

Divergence of a Vector Field

If $\vec{V}(x, y, z) = V_1(x, y, z)\hat{i} + V_2(x, y, z)\hat{j} + V_3(x, y, z)\hat{k}$ is a vector function and $\vec{\nabla} = \frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k}$ is the vector differential operator, then the divergence of \vec{V} which is denoted as $\operatorname{div} \vec{V}$ and is defined as

$$\operatorname{div} \vec{V} = \vec{\nabla} \cdot \vec{V} = \left(\frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k} \right) \cdot (V_1\hat{i} + V_2\hat{j} + V_3\hat{k})$$

i.e.
$$\operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z}$$
 [$\because \text{dot product } \vec{a} \cdot \vec{b} = a_1a_2 + b_1b_2 + c_1c_2$]

Note: As divergence of \vec{V} is a dot product of $\vec{\nabla}$ & \vec{V} , it is no doubt a scalar function/output.

Examples

Sol'n Ex-1 Find $\operatorname{div} \vec{V}$, where $\vec{V} = 3xz\hat{i} + 2xy\hat{j} - yz^2\hat{k}$

$$\operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z}, \text{ here } V_1 = 3xz, V_2 = 2xy, V_3 = -yz^2$$

$$\text{Now } \frac{\partial V_1}{\partial x} = \frac{\partial}{\partial x}(3xz) = 3z$$

$$\frac{\partial V_2}{\partial y} = \frac{\partial}{\partial y}(2xy) = 2x$$

$$\frac{\partial V_3}{\partial z} = \frac{\partial}{\partial z}(-yz^2) = -2yz$$

$$\therefore \operatorname{div} \vec{V} = 3z + 2x - 2yz \quad \underline{\text{Ans}} \quad (\text{scalar function})$$

Q Find divergence of the following vector functions.

- (a) $x^2\hat{i} + y^2\hat{j} + z^2\hat{k}$
- (b) $e^x(\cos y\hat{i} + \sin y\hat{j})$
- (c) $xyz(x\hat{i} + y\hat{j} + z\hat{k})$

Sol'n (a) Here $\vec{V} = x^2\hat{i} + y^2\hat{j} + z^2\hat{k}$, i.e. $V_1 = x^2, V_2 = y^2, V_3 = z^2$

$$\text{Now } \frac{\partial V_1}{\partial x} = 2x, \frac{\partial V_2}{\partial y} = 2y, \frac{\partial V_3}{\partial z} = 2z$$

$$\therefore \operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} = 2x + 2y + 2z = 2(x+y+z) \quad \underline{\text{Ans.}}$$

$$(b) \vec{V} = e^x (\cos y \hat{i} + \sin y \hat{j}) \text{ i.e. } v_1 = e^x \cos y, v_2 = e^x \sin y, v_3 = 0$$

$$\frac{\partial v_1}{\partial x} = \frac{\partial}{\partial x} (e^x \cos y) = e^x \cos y$$

$$\frac{\partial v_2}{\partial y} = \frac{\partial}{\partial y} (e^x \sin y) = e^x \cos y, \frac{\partial v_3}{\partial z} = 0$$

$$\therefore \operatorname{div} \vec{V} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} = e^x \cos y + e^x \cos y + 0 = 2e^x \cos y \text{ Ans}$$

$$(c) \vec{V} = xyz(x\hat{i} + y\hat{j} + z\hat{k}), \text{ i.e. } v_1 = x^2yz, v_2 = xy^2z, v_3 = xyz^2$$

$$\text{Now } \frac{\partial v_1}{\partial x} = \frac{\partial}{\partial x} (x^2yz) = 2xyz$$

$$\frac{\partial v_2}{\partial y} = \frac{\partial}{\partial y} (xy^2z) = 2xyz$$

$$\frac{\partial v_3}{\partial z} = \frac{\partial}{\partial z} (xyz^2) = 2xyz$$

$$\therefore \operatorname{div} \vec{V} = \frac{\partial v_1}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial v_3}{\partial z} = 2xyz + 2xyz + 2xyz = 6xyz \text{ Ans.}$$

Application (Physical) in Fluid Dynamics

The divergence of the velocity function in the motion of fluids are often used to express the governing equation i.e. equation of continuity. The eqn of continuity represents the conservation of mass i.e. In flow = out flow.

It is represented as:

$$\boxed{\frac{\partial \rho}{\partial t} + \operatorname{div}(\rho \vec{V}) = 0} \quad (A) \quad \text{Inflow} \rightarrow \vec{V} \rightarrow \vec{V} \rightarrow \text{outflow}$$

Hence ρ = density (mass per unit volume)

If the flow is steady i.e. time independent $\Rightarrow \frac{\partial \rho}{\partial t} = 0$

Thus eqn of continuity reduces to

$$\operatorname{div}(\rho \vec{V}) = 0 \quad (B)$$

If the fluid is incompressible, then $\rho = \text{const.}$

Thus eqn-B reduces to

$$\rho \operatorname{div}(\vec{V}) = 0 \quad (C)$$

$$\Rightarrow \boxed{\operatorname{div}(\vec{V}) = 0} \quad (\because \rho \neq 0)$$

Now eqn-C represents the eqn of continuity in the motion of incompressible fluids.

Note If $\operatorname{div} \vec{V} = 0$ i.e. divergence of velocity fn. is 0, then the fluid is incompressible otherwise compressible.

Examples

Q. Determine whether the fluid is incompressible or not if its velocity function is given as:

$$(a) \vec{V} = xi\hat{i} + yj\hat{j} - zk\hat{k} \quad (b) V = -\frac{y}{x} i\hat{i} + 4xj\hat{j} \quad (c) V = 2y^2 i\hat{i}, \quad (d) V = y\hat{i} - x\hat{j}$$

Soln (a) $\vec{V} = xi\hat{i} + yj\hat{j} - zk\hat{k}$

$$\begin{aligned} \text{Now } \operatorname{div} \vec{V} &= \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} \\ &= \frac{\partial}{\partial x}(x) + \frac{\partial}{\partial y}(y) - \frac{\partial}{\partial z}(z) \\ &= 1+1-1 = 1 \neq 0 \end{aligned}$$

\therefore The fluid is compressible.

$$(b) V = -\frac{y}{x} i\hat{i} + 4xj\hat{j}$$

$$\operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} = \frac{\partial}{\partial x}\left(-\frac{y}{x}\right) + \frac{\partial}{\partial y}(4x) + \frac{\partial}{\partial z}(0)$$

\therefore Fluid is incompressible.

$$(c) \vec{V} = 2y^2 i\hat{i}$$

$$\operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} = \frac{\partial}{\partial x}(2y^2) + 0 + 0 = 0$$

\therefore Fluid is incompressible.

$$(d) \vec{V} = y\hat{i} - x\hat{j}$$

$$\therefore \operatorname{div} \vec{V} = \frac{\partial V_1}{\partial x} + \frac{\partial V_2}{\partial y} + \frac{\partial V_3}{\partial z} = \frac{\partial}{\partial x}(y) - \frac{\partial}{\partial y}(x) = 0 - 0 = 0$$

\therefore Fluid is incompressible.

Note As gradient of a scalar function $f = f(x, y, z)$ is a vector function \Rightarrow The divergence of $(\operatorname{grad} f)$ exists and it is a scalar fn.

$$\text{Now } \operatorname{div}(\operatorname{grad} f) = \vec{f} \cdot (\vec{\nabla} f) = \left(\frac{\partial f}{\partial x} i\hat{i} + \frac{\partial f}{\partial y} j\hat{j} + \frac{\partial f}{\partial z} k\hat{k} \right) \cdot \left(\frac{\partial f}{\partial x} i\hat{i} + \frac{\partial f}{\partial y} j\hat{j} + \frac{\partial f}{\partial z} k\hat{k} \right)$$

$$\therefore \operatorname{div}(\operatorname{grad} f) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = \vec{\nabla}^2 f$$

where $\boxed{\vec{\nabla}^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}}$ (Laplacian operator)
The second order partial differential operator.

