

Problem set 1

(a) $\min f(x_1, x_2) = \left(x_1 - \frac{3}{2}\right)^2 + \left(x_2 - \frac{1}{2}\right)^4$

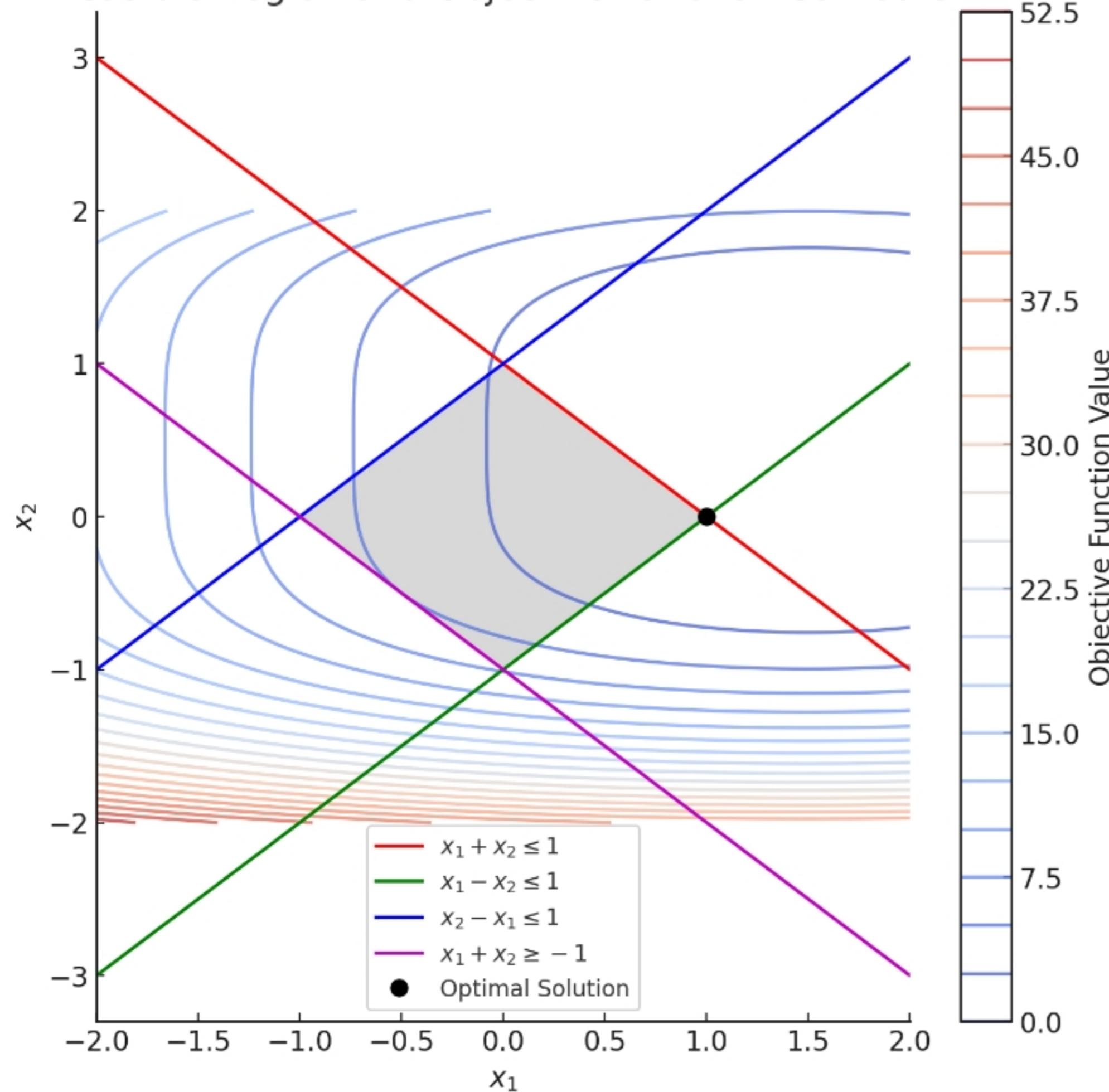
subject to: $C_1(\bar{x}) = 1 - x_1 - x_2 \geq 0 \Rightarrow x_1 + x_2 \leq 1$ •

$C_2(\bar{x}) = x_1 - x_2 - 1 \leq 0 \Rightarrow x_1 - x_2 \leq 1$ •

$C_3(\bar{x}) = x_2 - x_1 - 1 \leq 0 \Rightarrow x_2 - x_1 \leq 1$ •

$C_4(\bar{x}) = 1 + x_1 + x_2 \geq 0 \Rightarrow x_1 + x_2 \geq -1$ •

Feasible Region and Objective Function Contours



- Very hard to plot such complex contours by hand
so I used a computer.

