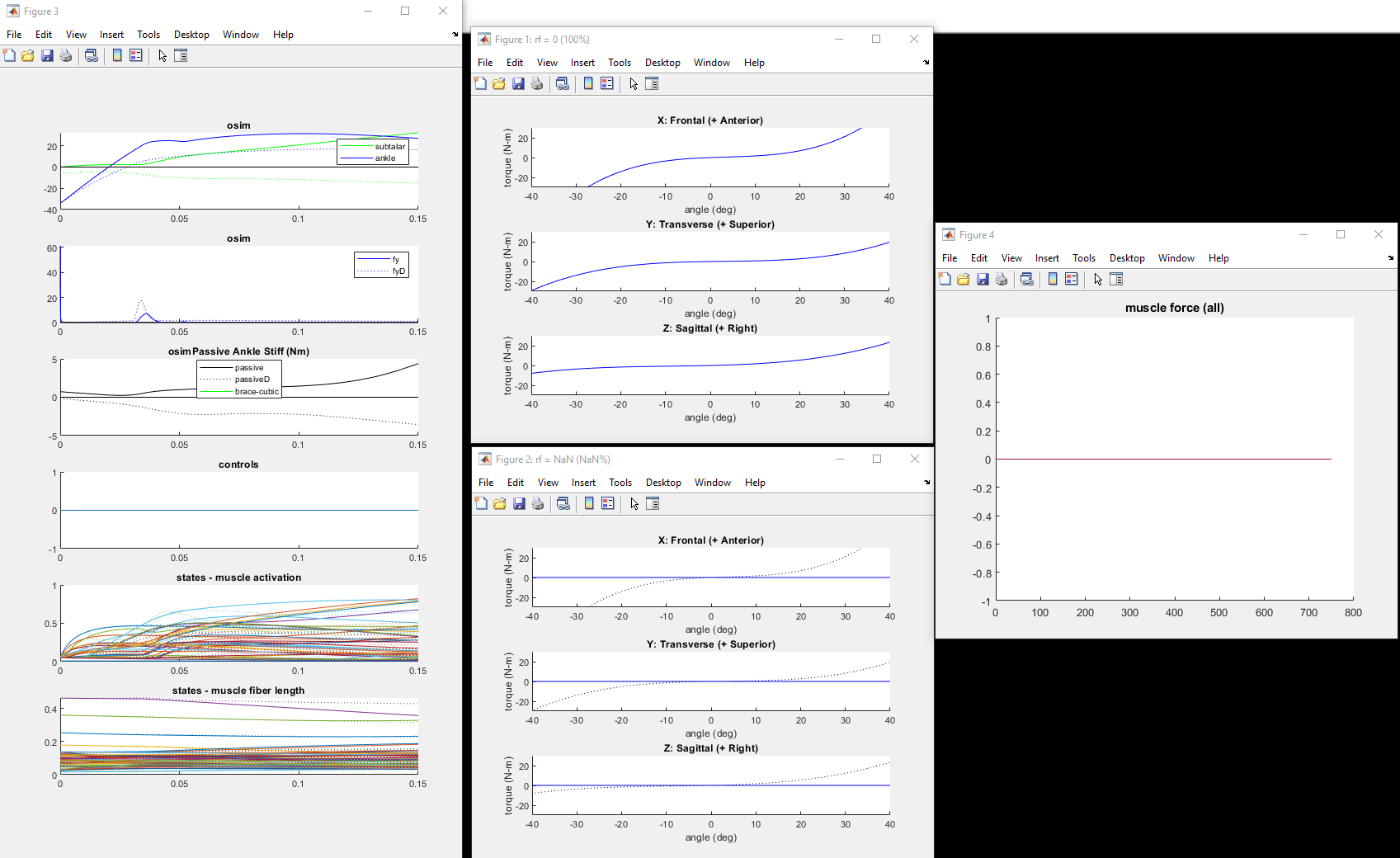
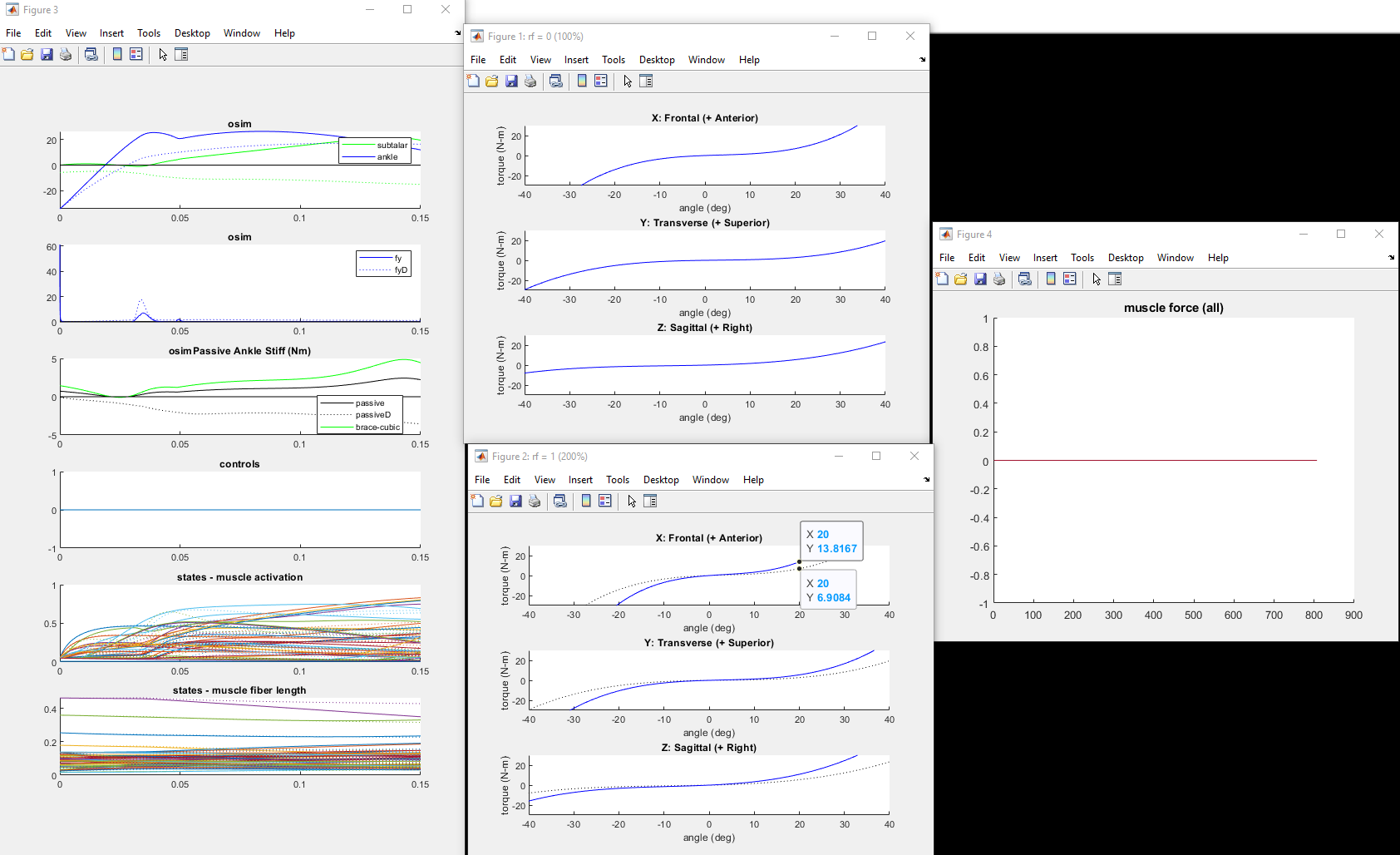
**trial1\_nomuscle\_1.0anatomy\_0.0brace**