Some useful Formulas

$$1. \operatorname{div}(k \vec{V}) = k \operatorname{div} \vec{V}$$

$$2. \operatorname{div}(f \vec{V}) = f \operatorname{div} \vec{V} + \vec{V} \cdot \nabla f$$

$$3. \operatorname{div}(f \nabla g) = f \nabla^2 g + \nabla f \cdot \nabla g$$

(Prove it) Assignment

Q Find the Laplacian of the following functions.

(a) $f = 4x^2 + 9y^2 + z^2$ (b) $f = e^{2x} \sin 2y$ (c) $f = \frac{xy}{z}$.

Sol' (a) Laplacian of $f = \nabla^2 f = \cancel{\frac{\partial^2 f}{\partial x^2}} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$

$$f = 4x^2 + 9y^2 + z^2$$

$$\therefore \frac{\partial^2 f}{\partial x^2} = 8, \frac{\partial^2 f}{\partial y^2} = 18, \frac{\partial^2 f}{\partial z^2} = 2$$

$$\therefore \nabla^2 f = 8 + 18 + 2 = 28$$

(b) $f = e^{2x} \sin 2y$

$$\frac{\partial f}{\partial x} = 2e^{2x} \sin 2y \quad \frac{\partial f}{\partial y} = 2e^{2x} \cos 2y \quad \frac{\partial f}{\partial z} = 0$$

$$\frac{\partial^2 f}{\partial x^2} = 4e^{2x} \sin 2y \quad \frac{\partial^2 f}{\partial y^2} = -4e^{2x} \sin 2y$$

$$\therefore \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 4e^{2x} \sin 2y - 4e^{2x} \sin 2y + 0 = 0$$

(c) $f = \frac{xy}{z}$

$$\frac{\partial f}{\partial x} = \frac{y}{z}, \quad \frac{\partial f}{\partial y} = \frac{x}{z}, \quad \frac{\partial f}{\partial z} = -\frac{xy}{z^2}$$

$$\frac{\partial^2 f}{\partial x^2} = 0, \quad \frac{\partial^2 f}{\partial z^2} = 0, \quad \frac{\partial^2 f}{\partial y^2} = -\frac{2xy}{z^3}$$

$$\therefore \nabla^2 f = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} = 0 + 0 + \frac{2xy}{z^3} = \frac{2xy}{z^3}$$

Assignments

Q Find the divergence of the following vector functions.

(a) $\vec{V} = xi + yj + zk$ (b) $\frac{-y}{x^2+y^2} i + \frac{x}{x^2+y^2} j$

(c) $\vec{V} = \frac{x}{\sqrt{x^2+y^2+z^2}} i + \frac{y}{\sqrt{x^2+y^2+z^2}} j + \frac{z}{\sqrt{x^2+y^2+z^2}} k$ (d) $\vec{V} = e^x i + ye^x j + 2ze^{xy} k$

Q Find the Laplacian ($\nabla^2 f$) for the following fns.

(a) $f = \frac{x-y}{x+y}$ (b) $f = \cos^2 x - \sin y$ (c) $f = z - \sqrt{x^2+y^2}$ (d) $f = \tan^{-1}(\frac{y}{x})$

Q-Determine whether the fluids are incompressible or not whose velocity functions are:

(a) $V = x^3 k$ (b) $\vec{V} = \sec x i + \operatorname{cosec} x j + \sin y i + \cos z k$

Curl of Vector Functions

The curl of a vector function $\vec{V} = v_1(x,y,z)\hat{i} + v_2(x,y,z)\hat{j} + v_3(x,y,z)\hat{k}$ is a vector fn and is defined & denoted as

$$\text{Curl } \vec{V} = \vec{\nabla} \times \vec{V} = \left(\frac{\partial}{\partial x}\hat{i} + \frac{\partial}{\partial y}\hat{j} + \frac{\partial}{\partial z}\hat{k} \right) \times (v_1\hat{i} + v_2\hat{j} + v_3\hat{k})$$

$$\therefore \text{Curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ v_1 & v_2 & v_3 \end{vmatrix} = \left(\frac{\partial v_3}{\partial y} - \frac{\partial v_2}{\partial z} \right) \hat{i} + \left(\frac{\partial v_1}{\partial z} - \frac{\partial v_3}{\partial x} \right) \hat{j} + \left(\frac{\partial v_2}{\partial x} - \frac{\partial v_1}{\partial y} \right) \hat{k}$$

Examples : Find curl for the following vector functions.

$$(a) V = yz\hat{i} + 3zx\hat{j} + z\hat{k}$$

$$(b) 2y\hat{i} + 5x\hat{j}$$

$$(c) xyz(x\hat{i} + y\hat{j} + z\hat{k})$$

$$(d) \frac{1}{2}(x^2 + y^2 + z^2)(\hat{i} + \hat{j} + \hat{k})$$

$$\text{Soln (a)} \quad \vec{V} = yz\hat{i} + 3zx\hat{j} + z\hat{k}$$

$$\Rightarrow v_1 = yz, v_2 = 3zx, v_3 = z$$

$$\therefore \text{Curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ yz & 3zx & z \end{vmatrix} = \left(\frac{\partial z}{\partial y} - \frac{\partial z}{\partial z} (3zx) \right) \hat{i} + \left\{ \frac{\partial}{\partial z} (yz) - \frac{\partial}{\partial x} (z) \right\} \hat{j} + \left\{ \frac{\partial}{\partial x} (3zx) - \frac{\partial}{\partial y} (yz) \right\} \hat{k}$$

$$\therefore \text{Curl } \vec{V} = -3x\hat{i} + y\hat{j} + 2z\hat{k} = (0-3x)\hat{i} + (y-0)\hat{j} + (3z-z)\hat{k}$$

$$(b) V = 2y\hat{i} + 5x\hat{j}$$

$$\text{Curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y & 5x & 0 \end{vmatrix} = \left\{ \frac{\partial}{\partial y} (0) - \frac{\partial}{\partial z} (5x) \right\} \hat{i} + \left\{ \frac{\partial}{\partial z} (2y) - \frac{\partial}{\partial x} (0) \right\} \hat{j} + \left\{ \frac{\partial}{\partial x} (5x) - \frac{\partial}{\partial y} (2y) \right\} \hat{k}$$

$$\therefore \text{Curl } \vec{V} = 0\hat{i} + 0\hat{j} + (5-2)\hat{k} = [0, 0, 3]$$

$$(c) \vec{V} = xyz(x\hat{i} + y\hat{j} + z\hat{k}) = x^2yz\hat{i} + xy^2z\hat{j} + xy^2z\hat{k}$$

$$\text{Curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ xyz & xyz & xyz \end{vmatrix} = \left\{ \frac{\partial}{\partial y} (xyz) - \frac{\partial}{\partial z} (xyz) \right\} \hat{i} + \left\{ \frac{\partial}{\partial z} (x^2yz) - \frac{\partial}{\partial x} (xyz) \right\} \hat{j} + \left\{ \frac{\partial}{\partial x} (xy^2z) - \frac{\partial}{\partial y} (xyz) \right\} \hat{k}$$

$$= (xz^2 - xy^2)\hat{i} + (x^2y - yz^2)\hat{j} + (yz^2 - x^2z)\hat{k} \quad \underline{\text{Ans.}}$$

Application (Physical)

In case of a rotation of a rigid body, if the curl of the velocity field = 0, the motion of the body is irrotational or else rotational.