- Optimal solution is $(1; 0)$

b) Check LICQ:

$$C_1(1,0) = 0 \therefore \text{Active}$$

$$C_2(1,0) = 0 \therefore \text{Active}$$

$$C_3(1,0) = -2 \therefore \text{Inactive}$$

$$C_4(1,0) = 2 \therefore \text{Inactive}$$

Active constraints:

$$C_1(\bar{x}) = 1 - x_1 - x_2 \Rightarrow \nabla C_1(\bar{x}) = \begin{bmatrix} -1 \\ -1 \end{bmatrix}$$

$$C_2(\bar{x}) = x_1 - x_2 - 1 \Rightarrow \nabla C_2(\bar{x}) = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$\det \begin{vmatrix} -1 & 1 \\ -1 & -1 \end{vmatrix} = 2 \therefore \text{linear independent.}$$

LICQ satisfied.



c) KKT conditions:

- 1) $\nabla_x \mathcal{L}(\bar{x}^*, \lambda^*) = 0$
- 2) $C_i(\bar{x}^*) = 0 \quad \forall i \in E$
- 3) $C_i(\bar{x}^*) \geq 0 \quad \forall i \in I$
- 4) $\lambda_i^* \geq 0 \quad \forall i \in I$
- 5) $\exists \lambda_i^* C_i(\bar{x}^*) \quad \forall i \in (I \cup E)$

$$\nabla_x \mathcal{L}(\bar{x}^*, \lambda^*) = \nabla f(\bar{x}) + \lambda_1 \nabla C_1 + \lambda_2 \nabla C_2 = 0$$

$$\Rightarrow \nabla f = \begin{bmatrix} 2(x_1 - \frac{3}{2}) \\ 4(x_2 - \frac{1}{2})^3 \end{bmatrix} \Rightarrow \nabla f(1, 0) = \begin{bmatrix} -1 \\ -0,5 \end{bmatrix}$$

$$\therefore \nabla_x \mathcal{L}(\bar{x}^*, \lambda^*) = \begin{bmatrix} -1 \\ -0,5 \end{bmatrix} + \lambda_1 \begin{bmatrix} -1 \\ -1 \end{bmatrix} + \lambda_2 \begin{bmatrix} 1 \\ -1 \end{bmatrix} = 0$$

$$\Rightarrow -1 - \lambda_1 + \lambda_2 = 0 \Rightarrow \lambda_2 - \lambda_1 = 1$$

$$\Rightarrow -0,5 - \lambda_1 - \lambda_2 = 0 \Rightarrow -\lambda_1 - \lambda_2 = 0,5$$

$$\Rightarrow \underline{\lambda_1^* = -0,75 \quad \lambda_2^* = 0,25}$$

$$2) \begin{aligned} C_1(\bar{x}) &= 4x_1^2 + x_2^2 - 4 \leq 0 \\ C_2(\bar{x}) &= (x_1 - 2)^2 + x_2^2 - 5 \leq 0 \\ C_3(\bar{x}) &= x_1 \geq 0 \\ C_4(\bar{x}) &= x_2 \geq 0 \end{aligned}$$

$$\bar{x}^* = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

$$\begin{aligned} C_1(\bar{x}^*) &= 0 \quad \therefore \text{Active} \\ C_2(\bar{x}^*) &= 0 \quad \therefore \text{Active} \\ C_3(\bar{x}^*) &= 0 \quad \therefore \text{Active} \\ C_4(\bar{x}^*) &= 1 \quad \therefore \text{non-active.} \end{aligned}$$

$$\nabla C_1(\bar{x}) = \begin{bmatrix} 2x_1 \\ 8x_2 \end{bmatrix}$$

$$\nabla C_3(\bar{x}) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

$$\nabla C_2(\bar{x}) = \begin{bmatrix} 2x_1 - 4 \\ 2x_2 \end{bmatrix}$$

$$\nabla C_1(\bar{x}^*) = \begin{bmatrix} 0 \\ 8 \end{bmatrix} \quad \nabla C_2(\bar{x}^*) = \begin{bmatrix} -4 \\ 2 \end{bmatrix} \quad \nabla C_3(\bar{x}^*) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$$

