

## Homework5-FCOE7205

**Dijkstra's algorithm using unsorted array for priority Q.**

```
#include <iostream>

#include <vector>

#include <list>

#include <queue>

using namespace std;

#define INT_MAX 100000 //initializing the distance to infinity in beginning

typedef pair<int, int> component ;

class Node // Defining graph with vertices and its respective weight
{
    int Vertex;

    list<pair<int, int>>* com; // to store vertices and weight
public:
    //Initializing a default constructor
    Node(int Vertex)
    {
        this->Vertex = Vertex;

        com = new list<component>[Vertex];
    }

    void addNode(int a, int b, int c);

    void shortdis(int dis);
};

// function to add edge oppositely
void Node::addNode(int a, int b, int c)
{
    com[a].push_back(make_pair(b, c));
```

```

    com[b].push_back(make_pair(a, c));
}

void Node::shortdis(int source) // source vertex
{
    // Creating a priority queue
    priority_queue<component, vector<component>, greater<component>> qp;
    vector<int> cost(Vertex, INT_MAX);
    qp.push(make_pair(0, source)); // push operation in queue
    cost[source] = 0;
    while (!qp.empty())
    { //Extracting min queue
        int a = qp.top().second;
        qp.pop();
        // 'i' gives adjacent vertices of each node in vertex
        list<pair<int, int>>::iterator i;
        for (i = com[a].begin(); i != com[a].end(); i++)
            //not going to the adjacent list
        {
            int b = (*i).first;
            int weight = (*i).second;

            // Check the shortest path
            if (cost[b] > cost[a] + weight)
            {
                // Updated distance
                cost[b] = cost[a] + weight;
                qp.push(make_pair(cost[b], b));
            }
        }
    }
}

```

```

    }
}
cout<<"Vertex \tDistance from Source \n";
for (int i = 0; i < Vertex; i++)
    cout<<i<<"\t\t"<<cost[i]<<"\n";
}

int main()
{
    int Vertex ;

    cout<<" Input enter the number of the vertices ";

    cin>>Vertex;

    Node n(Vertex);

    n.addNode(0, 1, 2); // add root node with neighbor vertex and weight
    n.addNode(0, 2, 4);
    n.addNode(1, 2, 1);
    n.addNode(1, 3, 7);
    n.addNode(2, 4, 3);
    n.addNode(3, 5, 1);
    n.addNode(4, 3, 2);
    n.addNode(4, 5, 5);

    n.shortdis(0); // call the function to find shortest path of graph using Dijkstra algorithm

    return 0;
}

```

OUTPUTS :

