

Shaft and Shaft Components

ME 310: Mechanical Design

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Outline

Overview

Shaft Layout

Shaft Design for Stress

Deflection Analysis

Critical Speeds for Shafts

Torque Transmission Components

Why Starting off with Shafts?

- Most engineering machines is powered by a rotational machines
- Rotational machines need shafts
- The source of powers... and mistakes

Design Criteria

- Material selection
- Layout
- Stress and strength
- Deflection and rigidity
- Vibration

Materials

- Stiffness and deflection: E same for all steels, so material choice does not matter.
- Size:
- For small diameter shafts, use cold drawn steel.
- If heat treatment is required, it should be machined after to provide work hardening.
- Production volume:
 - Low → Turning (using lathe or CNC)
 - High → hot rolling, cold rolling, casting

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Shaft Layout

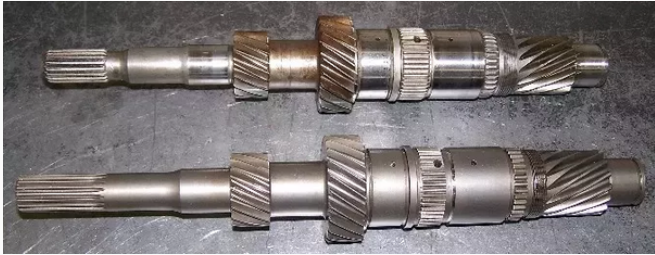
Shaft Design for Stress

Deflection Analysis

Critical Speeds for Shafts

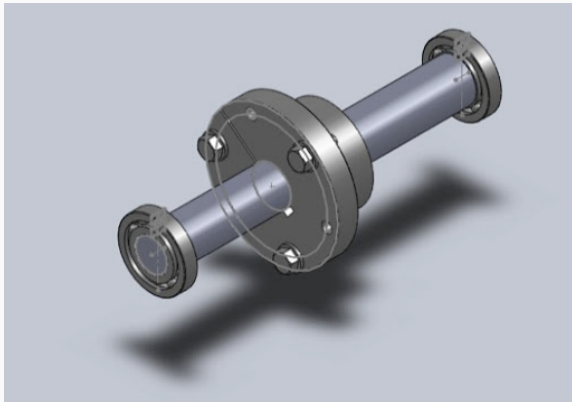
Torque Transmission Components

Layout



- steps to axially locate elements, i.e. gears, pulleys, bearings.
- support axial load using bearings
- provide torque transmission with gears, pulleys, sprockets...

Axial Location of Elements



- 2 bearings per shaft in most cases
- Shortest shaft possible to reduce bending
- Load bearing components should be close to bearings
- Use shoulders or retainer rings to fix axial locations

Axial Load Support



- If significant axial loads are present, support with appropriate bearings.

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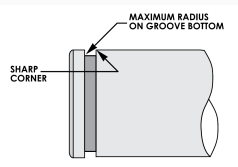
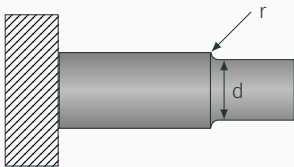
Critical Speeds for Shafts

Torque Transmission Components

Critical Locations

- Maximum bending moment
- Steps, grooves, and notches

Stress Concentrations in Shafts



	Bending	Torsion	Axial
Shoulder fillet—sharp ($r/d = 0.02$)	2.7	2.2	3.0
Shoulder fillet—well rounded ($r/d = 0.1$)	1.7	1.5	1.9
End-mill keyseat ($r/d = 0.02$)	2.14	3.0	—
Sled runner keyseat	1.7	—	—
Retaining ring groove	5.0	3.0	5.0

Shaft Stresses

- Torsion + Bending
- Axial load usually small and negligible

$$\begin{aligned}\sigma_a &= K_f \frac{M_a C}{I} & \sigma_m &= K_f \frac{M_m C}{I} \\ \tau_a &= K_{fs} \frac{T_a C}{J} & \tau_m &= K_{fs} \frac{T_m C}{J}\end{aligned}$$