Ex Determine whether the motion of a rigid body is rotational or irrotational whose velocity function once.

$$(a) \vec{V} = 2y^2 \hat{i} \quad (b) \vec{V} = x^3 \hat{k} \quad (c) V = y \hat{i} - x \hat{j}$$

Soln (a) $\vec{V} = 2y^2$

$$\text{curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 2y^2 & 0 & 0 \end{vmatrix} = \left(\frac{\partial}{\partial y}(0) - \frac{\partial}{\partial z}(0) \right) \hat{i} + \left(\frac{\partial}{\partial z}(2y^2) - \frac{\partial}{\partial x}(0) \right) \hat{j} + \left(\frac{\partial}{\partial x}(0) - \frac{\partial}{\partial y}(2y^2) \right) \hat{k}$$

$$(b) \vec{V} = x^3 \hat{k}, \text{ curl } \vec{V} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ 0 & 0 & x^3 \end{vmatrix} = \left(\frac{\partial}{\partial y}(x^3) - \frac{\partial}{\partial z}(0) \right) \hat{i} + \left(\frac{\partial}{\partial z}(0) - \frac{\partial}{\partial y}(x^3) \right) \hat{j} + \left(\frac{\partial}{\partial x}(0) - \frac{\partial}{\partial z}(0) \right) \hat{k} = -3x^2 \hat{j}$$

Note-1 $\text{curl}(\text{grad } f) = 0$ \Rightarrow rotational.

$$\text{pf curl } (\text{grad } f) = \vec{V} \times \left(\frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k} \right) = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} & \frac{\partial f}{\partial z} \end{vmatrix} = \left(\frac{\partial^2 f}{\partial y \partial z} - \frac{\partial^2 f}{\partial z \partial y} \right) \hat{i} + \left(\frac{\partial^2 f}{\partial z \partial x} - \frac{\partial^2 f}{\partial x \partial z} \right) \hat{j} + \left(\frac{\partial^2 f}{\partial x \partial y} - \frac{\partial^2 f}{\partial y \partial x} \right) \hat{k} = 0$$

Note-2 $\text{div } (\text{curl } \vec{V}) = 0$ Similar proof

Assignments

Q Find curl of the following functions.

$$(a) \vec{V} = \frac{x}{\sqrt{x^2+y^2+z^2}} \hat{i} + \frac{y}{\sqrt{x^2+y^2+z^2}} \hat{j} + \frac{z}{\sqrt{x^2+y^2+z^2}} \hat{k}$$

$$(b) xyz(x^2+y^2+z^2) \cdot (c) \frac{1}{2}(x^2+y^2+z^2)(\hat{i}+\hat{j}+\hat{k})$$

Q Determine whether the motion of the rigid body is rotational or not. whose velocity function once.
 $\vec{V} = \sec x \hat{i} + \operatorname{cosec} y \hat{j} + \operatorname{cosec} z \hat{k}$ (b) $x \hat{i} + y \hat{j} + z \hat{k}$ (c) $y \hat{i} - z \hat{j} + x \hat{k}$

Q Prove the followings.

$$(a) \text{curl } (\vec{u} + \vec{v}) = \text{curl } \vec{u} + \text{curl } \vec{v}$$

$$(b) \text{curl } (\text{grad } f) = 0 \quad (c) \text{div } (\text{curl } \vec{V}) = 0$$

$$(d) \text{div } (\vec{u} \times \vec{v}) = \vec{v} \cdot \text{curl } \vec{u} - \vec{u} \cdot \text{curl } \vec{v}$$

(Hints: Take $u = u_1 \hat{i} + u_2 \hat{j} + u_3 \hat{k}$, $v = v_1 \hat{i} + v_2 \hat{j} + v_3 \hat{k}$)
& then prove LHS = RHS

Vector Calculus: Line Integrals

The concept of line integrals is a generalization of definite integrals i.e. $\int_a^b f(x)dx$. (integration bet' [a,b])

The line integrals are represented by

$$\int_C F(r) \cdot dr \text{ or } \oint_C F(r) \cdot dr$$

Hence the vector function $F(r) = F_1(x,y,z)i + F_2(x,y,z)j + F_3(x,y,z)k$ is integrated along a curve called path 'C' instead of an interval (a,b).

In the second case the path of the integral is a closed curve.

The curve or path of the integral usually represented in its parametric form as:

$$C: r(t) = x(t)i + y(t)j + z(t)k, t \text{ is a parameter. } a \leq t \leq b$$

Hence a is the value of 't' corresponding to the initial point & b is the value of 't' corresponding to the terminal or end point on 'C'. $t=b$

Parametric Representation of some known curves

Name of the curve	Parametric Representation
1. Straight line	$r(t) = \vec{a} + t\vec{b}$ (Passing through $\vec{a} \neq 1 \neq \vec{b}$)
2. Circle ($x^2 + y^2 = a^2$)	$r(t) = a \cos t i + a \sin t j$ (center at (0,0) & radius = a) $0 \leq t \leq 2\pi$
3. Ellipse ($\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$)	$r(t) = a \cos t i + b \sin t j$ (")
4. Parabola ($y^2 = 4ax$)	$r(t) = at^2 i + 2at j$
5. Circular helix	$r(t) = a \cos t i + a \sin t j + ct k$ etc.

N.B Hence all the curves discussed here are assumed to be piecewise smooth.

Representation of Line Integrals

$$\begin{aligned} \int_C F(r) \cdot dr &= \int_C (F_1 dx + F_2 dy + F_3 dz) \\ &= \int_a^b (F_1 x' + F_2 y' + F_3 z') dt. \end{aligned}$$

Evaluation of Line Integrals

Working Formula: $\int_C \mathbf{F}(\mathbf{r}) \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \left(\frac{d\mathbf{r}}{dt} \right) dt.$ —(1)

Working Procedure:

Step-1: Write or note down the parametric representation of the curve 'C'
i.e. $C: \mathbf{r}(t) = x(t)\hat{i} + y(t)\hat{j} + z(t)\hat{k}$ & note down $x(t), y(t), z(t).$

Step-2: Find $\mathbf{F}(\mathbf{r}(t))$ i.e. replace x, y, z of 'F' by $x(t), y(t) & z(t)$ respectively from 'C': $\mathbf{r}(t)$ (obtained as in step-1)

Step-3: Differentiate $\mathbf{r}(t)$ w.r.t. 't' to get $\frac{d\mathbf{r}}{dt}$
i.e. $\frac{d\mathbf{r}}{dt} = \frac{dx(t)}{dt}\hat{i} + \frac{dy(t)}{dt}\hat{j} + \frac{dz(t)}{dt}\hat{k}$

Step-4: Note down the initial and terminal points on C
i.e. $t=a$ & $t=b$ respectively.

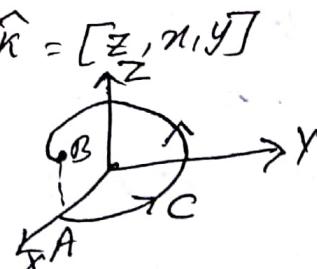
Step-5: Find the dot product of $\mathbf{F}(\mathbf{r}(t)) \cdot \frac{d\mathbf{r}}{dt}$
($\mathbf{F}(\mathbf{r}(t))$ from step-2 & $\frac{d\mathbf{r}}{dt}$ from step-3)

Step-6 Integrate & evaluate as

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_a^b \mathbf{F}(\mathbf{r}(t)) \cdot \frac{d\mathbf{r}}{dt} dt \text{ over the limits } t=a \text{ to } t=b.$$

Examples

Q1 Evaluate $\int_C \mathbf{F} \cdot d\mathbf{r}$, where $\mathbf{F}(\mathbf{r}) = z\hat{i} + x\hat{j} + y\hat{k} = [z, x, y]$
and $C: \mathbf{r}(t) = \cos t\hat{i} + \sin t\hat{j} + 3t\hat{k} \quad (0 \leq t \leq 2\pi)$



Sol'n Parametric representation of 'C' is

$$\mathbf{r}(t) = \cos t\hat{i} + \sin t\hat{j} + 3t\hat{k}$$

$$\Rightarrow x = \cos t, y = \sin t, z = 3t \quad (\text{step-1}) \quad (1)$$

$$\text{Now } \mathbf{F} = z\hat{i} + x\hat{j} + y\hat{k}$$

$$\Rightarrow \mathbf{F}(\mathbf{r}(t)) = 3t\hat{i} + \cos t\hat{j} + \sin t\hat{k} \quad (\text{from eqn 1}) \quad (2)$$

(Replacing x, y, z of \mathbf{F} by x, y, z of C) (step-2)

$$\text{Now } \vec{r}(t) = \cos t \hat{i} + 8 \sin t \hat{j} + 3t \hat{k} \quad (\text{step-3})$$

$$\Rightarrow \frac{d\vec{r}}{dt} = -\sin t \hat{i} + \cos t \hat{j} + 3 \hat{k}. \quad (3)$$

The representation 'C' confirms that $\boxed{a=0, b=2\pi} \quad (\because 0 \leq t \leq 2\pi) \quad (\text{step-4})$

