\frac{d}{dx}(\sin x) = \cos x$$
 14) $\frac{d}{dx}(\operatorname{arccot} x) = \frac{-1}{1+x^2}$

2.4 Indefinite integral

Definition: $F(x) = \int f(x)dx$ means that F'(x) = f(x).

Any primitive function of f(x) can be written F(x) + C, where C is an arbitrary constant.

General properties

1)
$$\int k \cdot u(x) dx = k \int u(x) dx$$
, $k = \text{const}$

2)
$$\int (u(x) \pm v(x))dx = \int u(x)dx \pm \int v(x)dx$$

3) Integration by parts:
$$\int u'(x)v(x)dx = u(x)v(x) - \int u(x)v'(x)dx$$

4) Substitution:
$$\int f(g(x)) \cdot g'(x) dx = \int f(t) dt$$
, where $t = g(x)$, $dt = g'(x) dx$

Useful integration formulas

1)
$$\int kdu = ku + C$$
, $k = \text{const}$

8)
$$\int e^u du = e^u + C$$

2)
$$\int u^n du = \frac{u^{n+1}}{n+1} + C, \ n \neq -1$$

2)
$$\int u^n du = \frac{u^{n+1}}{n+1} + C$$
, $n \neq -1$ 9) $\int a^u du = \frac{a^u}{\ln a} + C$ $(a \neq 1, a > 0)$

3)
$$\int \frac{du}{u} = \ln|u| + C$$

$$10) \int \frac{du}{\sqrt{a^2 - u^2}} = \arcsin \frac{u}{a} + C$$

4)
$$\int \sin u du = -\cos u + C$$

4)
$$\int \sin u du = -\cos u + C$$
 11)
$$\int \frac{du}{a^2 + u^2} = \frac{1}{a} \arctan \frac{u}{a} + C$$

$$5) \int \cos u du = \sin u + C$$

12)
$$\int \frac{du}{a^2 - u^2} = \frac{1}{2a} \ln \left| \frac{u + a}{u - a} \right| + C$$

6)
$$\int \frac{du}{\cos^2 u} = \tan u + C$$

6)
$$\int \frac{du}{\cos^2 u} = \tan u + C$$
 13) $\int \frac{du}{\sqrt{a^2 + u^2}} = \ln|u + \sqrt{a^2 + u^2}| + C$

$$7) \int \frac{du}{\sin^2 u} = -\cot u + C$$

2.5 Definite integral

The fundamental theorem of calculus

$$\int_a^b f(x)dx = F(b) - F(a), \text{ where } F'(x) = f(x).$$

Some properties

$$1) \int_a^a f(x)dx = 0$$

2)
$$\int_a^b f(x)dx = -\int_b^a f(x)dx$$

3)
$$\int_a^b f(x)dx = \int_a^c f(x)dx + \int_c^b f(x)dx$$
, where $a \le c \le b$

4)
$$f(x) \le g(x) \implies \int_a^b f(x)dx \le \int_a^b g(x)dx$$

5) Integration by parts:
$$\int_a^b u'(x)v(x)dx = u(x)v(x) \mid_a^b - \int_a^b u(x)v'(x)dx$$

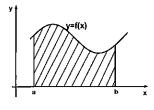
6) Substitution:
$$\int_a^b f(g(x)) \cdot g'(x) dx = \int_\alpha^\beta f(t) dt$$
, where $t = g(x)$, $dt = g'(x) dx$, $\alpha = g(a)$, $\beta = g(b)$

2.6 Applications of integrals

Curves in a function form y = f(x)

$$A = \int_a^b f(x)dx$$
 if $f(x) \ge 0$ on $[a,b]$ (Fig.1)

$$A = \int_a^b (f(x) - g(x)) dx$$
 if $f(x) \ge g(x)$ on $[a, b]$ (Fig.2)



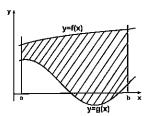


Fig. 1

Fig. 2

$$l = \int_a^b \sqrt{1 + (f'(x))^2} dx$$

$$V_x = \pi \int_a^b (f(x))^2 dx,$$

when one rotates the area bounded by the curve y = f(x), x-axis and the lines x = a, x = b about x-axis.