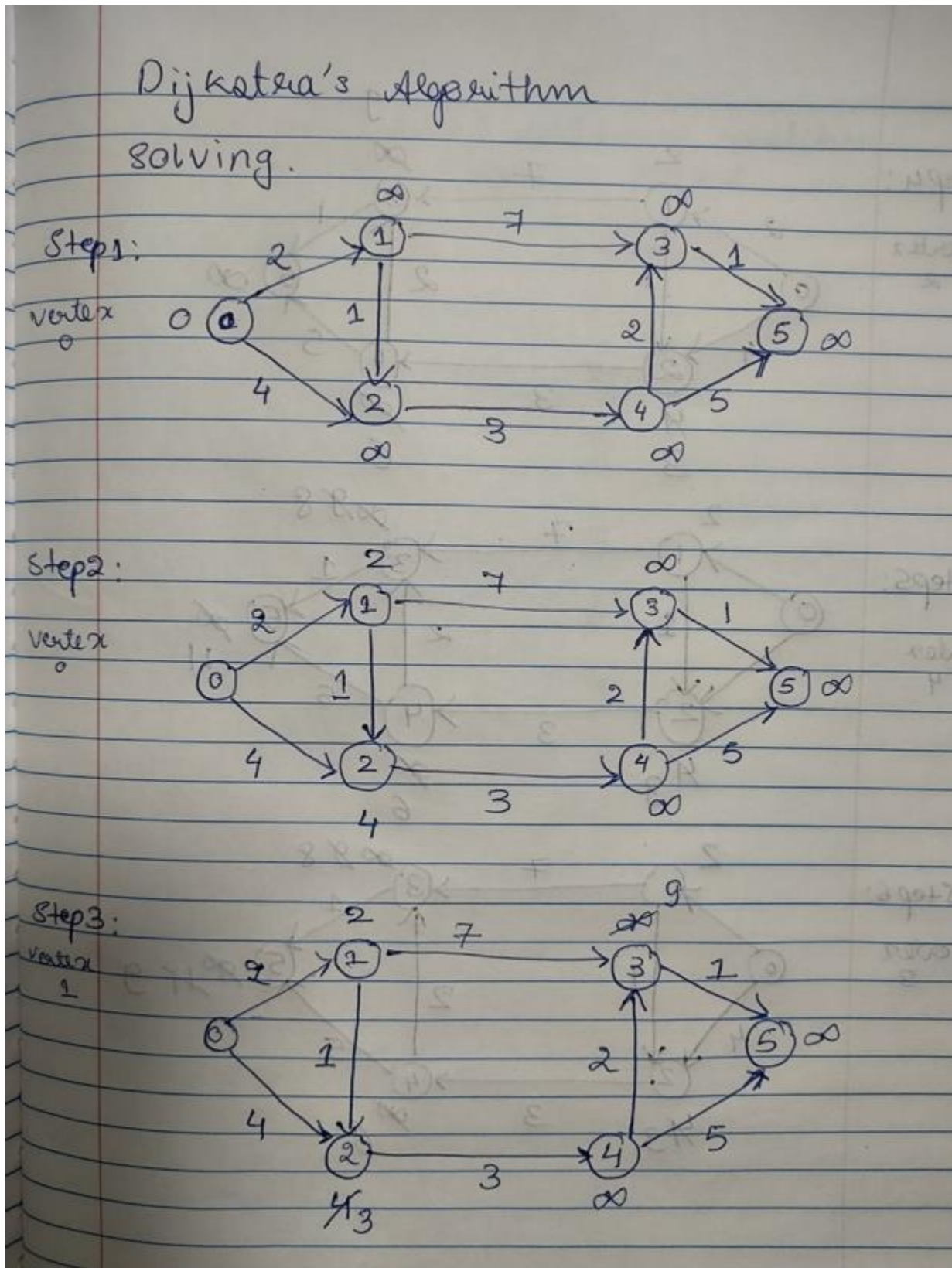
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```

Input enter the number of the vertices 6
Vertex  Distance from Source
0           0
1           2
2           3
3           8
4           6
5           9

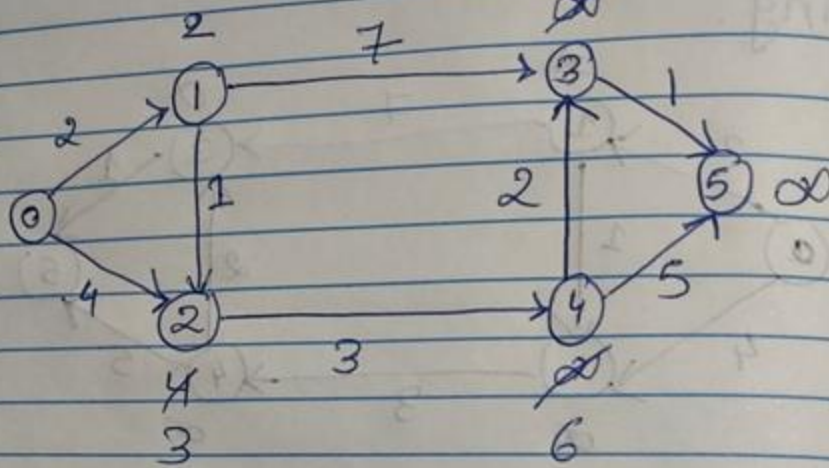
```

Solving Dijkstra's algorithm :



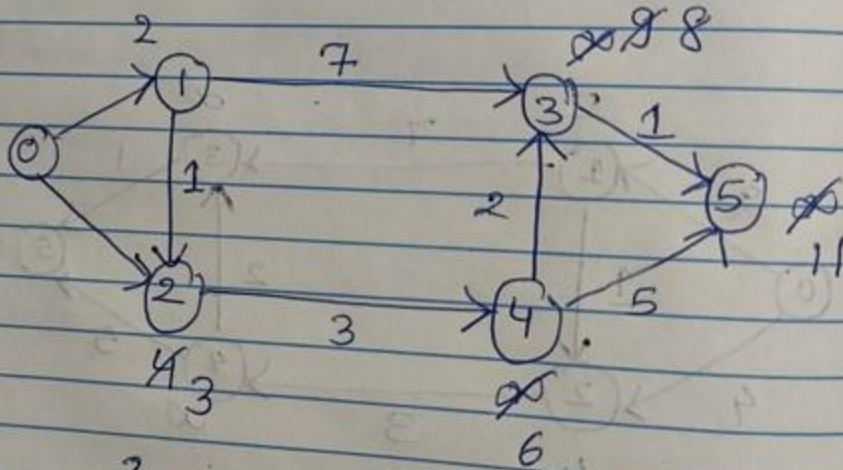
Step 4:

Vertex  
2



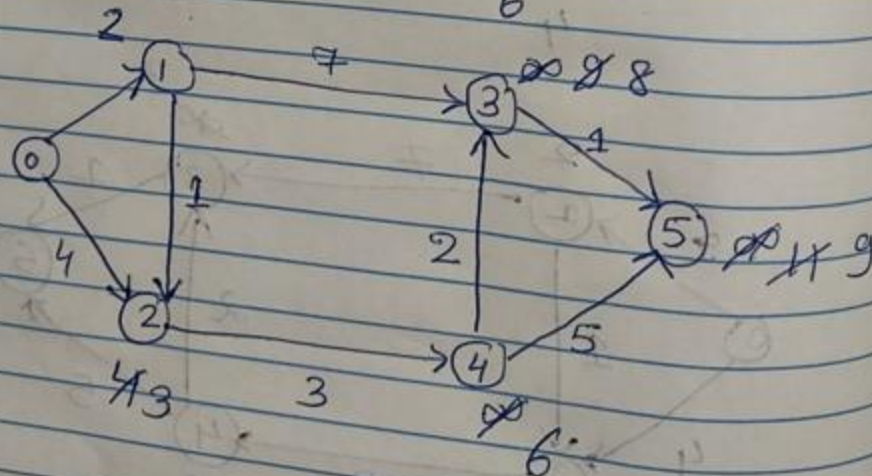
Step 5:

Vertex  
4



Step 6:

Vertex  
3



Hence the final distances matches as per the program output.

Vertex	Distance
0	0
1	2
2	3
3	8
4	6
5	9

### **Bellman ford algorithm**

