# TopHat: a stylish journey through modular interactive workflows

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## Task Oriented Programming (TOP)

Workflows

coordinate collaboration

elementary building blocks and concepts

Interactive

driven by user input

labeled transition system

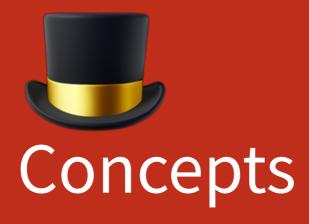
Modular

higher order

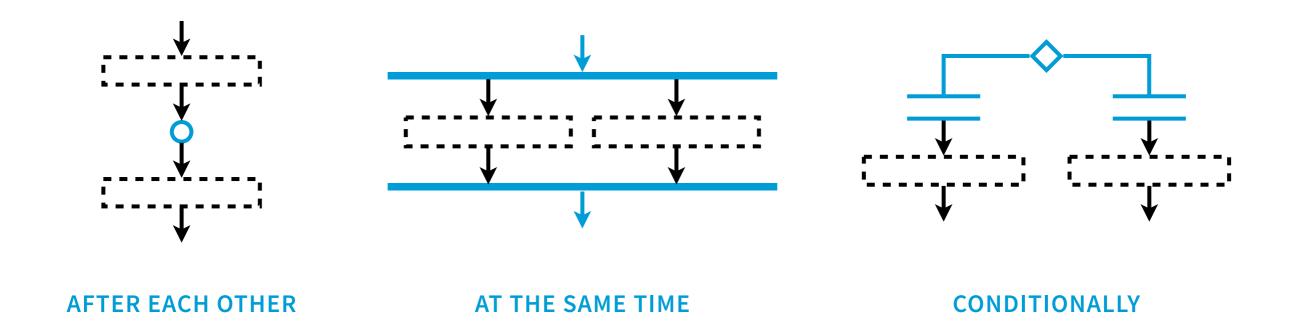
embedding in simply typed  $\lambda$ -calculus (with clearly separated semantics)

Foundation for formal reasoning and comparison to other frameworks





#### Collaboration



#### Communication is taken care of!

"We do A and B at the same time, then we continue with C."

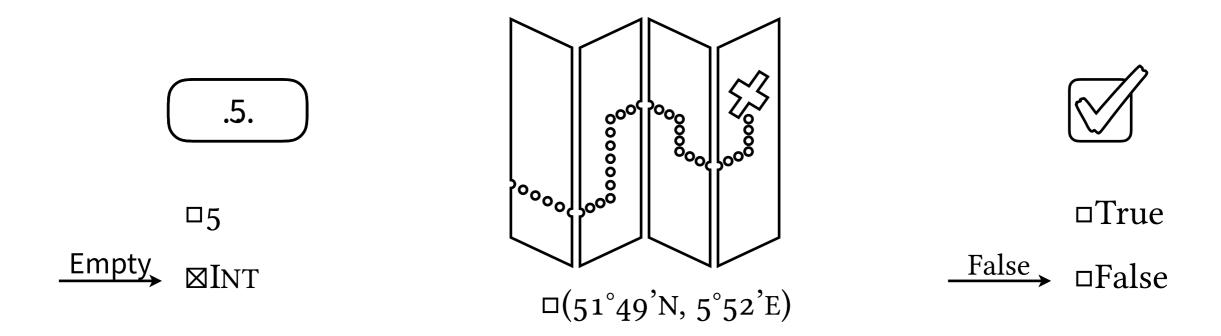


"When I send you M, you can do B and I'll wait for you to send N."

