# GEOLOCATION PREDICTION USING MACHINE LEARNING

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## INTRODUCTION

Localization is the task of determining the physical coordinates of a sensor node (or a group of sensor nodes) or the spatial relationships among objects. It comprises a set of techniques and mechanisms that allow a sensor to estimate its own location based on information gathered from the sensor's environment. While the Global Positioning System (GPS) is undoubtedly the most well-known location-sensing system, it is not accessible in all environments (e.g., indoors or under dense foliage) and may incur resource costs unacceptable for resource-constrained wireless sensor networks (WSNs). [1],[2]

In this work, we used WinProp<sup>™</sup> software suite are provided by AWE Communications for extracting geospatial information from simulation. The ProMan Propagation software package is designed to predict the path loss accurately between transmitter and receiver including all important parameters of the mobile radio channel. The ProMan (Network) software offers network planning modules for 2G/2.5G, 3G/B3G, WLAN, WiMAX networks. It offers Static network planning modules as well as dynamic network simulators

We propose nonlinear polynomial regression as a machine learning method to obtain excellent results on predicting emitter location.

#### SCENARIO DESCRIPTION

We received ray data in an ASCII (\*.str format) to evaluate characteristics of radio channel. We extracted channel's impulse response from this data to create dataset for machine learning application. Ray data format was extracted from following two statements given below:

POINT 396.00 580.00 515.46

PATH 2349.565300 58.71 0 1 414.0000 623.9900 539.3000 D 423 1

Figure: impulse response of channel in ASCII format

In the format shown above, statement POINT is nothing but geolocation coordinate of emitter location. First two fields in the second statement PATH is delay of path (in ns) and field strength (in dB $\mu$ V/m). We used these two statements to create dataset for our machine learning application by parsing rat data file.

#### MACHINE LEARNING IN EMITTER LOCALIZATION

Localization research has garnered a good deal of interest from both academia and industry, with numerous systems being proposed using a variety of technologies. A major disadvantage of many of these systems—such as infrared [3], ultrasound [4], and RFID [5], [6]—is that they require dedicated sensors and substantial infrastructure changes and as a result, incur a significant cost to deploy. Effort has been made to devise localization systems that require little to no infrastructure change using Bluetooth [7], [8] and WiFi signal strengths [9], [10], [11], [12] with some success. The systems developed using WiFi signal

Delay(ns)	Strength(dBuV/m)	X-coordinate	Y-coordinate	Z-coordinate
2349.565	58.71	396.00	580.00	515.46
926.787	74.92	736.00	980.00	515.06
808.820	76.04	756.00	980.00	517.05

Figure: Dataset adaption using parser written in python

strengths for localization show promise but have yet to receive widespread adoption. These systems can be divided into two categories: those using a fingerprinting approach using algorithms for "nearest neighbor in signal space" and those using more complex signal propagation algorithms to determine a device's distance from the access points in range.

#### DATA ANALYSIS

Once the data was prepared, several data analysis and data visualization techniques were used as a basis for debate to come up with a suitable machine learning model. Parallel Plot is a popular visualization technique used to plot individual data elements across many dimensions. This gives us a sense of relationship between path delay, field strength and their coordinates.

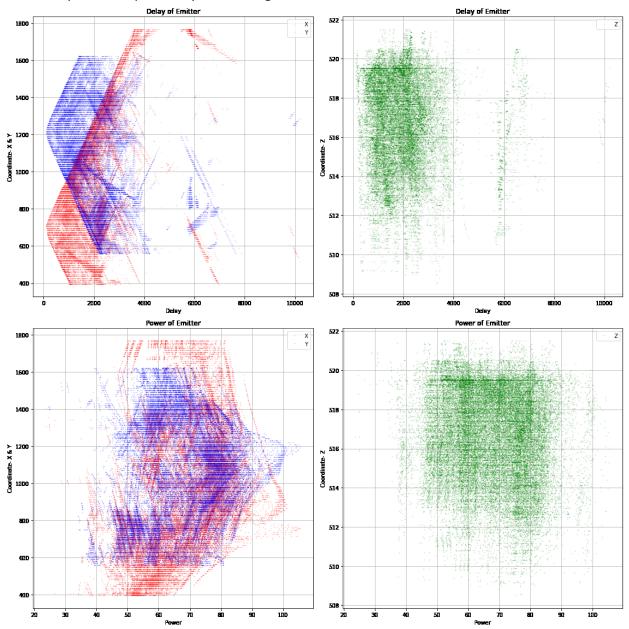


Figure: Parallel Plot Visualization for Path Delay and Field Strength

Figure: Parallel Plot Visualization for Path Delay and Field Strength shows parallel plots for following 6 relations.

