

spiri_api.get_state.Staterobot

- + state
- + orientation
- + altimeter_height
- + pressure_height
- + gps
- + gps_vel
- + x
- + y
- + z

- + __init__()
- + callback_state()
- + callback_imu()
- + callback_altimeter()
- + callback_pressure()
- + callback_gps()
- + callback_gps_vel()
- + getstate()
- + get_position()
- + get_orientation()
- and 9 more...