Now the dot product of eqn 2 & 3.

$$F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} = (3t \hat{i} + \cos t \hat{j} + 8 \sin t \hat{k}) \cdot (-\sin t \hat{i} + \cos t \hat{j} + 3 \hat{k}) \quad (\text{step-5})$$

$$\therefore \boxed{F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} = -3t \sin t + \cos^2 t + 3 \sin t} \quad (\because a \cdot b = a_1 a_2 + b_1 b_2 + c_1 c_2)$$

$$\text{Thus } \int_C \vec{F} \cdot d\vec{r} = \int_a^b F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} dt \quad (\text{step-6})$$

$$= \int_0^{2\pi} (-3t \sin t + \cos^2 t + 3 \sin t) dt.$$

$$= (-3) \left\{ -t \cos t \Big|_0^{2\pi} + \int_0^{2\pi} \cos t dt \right\} + \frac{1}{2} \left\{ \int_0^{2\pi} dt + \left[\frac{\sin 2t}{2} \right]_0^{2\pi} \right\} + 3 \left[\cos t \right]_0^{2\pi}$$

$$= (-3) \{(-2\pi - 0) + 0\} + \frac{1}{2} (2\pi + 0) - 3(1 - 1)$$

$$= 6\pi + \pi + 0$$

$$= 7\pi$$

$$\therefore \boxed{\int_C \vec{F} \cdot d\vec{r} = 7\pi} \quad \text{Ans.}$$

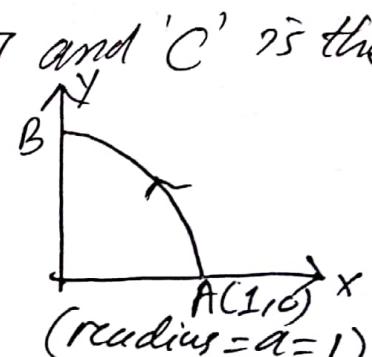
Q Find $\int_C \vec{F} \cdot d\vec{r}$ where $F(r) = [-y, -xy]$ and 'C' is the circular arc as shown in the fig.

SOLN From the figure the parametric representation of 'C' is $\boxed{(1)}$

$$C: \vec{r}(t) = \cos t \hat{i} + 8 \sin t \hat{j} \quad (0 \leq t \leq \frac{\pi}{2}) \quad (\text{step-1})$$

$$\Rightarrow x(t) = \cos t \text{ & } y(t) = 8 \sin t, z(t) = 0.$$

$$\text{Now } \boxed{F(\vec{r}) = -y \hat{i} - xy \hat{j}} \quad (\text{step-2})$$



$$r(t) = \cos t \hat{i} + \sin t \hat{j}$$

(PP-4)

Differentiating w.r.t. 't'

(Step-3)

$$\boxed{\frac{dr}{dt} = -\sin t \hat{i} + \cos t \hat{j}} \quad \text{--- (3)}$$

From the figure of curve 'C' it is clear that
 $a=0, b=\frac{\pi}{2}$ (\therefore Quarter of a circle $0 \leq t \leq \frac{\pi}{2}$) (Step-4)

Now making dot product of eq's 2 & 3.

$$F(r(t)) \cdot \frac{dr}{dt} = (-\sin t \hat{i} - \sin t \cdot \cos t \hat{j}) \cdot (-\sin t \hat{i} + \cos t \hat{j}) \quad (\text{Step-5})$$

$$\Rightarrow \boxed{F(r(t)) \cdot \frac{dr}{dt} = \sin^2 t - \cos^2 t \cdot \sin t} \quad (\because a \cdot b = a_1 a_2 + b_1 b_2 + c_1 c_2)$$

Now $\int_C \vec{F} \cdot d\vec{r} = \int_a^b F(r(t)) \cdot \frac{dr}{dt} dt$ (Step-6)

$$= \int_0^{\frac{\pi}{2}} (\sin^2 t - \cos^2 t \cdot \sin t) dt$$

$$= \int_0^{\frac{\pi}{2}} \left(\frac{1 - \cos 2t}{2} \right) dt - \int_0^{\frac{\pi}{2}} \cos 2t \cdot \sin t dt$$

$$= \frac{1}{2} \left\{ [t]_{0}^{\frac{\pi}{2}} - \left[\frac{\sin 2t}{2} \right]_{0}^{\frac{\pi}{2}} \right\} + \left[\frac{\cos^3 t}{3} \right]_{0}^{\frac{\pi}{2}}$$

$$= \frac{1}{2} \left\{ \left(\frac{\pi}{2} - 0 \right) - 0 \right\} + \frac{1}{3} (0 - 1) = \frac{\pi}{4} - \frac{1}{3}$$

$\therefore \boxed{\int_C \vec{F} \cdot d\vec{r} = \frac{\pi}{4} - \frac{1}{3}}$ Ans $\boxed{\text{Ans} = \frac{\pi}{4} - \frac{1}{3}}$

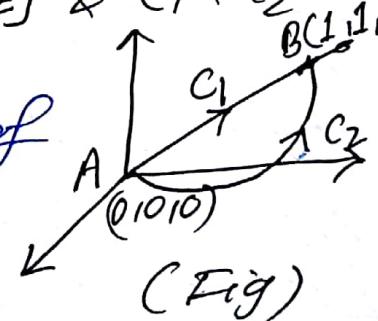
Path Dependence

Evaluate the line integral $\int_C \vec{F} \cdot d\vec{r}$ along two different paths C_1 & C_2 , where $F = [5z, xy, x^2 z]$ & C_1 & C_2 are as shown in the fig.

SOL The parametric representations of the curves are.

$$C_1: r_1(t) = t \hat{i} + t \hat{j} + t \hat{k} \quad (0 \leq t \leq 1)$$

$$C_2: r_2(t) = t \hat{i} + t \hat{j} + t^2 \hat{k} \quad (0 \leq t \leq 1)$$



Case-1Evaluation of $\int_C \vec{F} \cdot d\vec{r}$ along C_1

Here $r_1(t) = t\hat{i} + t\hat{j} + t\hat{k}$
 $\Rightarrow x = t, y = t \text{ & } z = t$.

$$F = 5z\hat{i} + xy\hat{j} + x^2z\hat{k} \quad (1)$$

$$\Rightarrow F(r_1(t)) = 5t\hat{i} + t^2\hat{j} + t^3\hat{k} \quad (\text{Replacing } x, y, z \text{ by } t, t, t \text{ respectively})$$

Now from the figure $0 \leq t \leq 1$

$$\text{Now } r_1(t) = t\hat{i} + t\hat{j} + t\hat{k}$$

$$\Rightarrow \left[\frac{dr_1}{dt} = \hat{i} + \hat{j} + \hat{k} \right] \quad (2)$$

Making dot product of 1 & 2

$$F(r_1(t)) \cdot \frac{dr_1}{dt} = (5t\hat{i} + t^2\hat{j} + t^3\hat{k}) \cdot (\hat{i} + \hat{j} + \hat{k})$$

$$\therefore F(r_1(t)) \cdot \frac{dr_1}{dt} = 5t + t^2 + t^3$$

$$\text{Hence } \int_C \vec{F} \cdot d\vec{r} = \int_C F(r_1(t)) \cdot \frac{dr_1}{dt} dt$$

$$= \int_0^1 (5t + t^2 + t^3) dt$$

$$= 5\left[\frac{t^2}{2}\right]_0^1 + \left[\frac{t^3}{3}\right]_0^1 + \left[\frac{t^4}{4}\right]_0^1$$

$$= \frac{5}{2} + \frac{1}{3} + \frac{1}{4} = \frac{30+4+3}{12} = \frac{37}{12}$$

Case-2Evaluation of $\int_{C_2} \vec{F} \cdot d\vec{r}$ along the path C_2 .

