

# Tall Tower Optimization

Siemens Corporation, Corporate Technology  
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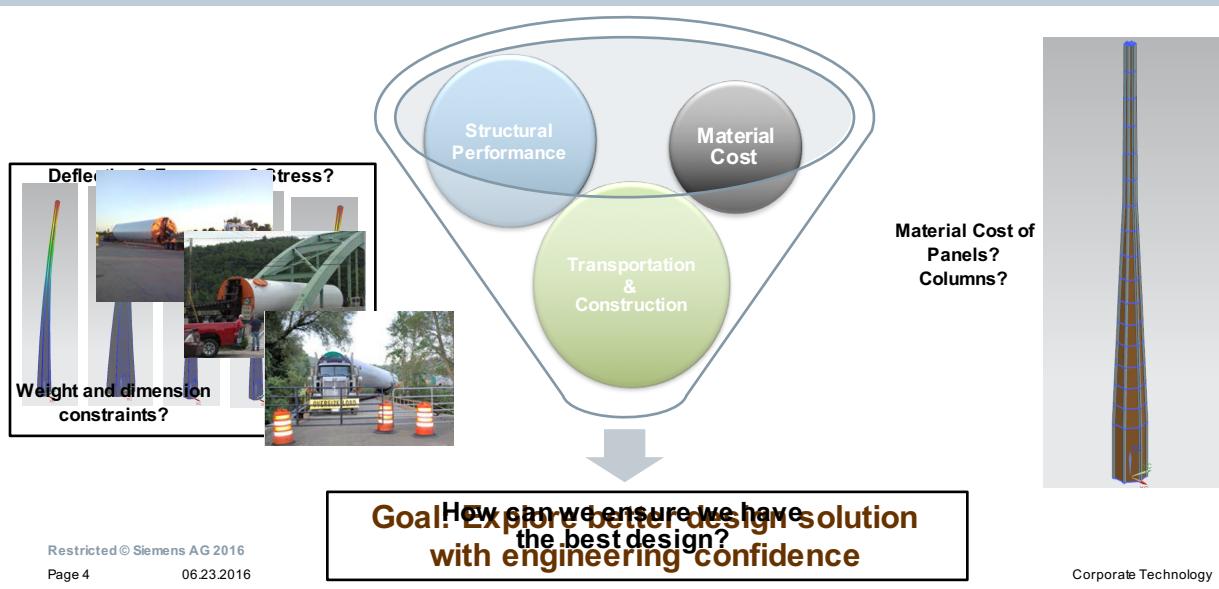
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## Overview

- Objectives and Siemens' Role
- Optimization Work Flow
- FEA Using Siemens NX Open
- Optimization Results
- Summary and Conclusions

## Roles and Objectives

### Why Tower Optimization?



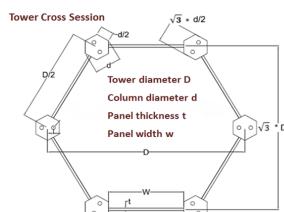
**Siemens's Role**

Siemens  
Wind  
Power

- Initial load estimates
- Tower design constraints (nacelle interface, blade clearance)
- Tower frequency, deflection range

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(CT RDA AUC PSM)