Curves in a parametric form $\left\{ egin{array}{ll} x=x(t) \\ y=y(t) \end{array}
ight.$ ${
m a}\leq {
m t}\leq {
m b}$

$$A = \int_{a}^{b} y(t)\dot{x}(t)dt \ y \ge 0$$
$$l = \int_{a}^{b} \sqrt{(\dot{x}(t))^{2} + (\dot{y}(t))^{2}}dt$$

Curves in polar coordinates $x = r\cos\theta$, $y = r\sin\theta$

Curve $C: r = r(\theta), \ \alpha \leq \theta \leq \beta$

$$A = \frac{1}{2} \int_{\alpha}^{\beta} r^{2}(\theta) d\theta \quad \text{(see Fig.3)}$$
$$l = \int_{\alpha}^{\beta} \sqrt{(r(\theta))^{2} + (r'(\theta))^{2}} d\theta$$

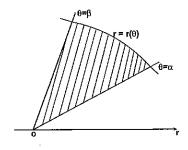


Fig. 3

2.7 Improper integrals

Integrals with infinite limits of integration

1) If f(x) is continuous on $[a, \infty)$, then

$$\int_{a}^{\infty} f(x)dx = \lim_{b \to \infty} \int_{a}^{b} f(x)dx.$$

2) If f(x) is continuous on $(-\infty, b]$, then

$$\int\limits_{-\infty}^{b}f(x)dx=\lim_{a o -\infty}\int\limits_{a}^{b}f(x)dx.$$

3) If f(x) is continuous on $(-\infty, \infty)$, then

$$\int_{-\infty}^{\infty} f(x)dx = \int_{-\infty}^{c} f(x)dx + \int_{c}^{\infty} f(x)dx,$$

where c is any real number.

Integrals of functions that become infinite at a point within the interval of integration

1) If f(x) is continuous on (a, b] and is discontinuous at a, then

$$\int\limits_a^b f(x)dx = \lim\limits_{c o a^+} \int\limits_c^b f(x)dx.$$

2) If f(x) is continuous on [a, b) and is discontinuous at b, then

$$\int_{a}^{b} f(x)dx = \lim_{c \to b^{-}} \int_{a}^{c} f(x)dx.$$

3) If f(x) is discontinuous at c, where a < c < b and continuous on $[a, c) \bigcup (c, b]$, then

$$\int_{b}^{a} f(x)dx = \int_{a}^{c} f(x)dx + \int_{c}^{b} f(x)dx.$$

2.8 Infinite sequences of real numbers

Sequence convergence laws

Let $\{a_n\}$ and $\{b_n\}$ be sequences of real numbers such that

$$\lim_{n \to \infty} a_n = A, \lim_{n \to \infty} b_n = B, \quad A, B \in \mathbb{R}.$$

- 1) $\lim_{n\to\infty} (a_n \pm b_n) = A \pm B$
- 2) $\lim_{n\to\infty}ka_n=kA, k=\mathrm{const}$
- $3) \lim_{n \to \infty} a_n b_n = AB$
- 4) $\lim_{n\to\infty} \frac{a_n}{b_n} = \frac{A}{B} \ (B \neq 0)$
- 5) The sandwich theorem. Let $\{a_n\}$, $\{b_n\}$ and $\{c_n\}$ be sequences of real numbers. If $a_n \leq b_n \leq c_n$, for all $n \geq N$ and $\lim_{n \to \infty} a_n = \lim_{n \to \infty} c_n = L$, then $\lim_{n \to \infty} b_n = L$ also.

Useful convergent sequences

$$1) \lim_{n\to\infty} \frac{\ln n}{n} = 0$$

$$2) \lim_{n \to \infty} {}^n \sqrt{n} = 1$$

3)
$$\lim_{n\to\infty} a^{1/n} = 1 \ (a>0)$$

4)
$$\lim_{n\to\infty} a^n = 0 \ (|a| < 1)$$

5)
$$\lim_{n \to \infty} \left(1 + \frac{a}{n} \right)^n = e^a$$

$$6) \lim_{n \to \infty} \frac{a^n}{n!} = 0$$

2.9 Infinite series

Series convergence laws

Let
$$\sum_{n=1}^{\infty} a_n = A$$
 and $\sum_{n=1}^{\infty} b_n = B$. Then

1)
$$\sum_{n=1}^{\infty} (a_n \pm b_n) = A \pm B$$

2)
$$\sum_{n=1}^{\infty} k \cdot a_n = k \cdot A$$
, $k = \text{const.}$

Useful convergent series

$$p ext{-series: } \sum_{n=1}^{\infty} rac{1}{n^p} = \left\{ egin{array}{ccc} ext{converges} & ext{if} & p>1, \\ ext{diverges} & ext{if} & p\leq 1. \end{array}
ight.$$

$$\text{Geometric series: } \sum_{n=1}^{\infty} ar^{n-1} = \left\{ \begin{array}{ll} \frac{a}{1-r} & \text{if} \quad |r| < 1, \\ \\ \text{diverges} \quad \text{if} \quad |r| \geq 1 \end{array} \right.$$

Divergence test

 $\sum_{n=1}^{\infty} a_n \text{ diverges if } \lim_{n \to \infty} a_n \neq 0 \text{ or fails to exist.}$

Convergence tests

Integral test. Let $\{a_n\}$ be a nonnegative sequence. Suppose that $a_n = f(n)$, where f(x) is a continuous positive decreasing function of x for all $x \geq N$, $N \in \mathbb{N}$. Then $\sum_{n=N}^{\infty} a_n$ and $\int_{N}^{\infty} f(n) dx$ either both converge or both diverge.

