

# Optimization HW1

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## Question 1

Prove or disprove the following claims.

Note that for this questions we assume  $x, y \in \mathbb{R}^n$ .

1. The expression  $\langle x, y \rangle_M = x^T M y$  is an inner product if  $M \in \mathbb{R}^{n \times n}$ .

By definition, an inner product maps  $\langle \cdot, \cdot \rangle : \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}$  and for every  $x, y \in \mathbb{R}^n, \lambda \in \mathbb{R}$  upholds:

- (a) Symmetry:  $\langle x, y \rangle = \langle y, x \rangle$
- (b) Additivity:  $\langle x + y, z \rangle = \langle x, z \rangle + \langle y, z \rangle$
- (c) Homogeneity:  $\langle \lambda x, y \rangle = \lambda \langle x, y \rangle$
- (d) Positive-definite:  $\langle x, x \rangle \geq 0$  and  $\langle x, x \rangle = 0$  iff  $x = 0$ .

We can easily show that the given product does not answer (d), meaning it is not positive definite. If  $M$  is the zero matrix (it contains only zeros) then:  $\langle x, x \rangle_M = x^T M x = 0$  even though  $x \neq 0$ . We got/ a contradiction, therefore the given expression is not an inner product.

2. The expression  $\langle x, y \rangle_Q = x^T Q y$  is an inner product if  $0 \prec Q \in \mathbb{R}^{n \times n}$ .

The definition of a positive definite matrix is that for a symmetrical matrix  $Q \in \mathbb{R}^{n \times n}$  and for every  $0 \neq x \in \mathbb{R}^n$  we get  $x^T Q x > 0$ . Marking  $0 \prec Q$ . Lets go over all 4 requirements for an inner product:

- (a) Symmetry:  $Q$  is symmetrical, therefore  $Q = Q^T$ .  $\langle x, y \rangle = x^T Q y = (y^T Q x)^T$  The product of this equation is a single value (not a matrix) therefore it is equal to its transpose.  
 $(y^T Q x)^T = y^T Q x = \langle y, x \rangle$
- (b) Additivity:  $\langle x + y, z \rangle = (x + y)^T Q z = (x^T + y^T) Q z = x^T Q z + y^T Q z = \langle x, z \rangle + \langle y, z \rangle$
- (c) Homogeneity:  $\langle \lambda x, y \rangle = (\lambda x)^T Q y = \lambda x^T Q y = \lambda \langle x, y \rangle$
- (d) Positive-definite: According to the positive definite matrix definition, the positive-definite requirement is met.

The expression answers all requirements, therefore it is an inner product.

## Question 2

Let  $A \in \mathbb{R}^{n \times n}$

1. Prove that if  $0 \prec A$  then it is invertible, and  $0 \prec A^{-1}$

By definition, a positive definite matrix is a symmetrical matrix  $A \in \mathbb{R}^{n \times n}$  that for every  $0 \neq x \in \mathbb{R}^n$  we get  $x^T A x > 0$ . Marking it  $0 \prec A$ .

According to tutorial 1,  $x \prec A$  iff all of its eigenvalues are positive definite. It is known that 0 is not an eigenvalue of a square matrix iff it is invertible.

For eigenvector  $0 \neq v \in \mathbb{R}^n$  and its corresponding eigenvalue  $\lambda$

$$\begin{aligned} Av &= \lambda v \\ A^{-1}Av &= A^{-1}\lambda v \\ A^{-1}v &= \frac{1}{\lambda}v \end{aligned}$$

Since  $v \neq 0$  it implies that it is the eigenvector for  $A^{-1}$  with the corresponding eigenvalue  $\frac{1}{\lambda}$ . Given that,  $\lambda > 0 \implies \frac{1}{\lambda} > 0 \implies 0 \prec A^{-1}$ .

2. Prove that if  $0 \preceq A$  and it is inevitable then  $0 \prec A$

As seen in tutorial 1,  $x \preceq A$  iff all of its eigenvalues are positive semidefinite. Because it is also invertible that means that  $\lambda \neq 0 \implies \lambda > 0$ . This means that  $x \prec A$  because all of its eigenvalues are positive definite.