- Design exploration and optimization
- Automate FEA for design variations

**Tall Tower Optimization Formulation****Optimization Problem****Objective Function:**

$$\text{Tower Cost} = f(H, D, d, n, t, \text{Mat})$$

**Constraints****Structural Constraints**

- Deflection Limit
- Frequency
- Section Moment Capability
- Section Stress

**Geometric Dimension Limit****Transportation Constraints**

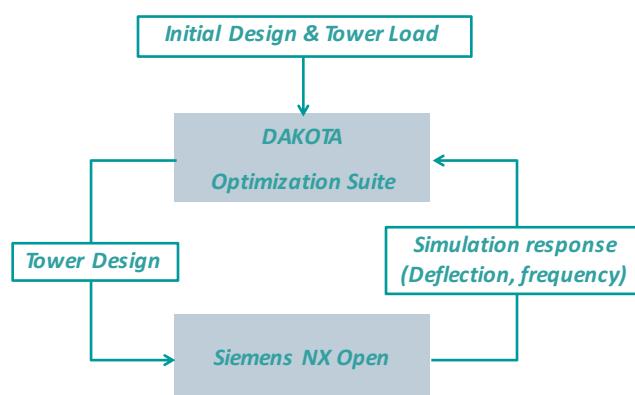
- Weight, length, width

**Construction Constraints**

- Section weight

## Optimization Workflow

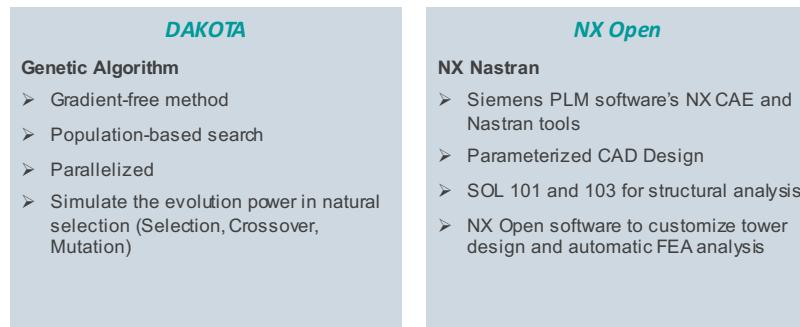
### Overall Workflow



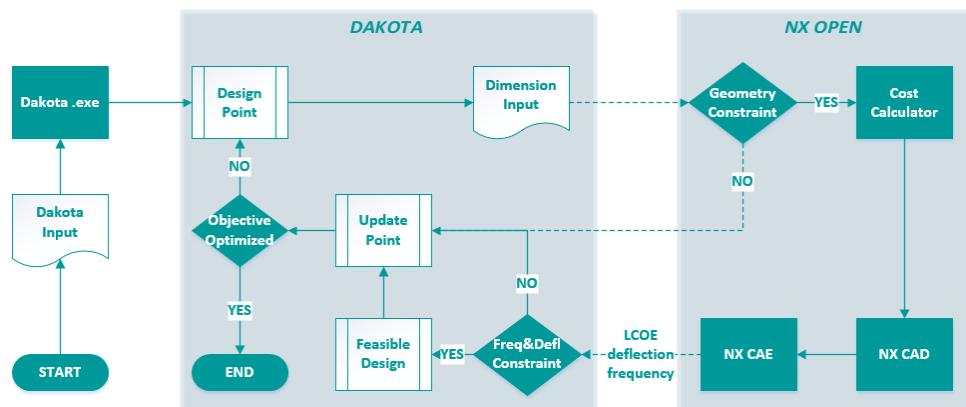
## Workflow Details

Integrate NX Nastran capability with DAKOTA optimization interface

- Explore better design solution with engineering confidence



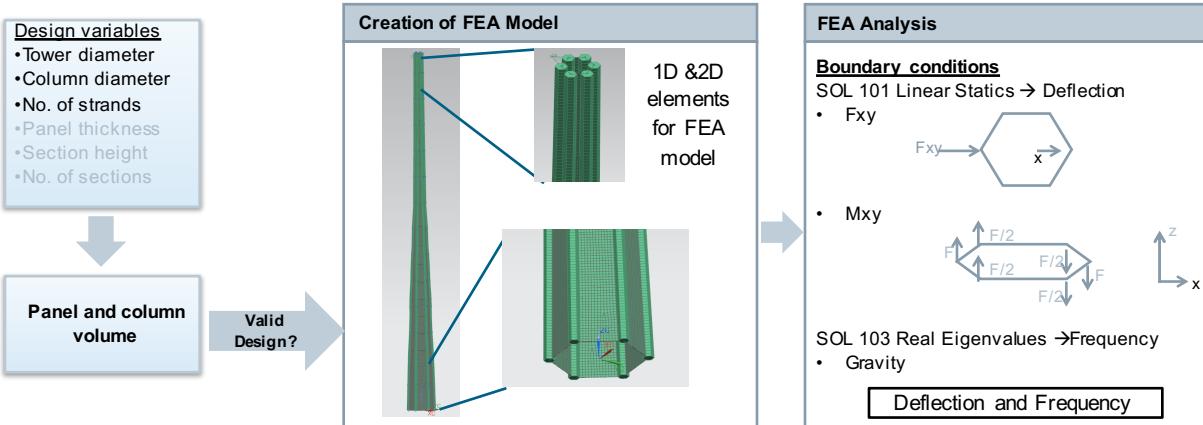
## Workflow Details



## FEA Using Siemens NX Open

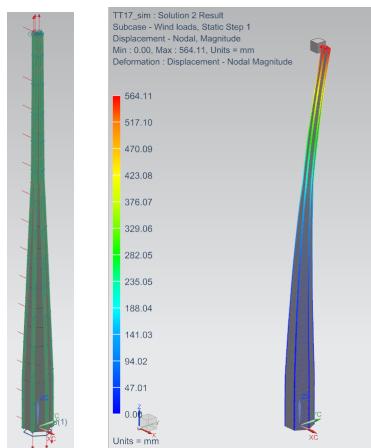