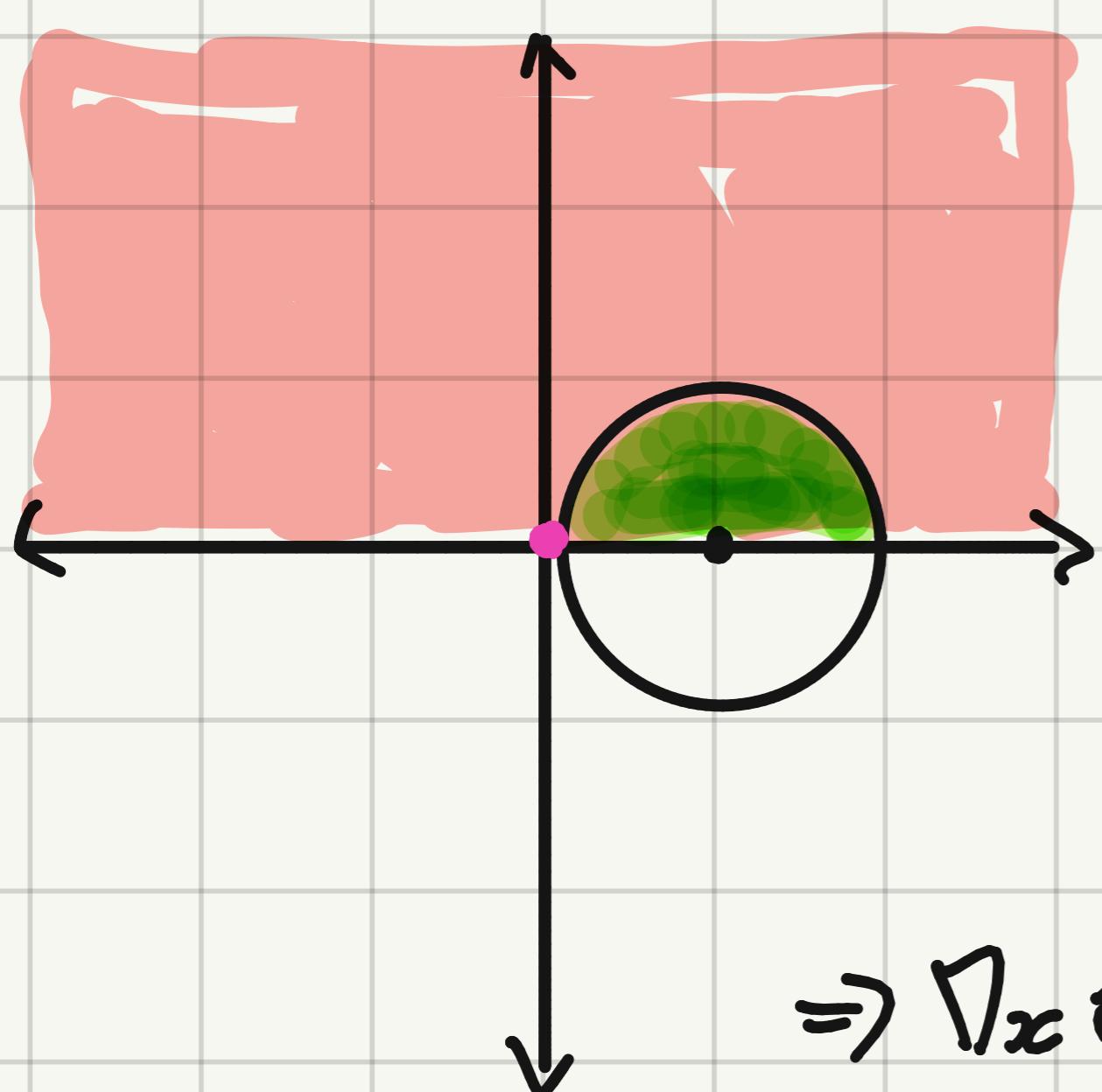
$$\alpha_1 \begin{bmatrix} 0 \\ 8 \end{bmatrix} + \alpha_2 \begin{bmatrix} -4 \\ 2 \end{bmatrix} + \alpha_3 \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \bar{0} \Rightarrow \begin{aligned} -4\alpha_2 + \alpha_3 &= 0 \Rightarrow \alpha_3 = 4\alpha_2 \\ 8\alpha_1 + 2\alpha_2 &= 0 \Rightarrow \alpha_1 = -\frac{1}{4}\alpha_2 \end{aligned}$$

\therefore Linearly dependent on each other
LICQ not satisfied.