```
#include <iostream>
#include <limits>
#define Int_max 10000;
using namespace std;
struct node
{
    int source;
    int destination;
    int cost;
```

```

};

struct graph{

    int v,e;

    struct node* n;

};

void BellmanFord(struct graph* g,int V,int E, int source)
{
    // int V= g->V;
    // int E= g->E;

    int distance[V];

    //step 1
    for (int i = 0; i < V; i++)

        distance[i] = INT_MAX;

    distance[source] = 0;

    //step 2
    for (int i = 1; i <= V - 1; i++)
    {
        for (int j = 0; j < E; j++)
        {
            int a = g->n[j].source;

            int b = g->n[j].destination;

            int cost = g->n[j].cost;

            if (distance[a] != INT_MAX && distance[a] + cost < distance[b])

                distance[b] = distance[a] + cost;

        }
    }

    //step3
    for (int i = 0; i < E; i++)

```

```

    {
        int c = g->n[i].source;
        int d = g->n[i].destination;
        int cost = g->n[i].cost;
        if (distance[c] != INT_MAX && distance[c] + cost < distance[d])
        {
            cout<<"Graph contains negative weight cycle";
            return; // If negative cycle is detected, simply return
        }
    }

    //print Graph
    cout<<"Vertex Distance from Source \n";
    for (int i = 0; i < V; ++i)
        printf("%d \t\t %d\n", i, distance[i]);
}

int main()
{
    int v,e;
    cout<<"Enter the Number of vertices ";
    cin>>v;
    cout<<"Enter the number of edges ";
    cin>>e;
    struct graph* g = new graph;
    g->v = v;
    g->e = e;
    g->n = new node[e];
    g->n[0].source=0;
    g->n[0].destination = 1;
    g->n[0].cost = 6;

```