### NX Open → CAD and CAE

- Automatic creation of parameterized CAD model → Dimensions encoded in NX expressions to allow easy update
- Number of sections can be varied as well



## Optimization Setup (FEA Results Using NX CAE)

### Initial Design



Tower D = 8.87 – 31.03 ft  
Column d = 3.59 – 3.83 ft  
No. of strands = 46

Total Panel Vol. (ft<sup>3</sup>) = 5671  
Total Column Vol. (ft<sup>3</sup>) = 23394

Max. deflection = 564.11 mm  
Frequency = 0.318 Hz

Tower Cost(\$) = 2.44e+006  
LCOE(\$/MWh) = 35.86

## Optimization Results

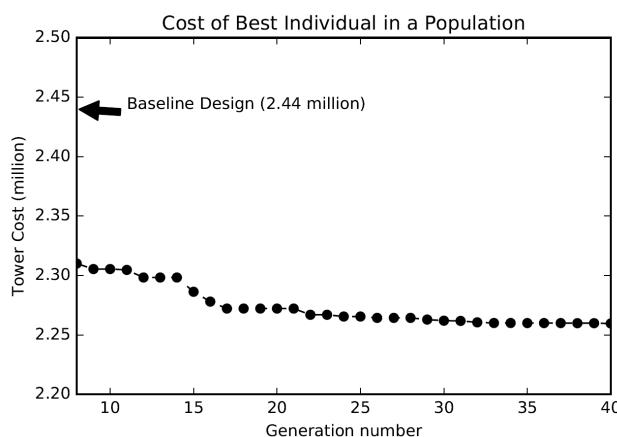
## Optimization Results – More cost efficiency solution

Genetic algorithm parameter settings

Population number	200
Generation number	40
Crossover rate	0.85
Mutation rate	0.15

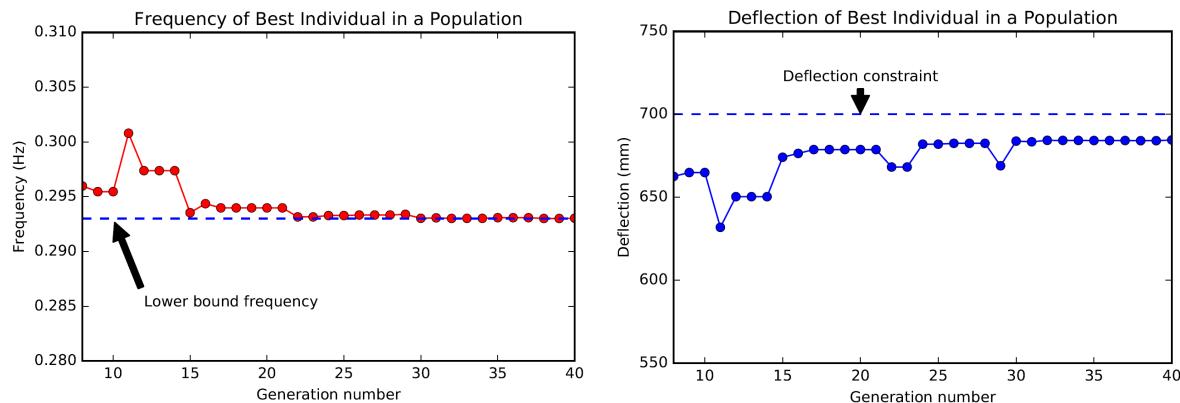
### Optimization case study run:

- 20 hours on 8 processors parallel simulation
- Optimal design showed 7.3% lower cost than baseline tower design, optimal total cost is reduced to 2.259 million.