Parametric representation of C_2 is:

$$C_2: r_2(t) = t\hat{i} + t\hat{j} + t^2\hat{k}$$

$$\Rightarrow x = t, y = t, z = t^2$$

$$\text{Now } F = 5z\hat{i} + xy\hat{j} + x^2z\hat{k}$$

$$\therefore F(r_2(t)) = 5t^2\hat{i} + t^2\hat{j} + t^4\hat{k} \quad (1)$$

PP-6

Now from the figure, it is clear that $0 \leq t \leq 1$
i.e. $a=0, b=1$

$$\text{Now } \vec{r}(t) = t\hat{i} + t\hat{j} + t^2\hat{k}$$

$$\therefore \boxed{\frac{d\vec{r}}{dt} = \hat{i} + \hat{j} + 2t\hat{k}} \quad (2)$$

Making dot product of 1 & 2

$$F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} = (5t^2\hat{i} + t^2\hat{j} + t^4\hat{k}) \cdot (\hat{i} + \hat{j} + 2t\hat{k})$$

$$\Rightarrow \boxed{F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} = 5t^2 + t^2 + 2t^5} = 6t^2 + 2t^5$$

$$\therefore \int_C \vec{F} \cdot d\vec{r} = \int_0^1 F(\vec{r}(t)) \cdot \frac{d\vec{r}}{dt} dt$$

$$= \int_0^1 (6t^2 + 2t^5) dt$$

$$= 6 \left[\frac{t^3}{3} \right]_0^1 + \frac{2}{6} \left[t^6 \right]_0^1 = 2(1-0) + \frac{1}{3}(1-0) = 2 + \frac{1}{3} = \frac{7}{3} \approx \frac{28}{12}$$

$$\therefore \boxed{\int_C \vec{F} \cdot d\vec{r} = \frac{7}{3} \approx \frac{28}{12}}$$

N.B. In case-1, the integral value was $\frac{37}{12}$ & now it is $\frac{28}{12}$
which shows that the line Integral may be path dependent.

Assignments

Evaluate $\int_C \vec{F} \cdot d\vec{r}$ along C for the following cases.

$$1. \vec{F} = [y^2, -x^2] \quad C: \text{straight line } \vec{r}(t) = t\hat{i} + 4t\hat{j} \quad (0 \leq t \leq 1)$$

$$2. \vec{F} = [xy, x^2y^2] \quad C: \vec{r}(t) = 2\cos t\hat{i} + 2\sin t\hat{j} \quad (0 \leq t \leq \frac{\pi}{2})$$

$$3. \vec{F} = [(x-y)^2, (y-x)^2] \quad C: \vec{r}(t) = t\hat{i} + \frac{1}{t}\hat{j} \quad 0 \leq t \leq 4$$

$$4. \vec{F} = [2z, x, -y] \quad C: \vec{r}(t) = \cos t\hat{i} + \sin t\hat{j} + 2t\hat{k}, \quad 0 \leq t \leq 2\pi$$

$$5. \vec{F} = [(x-y), (y-z), (z-x)], \quad C: \vec{r}(t) = 2\cos t\hat{i} + \frac{2\sin t}{2\pi}\hat{j} + 2\sin t\hat{k} \quad (0 \leq t \leq 2\pi)$$

$$6. \vec{F} = [e^x, e^y, e^z], \quad C: \vec{r}(t) = [t, t^2, t] \text{ from } (0,0,0) \text{ to } (1,1,1)$$

$$7. \vec{F} = [\cosh x, \sinh y, e^z], \quad C: \vec{r}(t) = [t, t^2, t^3] \text{ from } (0,0,0) \text{ to } (2,4,8)$$

— 0 —

Path Independence of Line Integrals

(PPT)

Definition: A line integral $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ is said to be independent of path in a domain D in space for every pair of end points A & B in D if the line integral has the same value for all paths in D that begin at A and end at B .

Theorem A line Integral: $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ with continuous F_1, F_2 & F_3 in a domain D in space is independent of path in D if & only if $\mathbf{F} = [F_1, F_2, F_3]$ is the gradient of some function in D . i.e. $\mathbf{F} = \nabla f$ & $F_1 = \frac{\partial f}{\partial x}, F_2 = \frac{\partial f}{\partial y}$ & $F_3 = \frac{\partial f}{\partial z}$

In components: $F_1 = \frac{\partial f}{\partial x}, F_2 = \frac{\partial f}{\partial y}$ & $F_3 = \frac{\partial f}{\partial z}$

Example: Show that the line integral $\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ is independent of path & hence evaluate from $A(0,0,0)$ to $B(2,2,2)$.

Sol: Here $\mathbf{F} = 2x\mathbf{i} + 2y\mathbf{j} + 2z\mathbf{k}$ which is the gradient of the function $f = x^2 + y^2 + z^2$ ($\because \nabla f = \frac{\partial f}{\partial x}\mathbf{i} + \frac{\partial f}{\partial y}\mathbf{j} + \frac{\partial f}{\partial z}\mathbf{k}$)
Hence there is no doubt that $\frac{\partial f}{\partial x} = 2x, \frac{\partial f}{\partial y} = 2y, \frac{\partial f}{\partial z} = 2z$
line integral $\int_C 2x dx + 2y dy + 2z dz$ is path independent.

As the line integral path independent, its value remains same irrespective of all paths from $A(0,0,0)$ to $B(2,2,2)$.

Let's choose the simplest path i.e. the straight line whose parametric form is

$$C: \mathbf{r}(t) = t\mathbf{i} + t\mathbf{j} + t\mathbf{k} \quad (0 \leq t \leq 2)$$

$$\therefore x = t, y = t, z = t$$

$$\Rightarrow \mathbf{F}(\mathbf{r}(t)) = 2t\mathbf{i} + 2t\mathbf{j} + 2t\mathbf{k}$$

$$\frac{d\mathbf{r}}{dt} = 2\mathbf{i} + 2\mathbf{j} + 2\mathbf{k}$$

$$\Rightarrow \mathbf{F}(\mathbf{r}(t)) \cdot \frac{d\mathbf{r}}{dt} = 4t\mathbf{i} + 4t\mathbf{j} + 4t\mathbf{k} = 12t \quad (\because a \cdot b = a_1a_2 + b_1b_2 + c_1c_2)$$

$$\therefore \int_C \mathbf{F} \cdot d\mathbf{r} = \int_C 2x dx + 2y dy + 2z dz = \int_0^2 12t dt = 12 \left[\frac{t^2}{2} \right]_0^2 = 6 \times 4 = 24 \text{ Ans.}$$

Theorem-2

The line Integral $\int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ is independent of path in a domain D if and only if its value around any closed path in D is zero.

(To remember)

Exactness and Path Independence

Defn The differential form under the integral sign of a line integral: $\int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ is i.e. $F_1 dx + F_2 dy + F_3 dz$ is said to be exact if we can find a function $f(x, y, z)$ st. $F_1 = \frac{\partial f}{\partial x}, F_2 = \frac{\partial f}{\partial y}$ & $F_3 = \frac{\partial f}{\partial z}$

$$\text{i.e. } F_1 dx + F_2 dy + F_3 dz = df \text{ i.e. } F = \text{grad } f.$$

Theorem-3 (Criterion for exactness & Path Independence)

Let F_1, F_2 & F_3 in the line integral $\int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy + F_3 dz$ be continuous and have continuous first order partial differential equations in a domain D in space. Then:

(a) If the line integral is independent of path in D & thus the differential form " $F_1 dx + F_2 dy + F_3 dz$ " under the integral sign is exact in D , then

$$\text{curl } F = 0$$

$$\text{i.e. } \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & F_3 \end{vmatrix} = 0 \Rightarrow \left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \hat{i} + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \hat{j} + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \hat{k} = 0$$

in components.

$$\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}, \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}, \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y} \quad \text{Cond' for exactness} \quad (1)$$

(b) If $\text{curl } F = 0$ in D & D is simply connected, then the line integral is independent of path in D . (imp.)

Note If the differential form is exact in a line integral $\int_C \vec{F} \cdot d\vec{r} = \int_C F_1 dx + F_2 dy + F_3 dz$, then then the line integral is path independent. (i.e. its value remains same along all paths bet' A to B)

TOPIC

Working procedure to test exactness & evaluation
of the line Integral $\int_C F \cdot dr = \int_C F_1 dx + F_2 dy + F_3 dz$

Step-1 Test the exactness of the differential form $F_1 dx + F_2 dy + F_3 dz$
i.e. show if $\frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$, $\frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x}$, $\frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$, If satisfies then
the line integral is exact & proceed to step-2 else
it is not exact & stop.

