Assignment-1-D

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1 Assignment 1 D

1.0.1 Import necessary modules

```
[1]: import torch
import torch.nn as nn
import torchvision
import torchvision.transforms as transforms
from torch.utils.data import DataLoader
import matplotlib.pyplot as plt
```

1.0.2 Layer class

```
[2]: class Layer:
         def __init__(self, neurons_size: int, inputs_size: int, activation: str =_
      leaky_slope: float = 0.01, softmax_dim: int = 0):
             Initialize the layer with random weights and biases
             Parameters:
                 neurons size: int
                     The number of neurons in the layer
                 inputs size: int
                     The number of inputs to the layer
                 activation: str
                     The activation function to use
                 leaky_slope: float
                     The slope of the leaky relu activation function
                 softmax_dim: int
                     The dimension of the softmax activation function
             111
             # initialize weights and biases with random values
             # use the He initialization method to initialize the weights if the
      →activation function is relu or leaky relu else use the Xavier initialization_
      \rightarrowmethod
             if activation == 'relu' or activation == 'leaky_relu':
```

```
self._weights: torch.Tensor = torch.randn(
              neurons_size, inputs_size) * torch.sqrt(2 / torch.
→tensor(inputs_size, dtype=torch.float32))
      else:
          self._weights: torch.Tensor = torch.randn(
              neurons_size, inputs_size) * torch.sqrt(1 / torch.
self._biases: torch.Tensor = torch.zeros(neurons_size)
      self._activation: str = activation
      self._leaky_slope: float = leaky_slope
      self._softmax_dim: int = softmax_dim
      self._activation_function: dict[str, callable] = {
          'sigmoid': nn.Sigmoid(),
          'tanh': nn.Tanh(),
          'relu': nn.ReLU(),
          'leaky_relu': nn.LeakyReLU(negative_slope=self._leaky_slope),
          'softmax': nn.Softmax(dim=self._softmax_dim)
      }
  def set_weights(self, weights: torch.Tensor):
      Set the weights of the layer
      Parameters:
          weights: torch. Tensor
              The weights to set
      self._weights = weights
  def get_weights(self) -> torch.Tensor:
      Get the weights of the layer
      Returns:
          torch. Tensor
              The weights of the layer
      111
      return self._weights
  def set_biases(self, biases: torch.Tensor):
      111
      Set the biases of the layer
      Parameters:
          biases: torch.Tensor
              The biases to set
```

```
self._biases = biases
  def get_biases(self) -> torch.Tensor:
       Get the biases of the layer
      Returns:
           torch. Tensor
               The biases of the layer
      return self._biases
  def forward(self, inputs: torch.Tensor) -> torch.Tensor:
      Forward pass
       Parameters:
           inputs: torch. Tensor
               The inputs to the layer
           activation: str
               The activation function to use
       Returns:
           torch. Tensor
               The outputs of the layer
       # calculate the sum of the inputs multiplied by the weights and add the
⇔biases
       # sum: torch.Tensor = torch.matmul(self._weights, inputs) + self._biases
      sum: torch.Tensor = self._weights @ inputs + self._biases
       if self._activation in self._activation_function:
          return self._activation_function[self._activation](sum)
      else:
          raise ValueError(
               f"Activation function {self._activation} not found")
```

1.0.3 Custom Layer class

```
Initialize the custom layer with the given neurons size, inputs size,
    activation, leaky slope, and softmax dimension
    111
    # initialize the custom layer
    self.layer = Layer(neurons_size, inputs_size,
                       activation, leaky_slope, softmax_dim)
    # register the weights and biases as parameters to PyTorch
    self.weights = nn.Parameter(self.layer.get weights())
    self.biases = nn.Parameter(self.layer.get_biases())
    # point the layer parameters to the PyTorch parameters
   self.layer.set_weights(self.weights)
   self.layer.set_biases(self.biases)
    # store the activation function parameters
    self.activation = activation
    self.leaky_slope = leaky_slope
    self.softmax_dim = softmax_dim
def forward(self, inputs: torch.Tensor) -> torch.Tensor:
    # use custom layer forward method
    return self.layer.forward(inputs)
```