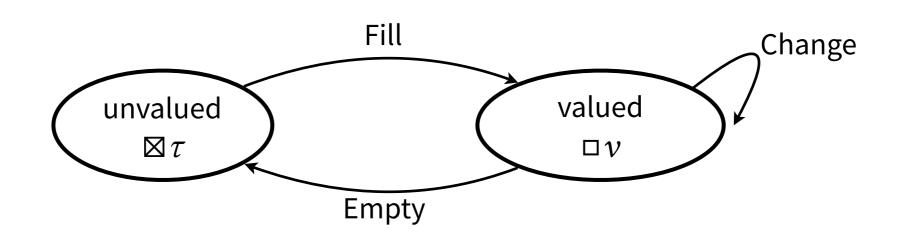




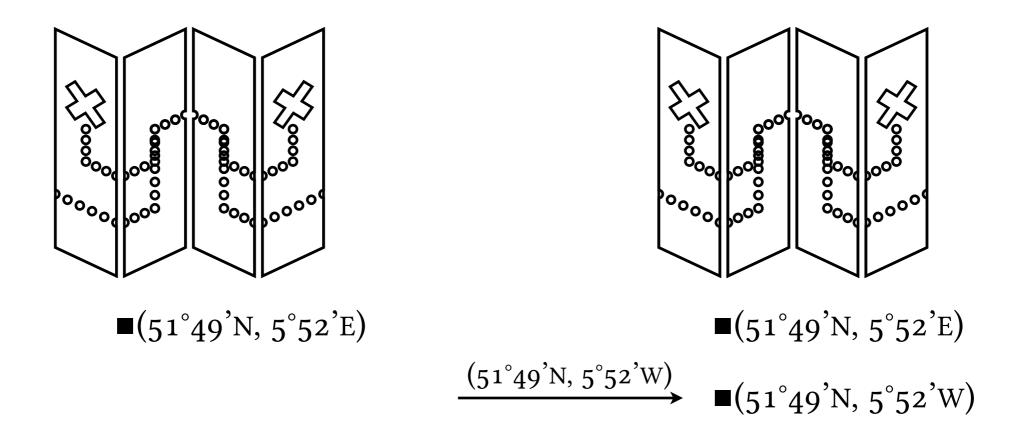
#### **Editors**

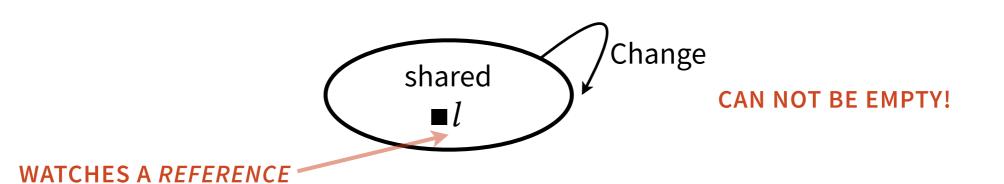


CAPTURE
THE EVER
CHANGING
NATURE OF
WIDGETS

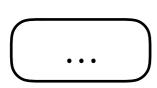


## **Shared editors**

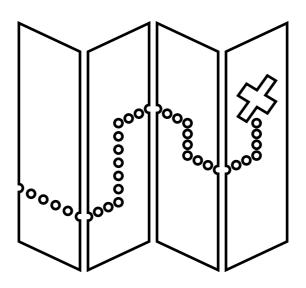




#### **Observations**



$$\mathcal{V}(\boxtimes INT) = \bot$$



$$\mathcal{V}(\Box(51^{\circ}49'\text{N}, 5^{\circ}52'\text{E}))$$
  
=  $(51^{\circ}49'\text{N}, 5^{\circ}52'\text{E})$ 



$$\mathcal{V}(\Box \text{True}) = \text{True}$$

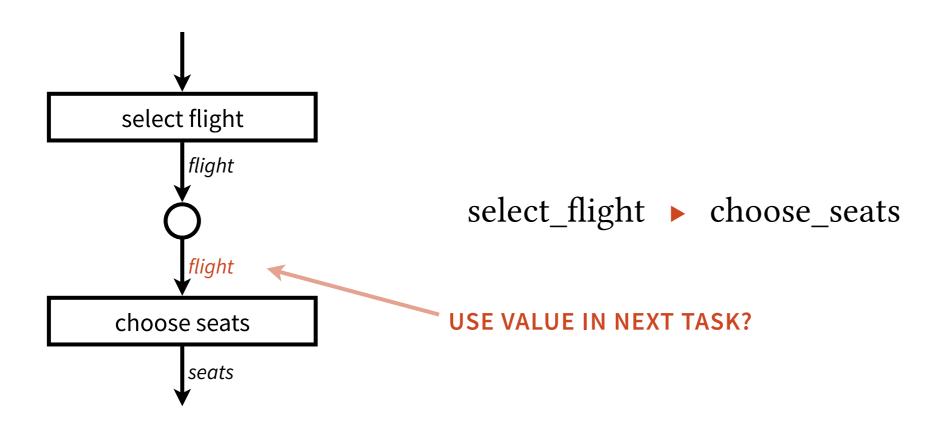