3.  $A = B^T B$  for some  $B \in \mathbb{R}^{m \times n}$ . We will prove that  $0 \preceq A$ .

$$\begin{aligned} x^T A x &= x^T B^T B x = (Bx)^T (Bx) \\ Bx &\in \mathbb{R}^m \\ Bx &= y \\ (Bx)^T (Bx) &= y^T y = \sum_{i=1}^m y_i^2 \geq 0 \end{aligned}$$

$0 \preceq A$  by definition.

Note that  $0 \not\prec A$ . For example

$$\begin{aligned} x &= \begin{bmatrix} 0 \\ 1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \\ A = B^T B &= \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \\ x^T A x &= \begin{bmatrix} 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \end{bmatrix} = 0 \end{aligned}$$

4. Prove that if  $A_{i,i} < 0$  for any  $1 \leq i \leq n$  then  $0 \not\prec A$ .

$$x^T A x = \sum_{i=1}^n \sum_{j=1}^n x_i x_j A_{i,j} = \sum_{i=1}^n \sum_{j \neq i}^n x_i x_j A_{i,j} + \sum_{i=1}^n x_i^2 A_{i,i}$$

If there exists  $A_{i,i} < 0$  then  $x_i^2 A_{i,i} < 0$  for  $x_i \neq 0$ . By choosing a vector  $x$  containing only zeros except  $x_i$  that corresponds to  $A_{i,i} < 0$  we get  $x^T A x < 0$  meaning  $0 \not\preceq A$ .

It is not a sufficient condition. For example

$$x = \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \quad A = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

$$x^T A x = \begin{bmatrix} 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \end{bmatrix} = 0$$

### Question 3

Function  $f : U \rightarrow \mathbb{R}$  is continuously differential while  $U \subseteq \mathbb{R}^n$ . Direction  $0 \neq d$  is called the downhill direction of the function at point  $x$  if there exists  $0 < T$  so that for every  $0 < t < T$

$$f(x + td) < f(x)$$

1. Prove that if direction  $d$  uphold  $f'(x, d) < 0$  for a certain  $x$ , then it is a downhill direction of  $f$  at  $x$ .

By definition:

$$f'(x, d) = \lim_{t \rightarrow 0^+} \frac{f(x + td) - f(x)}{t}$$

We assume  $0 < t < T$ .

$$\begin{aligned} f'(x, d) &< 0 \\ \lim_{t \rightarrow 0^+} \frac{f(x + td) - f(x)}{t} &< 0 \\ \frac{f(x + td) - f(x)}{t} &< 0 \\ f(x + td) - f(x) &< 0 \\ f(x + td) &< f(x) \end{aligned}$$

If direction  $d$  uphold  $f'(x, d) < 0$  then  $f(x + td) < f(x)$  which means it is a downhill direction.

2. Prove that if  $\nabla f(x) \neq 0$  then the direction  $d = -\nabla f(x)$  is a downhill direction of  $f$  at  $x$ .

By definition:

$$\begin{aligned} \frac{\partial f}{\partial x_i}(x) &= \lim_{t \rightarrow 0^+} \frac{f(x + te_i) - f(x)}{t} \\ \nabla f(x) &= \left[ \frac{\partial f}{\partial x_1}(x) \quad \frac{\partial f}{\partial x_2}(x) \quad \dots \quad \frac{\partial f}{\partial x_n}(x) \right]^T \end{aligned}$$

As seen in tutorial 1, if  $f$  is continuously differential then

$$\begin{aligned} f'(x, d) &= \nabla f(x)^T d, \quad \forall d \in \mathbb{R}^n \\ d &= -\nabla f(x) \rightarrow \nabla f(x) = -d \\ \Rightarrow f'(x, d) &= \nabla f(x)^T d = -d^T \times d = -\sum d_i^2 < 0 \end{aligned}$$

As seen in part 1, if  $f'(x, d) < 0$  for a certain  $x$  then it is a downhill direction of  $f$  at  $x$ .

3. Function  $f(x_1, x_2) = x_1^2 + x_2^2$  is continuously differential. Given point  $x^{(0)} = [x_1^{(0)} \ x_2^{(0)}]^T = [1 \ 1]^T$ :

$$\nabla f(x) = \left[ \frac{\partial f}{\partial x_1}(x) \quad \frac{\partial f}{\partial x_2}(x) \right]^T = \left[ 2x_1^{(0)} \quad 2x_2^{(0)} \right]^T = [2 \ 2]^T$$

According to part 2, if  $\nabla f(x) \neq 0$  then the direction  $d = -\nabla f(x)$  is a downhill direction of  $f$  at  $x$ . In our example  $d_1 = [-2 \ -2]^T$ . Because  $x^{(0)}$  is not a maximum or a minimum of the function  $f(x_1, x_2)$  the opposite from the downhill direction will not be a downhill direction as well. Meaning  $d_2 = [2 \ 2]^T$ .