1.0.4 Perceptron class

```
The size of the output layer
          hidden activation: str
               The activation function to use for the hidden layer
          output_activation: str
               The activation function to use for the output layer
          leaky_slope: float
              The slope of the leaky relu activation function
          softmax_dim: int
              The dimension of the softmax activation function
       ,,,
      # create a list of layer sizes including the input and output sizes
      layer_sizes: list[int] = [input_size] + hidden_size + [output_size]
      layers: list[CustomLayer] = []
      # create hidden layers
      for i in range(len(layer_sizes) - 2):
          layers.append(CustomLayer(
              layer_sizes[i+1], layer_sizes[i], hidden_activation,__
→leaky_slope, softmax_dim))
      # create output layer
      layers.append(CustomLayer(
          layer_sizes[-1], layer_sizes[-2], output_activation, leaky_slope,_u

softmax_dim))
      # store the layers
      self.layers = nn.ModuleList(layers)
  def forward(self, inputs: torch.Tensor) -> torch.Tensor:
      # get the dimension of the input
      input_dim: int = inputs.dim()
      # if the input is a single sample, unsqueeze it
      if input_dim == 1:
          inputs = inputs.unsqueeze(0)
      # if the input is a batch of samples, process each sample individually
      batch_output: list[torch.Tensor] = []
      # process each sample in the batch
      for sample in inputs:
          # process the sample through the layers
          for layer in self.layers:
              sample = layer(sample)
```

```
# store the output of the sample
batch_output.append(sample)

# stack the outputs of the samples into a single tensor
return torch.stack(batch_output, dim=0).squeeze(0)
```