Step-2 Assume a function 'f' & integrate to get 'f'
from the ~~integrand eqn~~

$$\frac{\partial f}{\partial x} = F_1 \quad (\text{Assume } x \text{ is only variable whereas } y \text{ &} z \text{ are constants})$$

i.e. $f = \int F_1 dx + h(y, z) \quad (\because y \text{ & } z \text{ are const & hence they may exist in integration constant})$
& get the function f.

Step-3 Find $\frac{\partial f}{\partial y}$ by partially differentiating w.r.t. y &
equate with F_2

$$\therefore \frac{\partial f}{\partial y} = F_2 \Rightarrow \boxed{f = \int F_2 dy + g(z)} \quad (\begin{matrix} (2) \\ \text{Treat } z \text{ as const} \\ y \text{ as variable} \end{matrix})$$

Step-4 Find $\frac{\partial f}{\partial z}$ by partially differentiating w.r.t. z &
equate with F_3

$$\text{i.e. } \frac{\partial f}{\partial z} = F_3 \Rightarrow \boxed{f = \int F_3 dz + k} \quad (3)$$

Step-5 Now 'f' as obtained in eq-3 is the solⁿ of the
given line integral & substitute the given A (initial pt)
and B (terminal pt) so as to find the desired value
of the given line integral.

$$\text{i.e. } I = \int_C F \cdot dr = \int_A^B F_1 dx + F_2 dy + F_3 dz = f(B) - f(A) \quad \text{Ans.}$$

Example Test the exactness of the differential form
of the line integral: $\int_{(1,-1,7)}^{(0,1,2)} 3x^2 dx + 2yz dy + y^2 dz$
and hence evaluate it.

SOLⁿ The given line integral is

$$\int_{(0,1,2)}^{(1,-1,7)} 3x^2 dx + 2yz dy + y^2 dz$$

Hence $F_1 = 3x^2$, $F_2 = 2yz$, $F_3 = y^2$.

Now for test of exactness

$$\frac{\partial F_3}{\partial y} = 2y, \quad \frac{\partial F_2}{\partial z} = 2y \Rightarrow \frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z} \quad \checkmark$$

$$\frac{\partial F_1}{\partial z} = 0, \quad \frac{\partial F_3}{\partial x} = 0 \Rightarrow \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x} \quad \checkmark$$

$$\frac{\partial F_2}{\partial x} = 0, \quad \frac{\partial F_1}{\partial y} = 0 \Rightarrow \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y} \quad \checkmark$$

(Step-1)

Hence the diff. form is exact.

Now Let $\frac{\partial f}{\partial x} = F_1$

$$\Rightarrow \frac{\partial f}{\partial x} = 3x^2$$

$$\Rightarrow f = \int 3x^2 dx + g(y, z) \quad (\text{step-2})$$

$$\Rightarrow \boxed{f = x^3 + g(y, z)} \quad (1)$$

Let Now from eqⁿ⁻¹

$$\frac{\partial f}{\partial y} = \frac{\partial g}{\partial y} = F_2$$

$$\Rightarrow \frac{\partial g}{\partial y} = 2yz \Rightarrow g = \int 2yz dy + h(z) \quad (\text{step-3})$$

$$\Rightarrow \boxed{g = y^2 z + h(z)} \quad (2)$$

Now from eqⁿ⁻² & eqⁿ⁻¹

$$\boxed{f = x^3 + y^2 z + h(z)} \quad (3)$$

Diff. partially w.r.t z.

$$\frac{\partial f}{\partial z} = y^2 + \frac{dh}{dz} = F_3 \Rightarrow \cancel{y^2} + \frac{dh}{dz} = y^2$$

$$\Rightarrow \frac{dh}{dz} = 0 \Rightarrow \boxed{h = C} \quad (4)$$

(Step-4)

Now from eqⁿ⁻³ & A: $\boxed{f = x^3 + y^2 z + C}$

$$\text{As } f = x^3 + y^2 z + c$$

$$\Rightarrow \int_{(0,1,2)}^{(1,-1,7)} 3x^2 dx + 2yz dy + y^2 dz = f(B) - f(A)$$

$$= f(1, -1, 7) - f(0, 1, 2)$$

$$= (1^3 + (-1)^2 \times 7 + c) - (0^3 + 1^2 \times 2 + c) = 8 - 2 = 6 \quad \underline{\text{Ans}}$$

Example-2

Evaluate the line integral:

$$\int_{(0,0,1)}^{(4,1,1,2)} 3y dx + 3x dy + 2z dz & \text{ & verify whether the differential} \\ \text{form under the integral sign is exact or not.}$$

Soln $F_1 = 3y, F_2 = 3x, F_3 = 2z.$

$$\text{Now } \frac{\partial F_3}{\partial y} = 0, \frac{\partial F_2}{\partial z} = 0 \Rightarrow \frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z} \quad \checkmark$$

$$\frac{\partial F_1}{\partial z} = 0, \frac{\partial F_3}{\partial x} = 0 \Rightarrow \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x} \quad \checkmark$$

$$\frac{\partial F_2}{\partial x} = 3, \frac{\partial F_1}{\partial y} = 3 \Rightarrow \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y} \quad \checkmark \Rightarrow \text{Exact.}$$

$$\text{Now Let } \frac{\partial f}{\partial x} = F_1 = 3y$$

$$\Rightarrow f = \int 3y dx + g(y, z) \quad (1)$$

$$\Rightarrow f = 3xy + g(y, z)$$

From-1 $\frac{\partial f}{\partial y} = 3x + \frac{\partial g}{\partial y} = F_2$

$$\Rightarrow 3x + \frac{\partial g}{\partial y} = 3x \Rightarrow \frac{\partial g}{\partial y} = 0$$

$$\Rightarrow g = \int dy + h(z)$$

$$\Rightarrow g = h(z) \quad (2)$$

From 1 & 2: $f = 3xy + h(z) \quad (3)$

From-3 $\frac{\partial f}{\partial z} = F_3 \Rightarrow \frac{dh}{dz} = 2z$

$$\Rightarrow h = \int 2z dz + c \Rightarrow h = z^2 + c \quad (4)$$

From 3 & 4 $f = 3xy + z^2 + c$

$$\text{Now } \int_{(0,0,0)}^{(4,1,1,2)} 3y dx + 3x dy + 2z dz = f(4, 1, 1, 2) - f(0, 0, 0)$$

$$= (3 \times 4 \times 1 + 2^2 + c) - (0 + 0 + c) = 16 \quad \underline{\text{Ans.}}$$

Ex-3 Show that the diff. form under the integral sign of the line integral $\int_{(0,0,1)}^{(1, \frac{\pi}{4}, 12)} 2xyz^2 dx + (x^2z^2 + z \cos yz) dy + (y \cos yz) dz$ is exact & hence evaluate it. pp-6

Soln Here $F_1 = 2xyz^2$, $F_2 = x^2z^2 + z \cos yz$, $F_3 = y \cos yz$. Now $\frac{\partial F_3}{\partial y} = 2x^2z - yz^2 \sin yz$, $\frac{\partial F_2}{\partial z} = 2xz^2 - yz \sin yz \Rightarrow \frac{\partial F_3}{\partial y} = \frac{\partial F_2}{\partial z}$

$$\frac{\partial F_1}{\partial z} = 4xyz, \frac{\partial F_3}{\partial x} = 4xyz \Rightarrow \frac{\partial F_1}{\partial z} = \frac{\partial F_3}{\partial x} = 1$$

$$\frac{\partial F_2}{\partial x} = 2xz^2, \frac{\partial F_1}{\partial y} = 2xz^2 \Rightarrow \frac{\partial F_2}{\partial x} = \frac{\partial F_1}{\partial y}$$

Hence the form is exact.