## Question 4

$C \subseteq \mathbb{R}^m$  is a convex domain and  $A \in \mathbb{R}^{m \times n}$ .

$$B_1 = \{x \in \mathbb{R}^n | x = A^T z, z \in C\}$$
$$B_2 = \{x \in \mathbb{R}^n | Ax \in C\}$$

By definition, domain  $C \in \mathbb{R}^m$  is convex if for all  $x, y \in C$  and  $\lambda \in [0, 1] \rightarrow \lambda x + (1 - \lambda)y \in C$ .

$$\begin{aligned}\lambda &\in [0, 1] \\ x, y &\in B_1 \\ x &= A^T z_x \\ y &= A^T z_y \\ z_x, z_y &\in C \\ q = \lambda x + (1 - \lambda)y &= \lambda A^T z_x + (1 - \lambda)A^T z_y = A^T(\lambda z_x + (1 - \lambda)z_y) = A^T z_q, \quad z_q \in C\end{aligned}$$

$\Rightarrow B_1$  is a convex domain by definition.

$$\begin{aligned}x, y &\in B_2 \\ Ax &\in C \\ Ay &\in C \\ Aq = A(\lambda x + (1 - \lambda)y) &= \lambda(Ax) + (1 - \lambda)(Ay) \in C\end{aligned}$$

$\Rightarrow B_2$  is a convex domain by definition.

## Question 5

**Definition 1** let there be a set  $S \subseteq \mathbb{R}^n$

1. Point  $a \in S$  is called an inner point of  $S$  if there exists  $\varepsilon > 0$  for which  $B(a, \varepsilon) \subseteq S$ .
2. Point  $x \in \mathbb{R}^n$  (not necessarily in  $S$ ) are called condensation point if for all  $\varepsilon > 0$  the open ball  $B(x, \varepsilon)$  contains at least one point  $y \in S, y \neq x$ .

**Definition 2** let there be a set  $S \subseteq \mathbb{R}^n$

1. Set  $S$  is called open if every point in  $S$  is an inner point.
2. Set  $S$  is called closed if its complimentary set,  $S^c$ , is an open set.

We will prove the following claims:

1. Let  $S \subseteq \mathbb{R}^n$  be some set and  $x \in \mathbb{R}^n$  its condensation point. Therefore for all  $\varepsilon > 0$  the open ball  $B(x, \varepsilon)$  contains an infinite amount of points from  $S$ .

Using proof by contradiction assuming for a certain  $\varepsilon > 0$  the open ball  $B(x, \varepsilon)$  contains a finite amount of points from  $S$ . Each one of the points from  $S$  in the ball have a different distance from point  $x$ . We will mark the closest point to  $x$  as  $a$  and the distance as  $\varepsilon_a$  where  $\varepsilon_a \leq \varepsilon$ . The open ball  $B(x, \varepsilon_a/2)$  does not contain any points from  $S$  because the closest point to  $x$  which is  $a$  is outside of it. Therefore  $B(x, \varepsilon_a/2)$  does not contains any points  $y \in S, y \neq x$  meaning we got a contradiction with definition 1.2 of a condensation point.

2. Set  $S$  is closed iff it contains all its condensation points.

Using proof by contradiction **given that set  $S$  is closed we assume it does not contain all of its condensation points**. Meaning there is at least one condensation point  $x \notin S$ .  $x \in S^c$  where  $S^c$  is the complimentary set of  $S$  and, according to definition 2.2, an open set. According to definition 1.2 ,because  $x$  is a condensation point then for all  $\varepsilon > 0$  the open ball  $B(x, \varepsilon)$  contains at least one point  $y \in S, y \neq x$  ( $y \notin S^c$ ). Therefore it is not an inner point of  $S^c$  according to definition 1.1. Looking at definition 2.1 we get a contradiction where not all points in the open set  $S^c$  are inner points.