Comparison test. Let $\sum_{n=1}^{\infty} a_n$, $\sum_{n=1}^{\infty} c_n$ and $\sum_{n=1}^{\infty} d_n$ be series with nonnegative terms.

- a) If $a_n \leq c_n$ for all $x \geq N$, $N \in \mathbb{N}$ and $\sum_{n=1}^{\infty} c_n$ converges, then $\sum_{n=1}^{\infty} a_n$ converges.
- b) If $a_n \geq d_n$ for all $x \geq N$, $N \in \mathbb{N}$ and $\sum_{n=1}^{\infty} d_n$ diverges, then $\sum_{n=1}^{\infty} a_n$ diverges.

Limit comparison. Suppose that $a_n > 0$ and $b_n > 0$ for all $n \geq N$, $N \in \mathbb{N}$.

- a) If $\lim_{n\to\infty} \frac{a_n}{b_n} = c > 0$, then $\sum_{n=1}^{\infty} a_n$ and $\sum_{n=1}^{\infty} b_n$ either both converge or both diverge.
- b) If $\lim_{n\to\infty} \frac{a_n}{b_n} = 0$ and $\sum_{n=1}^{\infty} b_n$ converges, then $\sum_{n=1}^{\infty} a_n$ converges.
- c) If $\lim_{n\to\infty} \frac{a_n}{b_n} = \infty$ and $\sum_{n=1}^{\infty} b_n$ diverges, then $\sum_{n=1}^{\infty} a_n$ diverges.

Ratio test. Let $\sum_{n=1}^{\infty} a_n$ be a series with positive terms and

$$\lim_{n\to\infty}\frac{a_{n+1}}{a_n}=p.$$

- a) If p < 1, then $\sum_{n=1}^{\infty} a_n$ converges.
- b) If p > 1, then $\sum_{n=1}^{\infty} a_n$ diverges.
- c) If p = 1, then the test is inconclusive.

Root test. Let $\sum_{n=1}^{\infty} a_n$ be a series with positive terms and

$$\lim_{n \to \infty} {}^n \sqrt{a}_n = p.$$

- a) If p < 1, then $\sum_{n=1}^{\infty} a_n$ converges.
- b) If p > 1, then $\sum_{n=1}^{\infty} a_n$ diverges.
- c) If p = 1, then the test is inconclusive.

Alternating series test (Leibniz's theorem). The series $\sum_{n=1}^{\infty} (-1)^{n+1} u_n$ converges if the following three conditions are satisfied:

- i) $u_n \geq 0$, for all $n \in \mathbb{N}$,
- ii) $u_n \ge u_{n+1}$ for all $n \ge N$, $N \in \mathbb{N}$,
- iii) $\lim_{n\to\infty} u_n = 0.$

Absolute convergence test. If $\sum_{n=1}^{\infty} |a_n|$ converges, then $\sum_{n=1}^{\infty} a_n$ converges.

Taylor series

Let y = f(x) be an infinitely differentiable function on some interval containing a as an interior point. Then the Taylor series of f(x) at x = a is

$$\sum_{k=0}^{\infty} \frac{f^{(k)}(a)}{k!} (x-a)^k = f(a) + f'(a)(x-a) + \frac{f''(a)}{2!} (x-a)^2 + \dots + \frac{f^{(n)}(a)}{n!} (x-a)^n + \dots$$

If a = 0, then the series is called a Maclaurin series for f(x).

Useful series

1)
$$\frac{1}{1-x} = \sum_{k=0}^{\infty} x^k$$
, $|x| < 1$

2)
$$\frac{1}{1+x} = \sum_{k=0}^{\infty} (-1)^k x^k, \quad |x| < 1$$

3)
$$e^x = \sum_{k=0}^{\infty} \frac{x^k}{k!}, \quad x \in R$$

4)
$$\sin(x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k+1}}{(2k+1)!}, \quad x \in \mathbb{R}$$

5)
$$\cos(x) = \sum_{k=0}^{\infty} \frac{(-1)^k x^{2k}}{(2k)!}, \quad x \in \mathbb{R}$$

6)
$$\ln(x+1) = \sum_{k=1}^{\infty} \frac{(-1)^{k-1} x^k}{k}, \quad -1 < x \le 1$$

2.10 Vectors

The vector **u** from $A(a_1, a_2, a_3)$ to $B(b_1, b_2, b_3)$ is

$$\mathbf{u} = \overrightarrow{AB} = \langle b_1 - a_1, b_2 - a_2, b_3 - a_3 \rangle$$

Let $\mathbf{u} = \langle u_1, u_2, u_3 \rangle$ and $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$.