## Optimization results – Frequency and Deflection analysis

- Record the frequency and deflection constraint function evaluations as optimization evolves



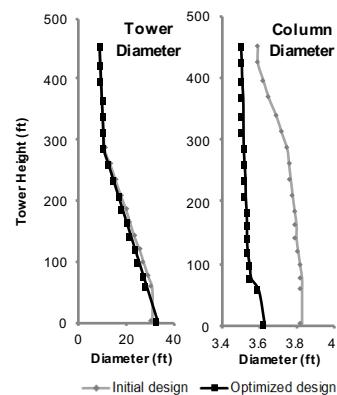
Lower bound frequency constraint is governing the optimal design solution

## Initial Design VS Optimized Design

17 Sections; Tower height = 450.6ft ; Panel thickness = 0.33 – 0.42 ft

Initial Design
Tower D = 8.87 – 31.03 ft Column d = 3.59 – 3.83 ft No. of strands = 46
Total Panel Vol. (ft <sup>3</sup> ) = 5671 Total Column Vol. (ft <sup>3</sup> ) = 23394
Max. deflection = 564.11 mm Frequency = 0.318 Hz Tower Cost(\$) = 2.44e+006 <b>LCOE(\$/MWh) = 35.86</b>

Optimized Design
Tower D = 8.90 – 33.11 ft Column d = 3.50 – 3.63 ft No. of strands = 45
Total Panel Vol. (ft <sup>3</sup> ) = 5501 Total Column Vol. (ft <sup>3</sup> ) = 20680
Max. deflection = 684.73 mm Frequency = 0.293 Hz Tower Cost(\$) = 2.26e+006 <b>LCOE(\$/MWh) = 35.17</b>

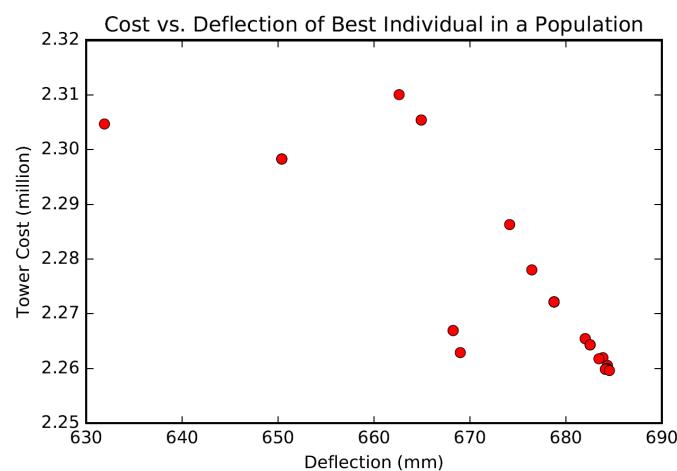


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## Optimization results – Plotting multiple design objectives

- Plot shows that Cost and Deflection are conflicting objectives (Optimal-cost design shows largest deflection)
- Multi-objective optimization (MOO) can reveal trade-offs between multiple design objectives for decision maker
- Maximize flexural stiffness; Minimize vibration, etc.
- Genetic algorithm can easily be used for MOO