Using proof by contradiction **given that  $S$  contains all of its condensation points we assume it is not a closed set**. According to definition 2.2 if  $S$  is not closed then  $S^c$  is not open. According to definition 2.1 if  $S^c$  is not open then it has at least one point  $x \in S^c$  that is not an inner point. According to definition 1.1 for all  $\varepsilon > 0$  the open ball  $B(x, \varepsilon) \not\subseteq S^c$  meaning it has at least one point  $y \in B(x, \varepsilon), y \in S$ . If  $y \in S$  then point  $x$  is a condensation point according to definition 1.2 and we got a contradiction because  $x \notin S$ .

3. If  $S$  is a closed set and the series  $i = 1, 2, \dots, x_i \in S$  converges to  $x$  (meaning  $\lim_{i \rightarrow \infty} \|x_i - x\| = 0$ ) then  $x \in S$ .

Using proof by contradiction assuming  $x \notin S$ . Given that  $S$  is closed it contains all its condensation points meaning  $x$  is not a condensation point. According to definition 1.2 there exists a  $\varepsilon > 0$  for which the open ball  $B(x, \varepsilon) \not\subseteq S$ . Meaning  $B(x, \varepsilon)$  does not contain any point of the series  $x_i$  and we get a contradiction from a conclusion from the definition of a limit that says that for all  $\varepsilon > 0$  there exists an  $i_0$  such that for all  $i > i_0$  we get  $x_i \in B(x, \varepsilon)$ .

## Question 6

$C \subseteq \mathbb{R}$  is a convex and closed domain.  $x_0 \notin C$ . Given the optimization problem

$$\min_{y \in C} \|y - x_0\|$$

Assume there is a solution  $y_0 \in C$  for the optimization problem. We will prove that it is singular. Let us assume there are 2 solutions  $y_0, z_0 \in C$  such that

$$\|y_0 - x_0\|^2 = \|z_0 - x_0\|^2 = \left(\min_{y \in C} \|y - x_0\|\right)^2 = \delta^2$$

By definition of a convex domain

$$\begin{aligned} y_0\lambda + z_0(1 - \lambda) &\in C \\ \lambda &= 0.5 \\ \implies m_0 &= (y_0 + z_0)/2 \in C \end{aligned}$$

$$\begin{aligned} \|m_0 - x_0\|^2 &= \|(y_0 + z_0)/2 - x_0\|^2 = \|(y_0 - x_0 + z_0 - x_0)/2\|^2 = \\ &\quad \langle (y_0 - x_0 + z_0 - x_0)/2, (y_0 - x_0 + z_0 - x_0)/2 \rangle = \\ &\quad \frac{1}{4} \langle y_0 - x_0, y_0 - x_0 \rangle + \frac{1}{2} \langle z_0 - x_0, y_0 - x_0 \rangle + \frac{1}{4} \langle z_0 - x_0, z_0 - x_0 \rangle = \\ &\quad \frac{1}{4} \|y_0 - x_0\|^2 + \frac{1}{2} \langle z_0 - x_0, y_0 - x_0 \rangle + \frac{1}{4} \|z_0 - x_0\|^2 = \\ &\quad \frac{1}{4} \delta^2 + \frac{1}{2} \langle z_0 - x_0, y_0 - x_0 \rangle + \frac{1}{4} \delta^2 = \\ &\quad \frac{1}{2} \delta^2 + \frac{1}{2} \langle z_0 - x_0, y_0 - x_0 \rangle \end{aligned}$$

$$\begin{aligned} \|m_0 - x_0\|^2 &\geq \left(\min_{y \in C} \|y - x_0\|\right)^2 = \delta^2 \\ \implies \frac{1}{2} \delta^2 + \frac{1}{2} \langle z_0 - x_0, y_0 - x_0 \rangle &\geq \delta^2 \\ \langle z_0 - x_0, y_0 - x_0 \rangle &\geq \delta^2 \\ -2 \langle z_0 - x_0, y_0 - x_0 \rangle + 2\delta^2 &\leq 0 \\ \|y_0 - x_0\|^2 - 2 \langle z_0 - x_0, y_0 - x_0 \rangle + \|z_0 - x_0\|^2 &\leq 0 \\ \|(y_0 - x_0) - (z_0 - x_0)\|^2 &\leq 0 \\ \|y_0 - z_0\|^2 &\leq 0 \end{aligned}$$

By definition  $\|\cdot\| \geq 0$  meaning

$$\begin{aligned} y_0 - z_0 &= 0 \\ y_0 &= z_0 \end{aligned}$$