#### SOME TASKS DO NOT HAVE A VALUE

value  $\mathcal{V}: \text{TASK } \tau \longrightarrow \text{MAYBE } \tau$ 

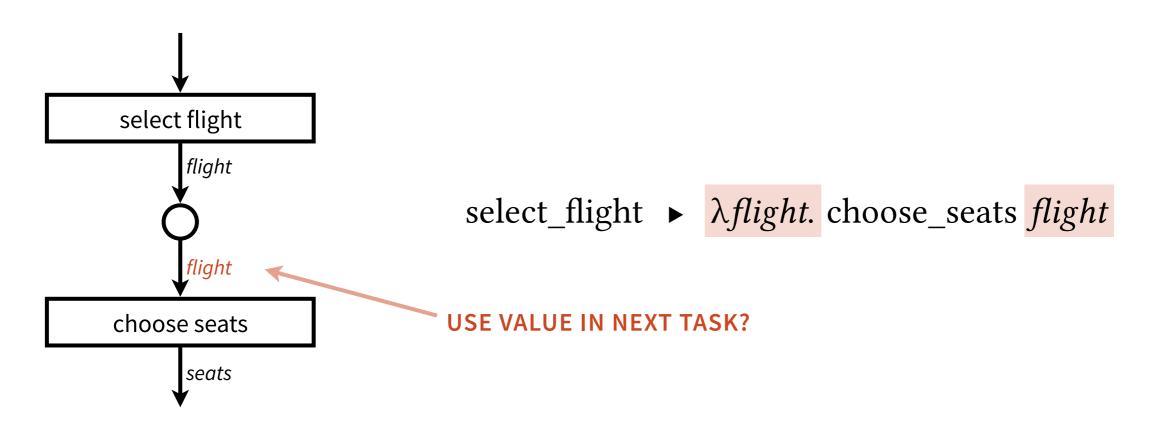
user interface  $\mathcal{U}: \text{Task } \tau \to \text{Html}$  (or  $\mathcal{U}: \text{Task } \tau \to \text{String}$  or  $\mathcal{U}: \text{Task } \tau \to ...$ )

possible inputs  $\mathcal{J}$ : Task  $\tau \to \text{List Input}$ 

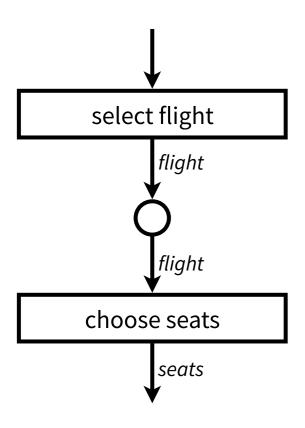
## **Steps**



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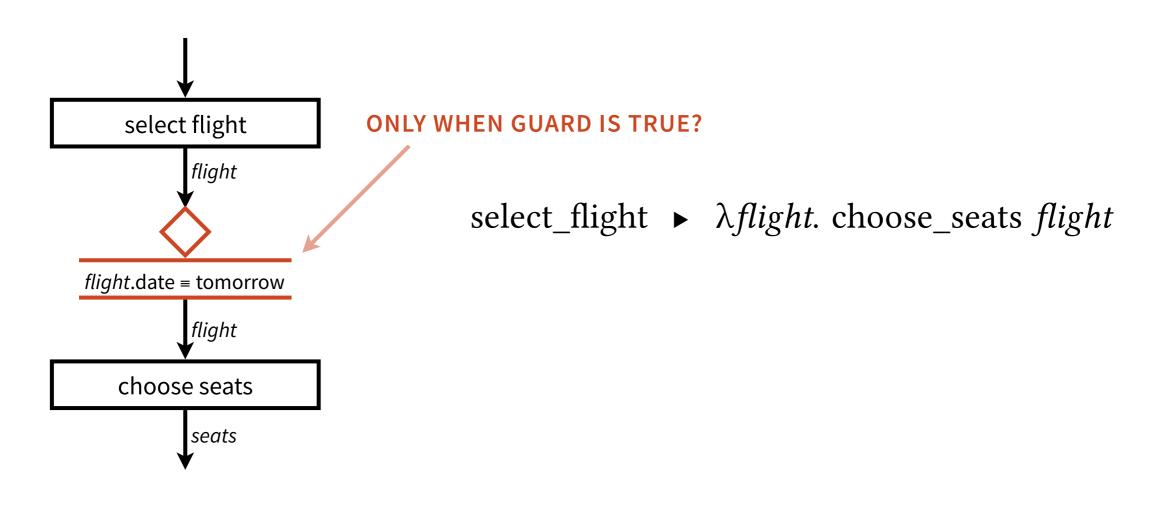


select\_flight ► \(\lambda flight\). choose\_seats \(flight\)