Magnitude:

 $|\mathbf{u}| = \sqrt{u_1^2 + u_2^2 + u_3^2}$ $\mathbf{u} + \mathbf{v} = \langle u_1 + v_1, u_2 + v_2, u_3 + v_3 \rangle$ Addition:

 $k\mathbf{u} = \langle ku_1, ku_2, ku_3 \rangle$ Scalar multiplication:

The dot product

$$\mathbf{u} \cdot \mathbf{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$

or

$$\mathbf{u} \cdot \mathbf{v} = |\mathbf{u}| |\mathbf{v}| \cos \theta,$$

where θ is the angle between **u** and **v**.

The cross product

$$\mathbf{u} \times \mathbf{v} = (|\mathbf{u}||\mathbf{v}|\sin\theta)\mathbf{n},$$

where θ is the angle between u and v, n is a unit vector perpendicular to the plane of uv vectors by the right-hand rule.

$$\mathbf{u} imes\mathbf{v}=\left|egin{array}{ccc} i&j&k\ u_1&u_2&u_3\ v_1&v_2&v_2\ \end{array}
ight|=\mathbf{i}\left|egin{array}{ccc} u_2&u_3\ v_2&v_3\ \end{array}
ight|-\mathbf{j}\left|egin{array}{ccc} u_1&u_3\ v_1&v_3\ \end{array}
ight|+\mathbf{k}\left|egin{array}{ccc} u_1&u_2\ v_1&v_2\ \end{array}
ight|$$

2.11Lines and planes in space

Parametric equations for the line L through $P_0(x_0, y_0, z_0)$ parallel to $\mathbf{v} = \langle v_1, v_2, v_3 \rangle$

$$L: \begin{cases} x = x_0 + tv_1 \\ y = y_0 + tv_2, & -\infty < t < \infty. \\ z = z_0 + tv_3 \end{cases}$$

The plane through $P_0(x_0, y_0, z_0)$ normal to $\mathbf{n} = A\mathbf{i} + B\mathbf{j} + C\mathbf{k}$:

$$A(x-x_0)+B(y-y_0)+C(z-z_0)=0.$$

3 CALCULUS II

3.1 Partial Derivation

Chain Rule

Let w = f(x, y, z) then

1)
$$x = x(t), y = y(t), z = z(t):$$

$$\frac{dw}{dt} = \frac{\partial f}{\partial x}\frac{dx}{dt} + \frac{\partial f}{\partial y}\frac{dy}{dt} + \frac{\partial f}{\partial z}\frac{dz}{dt}.$$

2) x = x(u, v), y = y(u, v), z = z(u, v):

$$\frac{dw}{du} = \frac{\partial f}{\partial x}\frac{dx}{du} + \frac{\partial f}{\partial y}\frac{dy}{du} + \frac{\partial f}{\partial z}\frac{dz}{du}, \quad \frac{dw}{dv} = \frac{\partial f}{\partial x}\frac{dx}{dv} + \frac{\partial f}{\partial y}\frac{dy}{dv} + \frac{\partial f}{\partial z}\frac{dz}{dv}.$$

The total differential of f is $df = f_x dx + f_y dy + f_z dz$.

The directional derivative of f at P = (x, y, z) in the direction of the unit vector $\mathbf{u} = u_1 \mathbf{i} + u_2 \mathbf{j} + u_3 \mathbf{k}$, $\mathbf{i} = (1, 0, 0)$, $\mathbf{j} = (0, 1, 0)$ and $\mathbf{k} = (0, 0, 1)$, is the number

$$(D_{\mathbf{u}}f)|_{P} = \lim_{s \to 0} \frac{f(x + su_1, y + su_2, z + su_3) - f(x, y, z)}{s}$$

The gradient of f is $grad(f) = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}$. The alternative notation $grad(f) = \nabla f$.