- 1. X coordinate and path delay
- 2. Y coordinate and path delay

- 3. Z coordinate and path delay
- 4. X coordinate and field strength
- 5. Y-coordinate and field strength
- 6. Z-coordinate and field strength

There were several other plots that were visualized in an effort to find data relationship that can be harnessed in the choices of machine learning models. Some of the other plot (not shown here, will be delivered along with code) were 3D scatter plots. Euclidean distance plots and Power Delay Profile of the dataset.

#### DATA MODEL

Based on the visualization results, we came to conclusion that regression using single kernel was most appropriate model for the localization task. Mathematical equation below describes final regression model used in the delivery.

$$X_{pred} = \sqrt[2]{dw_x \cdot delay^2 + pw_x \cdot (power^2 - power) + b_x}$$

$$Y_{pred} = \sqrt[2]{dw_y \cdot delay^2 + pw_y \cdot (power^2 - power) + b_y}$$

$$Z_{pred} = \sqrt[2]{dw_z \cdot delay^2 + pw_z \cdot (power^2 - power) + b_z}$$

This model gave us a total of 9 model parameters to train enumerated below:

- 1.  $dw_x$ ,  $pw_x$ ,  $b_x$
- 2.  $dw_y$ ,  $pw_y$ ,  $b_y$
- 3. dw<sub>z</sub>, pw<sub>z</sub>, b<sub>z</sub>

# MACHINE LEARNING FRAMEWORK

We used set of tools as machine learning framework to develop and test the application

- 1. Jupyter Notebook version 5.1.0 (<a href="http://jupyter.org">http://jupyter.org</a>)
- 2. Python version 3.6.3 (https://www.python.org)
- 3. Python numpy version 1.13.3 (<a href="http://www.numpy.org">http://www.numpy.org</a>)
- 4. Tensorflow version 1.4.0 (http://tensorflow.org)
- 5. CentOS version 7.4.1708 (https://www.centos.org) in Google cloud (http://cloud.google.com)

## DATA CONDITIONING

Later analysis revealed that adapting the raw data obtained from simulation to machine leaning framework wasn't enough, since it performed poorly on training and accuracy expectation. We performed following operation to adapt the data to our framework.

- 1. Randomize
- 2. Normalize
- 3. Divide for training and validation

## TRAINING AND MODEL GENERATION

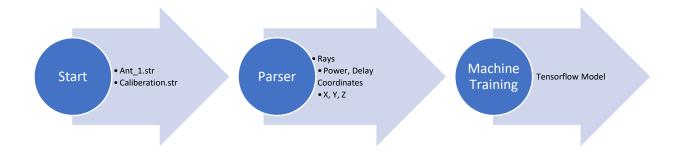


Figure: Training and Model Generation for Predicting Emitter Location in WSN

Figure on Training and Model Generation for Predicting Emitter Location in WSN shows software control flow. We used square mean error as a loss function with gradient descent optimization method to give us model parameters with best possible accuracy for the given dataset. We trained the model for 1000 epochs to achieve acceptable level of accuracy. At the end of 1000<sup>th</sup> iteration, mean square error was 0.142. Model parameters were saved in a file model\_param.py ready for use in generated regression model. The model is supplied with model.py