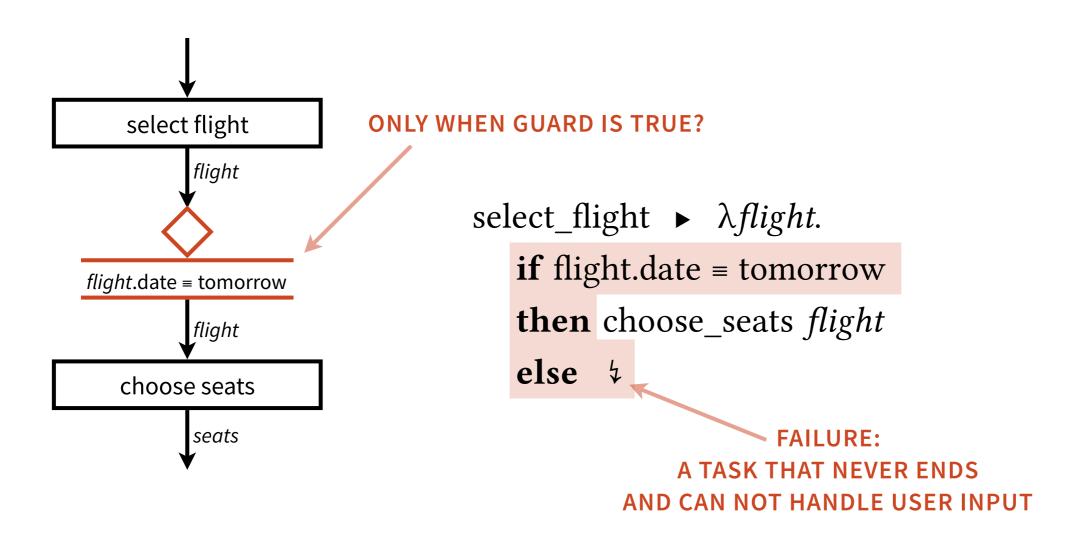
WHEN TO PROCEED TO THE NEXT TASK?

$$\Rightarrow \mathcal{V}(\text{select\_flight}) = v$$

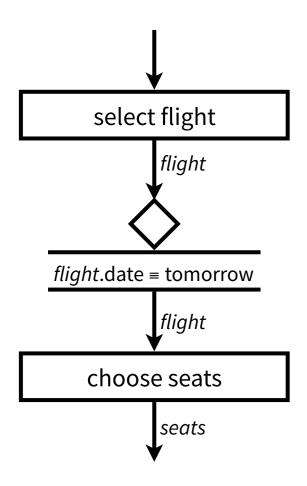
## **Guarded steps**



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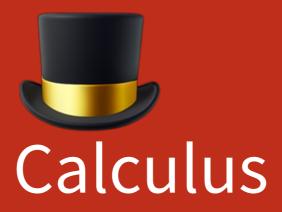


#### WHEN TO PROCEED TO THE NEXT TASK?

$$\Rightarrow \mathcal{V}(\text{select\_flight}) = v$$



**USING HOST LANGUAGE SEMANTICS!** 



#### Grammar

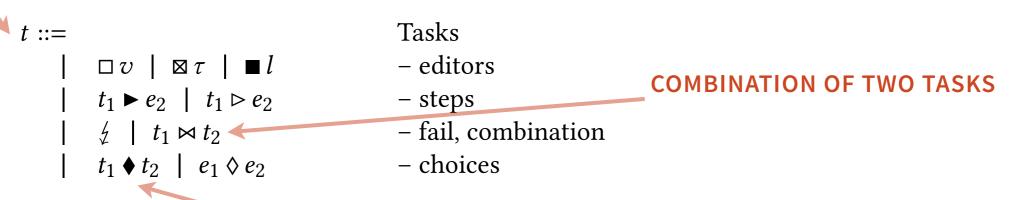
#### Take a λ-calculus...

```
Expressions
e :=
                                          - abstraction, application
        \lambda x : \tau . \ e \mid \ e_1 \ e_2
        x \mid c \mid e_1 \star e_2
                                          - variable, constant, operation
        if e_1 then e_2 else e_3 \mid \langle \rangle
                                          - branch, unit
        \langle e_1, e_2 \rangle | fst e | snd e
                                          - pair, projections
                                          - references, location
        ref e \mid !e \mid e_1 := e_2 \mid l
                                          – pretask
                                          Constants
c ::=
        B \mid I \mid S
                                          - boolean, integer, string
```