Properties

- 1) ∇f is normal to the level curve f(x, y, z) = C.
- 2) $D_{\mathbf{u}}f = \nabla f \cdot \mathbf{u}$
- 3) $D_{\mathbf{u}}f$ has its maximum value in the direction $\mathbf{u} = \frac{\nabla f}{|\nabla f|}$, and it is equal $|\nabla f|$.
- 4) Algebraic properties:

$$\nabla(kf) = k\nabla f$$
 for any $k = const$, $\nabla(f \pm g) = \nabla f \pm \nabla g$,

$$\nabla(fg) = f\nabla g + g\nabla f,$$
 $\qquad \qquad \nabla\left(\frac{f}{g}\right) = \frac{g\nabla f - f\nabla g}{g^2}.$

3.2 Tangent plane and normal line

The tangent plane to f(x, y, z) = c at $P = (x_0, y_0, z_0)$ is

$$f_x(P)(x-x_0) + f_y(P)(y-y_0) + f_z(P_0)(z-z_0) = 0.$$

If the surface is given by z = f(x, y), the tangent plane at $P = (x_0, y_0, f(x_0, y_0))$ is

$$f_x(x_0, y_0)(x - x_0) + f_y(x_0, y_0)(y - y_0) - (z - z_0) = 0.$$

The normal line to f(x, y, z) = c at $P = (x_0, y_0, z_0)$ is

$$x = x_0 + f_x(P)t$$
, $y = y_0 + f_y(P)t$, $z = z_0 + f_z(P)t$.

The tangent plain to a parameterized surface $S: r(u, v) = x(u, v)\mathbf{i} + y(u, v)\mathbf{j} + z(u, v)\mathbf{k}$ at $P = (x_0, y_0, z_0)$ is

$$A(x - x_0) + B(y - y_0) + C(z - z_0) = 0,$$

where the normal vector $\mathbf{n} = (A, B, C) = \mathbf{r}_u \times \mathbf{r}_v$,

$$\mathbf{r}_{u} = \frac{d\mathbf{r}}{du} = \frac{dx}{du}\mathbf{i} + \frac{dy}{du}\mathbf{j} + \frac{dz}{du}\mathbf{k}, \quad \mathbf{r}_{v} = \frac{d\mathbf{r}}{dv} = \frac{dx}{dv}\mathbf{i} + \frac{dy}{dv}\mathbf{j} + \frac{dz}{dv}\mathbf{k}.$$

3.3 Extreme Values and Saddle Points

Derivative test for local extreme values for functions of two variables Let (a, b) be a critical point of the function f(x, y) and D(a, b) is given as

$$D(a,b) = \left|egin{array}{ccc} f_{xx}(a,b) & f_{xy}(a,b) \ f_{yx}(a,b) & f_{yy}(a,b) \end{array}
ight|.$$

- 1) f has a local maximum at (a,b) if D(a,b) > 0 and $f_{xx}(a,b) < 0$,
- 2) f has a local minimum at (a,b) if D(a,b) > 0 and $f_{xx}(a,b) > 0$,
- 3) f has a saddle point at (a, b) if D(a, b) < 0,
- 4) The test is inconclusive if D(a, b) = 0.

Global extreme points

Let f(x,y) is defined on a closed domain R. The global extremums of f(x,y) can occur only at boundary points of R or at critical points of the function in R.

Method of Lagrange Multipliers

The necessary condition for maximum or minimum of f(x, y, z) with the constrain g(x, y, z) = 0 is

$$\nabla f = \lambda \nabla g, \quad g(x, y, z) = 0.$$

If there are two constrains $g_1(x, y, z) = 0$ and $g_2(x, y, z) = 0$, then the condition is

$$abla f = \lambda \nabla g_1 + \mu \nabla g_2, \quad g_1(x,y,z) = 0, \ g_2(x,y,z) = 0.$$

Global extreme points of f(x, y, z) with constrains

Global maximum(minimum) value of f(x,y) with constrains can be found as the largest(smallest) value that f takes in critical points defined by Lagrange method.

3.4 Coordinate conversion formulas

Cylindrical to rectangular:

$$x = r \cos \theta$$

 $y = r \sin \theta$
 $z = z$

Spherical to rectangular:

$$x = \rho \sin \phi \cos \theta$$
$$y = \rho \sin \phi \sin \theta$$
$$z = \rho \cos \phi$$

Spherical to cylindrical:

$$r = \rho \sin \phi$$
$$z = \rho \cos \phi$$
$$\theta = \theta$$

Corresponding formulas for dV in triple integrals:

$$dV = dx dy dz = dz r dr d\theta = \rho^2 \sin \phi d\rho d\phi d\theta$$

3.5 Multiple integrals

Double integral $\iint_R f(x,y)dA$ or $\iint_R f(x,y)dxdy$

Fubini's formula Let f(x,y) be continuous on a region R

1) If $R: a \leq x \leq b$, $\alpha(x) \leq y \leq \beta(x)$, then

$$\iint\limits_R f(x,y)dxdy = \int\limits_a^b \int\limits_{\alpha(x)}^{\beta(x)} f(x,y)dydx$$

