

Project Description

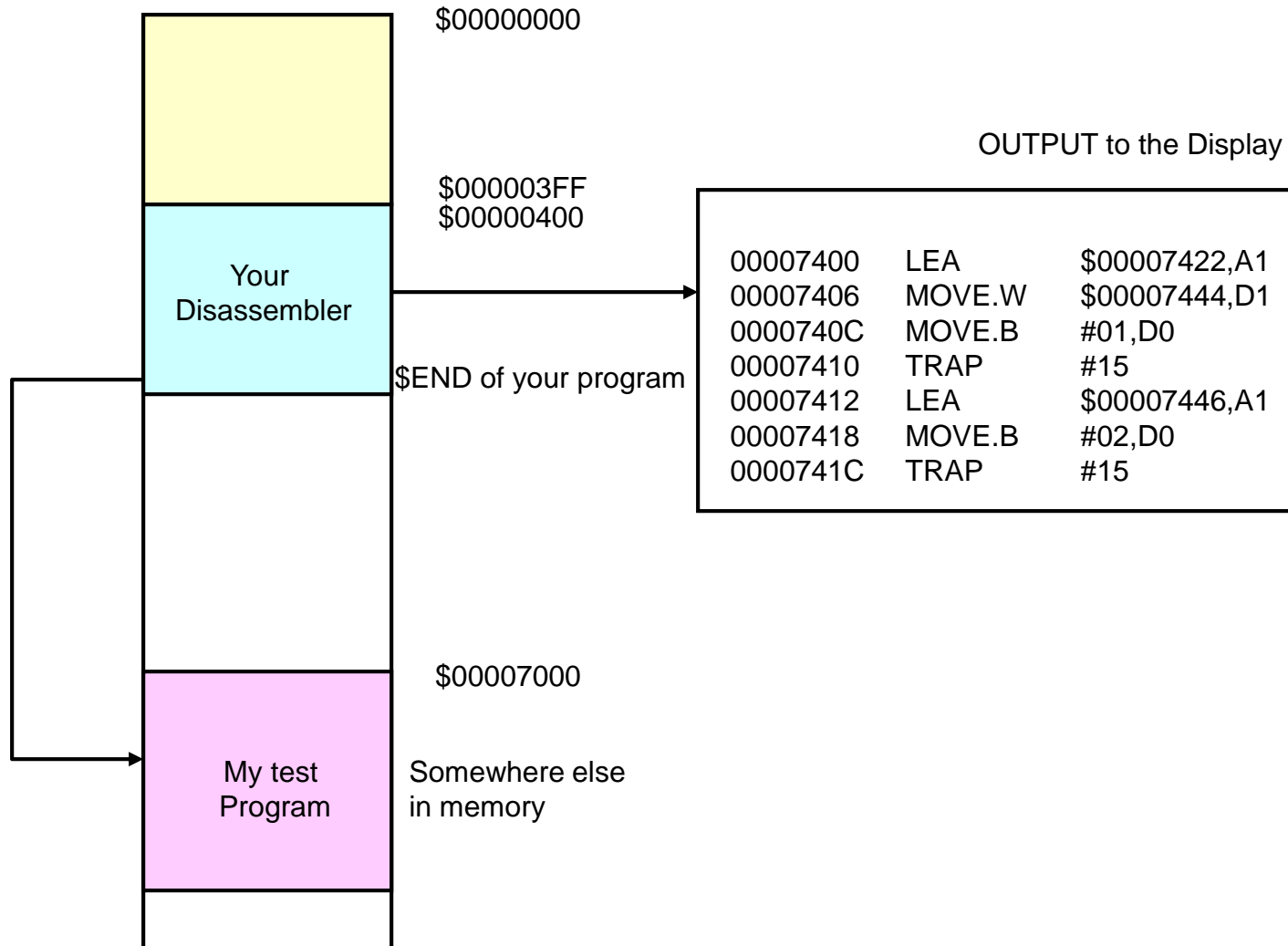
Project Description

- See the canvas for the project description
- Progress reports
- Confidential evaluation
- Specification (how to program, etc.)
- Deliverable (what to submit, when, how)
- Simulator issues and Easy68k bug report (reported by students from previous class)
- Grading standards
- Required op-code and EA
- Addendum (additional information, will be continuously updated)

What is a disassembler?