#### Grammar

#### Take a λ-calculus...

## ...embed a workflow language



**CHOICE BETWEEN TWO TASKS** 



## **Semantics**

Two layers ⇒ two semantics

$$e\downarrow v$$
 standard big step semantics

MAKES USE OF

$$p \rightarrow t$$

 $p \rightarrow t$  Special task semantics

S-ThenStay
$$\frac{t_{1}, s \rightsquigarrow t_{1}', s'}{t_{1} \blacktriangleright e_{2}, s \rightsquigarrow t_{1}' \blacktriangleright e_{2}, s'} \mathcal{V}(t_{1}', s') = \bot$$

S-ThenFail
$$\frac{t_{1}, s \rightsquigarrow t_{1}', s'}{t_{1} \blacktriangleright e_{2}, s \rightsquigarrow t_{1}' \blacktriangleright e_{2}, s'} \mathcal{V}(t_{1}', s') = v_{1} \land \mathcal{F}(t_{2}, s'')$$

S-ThenCont
$$\frac{t_{1}, s \rightsquigarrow t_{1}', s'}{t_{1} \blacktriangleright e_{2}, s \rightsquigarrow t_{1}' \blacktriangleright e_{2}, s'} \mathcal{V}(t_{1}', s') = v_{1} \land \mathcal{F}(t_{2}, s'')$$

$$\frac{t_{1}, s \rightsquigarrow t_{1}', s'}{t_{1} \blacktriangleright e_{2}, s \rightsquigarrow t_{2}, s'''} \mathcal{V}(t_{1}', s') = v_{1} \land \neg \mathcal{F}(t_{2}, s'')$$

## **Semantics**

$$e \downarrow v$$
 standard big step semantics

$$p \rightarrow t$$
 Special task semantics

But interaction... ⇒ additional layer

$$t \stackrel{i}{\longrightarrow} t'$$
 HANDLING OF USER INPUT

S-ThenStay
$$\frac{t_{1}, s \rightsquigarrow t_{1}', s'}{t_{1} \blacktriangleright e_{2}, s \rightsquigarrow t_{1}' \blacktriangleright e_{2}, s'} \mathcal{V}(t_{1}', s') = \bot$$

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#### Language & formal semantics

#### Still to do...

- Task equality
- Pre- and postconditions
- Symbolic execution

**IDEAS APPRECIATED!** 





## **Summary**



Language & formal semantics



Proved progress & preservation



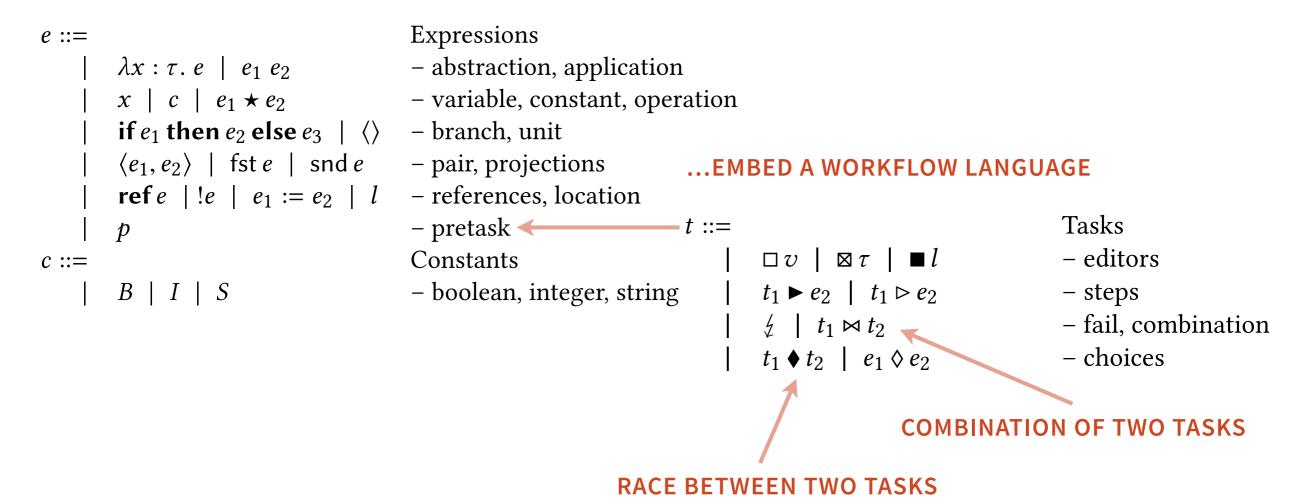
Implemented in Idris



Essence of task oriented programming

#### Grammar

#### TAKE A Λ-CALCULUS...





- Language for modular interactive workflows
- Essence of task oriented programming
- Formal semantics
- Proved progress & preservation
- Implemented in Idris

## **Tasks**