**Anatomy**

**Brace**

**Trial2\_nomuscle\_1.0anatomy\_1.0brace *(2x stiffer than anatomy at fixed displacements)***



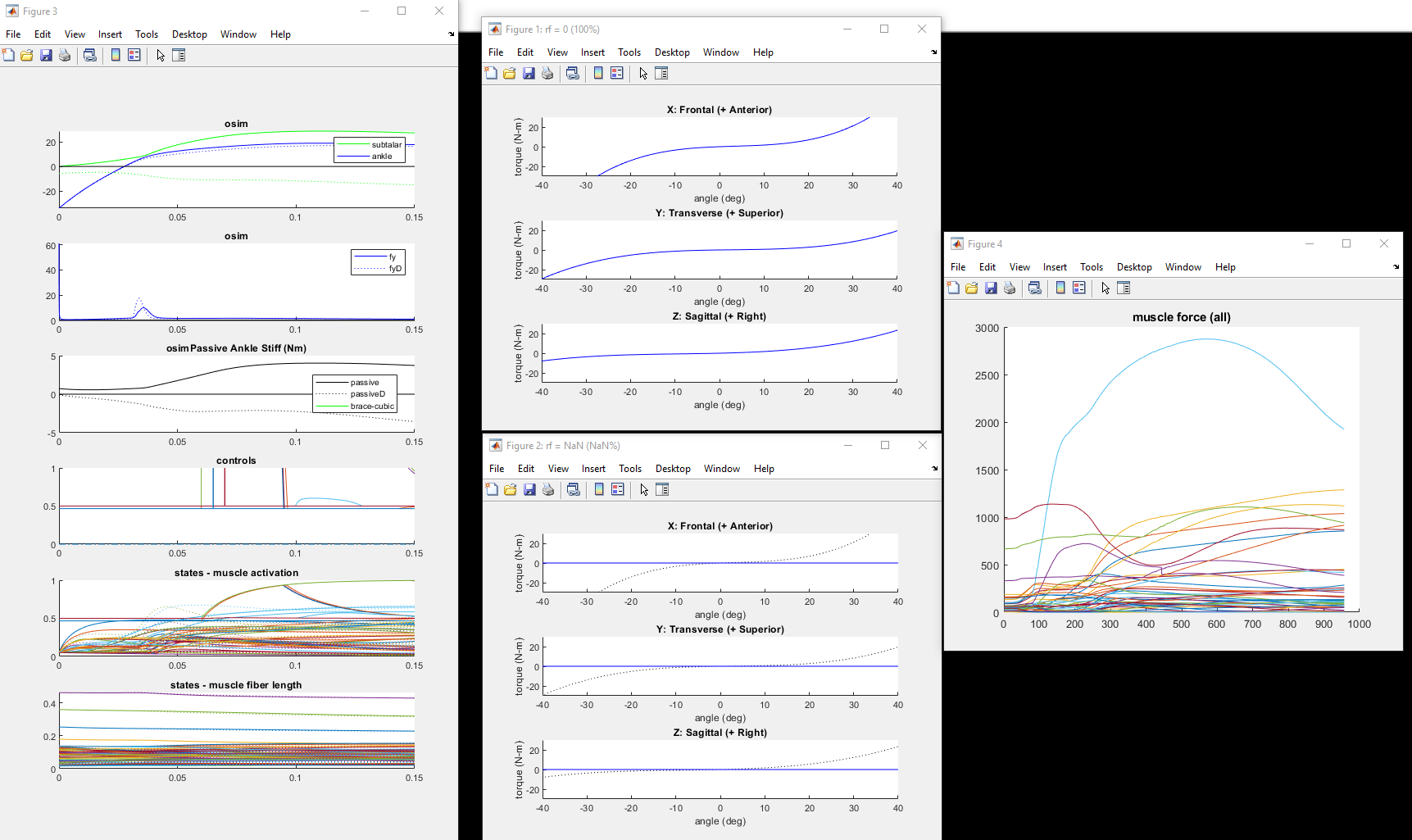
**Anatomy**

**Brace**

**Trial3\_withmuscles\_1.0anatomy\_0.0brace**

**(used 50% Inv/Ev co-activation, and 5.0 reflex gain)**

**These should produce physiologically reasonable JCS angles and velocities w.r.t literature**



**This is soleus\_r @2800N**

**Brace**

**Anatomy**