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## Summary and Conclusions

### - Summary

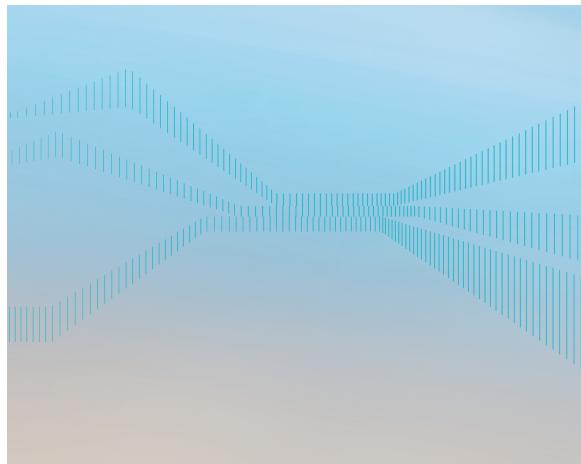
- Implemented automated NX Open software to generate CAD and simulation models for frequency and deflection
- Optimization framework implementation completed
- Integration of CAD models, simulation models, cost calculators, constraint checkers, and optimization tool
- Performed optimization studies, tested and refined optimization framework
- Included tower diameter, column diameter and no. of strands as design variables

### - Conclusions

- Setting up initial design and determine the appropriate load conditions takes more time than optimization itself
- Optimization improved initial design without violating constraints
- LCOE modeling is a complex problem, difficult to access realistic cost model
- Genetic Algorithm is complex and time consuming → Possible use of High Performance Computing

## Contact

Questions/Comments/Suggestions?



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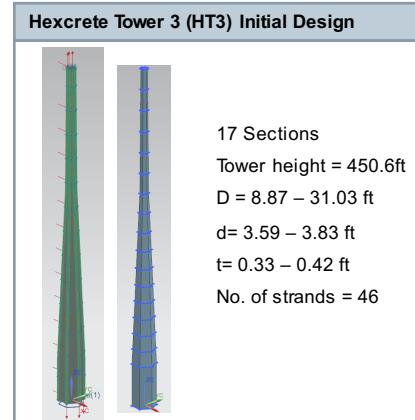
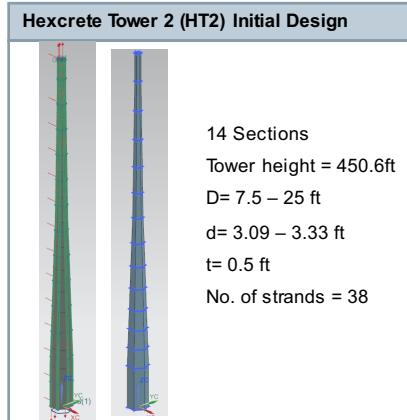
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## Tower Design and Tower Loads



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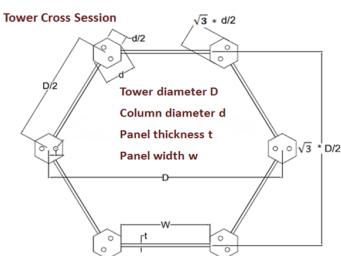
## Tall Tower Optimization Formulation

### Optimization Problem

Objective Function – the Levelized Cost of Energy:

$$LCOE = f(\mathbf{H}, \mathbf{D}, \mathbf{d}, \mathbf{n}, \mathbf{t}, \mathbf{Mat})$$

Optimization Goal → Minimize (LCOE)



### Constraints

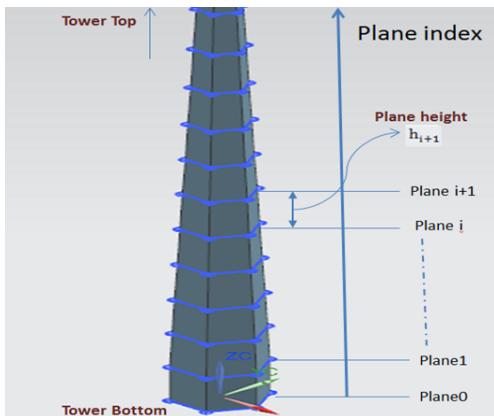
- Structural constraints
  - deflection  $\leq 5 \text{ [mm/m]} = 700 \text{ [mm]}$
  - $0.293 \text{ [Hz]} \leq \text{frequency} \leq 0.6 \text{ [Hz]}$
  - Section Moment Capacity:  $M_i \geq M_i^{\text{load}}, i = 0, 1, \dots, 17$
  - Section Stress:  $\left(\frac{F}{A_i}\right) + \left(\frac{M_i}{I_i}\right) \leq 5.85 \text{ [ksi]}, i = 0, 1, \dots, 17$
- Dimension bound
  - $22 \text{ [ft]} \leq D_0 \leq 36 \text{ [ft]}, D_i (i = 1 \sim 11) \text{ in taper1}, D_i (i = 11 \sim 17) \text{ in taper2}$
  - $3.5 \text{ [ft]} \leq d \leq 6 \text{ [ft]}, d_{i+1} \leq d_i, 60 \leq n \leq 130$
- Transportation constraints
  - Max Length  $\leq$  Truck Length Limit = 54[ft]
  - Max Width  $\leq$  Truck Height Limit = 14[ft]
  - Max Weight  $\leq$  Truck Load Limit = 80,000 [lb]
- Construction constraints
  - Crane below 260[ft]: Section Weight  $\leq 240 \text{ [kips]}$
  - Crane above 260[ft]: Section Weight  $\leq 225 \text{ [kips]}$
  - Blade Tip: Outermost Diameter at 274[ft]  $\leq 14.75 \text{ [ft]}$