- Disassembler (also called an ***Inverse Assembler***):
 - **Scans** a section of memory, and
 - **Attempts to convert** the memory's contents to a listing of valid assembly language instructions
- Most disassemblers cannot recreate symbolic, or label information
- Disassemblers **can be easily fooled** by not starting on an instruction boundary
- How it works:
 - The disassembler program **parses the op-code word** of the instruction and then **decides how many additional words** of memory need to be read in order to complete the instruction
 - If necessary, reads additional instruction words
 - The disassembler program **prints out the complete instruction** in **ASCII-readable format**
 - Converts binary information to readable Hex

What is a disassembler?



What is a disassembler?

- Source file contains symbolic names for numerical values, comments, symbol names for memory locations (variables)
- Source file **does not contain detailed memory location information**

NUM1	EQU	\$AA	*First number
NUM2	EQU	\$55	*Second Number
stack	EQU	\$7000	*Stack pointer
temp	EQU	\$1000	*Memory variable
	ORG	\$400	*Starting address
start	NOP		
	MOE.W	#STACK,SP	*Initialize the stack pointer
	MOVE.B	#\$D7,D0	*Load D0 with D7
	MOVE.B	#NUM1,D1	*Load first number
	MOVE.B	#NUM2,D2	*Load the second number
	MOVEA.W	#temp,A0	*Load temp address
	MOVE.B	D1,(A0)+	*Save it
	MOVE.B	D0,(A0)	*Save next
	SUBA.W	#\$0001,A0	*Store address
	ASR.W	(A0)	*Shift it
	MOVE.W	(A0),D7	*Get it back
	BRA	start	*Go back and do it again
	END	\$400	*End of code

What is a disassembler?

- List file contains symbolic names for numerical values, comments, symbol names for memory locations (variables)
- **List file also contains detailed memory location information** not found in source file, including line numbers, other cross-reference information, and object code

1	000000AA	NUM1:	EQU	\$AA	;*First number
2	00000055	NUM2:	EQU	\$55	;*Second Number
3	00007000	STACK:	EQU	\$7000	;*Stack pointer
4	00001000	TEMP:	EQU	\$1000	;*Memory variable
5					
6	00000400		ORG	\$400	;*Starting address
7	00000400 4E71	START:	NOP		
8	00000402 3E7C7000		MOVE.W	#STACK,SP	;*Initialize the stack pointer
9	00000406 103C00D7		MOVE.B	#\$D7,D0	;*Load D0 with D7
10	0000040A 123C00AA		MOVE.B	#NUM1,D1	;*Load first number
11	0000040E 143C0055		MOVE.B	#NUM2,D2	;*Load the second number
12	00000412 307C1000		MOVEA.W	#TEMP,A0	;*Load temp address
13	00000416 10C1		MOVE.B	D1,(A0)+	;*Save it
14	00000418 1080		MOVE.B	D0,(A0)	;*Save next
15	0000041A 90FC0001		SUBA.W	#\$0001,A0	;*Store address
16	0000041E E0D0		ASR.W	(A0)	;*Shift it
17	00000420 3E10		MOVE.W	(A0),D7	;*Get it back
18	00000422 60DC		BRA	START	;*go back and do it again
19	00000400		END	\$400	;*end of code

What is a disassembler?

- What the same memory region would look like if displayed by an inverse assembly program
- Displays memory addresses and instructions at that address
- **All symbolic information and comments are lost!**

00000400	NOP	
00000402	MOVE.W	\$7000, SP
00000406	MOVE.B	#\$D7, D0
0000040A	MOVE.B	#\$AA, D1
0000040E	MOVE.B	#\$55, D2
00000412	MOVEA.W	\$1000, A0
00000416	MOVE.B	D1, (A0) +
00000418	MOVE.B	D0, (A0)
0000041A	SUBA.W	#\$0001, A0
0000041E	ASR.W	(A0)
00000420	MOVE.W	(A0), D7
00000422	BRA	\$00000400

Important! Testing Your Code!

