

## Staterobot

- + imu
- + odom
- + pressure
- + gps
- + gps\_vel
- + altimeter
- + img
- + cv\_ptr
- + sub
- + result
- + errorPtr
- + status

- + Staterobot()
- + get\_imu()
- + image\_left\_callback()
- + image\_right\_callback()
- + image\_bottom\_callback()
- + get\_state()
- + get\_height\_pressure()
- + wait\_goal()
- + callback\_goal()
- + get\_gps\_data()
- and 18 more...