2) If $R: \gamma(y) \le x \le \delta(y), c \le y \le d$, then

$$\iint\limits_{\mathbb{R}} f(x,y)dxdy = \int\limits_{c}^{d} \int\limits_{\gamma(y)}^{\delta(y)} f(x,y)dxdy$$

Application of double integral

$$A(R) = \iint\limits_R dx dy$$

$$V(D) = \iint\limits_R (f(x,y) - g(x,y)) dx dy, \text{ where } g(x,y) \le z \le f(x,y) \text{ (see Fig.4)}$$

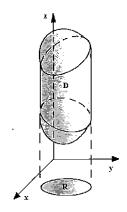


Fig. 4

Integration by substitution

$$\iint\limits_{R_{xv}} f(x,y)dxdy = \iint\limits_{R_{xv}} f(x(u,v),y(u,v))|J(u,v)|dudv$$

where

$$J(u,v) = \left| egin{array}{cc} x_u & x_v \ y_u & y_v \end{array}
ight|.$$

For example, J = r for polar coordinates.

Triple integral
$$\iiint\limits_D f(x,y,z) dV$$
 or $\iiint\limits_D f(x,y,z) dx dy dz$

Fubini's formula Let f(x, y, z) be continuous on a region D given as

$$\gamma(y,z) \le x \le \delta(y,z), \ \alpha(z) \le y \le \beta(z), \ a \le z \le b.$$

$$\int \int \int \int f(x,y,z) dx dy dz = \int_a^b \int_{lpha(z)}^{eta(z)} \int_{\gamma(y,z)}^{\delta(y,z)} f(x,y,z) dx \; dy \; dz.$$

Application of triple integral

$$V(D) = \iiint_D dxdydz$$
 (see Fig. 4)

Integration by substitution

$$\iint\limits_{D_{xyz}} f(x,y,z) dx dy dz = \iint\limits_{D_{uvw}} f(x(u,v,w),y(u,v,w),z(u,v,w)) |J(u,v,w)| du dv dw$$

where

$$J(u,v,w) = \left|egin{array}{ccc} x_u & x_v & x_w \ y_u & y_v & y_w \ z_u & z_v & z_w \end{array}
ight|.$$

For example, J=r for cylindrical coordinates and $J=\rho^2\sin\Phi$ for spherical coordinates.

3.6 Integration in Vector Fields

Line integrals $\int_C f(x, y, z) ds$

Curve $C: \mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}, \ a \le t \le b$. Then

$$d\mathbf{r} = (dx, dy, dz), \quad ds = |d\mathbf{r}| = \sqrt{(x')^2 + (y')^2 + (z')^2} dt.$$

Line integral is $\int\limits_C f(x,y,z)ds = \int\limits_a^b f(x(t),y(t),z(t))\sqrt{(x')^2+(y')^2+(z')^2}dt$.

The length of the curve C is $l = \int_C ds = \int_a^b \sqrt{(x')^2 + (y')^2 + (z')^2} dt$.

The mass of the curve C with density $\sigma = \sigma(x,y,z)$ is $M = \int_C \sigma(x,y,z) ds$.

Let $C: \mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}$ be a closed curve in the plane, \mathbf{n} be the outward-pointing unit normal vector to the curve C, and $\mathbf{F} = M(x,y)\mathbf{i} + N(x,y)\mathbf{j}$ be a vector field. Then the flux across the curve C is

$$\int\limits_{C} \mathbf{F} \cdot \mathbf{n} ds = \int\limits_{C} (M \frac{dy}{ds} - N \frac{dx}{ds}) ds = \oint\limits_{C} M dy - N dx.$$

Let **T** be a unit tangent vector, **n** be a outward-pointing unit normal vector to the curve C, $\mathbf{F}(x,y,z) = M(x,y,z)\mathbf{i} + N(x,y,z)\mathbf{j} + P(x,y,z)\mathbf{k}$ be a vector field. Then the flow along C is

$$\int\limits_C \mathbf{F} \cdot \mathbf{T} ds = \int\limits_C \mathbf{F} \cdot d\mathbf{r} = \int\limits_a^b M dx + N dy + P dz = \int\limits_a^b \left(M \frac{dx}{dt} + N \frac{dy}{dt} + P \frac{dz}{dt} \right) dt.$$

The *circulation* of a field $\mathbf{F} = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$ around a closed positive oriented curve C is $\oint_C \mathbf{F} \cdot \mathbf{T} ds$.

