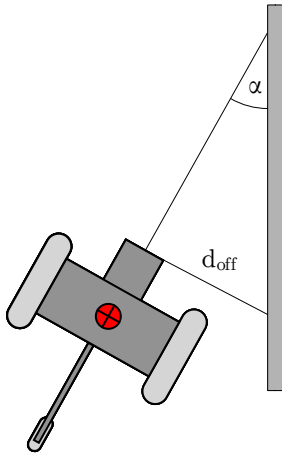
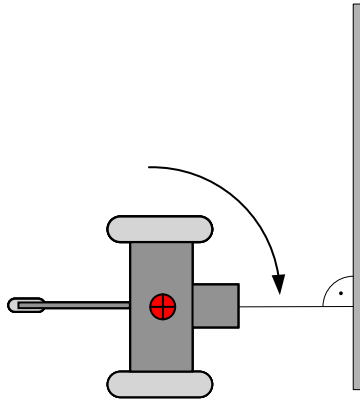


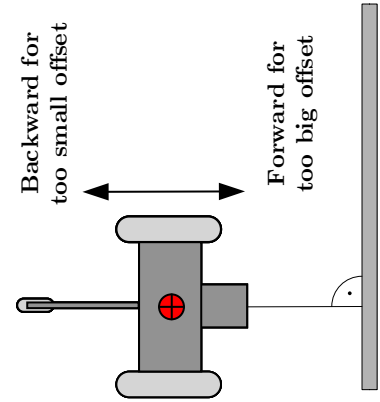
1. Measuring offset and angle



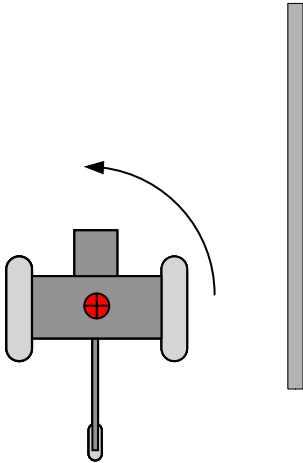
2. Rotation to the right



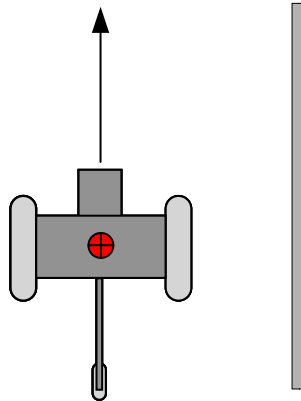
3. Correct offset



4. Rotate left parallel to wall



5. Drive along wall



6. Stop when angle out of tolerance