Solid round shafts

$$\sigma_a = K_f \frac{32M_a}{\pi d^3}$$

$$\sigma_m = K_f \frac{32M_m}{\pi d^3}$$

$$\tau_a = K_{fs} \frac{16T_a}{\pi d^3}$$

$$\tau_m = K_{fs} \frac{16T_m}{\pi d^3}$$

Combine Normal and Shear Stresses

Use MDET

$$\sigma_e = (\sigma^2 + 3\tau^2)^{1/2}$$

$$\sigma_{ae} = (\sigma_a^2 + 3\tau_a^2)^{1/2} = \left[\left(\frac{32K_f M_a}{\pi d^3} \right)^2 + 3 \left(\frac{16K_{fs} T_a}{\pi d^3} \right)^2 \right]^{1/2}$$

$$\sigma_{me} = (\sigma_m^2 + 3\tau_m^2)^{1/2} = \left[\left(\frac{32K_f M_m}{\pi d^3} \right)^2 + 3 \left(\frac{16K_{fs} T_m}{\pi d^3} \right)^2 \right]^{1/2}$$

Apply Fatigue Limit

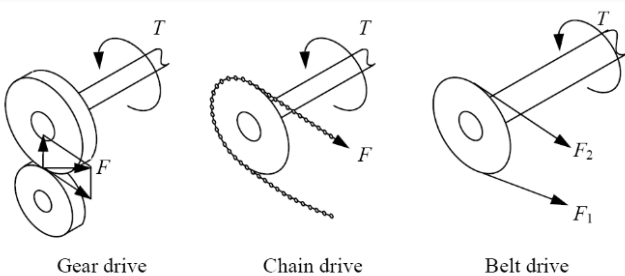
$$\frac{1}{N_s} = \frac{\sigma_{ae}}{S_e} + \frac{\sigma_{me}}{S_y}$$

$$\frac{1}{N_s} = \frac{16}{\pi d^3} \left\{ \frac{1}{S_e} \left[4 (K_f M_a)^2 + 3 (K_{fs} T_a)^2 \right]^{1/2} + \frac{1}{S_y} \left[4 (K_f M_m)^2 + 3 (K_{fs} T_m)^2 \right]^{1/2} \right\}$$

$$d = \left(\frac{16 N_s}{\pi} \left\{ \frac{1}{S_e} \left[4 (K_f M_a)^2 + 3 (K_{fs} T_a)^2 \right]^{1/2} + \frac{1}{S_y} \left[4 (K_f M_m)^2 + 3 (K_{fs} T_m)^2 \right]^{1/2} \right\} \right)^{1/3}$$

Shaft Loading Conditions

- Torque
- Bending \implies radial load from torque transmission



$$F = \frac{T}{r \cos \theta}$$

$$F = \frac{T}{r}$$

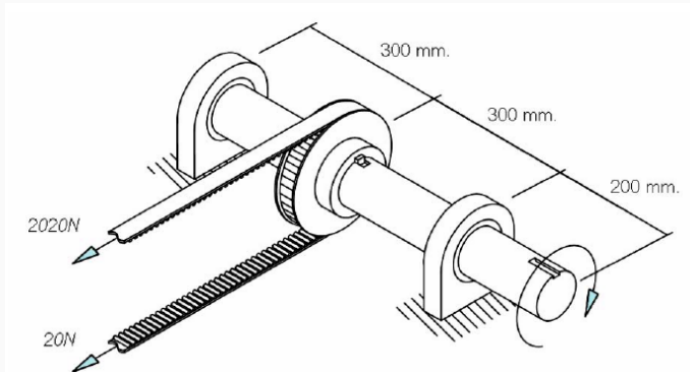
$$F_2 - F_1 = \frac{T}{r}$$

Example: Timing Belt Shaft

Size the shaft (AISI 1040, $S_y = 400$ MPa, $S_{ut} = 600$ MPa) using

1. MDET (Static Loading)
2. Soderberg theory (Dynamic Loading)

Take $r_{\text{pulley}} = 10$ cm and $N_s = 3$



- The applied torque T is $(2020 - 20)(0.1) = 200$ N-m.
- Midpoint load of $2020 + 20 = 2040$ N
- Assuming end-mill keyseat at the sheave: $K_f = 2.14$, $K_{fs} = 3$

Calculating Stresses

$$M = \frac{FL}{4} = \frac{2040(0.6)}{4} = 306$$

$$\sigma_{bending} = K_f \frac{My}{I} = 2.14 \frac{306(d/2)}{(\pi/4)(d/2)^4} = \frac{6670}{d^3}$$

$$\tau_T = K_{fs} \frac{Tr}{J} = 3 \frac{200(d/2)}{(\pi/2)(d/2)^4} = \frac{3056}{d^3}$$