$$3)a) \min f(\bar{x}) = x_1$$

$$\text{st. } C_1(\bar{x}) = (x_1 - 1)^2 + x_2^2 - 1 \leq 0$$

$$C_2(\bar{x}) = x_2 \geq 0$$



\therefore Optimal point: $(0, 0)$

$$\nabla_x L(\bar{x}^*, \lambda^*) = \nabla f(\bar{x}) + \lambda_1 \nabla C_1(\bar{x}) + \lambda_2 \nabla C_2(\bar{x}) = 0$$

$$\Rightarrow \nabla f(\bar{x}) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}; \nabla C_1(\bar{x}) = \begin{bmatrix} 2x_1 - 2 \\ 2x_2 \end{bmatrix}; \nabla C_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

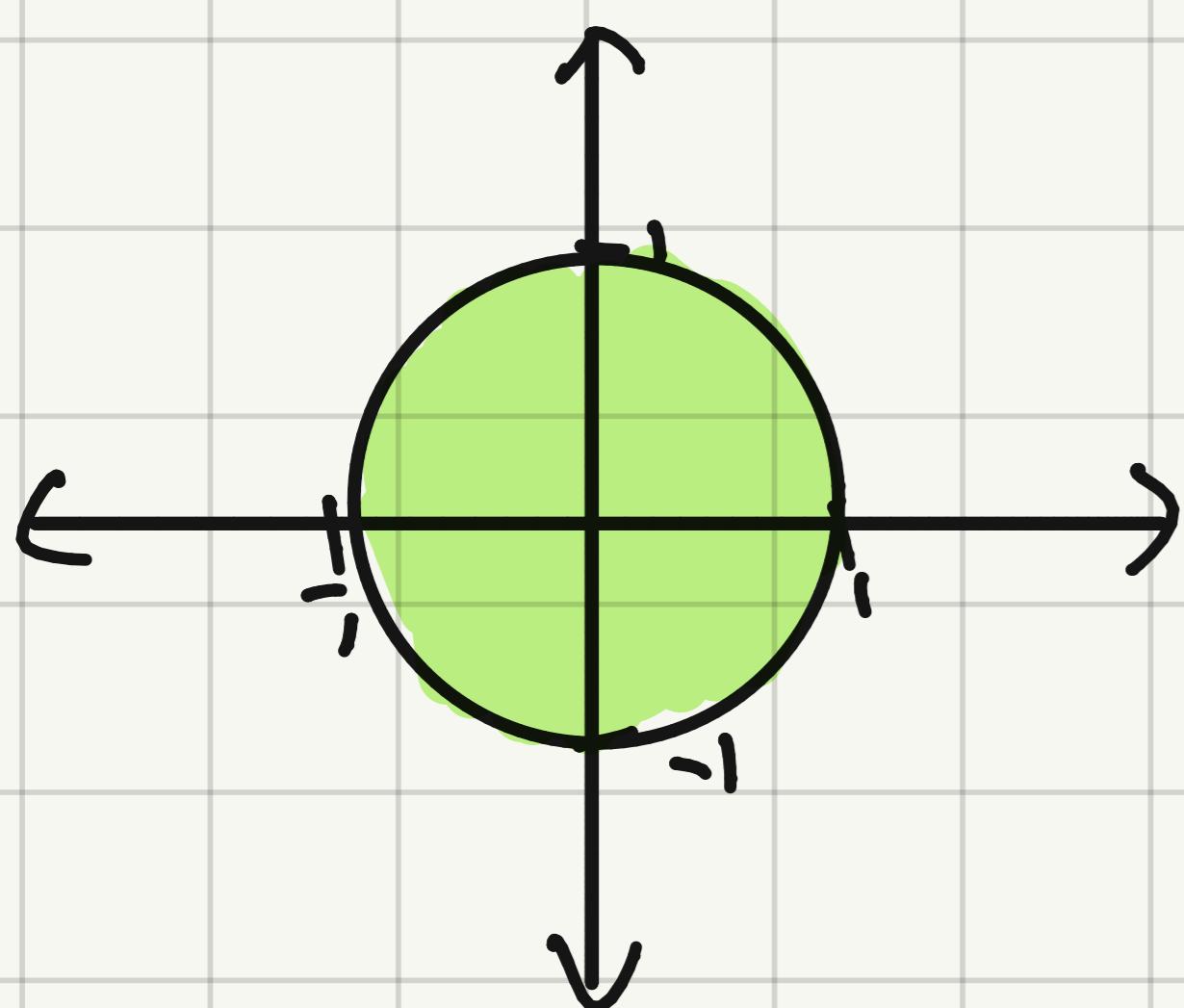
$$\Rightarrow \nabla_x L(\bar{x}^*, \lambda^*) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} + \lambda_1 \begin{bmatrix} -2 \\ 0 \end{bmatrix} + \lambda_2 \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0$$