#### USING THE MODEL

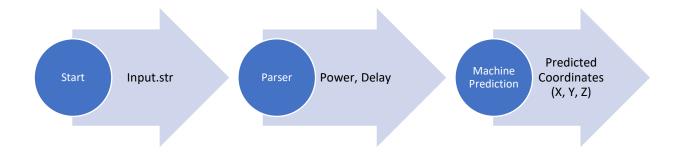


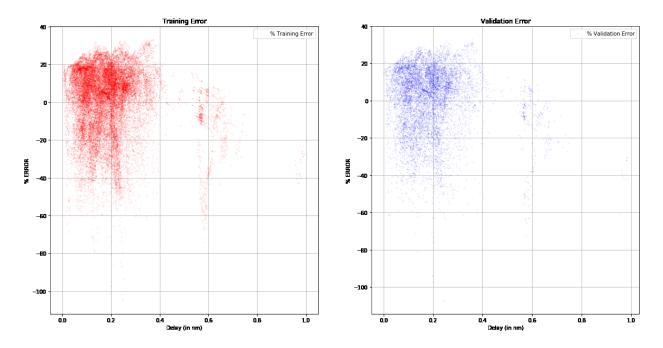
Figure: Using Regression Model with new dataset

Figure 'using the regression model with new dataset' shows the data flow for testing the dataset. Remember to limit the new test dataset with a range (X, Y, Z, path delay and field strength) similar to training dataset to continue getting expected accuracy. If the new test dataset is beyond the range, remember to train the model before using it.

## **RESULTS**

With regression model, we could bring the prediction error to under 2% as shown below:

- 1. Training error mean= 1.82759938221 %
- 2. Validation error mean= 1.7151372943 %



**Figure: Error Distribution Plot** 

These numbers may differ slightly depending on the permutation of randomization used before training. They were always observed under 2%, which is well below accepted range of 5%. Figure 'Error Distribution Plot' shows training and validation error.

# **SETUP**

To make the setup easy, following python files will be delivered.

- 1. Generating+Model+for+Predicting+Geo+Location+of+Emitters.py
- 2. Using+Model+for+Predicting+Geo+Location+of+Emitters.py
- 3. model\_parms.py

Remember to install python with numpy and tensorflow libraries with versions mentioned in Machine Learning Framework section.

Once installation requirements are met, you can run it on command line. Our development environment was in google cloud. We downloaded our scripts on a windows-10 computer to check for a cross platform test. A typical session of training and test on windows10 is shown below:

```
Windows PowerShell
                                                                                                                                                                                                                                                                                                                                                                                                П
                                                                                                                                                                                                                                                                                                                                                                                                                          X
   S C:\Users\srohit\Downloads\fiverr> python.exe ..\Generating+Model+for+Predicting+Geo+Location+of+Emitters.py .\Ant_1.
   .
Min= 9.67797344297e-05 Max= 1.00009677973 Mean= 0.185761421955 sigma= 0.111279072513
 Min= 0.00290535583272 Max= 1.00290535583 Mean= 0.538774195008 sigma= 0.144676403079
Min= 0.00289051094891 Max= 1.00289051095 Mean= 0.40914726192 sigma= 0.244345989001
  Min= 0.00528301886792 Max= 1.00528301887 Mean= 0.499474515836 sigma= 0.253718911403
Min= 0.391153846154 Max= 1.39115384615 Mean= 1.01887830531 sigma= 0.178626027054
Dataset size (46391, 5)
2018-01-26 11:41:11.508990: I C:\tf_jenkins\home\workspace\rel-win\M\windows\PY\36\tensorflow\core\platform\cpu_feature_
   guard.cc:137] Your CPU supports instructions that this TensorFlow binary was not compiled to use: AVX poch: 0100 cost= 0.155911833
   poch: 0200 cost= 0.154088929
poch: 0300 cost= 0.152468234
   poch: 0400 cost= 0.151023477
poch: 0500 cost= 0.149738297
   .
|poch: 0600 cost= 0.148600176
|poch: 0700 cost= 0.147602245
   poch: 0800 cost= 0.146741197
poch: 0900 cost= 0.146024063
     poch: 1000 cost= 0.145483941
   Optimization Finished!
   1.11095 - 0.256167 0.79049 0.483389 0.31717 0.789653 0.224165 0.335358 1.18359 0.516.47 4.7 : [ 706. 1270. 518.99] -> 1013.967 1072.746 516.839 0.526.0 : [ 1166. 1040. 515.39] -> 935.222 1077.795 516.574 73.0 63.5 : [ 726. 1430. 516.6] -> 842.993 1089.635 516.349 0.604.8 76.4 : [ 1036. 980. 519.07] -> 901.653 1091.939 516.549 0.801.5 54.1 : [ 1186. 1350. 512.16] -> 909.223 1088.404 516.551 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.601.7 1 0.6
  2320.2 66.0 :
773.0 63.5 : [
773.0 63.5 : [
1604.8 76.4 :
1801.5 54.1 :
1045.7 60.7 :
2198.5 76.2 :
1217.7 52.1 :
2412.6 52.6 :
1616.4 60.2 :
                                                                                                                                                      => 854.817 1089.119 516.381
=> 942.417 1086.120 516.652
                                                      716.
1186.
                                                                                      1340.
                                                                                                                         518.03
                                                                              1480. 516.41]
880. 518.09] =:
770. 518.93] =:
1.29047480921 %
                                                          456.
                                                                                                                                            1] => 882.170 1095.058 516.505
=> 959.673 1083.618 516.699
=> 885.346 1085.574 516.454
                                                       506.
    raining
                                   error mean=
 Validation error mean= 1.25610464433 %
PS C:\Users\srohit\Downloads\fiverr>
```