Applying MDET

Using MDET, we have that

$$\sigma_e = \sqrt{\left(\frac{6670}{d^3}\right)^2 + 3\left(\frac{3056}{d^3}\right)^2} = \frac{8514}{d^3}$$

$$N_s = 3 = \frac{S_y}{\sigma_e} = \frac{400 \times 10^6}{\sigma_e}$$

$$d^3 = \frac{8514}{400 \times 10^6} = 2.13 \times 10^{-5}$$

$$d = 0.0277$$

Applying Soderberg

- Bending \rightarrow repeated stress (tensile and compressive)
- $\sigma_a = \sigma_{bending}, \sigma_m = 0$
- Torsion \rightarrow constant stress
- $\tau_a = 0, \tau_m = \tau_T$

$$\sigma_{ae} = \sqrt{\sigma_a^2 + 3\tau_a^2} = \sigma_{bending}$$

$$\sigma_{me} = \sqrt{\sigma_m^2 + 3\tau_m^2} = \sqrt{3}\tau_T$$

Applying Soderberg II

$$\frac{1}{N_s} = \frac{1}{3} = \frac{\sigma_{ae}}{S_e} + \frac{\sigma_{me}}{S_y} = \frac{6670}{d^3(0.5)(600 \times 10^6)} + \frac{\sqrt{3}(3056)}{d^3(400 \times 10^6)}$$

$$d^3 = 1.06 \times 10^{-4}$$

$$d = 0.0474$$

General Guidelines

1. shaft should be as short as possible
2. avoid sharp step
3. round shaft if possible
4. to save weight → hollow shaft

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Deflection Considerations

- Need geometry for entire shaft
- Should evaluate at gears and bearings – why?
- Maximum deflection < gear teeth size
- In most case, software is needed

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Shaft Whirling or Shaft Whip

- At high speed, the centrifugal force can cause shaft deflection \sim buckling
- For simple shafts:

$$\omega_1 = \left(\frac{\pi}{l}\right)^2 \sqrt{\frac{EI}{m}} = \left(\frac{\pi}{l}\right)^2 \sqrt{\frac{EI}{A\rho}}$$

m mass per unit length

ρ density

E Young's modulus

A cross-sectional area

Example: Resize the Shaft

From previous example, use $E = 210$ GPa and reconsider the proper shaft size if $\omega_{\max} = 10000$ rpm

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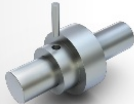
Critical Speeds for Shafts

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Mechanical Retaining Methods

There are three common mechanical methods used to join cylindrical components such as gears, bearings, shafts and hubs:

Types of Fits



**Mechanical-Drive
Assembly**

Design World | Webinar Series



**Interference Fit
Assembly**

Henkel



**Tack In Place
Assembly**

LOCTITE

- Mechanical drive assembly
- Interference fit assembly
- Welded assembly

Mechanical Drive Assemblies



Set Screw



Pin



Keyway



Spline Shaft

The most common mechanical-drive assembly is the conventional key/keyway.

Other mechanical-drive assemblies are set screws, pins and spline shafts.

All transmit torque levels related to their mechanical interlocking:

Set screw << pin << keyway << spline shaft

All are easy to assemble or disassemble.

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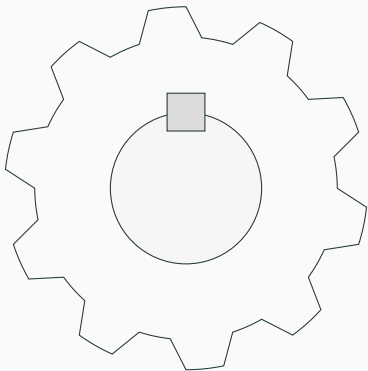
% % - Set screw % - Pin % - Key % - Spline shaft %

** Setscrews}

- Use friction to hold a component on the shaft → *holding power*

Example: Key sizing

A steel shaft whose $S_y = 450$ MPa has a radius of 5 cm. The shaft rotates at 600 rpm and transmits 40 hp through a gear. Select an appropriate key for the gear. Use safety factor = 3.