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## Tall Tower Optimization Formulation

### Design Parameters



### HT3 TOWER DETAILS

- 18 sections : 19 planes ( index = 0, ... 18)
- Tower plane Diameter  $D = [D_0, D_1, \dots, D_{18}] \in R^{19}$
- Column Diameter  $d = [d_0, d_1, \dots, d_{18}] \in R^{19}$
- Plane height  $H = [h_0, h_1, h_2, \dots, h_{18}] \in R^{19}$
- Column Strand  $n \in [60, 130]$
- Panel Thickness  $t -- tbd$
- Column/Panel Material **Mat** -- tbd
- Transportation Parameter  $T -- tbd$
- Material cost parameter --  $M -- tbd$
- Construction parameter --  $C -- tbd$

## Tall Tower Optimization Formulation

### Optimization Constraints (cont.)



Transportation constraint:

- Maximal part weight <= 40,000 lb
- Maximal part length <= 48 ft
- Maximal part width <= 14 ft

Source: *Federal Size Regulations for Commercial Motor Vehicles* (U.S. Department of Transportation Federal Highway Administration)

Construction constraint:

- Tower plane diameter at top  $D_{18} = 8.86$  ft

## LCOE

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Levelized Cost of Energy(\$/MWh)

$$LCOE = \frac{ICC \times FCR + AOE}{AEP_{net}}$$

ICC	Installed Capital Cost (\$/kW)	Tower Cost included
FCR <sup>1</sup>	Fixed Charge Rate (%)	9.5%
AOE <sup>1</sup>	Annual Operating Expenses (\$/kW/yr)	35 \$/kW/yr
AEP <sub>net</sub> <sup>2</sup>	Net Annual Energy Production (MWh/MW/yr)	7697 MWh/MW/yr

1. Source: NREL Cost of Wind Energy Review
2. Source: Iowa State University

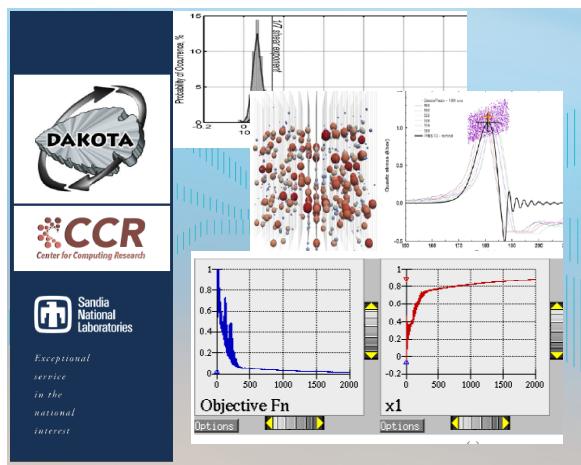
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## Tall Tower Optimization Formulation

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### Introduction to DAKOTA



Dakota is a computing framework which is/allows

- Multilevel Parallel
- Object-Oriented
- Design Optimization
- Parameter Estimation
- Uncertainty Quantification
- Sensitivity analysis

The key Dakota capabilities

- Generic interface to simulations
- Time-tested and advanced algorithms
- Strategies to combine methods for advanced studies
- Mixed deterministic / probabilistic analysis
- Supports scalable parallel computations on cluster