```

        g->n[1].source=0;
        g->n[1].destination = 2;
        g->n[1].cost = 5;
    g->n[2].source=1;
        g->n[2].destination = 3;
        g->n[2].cost = -1;
        g->n[3].source=2;
        g->n[3].destination = 1;
        g->n[3].cost = -2;
        g->n[4].source=2;
        g->n[4].destination = 3;
        g->n[4].cost = 4;
        g->n[5].source=2;
        g->n[5].destination = 4;
        g->n[5].cost = 3;
        g->n[6].source=3;
        g->n[6].destination = 4;
        g->n[6].cost = 3;
    BellmanFord(g,v,e,0);
    return 0;
}

```

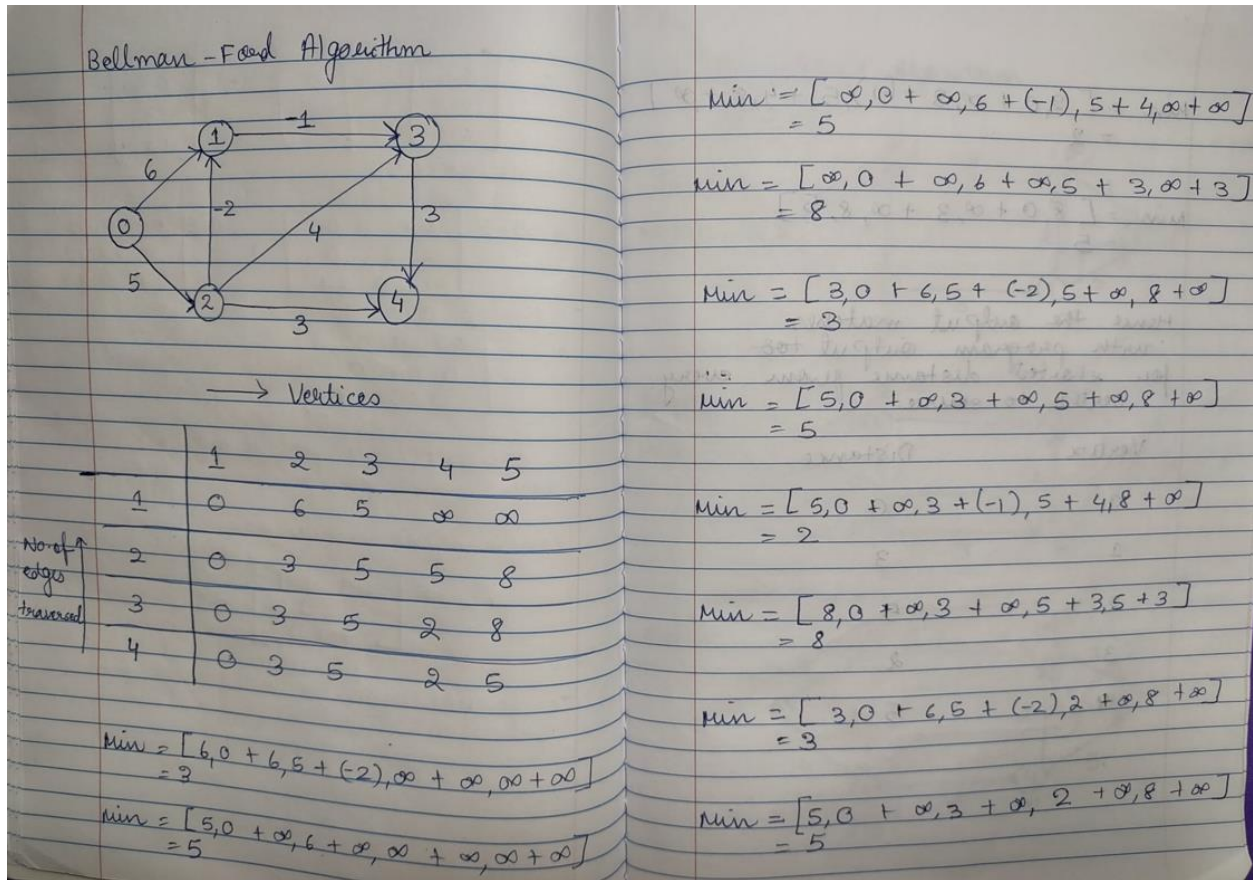
OUTPUT :

```

Enter the  Number of vertices 5
Enter the number of edges 7
Vertex Distance from Source
0           0
1           3
2           5
3           2
4           5

```

# Solving of BellmanFord Algorithm :



$$\min = [2, 0 + \infty, 3 + (-1), 5 + 4, 8 + \infty] \\ = 2$$

$$\min = [8, 0 + \infty, 3 + \infty, 8, 5] \\ = 5$$

Hence the output matches with program output too for shortest distance from every vertex to source.

Vertex	Distance
--------	----------

0	0
---	---

1	3
---	---

2	5
---	---

3	2
---	---

4	5
---	---