Solution: Key sizing

To keep things simple, pick a square key and pick key length = 2 cm.

$$\begin{aligned} T &= \frac{\text{Power}}{\omega} = \frac{40(746)}{600(2\pi/60)} \\ &= 475 \text{ N-m} \end{aligned}$$

For the width (and height) of the key section,

$$\begin{aligned} N_s T_{\max} &= 0.577 S_y b l r_{\text{shaft}} \\ b &= \frac{3(475)}{0.577(450 \times 10^6)(0.02)(0.05)} \\ b &= 0.00549 \text{ m} \end{aligned}$$

** Retaining Rings}

- Used to axially locate a component on a shaft or a hub.
- Need to cut grooves in shaft to fit → stress concentration

Limitation of Mechanical Drive

- Stress concentration
- Backlash
- Machining costs
- Uneven distribution of mass

Interference Fit Assemblies

- Press fit: $d_{\text{shaft}} > d_{\text{hub}}$
- Tapered fit: Taper + Fastener = Fit
- Shrink fit: Hole is heated or shaft is cooled before assembly
- Used to minimize need for shoulders and keyways

Limitations of Interference Fits

- Material, surface, and design restrictions – need sufficient friction
- Close tolerance → high machining costs
- Micro-movement causes fretting corrosion
- Surface galling → difficult disassembly
- High stress in components

Stress in Interference Fits

- Assumed uniform pressure on shaft and hub

$$p = \frac{d_{\text{shaft}} - d_{\text{hub}}}{\frac{d}{E_o} \left(\frac{d_o^2 + d^2}{d_o^2 - d^2} + \nu_o \right) + \frac{d}{E_i} \left(\frac{d^2 + d_i^2}{d^2 - d_i^2} - \nu_i \right)}$$

- When both are of the same material

$$p = \frac{E(d_{\text{shaft}} - d_{\text{hub}})}{2d^3} \left[\frac{(d_o^2 - d^2)(d^2 - d_i^2)}{d_o^2 - d_i^2} \right]$$

d nominal shaft diameter

d_i inside diameter of shaft

d_o outside diameter of hub

Stress in Interference Fits

- Tangential and radial stresses in shaft and hub are

$$\sigma_{t,\text{shaft}} = -p \frac{d^2 + d_i^2}{d^2 - d_i^2}$$

$$\sigma_{t,\text{hub}} = p \frac{d_o^2 + d^2}{d_o^2 - d^2}$$

$$\sigma_{r,\text{shaft}} = -p$$

$$\sigma_{r,\text{hub}} = -p$$

- Combine σ_t and σ_r using MDET to determine failure

Torque Capacity in Interference Fits

- Depends on friction generated between shaft and hub → pressure from interference fits

$$f = \mu N = \mu(pA)$$

$$= \pi \mu p l d$$

$$T = f d / 2 = \pi \mu p l d (d / 2)$$

$$= \frac{\pi}{2} \mu p l d^2$$

Example: Torque Capacity of a Gear on a Shaft

A solid shaft whose diameter is 5 cm is pressed onto a gear whose hub inner diameter is 4.99 cm and outer diameter is 6 cm. If both are made of the same steel whose $E = 210$ GPa and $\nu = 0.3$, determine the radial and tangential stresses, along with the torque capacity of the fit. Assume steel-on-steel $\mu = 0.3$, and the hub is 7 cm long.

Solution: Torque Capacity of a Gear on a Shaft

$$\begin{aligned} p &= \frac{E(d_{\text{shaft}} - d_{\text{hub}})}{2d^3} \left[\frac{(d_o^2 - d^2)(d^2 - d_i^2)}{d_o^2 - d_i^2} \right] \\ &= \frac{210 \times 10^9 (0.05 - 0.0499)}{2(0.05)^3} \left[\frac{(0.06^2 - 0.05^2)(0.05^2 - 0)}{0.06^2 - 0} \right] \\ &= 64.2 \text{ MPa} \end{aligned}$$

$$\sigma_{r,\text{shaft}} = \sigma_{r,\text{hub}} = -64.2 \text{ MPa}$$

$$\sigma_{t,\text{shaft}} = -64.2 \frac{0.05^2}{0.05^2} = -64.2 \text{ MPa}$$

$$\sigma_{t,\text{hub}} = 64.2 \frac{0.06^2 + 0.05^2}{0.06^2 - 0.05^2} = 356 \text{ MPa}$$

$$T = \frac{\pi}{2} \mu p l d^2 = \frac{\pi}{2} (0.3) 64.2 \times 10^6 (0.07)(0.05^2) = 5294 \text{ N-m}$$

Welded Assembly



- Connections by welding the part
- Load carried by small welded area

Limitations of welded assembly

- Only compatible materials
- Heating can cause warpage
- Difficult disassembly
- Additional costs
- Need skilled personnel
- Additional cleaning and grinding afterwards