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## Tall Tower Optimization Formulation

### Example -- Parameter Study

```
TTsim_multi_3v_eval.in
1 # Dakota Input File: TTsim_multi_3v_eval.in
2 # Usage:
3 # dakota -i TTsim_multi_3v_eval.in -o TTsim_multi_3v_eval.out
4
5 environment
6   # graphics
7   tabular_data
8     tabular_data_file = 'TTsim_multi_3v_eval.dat'
9
10 method
11   multidim_parameter_study
12   partitions 3 7 7
13
14 model
15   II_Command dakota -i TTsim_multi_3v_eval.in -o TTsim_multi_3v_eval.out
16   single
17
18 variables
19   continuous_design = 3
20   lower_bounds    1.0    1.0    1.0
21   upper_bounds    2.0    2.0    2.0
22   descriptors     'x1'   'x2'   'x3'
23
24 interface
25   analysis_driver = 'TTSimBuilderNX9'
26   fork
27   #file_ras
28   #file_save
29   parameters_file = 'params.in'
30   results_file    = 'results.out'
31
32 responses
33   num_response_functions = 1
34   no_gradients
35   no_hessians
36
37
```

### Six specification blocks

- Environments
- Method
- Model
- Variables
- Interface
- Response

### In this task:

method = "multidim\_parameter\_study"

– meaning to evaluate to multi variables.

### Interface:

analysis\_driver = 'TTSimBuilderNX9'

– specify the simulation.exe generated from NX Open

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## Tall Tower Optimization Formulation

### Example -- Genetic Algorithm

```
TTsim_3v_soga.in
1 # Dakota Input File: TTsim_3v_soga.in
2 # Usage:
3 # dakota -i TTsim_3v_soga.in -o TTsim_3v_soga.out > TTsim_3v_soga.stdout
4
5 environment
6   # graphics
7   tabular_data
8     tabular_data_file = 'TTsim_3v_soga.dat'
9
10 method
11   max_iterations = 20
12   max_function_evaluations = 400
13   seed = 11011011
14   population_size = 20
15   fitness_function
16   mutation_type replace_uniform
17   mutation_rate 1.0
18   crossover_type multi_point_binary = 4
19   crossover_rate 0.0
20   replacement_type favor_feasible
21
22 model
23   single
24
25 variables
26   continuous_design = 3
27   lower_bounds    1.0    1.0    1.0
28   upper_bounds    2.0    2.0    2.0
29   descriptors     'x1'   'x2'   'x3'
30
31 interface
32   analysis_driver = 'TTSimBuilderNX9_Cpp'
33   fork
34   #file_ras
35   #file_save
36   parameters_file = 'params.in'
37   results_file    = 'results.out'
38
39 responses
40   objective_functions = 1
41   no_gradients
42   no_hessians
43
```

### Running Genetic Algorithm

- 'soga' – single object genetic algorithm
- Seed – the specified starting random value for population
- population\_size – the number of children for each iteration
- mutation\_rate – control how the evolution to reach out to different area (exploration)
- crossover\_rate – control how well the algorithm can reserve good candidates (exploitation).

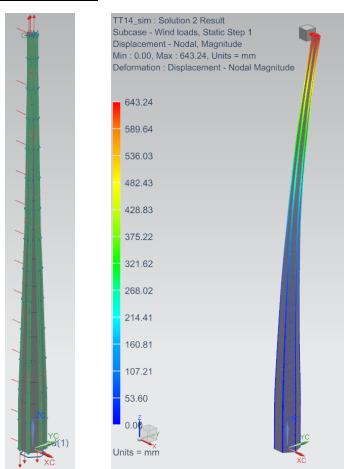
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## HT2 Baseline Model – FEA Results Using NX CAE

### Initial Design



14 Sections  
Tower height = 450.6ft  
D= 7.5 – 25 ft  
d= 3.09 – 3.33 ft  
t= 0.5 ft  
No. of strands = 38

Total Panel Vol. (ft<sup>3</sup>) = 6535  
Total Column Vol. (ft<sup>3</sup>) = 16750

Max. deflection = 643.24 mm  
Frequency = 0.266 Hz

Tower Cost(\$) = 2.04e+006