Figure: Training Regression Model with ASCII Ray Data file.

And the next figure shows typical session of using the model on a different ray data file for prediction

```
Windows PowerShell
  S C:\Users\srohit\Downloads\fiverr> <mark>python.exe ..\</mark>Using+Model+for+Predicting+Geo+Location+of+Emitters.py .\Calib_1.str
 ataset properties:
 ataset size (784, 5)
 Min= 0.00127944267486 Max= 1.00127944267 Mean= 0.179466008977 sigma= 0.18481504455
 Min= 0.00622068024842 Max= 1.00622068025 Mean= 0.62657493406 sigma= 0.144190847335
Min= 0.0312525560868 Max= 1.03125255609 Mean= 0.47824121045 sigma= 0.186312056997
Min= 0.00469889924264 Max= 1.00469889924 Mean= 0.403156520141 sigma= 0.2641023245
Min= 0.0262294279157 Max= 1.02622942792 Mean= 0.586458040488 sigma= 0.190530368099
#Path_Delay Field Strength: [X Y X] => predicted_X predicted_Y predicted_Z 2299.2 58.7 : [ 426.381 587.823 572.276] => [ 937.557 1079.633 516.593] 2537.2 53.5 : [ 426.381 587.823 572.276] => [ 968.038 1081.017 516.712] 2325.7 52.1 : [ 426.381 587.823 572.276] => [ 954.106 1085.236 516.688] 2444.7 52.0 : [ 426.381 587.823 572.276] => [ 964.236 1083.928 516.716] 2311.5 53.7 : [ 426.381 587.823 572.276] => [ 948.618 1083.609 516.657] 2326.4 50.7 : [ 426.381 587.823 572.276] => [ 948.618 1083.609 516.657]
 246.1 59.9
                                 580.393
                                             504.295]
                     395.597
                                                                   931.672 1079.625 516.572
 233.8 55.2
                     395.597
                                 580.393
                                             504.295]
                                                                   938.621 1082.976 516.618
                                 580.393
                                             504.295]
                                                                   959.323 1087.489 516.721
2525.6 55.3 :
                     395.597
                                 580.393
                                             504.295]
                                                                   962.848 1079.377 516.683
2441.8 55.2 :
2244.9 62.1 :
                     395.597
                                 580.393
                                             504.2951
                                                                   955.719 1080.477 516.663
                                                                   929.680 1078.875 516.560
                     376.232
                                 610.186
                                             480.0971
                                                                   939.153 1077.947 516.588
2350.0 61.0 :
                                 610.186 480.0971
 385.1 59.0 :
                     376.232
                                             480.0971
                                 610.186
 340.0 52.0 :
                                                                   955.675 1085.234 516.693
                                             480.0971
                                 610.186
2317.6 60.9
                     395.642
                                 643.962
                                             526.865]
                                                                   936.511 1078.366 516.581
 164.7 56.2 :
                     395.642
                                 643.962
                                             526.865]
                                                                   930.967 1082.863 516.590
  354.3 56.1
                     395.642
                                 643.962
                                              526.865]
                                                                   946.627 1080.825 516.633
```

Figure: Using Regression Model with ASCII Ray Data file.

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