Remember this page! You will check this page many times!

Assume that you have your disassembler program ready.

1. Write a testing source code (testing.X68→ testing.S68)
 - List all the required opcode and EA
 - Any non-required opcodes to see if your program can catch it as invalid data
2. Run your disassembler program from the source file
3. Your program will open in the simulator program
4. In the simulator, go to **File→Open Data**
5. Choose the “testing.S68” file as a testing file
6. Then, the assembled testing file will be loaded into your memory
7. See where the “data” is loaded
8. Go to **Run→Log Start** to have a log file
9. Run your program, and give the starting and ending address when prompt (\$7FC0 and \$814F, for example)
10. Should show one screen of data at a time, hitting the ENTER key should display the next screen

Group Dynamics and Logistics

- 2 or 3 students per team
- Get an early jump on this project. Don't wait! You still have two exams, five assignments, and 14 exercises to prepare for!
- Plan, plan, plan! Do not write code until you know what you are doing!
- Back-ups and version control!
- Integration!
- Develop a test program early!
- Test thoroughly, do incremental development!
- Develop a schedule and follow it!
- Meet regularly to sync-up your code and do a status check face-to-face. Don't depend exclusively on emails!

Why Projects Fail

- **Insufficient testing**
 - Fail to find subtle bugs
 - Side effects due to word addressing
 - Incomplete test program
- Having to write too much code due to poor up-front planning
- **Team becomes dysfunctional**
 - Must be self-directed, no manager to beat you into submission
 - Poor division of responsibilities among team members
- **Underestimating** the needed effort and time
 - Waiting too long to start
- **Poor project management!!!**
 - No back-up or version control
 - Late code integration
- **Time management!!!**
- Caught cheating

Some Representative Milestones

1. Team is organized
2. Team meets to discuss and set expectations and team values
3. Team decides who does what
4. Development schedule is created
5. Test program is built
6. Team meets and decides on API's
7. I/O skeleton is complete, will display all memory as data
8. NOP is decoded
9. Other op-codes and effective address modes are added
10. Team meets regularly to check status, integrate SW
11. Begin abuse testing, start write-up
12. Complete personal statements
13. Complete all deliverables, pack everything up, cross your fingers and study for the final!

Team Organization 1

- Disclaimer: This is only *one way out of many possible ways* to organize your teams
- Team Roles based on **Functions/Libraries/Subroutines**
 - I/O Person: Handles all inputs from the user and displays to the screen – I/O Library
 - Op-Code Person: Handles decoding the OP-Codes and passing EA information to EA person – OPCode Library
 - EA Person: Decodes Effective Addresses – EA Library

Team Organization 2

- Disclaimer: This is only *one way out of many possible ways* to organize your teams
- Team Roles based on **workload**
 - Each member takes care of a certain amount of OpCode work
 - Each member takes care of a certain amount of EA work
 - Work together on I/O work – critical for testing and debugging

Team Organization 3

- Disclaimer: This is only ***one way out of many possible ways*** to organize your teams
- All team members work together on basic, common routines
- Team members divide the rest of work to balance workload