1.0.5 Test Training in GPU with graphs

```
[5]: # set the random seed for reproducibility
     torch.manual_seed(42)
     if torch.cuda.is_available():
         num_gpus = torch.cuda.device_count()
         print(f'Number of GPUs available: {num_gpus}')
         for i in range(num_gpus):
             print(f'GPU {i}: {torch.cuda.get device name(i)}')
     else:
         print('CUDA is not available.')
     # get the device to use
     device = torch.device('cuda' if torch.cuda.is_available() else 'cpu')
     print(f'Using device: {device}\n')
     # define the transformations to apply to the dataset
     transform = transforms.Compose([
         transforms.ToTensor(),
         transforms.Normalize((0.5,), (0.5,))
     ])
     # load the MNIST dataset
     train dataset = torchvision.datasets.MNIST(
         root='./data',
         train=True,
         download=True.
         transform=transform
     )
     test_dataset = torchvision.datasets.MNIST(
        root='./data',
         train=False,
         download=True,
         transform=transform
     # create the data loaders
     train_loader = DataLoader(
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train_dataset, batch_size=64, shuffle=True, pin_memory=True)
test_loader = DataLoader(
   test_dataset, batch_size=64, shuffle=False, pin_memory=True)
# create the model
input_size = 28 * 28 # MNIST images are 28x28 pixels
hidden_size = [128] # one hidden layer
output_size = 10 # 10 classes (digits 0-9)
model = Perceptron(
    input_size=input_size,
   hidden size=hidden size,
   output_size=output_size,
   hidden_activation='relu',
   output_activation='softmax',
   softmax dim=0
).to(device)
# define the optimizer
criterion = nn.CrossEntropyLoss()
optimizer = torch.optim.Adam(model.parameters(), lr=0.001)
# lists to store metrics for visualization
train_losses = []
test losses = []
test_accuracies = []
# training loop
num_epochs = 10
print("Starting training...")
for epoch in range(num_epochs):
   model.train()
   running_loss = 0.0
   for i, (images, labels) in enumerate(train_loader):
        # flatten the images
        images = images.view(-1, input_size).to(device)
       labels = labels.to(device)
        # forward propagation
       outputs = model.forward(images)
       loss = criterion(outputs, labels)
        # back propagation and optimization step
        optimizer.zero_grad()
        loss.backward()
        optimizer.step()
```

```
# calculate the running loss for the training set
       running_loss += loss.detach().item()
        # print the loss for the training set every 100 steps
       if (i+1) \% 100 == 0:
           print(
               f'Epoch [{epoch+1}/{num_epochs}], Step [{i+1}/
 # calculate the average loss for the training set
   epoch_loss = running_loss / len(train_loader)
   train_losses.append(epoch_loss)
   print(f'Epoch [{epoch+1}/{num_epochs}], Loss: {epoch_loss:.4f}\n')
   # evaluate on test set after each epoch (without printing during training)
   model.eval()
   with torch.no_grad():
       correct = 0
       total = 0
       test_loss = 0.0
       for images, labels in test_loader:
           images = images.view(-1, input_size).to(device)
           labels = labels.to(device)
           outputs = model.forward(images)
           loss = criterion(outputs, labels)
           test_loss += loss.item()
           _, predicted = torch.max(outputs.data, 1)
           total += labels.size(0)
           correct += (predicted == labels).sum().item()
       avg_test_loss = test_loss / len(test_loader)
       test_accuracy = 100 * correct / total
        # Store metrics for visualization
       test_losses.append(avg_test_loss)
       test_accuracies.append(test_accuracy)
print("Training complete!")
# evaluate the model
model.eval()
with torch.no_grad():
   correct = 0 # correct predictions
   total = 0 # total samples
```

```
test_loss = 0.0 # running loss
    # process each sample in the test set
    for images, labels in test_loader:
        images = images.view(-1, input_size).to(device)
        labels = labels.to(device)
        outputs = model.forward(images)
        # calculate the loss for the test set
        loss = criterion(outputs, labels)
        test loss += loss.item()
        # calculate the accuracy for the test set
        _, predicted = torch.max(outputs.data, 1)
        total += labels.size(0)
        correct += (predicted == labels).sum().item()
# calculate the average loss for the test set
final_test_loss = test_loss / len(test_loader)
print(f'Test Loss: {final_test_loss:.4f}')
# calculate the accuracy for the test set
final_accuracy = 100 * correct / total
print(f'Test Accuracy: {final_accuracy:.2f}%')
print('')
# now create the visualization graphs
plt.figure(figsize=(12, 10))
# plot training loss
plt.subplot(2, 1, 1)
plt.plot(range(1, num epochs + 1), train losses, label='Training Loss', u