Now let $\frac{\partial f}{\partial x} = F_1 = 2xyz^2$

$$\Rightarrow f = \int 2xyz^2 dx + g(y, z)$$

$$\Rightarrow f = x^2yz^2 + g(y, z) \quad \text{--- (1)}$$

From -1 $\frac{\partial f}{\partial y} = F_2 \Rightarrow x^2z^2 + \frac{\partial g}{\partial y} = x^2z^2 + z \cos yz$

$$\Rightarrow \frac{\partial g}{\partial y} = z \cos yz \Rightarrow g = \int z \cos yz dy + h(z)$$

$$\Rightarrow g = \sin yz + h(z) \quad \text{--- (2)}$$

From 1 & 2

$$f = x^2yz^2 + \sin yz + h(z) \quad \text{--- (3)}$$

Now from -3: $\frac{\partial f}{\partial z} = F_3$

$$\Rightarrow 2x^2yz + y \cancel{\cos yz} + \frac{dh}{dz} = 2x^2yz + y \cos yz + \cancel{h} \quad \text{--- (4)}$$

$$\Rightarrow \frac{dh}{dz} = 0 \Rightarrow h = C \quad \text{--- (4)}$$

From eqn-3 & 4, we have

$$f = x^2yz^2 + \sin yz + C$$

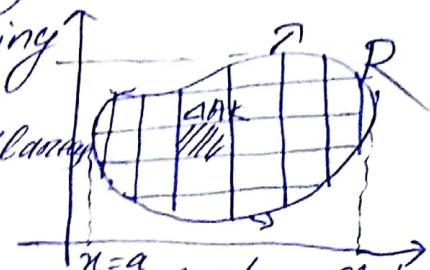
$$\begin{aligned} \therefore I &= \int_{(0,0,1)}^{(1, \frac{\pi}{4}, 12)} [2xyz^2 dx + (x^2z^2 + z \cos yz) dy + (y \cos yz) dz] \\ &= f(1, \frac{\pi}{4}, 12) - f(0, 0, 1) \\ &= ((1^2 \times \frac{\pi}{4} \times 2^2 + 8 \sin \frac{\pi}{2}) - (0 + 8 \sin 0)) = \pi + 1 \quad \text{Ans} \end{aligned}$$

Double Integrals

The definition and evaluation of Double Integrals are quite similar to the definite integrals (e.g. $\int_a^b f(x) dx$)

We subdivide the region R by drawing vertical lines to x -axis & y -axis.

Then $J_n = \sum f(x_k, y_k) \Delta A_k$ (i.e. summation of all areas of rectangles in R)



N.B. All the properties of definite integrals ($\int_a^b f(x) dx$) are also preserved by the double integrals.

$$\text{i.e. } \iint K f(x, y) dxdy = K \iint f(x, y) dxdy$$

$$2) \iint_R (f+g) dxdy = \iint_R f dxdy + \iint_R g dxdy$$

$$3) \text{ If } R = R_1 \cup R_2, \text{ then } \iint_R f(x, y) dxdy = \iint_{R_1} f(x, y) dxdy + \iint_{R_2} f(x, y) dxdy$$



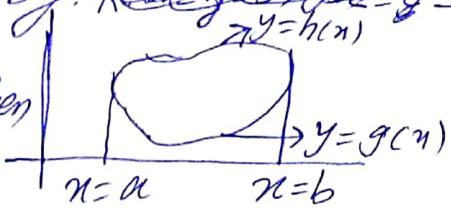
Evaluation of Double Integrals

The double integrals are evaluated by two successive integrations as per the following cases.

Case-1: If the region R is described by: ~~$x \in [a, b], y \in [g(x), h(x)]$~~

$$R: a \leq x \leq b, g(x) \leq y \leq h(x), \text{ then}$$

$$\iint_R f(x, y) dxdy = \int_a^b \left[\int_{g(x)}^{h(x)} f(x, y) dy \right] dx$$



(i.e. $f(x, y)$ first is to be integrated w.r.t. y by treating ' x ' as a constant and then the resulting function (of x only) is to be integrated w.r.t. ' x ' over $a \leq x \leq b$)

Example Evaluate $\iint_{0 \leq x \leq 3} (x^2 + y^2) dy dx$.

$$\text{SOL} \quad \int_0^3 \int_{-x}^x (x^2 + y^2) dy dx = \int_0^3 \left[\int_{-x}^x (x^2 + y^2) dy \right] dx$$

(next x as const)

$$= \int_0^3 \left(x^2 \left[y \right]_{-x}^x + \left[\frac{y^3}{3} \right]_{-x}^x \right) dx$$

$$= \int_0^3 \left(x^2 (2x) + \frac{1}{3} (x^3 - (-x)^3) \right) dx = \int_0^3 \left(2x^3 + \frac{2}{3} x^3 \right) dx$$

$$= \int_0^3 \left(2 + \frac{2}{3}x\right) x^3 dx = \frac{8}{3} \int_0^3 x^3 dx$$

$$= \frac{8}{3} \left[\frac{x^4}{4} \right]_0^3 = \frac{2}{3} (81 - 0) = \underline{\underline{\frac{162}{3}}} \text{ Ans.}$$

CASE-2 If the region R is described by $y \leq b$ & $p(y) \leq x \leq q(y)$, then $y=a$

$$\iint_R f(x,y) dx dy = \int_a^b \left[\int_{p(y)}^{q(y)} f(x,y) dx \right] dy$$

(treat y as const.)

Example Evaluate $\int_0^{\frac{\pi}{4}} \int_0^y \frac{\sin y}{y} dx dy$

Solution

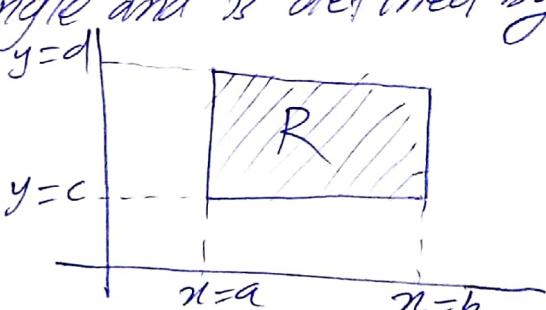
$$\begin{aligned} & \int_0^{\frac{\pi}{4}} \int_0^y \frac{\sin y}{y} dx dy = \int_0^{\frac{\pi}{4}} \left[\int_0^y \frac{\sin y}{y} dx \right] dy \\ &= \int_0^{\frac{\pi}{4}} \frac{\sin y}{y} [x]_0^y dy = \int_0^{\frac{\pi}{4}} \frac{\sin y}{y} (y-0) dy \\ &= \int_0^{\frac{\pi}{4}} \sin y dy = -[\cos y]_0^{\frac{\pi}{4}} = -(\frac{1}{\sqrt{2}} - 1) = \underline{\underline{1 - \frac{1}{\sqrt{2}}}} \text{ Ans} \end{aligned}$$

CASE-3 If the region is a rectangle and is defined by

R: $a \leq x \leq b$, $c \leq y \leq d$, then

$$\iint_R f(x,y) dx dy = \int_c^d \left[\int_a^b f(x,y) dx \right] dy$$

(treat y as const)



Example Evaluate $\int_0^2 \int_0^4 (x^2 + y^2) dx dy$

Solution

$$\begin{aligned} & \int_0^2 \left[\int_0^4 (x^2 + y^2) dx \right] dy = \int_0^2 \left(\left[\frac{x^3}{3} \right]_0^4 + y^2 [x]_0^4 \right) dy \\ &= \int_0^2 \left(\frac{64}{3} + 4y^2 \right) dy = \frac{64}{3} [y]^2 + \frac{4}{3} [y^3]_0^2 \\ &= \frac{128}{3} + \frac{32}{3} = \underline{\underline{\frac{160}{3}}} \text{ Ans.} \end{aligned}$$

Applications of Double Integrals

Double Integrals have various geometrical and physical applications as per the followings.