Team Organization 4

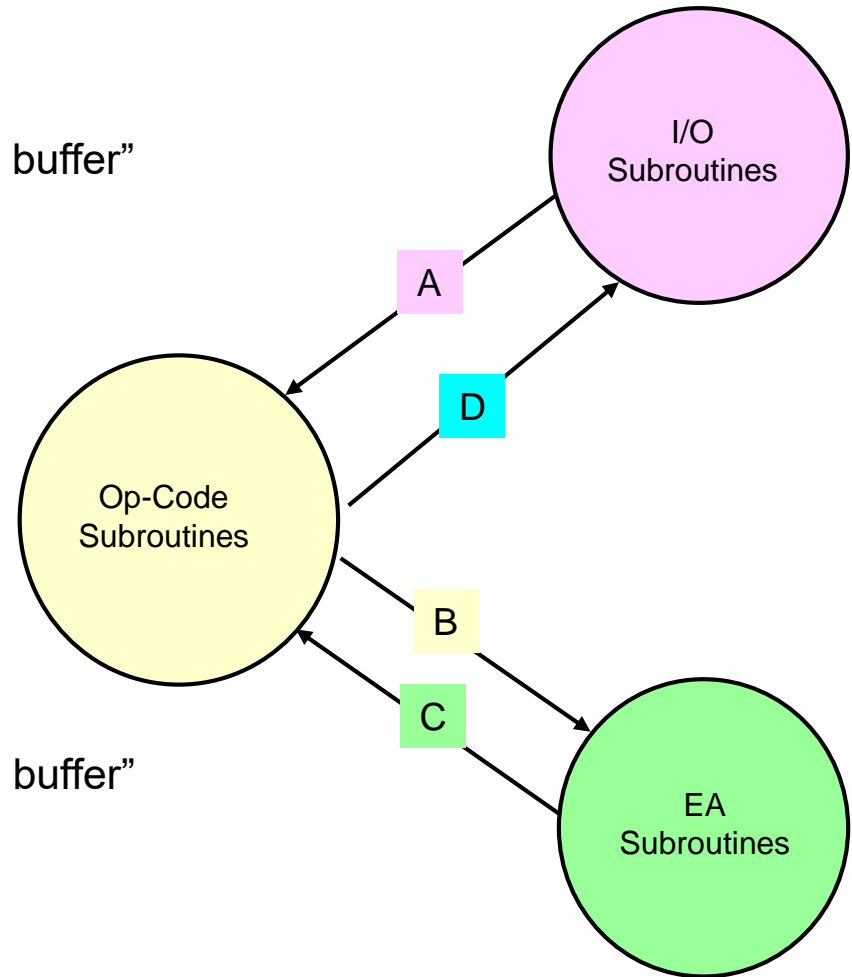
- Disclaimer: This is only *one way out of many possible ways* to organize your teams
- Team Roles based on **subroutines/functions**
 - All team members sit together to define the needed functions and the APIs
 - All team members sit together to define how to parse in and out data between functions
 - Allocate different functions to different members to balance the workload

General Program Flow

1. I/O subroutines prompt user (me) for a starting and ending address in memory
2. User enters starting and ending addresses for region of memory to be disassembled
3. I/O subroutines check for errors and if address are correct, prepare the display buffer and send address in memory to Op-Code routines
4. Op-Code subroutines can either decode word to legitimate instruction or cannot.
 1. If word in memory cannot be decoded to legitimate instruction, I/O routines writes to screen: XXXXXXXX DATA YYYY, where XXXXXXXX is the memory address of the word and YYYY is the hex value of the word
 2. If it can be decoded then it is prepared for display and the EA information is passed to the EA routines
5. EA subroutines decode EA field(s) and
 1. If EA cannot be decoded, signals this back, or
 2. Prepares operands for display
6. Once the instruction is displayed, process repeats itself

Parameter Passing

- A Parameters
 - Pointer to memory to decode
 - Pointer to next available space in “Good buffer”
 - Good/bad flag
- B Parameters
 - Memory pointer to next word after the op-code word
 - 6 bits from EA field of op-code word
 - Pointer to next available space in “Good buffer”
 - Good/bad flag
- C Parameters
 - Memory pointer to next word after the EA word
 - Pointer to next available space in “Good buffer”
 - Good/bad flag
- D Parameters
 - Memory pointer to next op-code word
 - Good/bad flag



Required Op-code and EA

- Not all op-codes/EA are required to disassemble

Required op-codes and addressing modes:

Instructions:

NOP
MOVE, MOVEQ, MOVEM, MOVEA
ADD, ADDA, ADDQ
SUB
LEA
AND, OR, NOT
LSL, LSR, ASL, ASR
ROL, ROR
Bcc (BGT, BLE, BEQ)
JSR, RTS
BRA

Effective Addressing Modes:

Data Register Direct
Address Register Direct
Address Register Indirect
Immediate Addressing
Address Register Indirect with Post-incrementing
Address Register Indirect with Pre-decrementing
Absolute Long Address
Absolute Word Address