The work done by a force **F** over C is $W = \int_C \mathbf{F} \cdot \mathbf{T} ds$.

Fundamental theorem of line integrals

If **F** is conservative, i.e. $\mathbf{F} = \nabla f$, then $\int_A^B \mathbf{F} \cdot d\mathbf{r}$ is independent of the path joining A and B and

$$\int_{A}^{B} \mathbf{F} \cdot d\mathbf{r} = f(B) - f(A).$$

Component test for conservative fields

1)
$$\mathbf{F} = M\mathbf{i} + N\mathbf{j}$$
 is conservative if and only if $\frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}$.

2) $\mathbf{F} = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$ is conservative if and only if

$$\frac{\partial P}{\partial y} = \frac{\partial N}{\partial z}, \quad \frac{\partial M}{\partial z} = \frac{\partial P}{\partial x}, \quad \frac{\partial N}{\partial x} = \frac{\partial M}{\partial y}.$$

Green's theorem in the plane

1) The circulation of a field $\mathbf{F} = M\mathbf{i} + N\mathbf{j}$ around a closed positive oriented curve C is given as

$$\oint\limits_C (\mathbf{F}\cdot\mathbf{T})ds = \oint\limits_C Mdx + Ndy = \iint\limits_R \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y}\right)dA$$

where the region R is enclosed by C (see Fig. 5).

2) Flux of the field $F = M\vec{i} + N\vec{j}$ across closed positive oriented curve C is given as

$$\oint\limits_C (\mathbf{F}\cdot\mathbf{n})ds = \oint\limits_C M dy - N dx = \iint\limits_R \left(rac{\partial M}{\partial x} + rac{\partial N}{\partial y}
ight) dA$$

where the region R is enclosed by C (see Fig. 5).

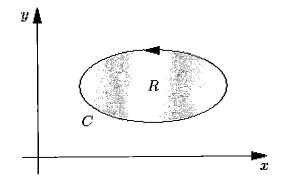


Fig. 5

Surface integrals $\iint_S g(x, y, z) d\sigma$

1)Let surface S be given by f(x, y, z) = c, R be the "shadow" of S on a coordinate plane, **p** be a unit vector normal to R such that $\nabla f \cdot \mathbf{p} \neq 0$. Then the surface area differential $d\sigma$ is

$$d\sigma = rac{|
abla f|}{|
abla f \cdot \mathbf{p}|} dA$$

and the surface integral is

$$\iint\limits_{S}g(x,y,z)d\sigma=\iint\limits_{R}g(x,y,z)rac{|
abla f|}{|
abla f\cdot\mathbf{p}|}dA.$$

The flux of a three-dimensional vector field \mathbf{F} across an oriented surface S in the direction of \mathbf{n} is

$$Flux = \iint_{\sigma} \mathbf{F} \cdot \mathbf{n} d\sigma,$$

where n is one of the two fields $\mathbf{n} = \pm \frac{\nabla f}{|\nabla f|}$, depending on which one gives the preferred direction.

2) Let S be a smooth surface given by

$$r(u,v) = x(u,v)\mathbf{i} + y(u,v)\mathbf{j} + z(u,v)\mathbf{k}, \quad a \le u \le b, \quad c \le v \le d.$$

Then the surface area differential $d\sigma$ is

$$d\sigma = |r_u \times r_v| du dv,$$

where

$$\mathbf{r}_{u} = \frac{d\mathbf{r}}{du} = \frac{dx}{du}\mathbf{i} + \frac{dy}{du}\mathbf{j} + \frac{dz}{du}\mathbf{k}, \quad \mathbf{r}_{v} = \frac{d\mathbf{r}}{dv} = \frac{dx}{dv}\mathbf{i} + \frac{dy}{dv}\mathbf{j} + \frac{dz}{dv}\mathbf{k},$$

and the area of S is

$$A = \int\limits_{c}^{d}\int\limits_{a}^{b}|r_{u} imes r_{v}|dudv.$$

The parametric surface integral is given by

$$\iint\limits_S g(x,y,z)d\sigma = \int\limits_c^d \int\limits_a^b g(x(u,v),y(u,v),z(u,v)) |r_u imes r_v| du dv.$$

The flux of a vector field F across an oriented smooth surface S in the direction of n is

$$Flux = \int \int \limits_{\mathcal{C}} \mathbf{F} \cdot \mathbf{n} d\sigma,$$

where n is one of the two fields $\mathbf{n} = \pm \frac{r_u \times r_v}{|r_u \times r_v|}$, depending on which one gives the preferred direction.