 →marker='o', color='blue')
plt.plot(range(1, num_epochs + 1), test_losses, label='Test Loss', marker='s',

¬color='red')
plt.xlabel('Epochs')
plt.ylabel('Loss')
plt.title('Training and Test Loss')
plt.legend()
plt.grid(True)
# plot test accuracy
plt.subplot(2, 1, 2)
plt.plot(range(1, num_epochs + 1), test_accuracies, label='Test Accuracy', u
 →marker='o', color='green')
plt.xlabel('Epochs')
plt.ylabel('Accuracy (%)')
```

```
plt.title('Test Accuracy')
plt.legend()
plt.grid(True)
plt.tight_layout()
plt.show()
Number of GPUs available: 1
GPU 0: NVIDIA GeForce RTX 5080
Using device: cuda
Starting training...
Epoch [1/10], Step [100/938], Loss: 1.6681
Epoch [1/10], Step [200/938], Loss: 1.6454
Epoch [1/10], Step [300/938], Loss: 1.6781
Epoch [1/10], Step [400/938], Loss: 1.5779
Epoch [1/10], Step [500/938], Loss: 1.6492
Epoch [1/10], Step [600/938], Loss: 1.5705
Epoch [1/10], Step [700/938], Loss: 1.5913
Epoch [1/10], Step [800/938], Loss: 1.5494
Epoch [1/10], Step [900/938], Loss: 1.5079
Epoch [1/10], Loss: 1.6410
Epoch [2/10], Step [100/938], Loss: 1.6570
Epoch [2/10], Step [200/938], Loss: 1.5602
Epoch [2/10], Step [300/938], Loss: 1.5973
Epoch [2/10], Step [400/938], Loss: 1.5766
Epoch [2/10], Step [500/938], Loss: 1.5878
Epoch [2/10], Step [600/938], Loss: 1.5463
Epoch [2/10], Step [700/938], Loss: 1.5489
Epoch [2/10], Step [800/938], Loss: 1.5051
Epoch [2/10], Step [900/938], Loss: 1.5264
Epoch [2/10], Loss: 1.5437
Epoch [3/10], Step [100/938], Loss: 1.5613
Epoch [3/10], Step [200/938], Loss: 1.5349
Epoch [3/10], Step [300/938], Loss: 1.5393
Epoch [3/10], Step [400/938], Loss: 1.5750
Epoch [3/10], Step [500/938], Loss: 1.5070
Epoch [3/10], Step [600/938], Loss: 1.5312
Epoch [3/10], Step [700/938], Loss: 1.5510
Epoch [3/10], Step [800/938], Loss: 1.5511
Epoch [3/10], Step [900/938], Loss: 1.4712
Epoch [3/10], Loss: 1.5270
Epoch [4/10], Step [100/938], Loss: 1.5599
Epoch [4/10], Step [200/938], Loss: 1.5479
Epoch [4/10], Step [300/938], Loss: 1.5531
```

```
Epoch [4/10], Step [400/938], Loss: 1.4924
Epoch [4/10], Step [500/938], Loss: 1.5235
Epoch [4/10], Step [600/938], Loss: 1.5241
Epoch [4/10], Step [700/938], Loss: 1.4961
Epoch [4/10], Step [800/938], Loss: 1.5309
Epoch [4/10], Step [900/938], Loss: 1.4776
Epoch [4/10], Loss: 1.5170
Epoch [5/10], Step [100/938], Loss: 1.4781
Epoch [5/10], Step [200/938], Loss: 1.5267
Epoch [5/10], Step [300/938], Loss: 1.5046
Epoch [5/10], Step [400/938], Loss: 1.5251
Epoch [5/10], Step [500/938], Loss: 1.4770
Epoch [5/10], Step [600/938], Loss: 1.5339
Epoch [5/10], Step [700/938], Loss: 1.4946
Epoch [5/10], Step [800/938], Loss: 1.4950
Epoch [5/10], Step [900/938], Loss: 1.4974
Epoch [5/10], Loss: 1.5100
Epoch [6/10], Step [100/938], Loss: 1.4717
Epoch [6/10], Step [200/938], Loss: 1.4782
Epoch [6/10], Step [300/938], Loss: 1.4771
Epoch [6/10], Step [400/938], Loss: 1.5544
Epoch [6/10], Step [500/938], Loss: 1.4832
Epoch [6/10], Step [600/938], Loss: 1.4923
Epoch [6/10], Step [700/938], Loss: 1.4996
Epoch [6/10], Step [800/938], Loss: 1.5296
Epoch [6/10], Step [900/938], Loss: 1.5139
Epoch [6/10], Loss: 1.5045
Epoch [7/10], Step [100/938], Loss: 1.5068
Epoch [7/10], Step [200/938], Loss: 1.4960
Epoch [7/10], Step [300/938], Loss: 1.4873
Epoch [7/10], Step [400/938], Loss: 1.5336
Epoch [7/10], Step [500/938], Loss: 1.5378
Epoch [7/10], Step [600/938], Loss: 1.4864
Epoch [7/10], Step [700/938], Loss: 1.4849
Epoch [7/10], Step [800/938], Loss: 1.4843
Epoch [7/10], Step [900/938], Loss: 1.4666
Epoch [7/10], Loss: 1.5005
Epoch [8/10], Step [100/938], Loss: 1.5227
Epoch [8/10], Step [200/938], Loss: 1.4769
Epoch [8/10], Step [300/938], Loss: 1.4849
Epoch [8/10], Step [400/938], Loss: 1.4883
Epoch [8/10], Step [500/938], Loss: 1.4935
Epoch [8/10], Step [600/938], Loss: 1.5087
Epoch [8/10], Step [700/938], Loss: 1.5048
```

```
Epoch [8/10], Step [800/938], Loss: 1.4741
Epoch [8/10], Step [900/938], Loss: 1.5266
Epoch [8/10], Loss: 1.4969
Epoch [9/10], Step [100/938], Loss: 1.5066
Epoch [9/10], Step [200/938], Loss: 1.5228
Epoch [9/10], Step [300/938], Loss: 1.4774
Epoch [9/10], Step [400/938], Loss: 1.4648
Epoch [9/10], Step [500/938], Loss: 1.4957
Epoch [9/10], Step [600/938], Loss: 1.4767
Epoch [9/10], Step [700/938], Loss: 1.5271
Epoch [9/10], Step [800/938], Loss: 1.4818
Epoch [9/10], Step [900/938], Loss: 1.5090
Epoch [9/10], Loss: 1.4945
Epoch [10/10], Step [100/938], Loss: 1.4871
Epoch [10/10], Step [200/938], Loss: 1.4814
Epoch [10/10], Step [300/938], Loss: 1.4754
Epoch [10/10], Step [400/938], Loss: 1.5280
Epoch [10/10], Step [500/938], Loss: 1.4922
Epoch [10/10], Step [600/938], Loss: 1.4694
Epoch [10/10], Step [700/938], Loss: 1.4998
Epoch [10/10], Step [800/938], Loss: 1.4636
Epoch [10/10], Step [900/938], Loss: 1.4889
Epoch [10/10], Loss: 1.4923
```

Training complete!
Test Loss: 1.4936
Test Accuracy: 96.89%