$$\begin{aligned} ③ \quad \nabla_x^2 L &= \begin{bmatrix} 2\lambda_1 & 0 \\ 0 & 2\lambda_2 \end{bmatrix} \quad \Rightarrow 1 - 2\lambda_1 = 0 \Rightarrow \lambda_1 = \frac{1}{2} \\ &\Rightarrow \lambda_2 = 0 \quad \therefore \lambda_1, \lambda_2 \geq 0 \quad \text{KKT satisfied.} \\ \Rightarrow \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} &\quad \therefore \text{positive definite} \quad \therefore \text{minimum.} \end{aligned}$$

$C_1(\bar{x}^*) = 0 \quad \therefore \text{Active}$
 $C_2(\bar{x}^*) = 0 \quad \therefore \text{Active.}$

$$3b) \min f(x) = -0,1(x_1 - 4)^2 + x_2^2$$

stt. $C_1(x) = 1 - x_1^2 - x_2^2 \geq 0$



$$L = -0,1(x_1 - 4)^2 + x_2^2 + \lambda(1 - x_1^2 - x_2^2)$$

$$\nabla_{x_1} L = -0,2(x_1 - 4) - 2\lambda x_1 = 0$$

$$\nabla_{x_2} L = 2x_2 - 2\lambda x_2 = 2x_2(1 - \lambda) = 0$$

$$\nabla \lambda L = 1 - x_1^2 - x_2^2 = 0$$

① if $x_2 = 0 \Rightarrow x_1 = \pm 1$

if $x_1 = -1 \Rightarrow \lambda = -\frac{1}{2}$ ($\lambda \geq 0$ since inequality constraint.)

$$\therefore x_1 \neq -1$$

if $x_1 = 1 \Rightarrow \lambda = 0,3$ (valid)

\therefore Possible solution $(1, 0)$

② if $x_2 \neq 0 \Rightarrow \lambda = 1$

if $\lambda = 1 \Rightarrow x_1 = \frac{4}{11}$

if $x_1 = \frac{4}{11} \Rightarrow x_2 = \pm 0,9315$

\therefore Possible solutions $(0,3636, \pm 0,9315)$

$$H = \begin{bmatrix} -0,2 - 2\lambda & 0 \\ 0 & 2 - 2\lambda \end{bmatrix}, \text{ if } \lambda = 1 \Rightarrow H = \begin{bmatrix} -2,2 & 0 \\ 0 & 0 \end{bmatrix} \therefore \text{Not positive definite.}$$

$$\text{if } \lambda = 0,3 \Rightarrow H = \begin{bmatrix} -0,8 & 0 \\ 0 & 1,4 \end{bmatrix} \therefore \text{indefinit. -}$$

$$4) \text{ a) min } f(\bar{v}) = (x-1)^2 + (y-2)^2 \\ \text{ st. } C_1(v): y - \frac{1}{5}(x-1)^2 = 0$$

$$\text{b) } L = (x-1)^2 + (y-2)^2 + \lambda \left(y - \frac{1}{5}(x-1)^2 \right)$$

$$\nabla_x L = 2x-2 - \frac{2\lambda}{5}x + \frac{2\lambda}{5} = 0 \Rightarrow \left(2 - \frac{2}{5}\lambda\right)(x-1) = 0$$

$$\nabla_y L = 2y-2 + \lambda = 0 \Rightarrow$$

$$\therefore \text{ if } x=1 \Rightarrow \lambda=4 \quad \therefore \textcircled{1} \quad (1, 0) \quad \lambda=4$$

$$\therefore \text{ if } \lambda=5 \Rightarrow (x-1)^2 = -\frac{5}{2} \quad \therefore \text{ Not possible.}$$

$$\nabla C_1 = \begin{bmatrix} -\frac{2}{5}(x-1) \\ 1 \end{bmatrix} \Rightarrow \nabla C_1(x^*) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} \quad !, \text{ non-zero and linearly dependent.}$$

c) $(1, 0)$ global minum.

$$\text{d) } f(x) = (x-1)^2 + \left(\frac{1}{25}(x-1)^4 - 4 \frac{1}{5}(x-1)^2 + 4 \right)$$

taking the derivative and setting it to 0 will give a different solution.

5 and 6 for test prep.