Denote by ∇ the operator given by $\nabla = \frac{\partial}{\partial x}\mathbf{i} + \frac{\partial}{\partial y}\mathbf{j} + \frac{\partial}{\partial z}\mathbf{k}$. For instance, when ∇ applied to a scalar function f = f(x, y, z), it gives the gradient of f

$$\nabla f = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}.$$

The divergence (flux density) of a vector field $\mathbf{F} = M(x,y,z)\mathbf{i} + N(x,y,z)\mathbf{j} + P(x,y,z)\mathbf{k}$ is

$$div\mathbf{F} = \nabla \cdot \mathbf{F} = \frac{\partial M}{\partial x} + \frac{\partial N}{\partial y} + \frac{\partial P}{\partial z}.$$

The curl vector (circulation density) of a vector field F is

$$curl\mathbf{F} = \nabla \times \mathbf{F} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ M & N & P \end{vmatrix} = \left(\frac{\partial P}{\partial y} - \frac{\partial N}{\partial z} \right) \mathbf{i} + \left(\frac{\partial M}{\partial z} - \frac{\partial P}{\partial x} \right) \mathbf{j} + \left(\frac{\partial N}{\partial x} - \frac{\partial M}{\partial y} \right) \mathbf{k}.$$

Stoke's theorem

The circulation of a vector field $\mathbf{F} = M\mathbf{i} + N\mathbf{j} + P\mathbf{k}$ around the boundary C of an oriented surface S in the direction counterclockwise with respect to the surface's unit normal vector \mathbf{n} equals the integral of $\nabla \times \mathbf{F} \cdot \mathbf{n}$ over S:

$$\oint\limits_C \mathbf{F} \cdot d\mathbf{r} = \iint\limits_S \nabla \times \mathbf{F} \cdot \mathbf{n} d\sigma \quad \text{(see Fig. 6)}.$$

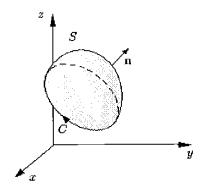


Fig. 6

Gauss' theorem (Divergence theorem)

The flux of a vector field \mathbf{F} across a closed oriented surface S in the direction of the surface's outward unit normal vector \mathbf{n} equals the integral of $\nabla \cdot \mathbf{F}$ over the region D enclosed by the surface:

$$\iint\limits_{S} \mathbf{F} \cdot \mathbf{n} d\sigma = \iiint\limits_{D} \nabla \cdot \mathbf{F} dV \quad \text{(see Fig. 7)}.$$

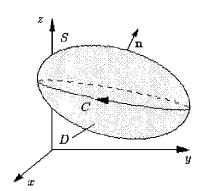
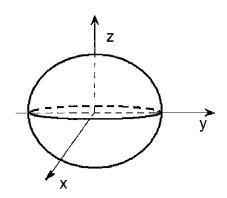


Fig. 7

3.7 Second degree surfaces in standard form

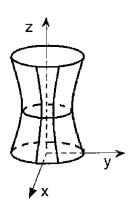
Ellipsoid

Elliptic Hyperboloid of one sheet



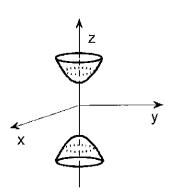
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$$

Elliptic Hyperboloid of two sheets

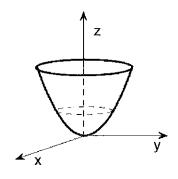


$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 1$$

Elliptic Paraboloid



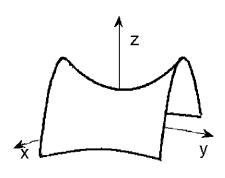
$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = -1$$

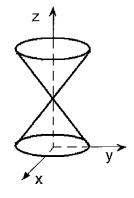


$$z = \frac{x^2}{2p} + \frac{y^2}{2q}$$

Hyperbolic Paraboloid

Elliptic Cone



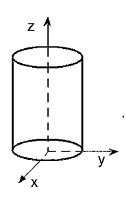


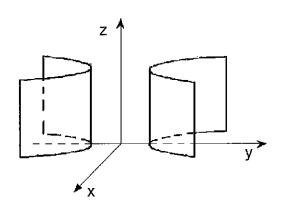
$$z = \frac{x^2}{2p} - \frac{y^2}{2q}$$

$$\frac{x^2}{a^2} + \frac{y^2}{b^2} - \frac{z^2}{c^2} = 0$$

Elliptic Cylinder

Hyperbolic Cylinder

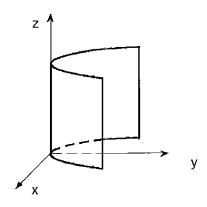




$$\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$\frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

Parabolic Cylinder



 $x^2 = 2py$