① Area of a region R in XY-plane.

$$A = \iint_R dxdy$$



② Volume (V) beneath the surface $Z = f(x,y)$ and above a region R in XY-plane

$$V = \iint_R f(x,y) dxdy$$

③ Let $f(x,y)$ be the density (mass per unit area) of a distribution of mass in XY-plane, then the total mass is

$$m = \iint_R f(x,y) dxdy$$

④ Center of gravity (\bar{x}, \bar{y}) in co-ordinates of a mass

$$\bar{x} = \frac{1}{m} \iint_R xf(x,y) dxdy \quad \bar{y} = \frac{1}{m} \iint_R yf(x,y) dxdy$$

⑤ Moment of inertia: I_x & I_y of a mass in R about X-axis and Y-axis is

$$I_x = \iint_R y^2 f(x,y) dxdy, \quad I_y = \iint_R x^2 f(x,y) dxdy$$

Polar moment of inertia $I_o = I_x + I_y = \iint_R (x^2 + y^2) f(x,y) dxdy$

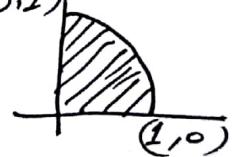
Examples

Q Let $f(x,y)=1$ be the density of a mass distribution in the region $R: 0 \leq y \leq \sqrt{1-x^2}, 0 \leq x \leq 1$. Then find the C.G. & moment of inertia $I_x, I_y & I_o$.

Solution The total mass (m) in R is given by

$$m = \iint_R dxdy = \int_0^1 \int_0^{\sqrt{1-x^2}} dy dx = \int_0^1 [y]_0^{\sqrt{1-x^2}} dx = \int_0^1 \sqrt{1-x^2} dx$$

$$\begin{aligned} \text{Let } x = \sin\theta &\Rightarrow dx = \cos\theta d\theta \\ \Rightarrow \int_0^1 \sqrt{1-x^2} dx &= \int_0^{\pi/2} \cos^2 \theta d\theta = \int_0^{\pi/2} (\cos^2 \theta - \sin^2 \theta) d\theta = \frac{1}{2} \left[\theta \right]_0^{\pi/2} + \left[\frac{\sin 2\theta}{2} \right]_0^{\pi/2} = \frac{\pi}{4} \end{aligned}$$



Now for center of gravity (\bar{x}, \bar{y}) given $f(x,y)=1$

$$\begin{aligned}\bar{x} &= \frac{1}{m} \iint_R x f(x,y) dxdy = \frac{1}{(II)} \iint_R x \cdot 1 dxdy \\ &= \frac{4}{\pi} \int_0^1 \left[\int_0^{\sqrt{1-x^2}} dy \right] dx = \frac{4}{\pi} \int_0^1 x \sqrt{1-x^2} dx = -\frac{4}{\pi} \int_0^1 z^2 dz \\ &= \frac{4}{3\pi}\end{aligned}$$

Due to symmetry $\bar{y} = \frac{4}{3\pi}$

$$\text{Hence } C.G = \left(\frac{4}{3\pi}, \frac{4}{3\pi} \right) \underline{\underline{\text{Ans}}}$$

For moment of inertia

$$\begin{aligned}I_x &= \iint_R y^2 f(x,y) dxdy, I_y = \iint_R x^2 f(x,y) dxdy. \\ \therefore I_x &= \iint_R y^2 dxdy = \int_0^1 \left[\int_0^{\sqrt{1-x^2}} y^2 dy \right] dx = \int_0^1 \left[\frac{y^3}{3} \right]_0^{\sqrt{1-x^2}} dx \\ &= \frac{1}{3} \int_0^1 (\sqrt{1-x^2})^3 dx = \frac{1}{3} \int_0^{\frac{\pi}{2}} \cos^4 \theta d\theta \quad (\text{take } x = \sin \theta) \\ &= \frac{1}{3} \left(\frac{3\pi}{16} \right) = \frac{\pi}{16} \quad (\sqrt{1-\sin^2 \theta} = \cos \theta)$$

$$I_y = \iint_R x^2 f(x,y) dxdy = \frac{\pi}{16} \quad (\text{due to symmetry})$$

$$\therefore I_o = I_x + I_y = \frac{\pi}{16} + \frac{\pi}{16} = \frac{2\pi}{16} = \frac{\pi}{8} \quad \underline{\underline{\text{Ans}}}$$

Assignments

Exercise - 9-3

Green's Theorem in the Plane

(Transformation between double Integral & Line Integral)

Theorem

Let R' be a closed bounded region in xy -plane whose boundary C consists of finitely many smooth curves. Let $F_1(x, y)$ and $F_2(x, y)$ be functions that are continuous and have continuous partial derivatives $\frac{\partial F_1}{\partial y}$ & $\frac{\partial F_2}{\partial x}$ everywhere in some domain containing R . Then

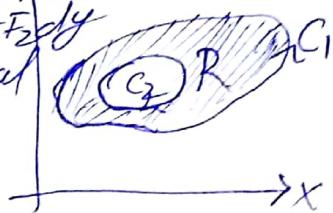
$$\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \oint_C (F_1 dx + F_2 dy)$$

i.e. $\int F \cdot dr = \iint (\operatorname{curl} F) dxdy$

Hence we integrate along the entire boundary C of R' st. R' is on the left as we advance in the direction of integration

(Hence the line integral $\oint F \cdot dr = \int_{C'} F_1 dx + F_2 dy$ can be evaluated by the double integral

$$\iint_R (\operatorname{curl} F) \cdot \hat{n} dxdy$$



Verification (Through Example)

Verify Green's Theorem in plane for $F = (y^2 - 7y)\hat{i} + (2ny + 2n)\hat{j}$ and $C: x^2 + y^2 = 1$ (circle)

Left Hand Side (LHS)

$$\iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dxdy, \text{ Here } F_1 = y^2 - 7y, F_2 = 2ny + 2n$$

$$\text{Now } \frac{\partial F_2}{\partial x} = \frac{\partial}{\partial x}(2ny + 2n) = 2n$$

$$\frac{\partial F_1}{\partial y} = \frac{\partial}{\partial y}(y^2 - 7y) = 2y - 7$$

$$\text{Now } \iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dxdy = \iint_R (2n - (2y - 7)) dxdy$$

$$= \iint_R q dxdy = q \left(\iint_R dxdy \right) = q \times \text{Area of } R = q(\pi \times 1^2)$$

$(\because A = \iint_R dxdy) = (q\pi)$

Right Hand Side (RHS)

$$\text{Here } F = (y^2 - 7y)\hat{i} + (2ny + 2n)\hat{j}$$

$$C: r(\theta) = \cos \theta \hat{i} + \sin \theta \hat{j} \quad (C: x^2 + y^2 = 1, \text{ circle with radius } 1)$$

$$\Rightarrow x = \cos \theta, y = \sin \theta \quad (0 \leq \theta \leq 2\pi)$$

$$\text{Now } F(rt) = (\sin^2t - 78\sin t)i + (28\sin t \cdot \cos t + 2\cos^2t)j$$

$$\frac{dR}{dt} = -8\sin t i + \cos t j$$

$$\text{Now } F(rt) \cdot \frac{dR}{dt} = -8\sin^3 t + 78\sin^2 t + 28\sin t \cdot \cos^2 t + 2\cos^3 t$$

$$= -8\sin^3 t + 58\sin^2 t + 28\sin t \cdot \cos^2 t + 2$$

$$\therefore \oint F_1 dx + F_2 dy = \int_0^{2\pi} (-8\sin^3 t + 58\sin^2 t + 28\sin t \cdot \cos^2 t + 2) dt$$

$$= 0 + 7\pi + 0 + 2\pi = 9\pi$$

Thus LHS = RHS \Rightarrow Green's Theorem is verified.

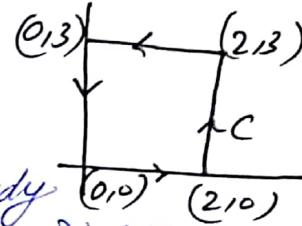
Evaluation Of Line Integrals by Green's Theorem

Q Using Green's theorem evaluate $\oint F \cdot dr$ counterclockwise around the boundary of C defined as the rectangle with vertices $(0,0), (2,0), (2,3), (0,3)$ where $F = [x^2 e^y, y^2 e^x] = x^2 e^y i + y^2 e^x j$

$$\text{soln } F_1 = x^2 e^y, F_2 = y^2 e^x$$

$$\text{Now } \frac{\partial F_2}{\partial x} = y^2 e^x, \frac{\partial F_1}{\partial y} = x^2 e^y$$

$$\text{Now As per Green's Theorem } \oint_C F \cdot dr = \iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dxdy$$



R: $0 \leq x \leq 2, 0 \leq y \leq 3$

$$= \iint_R (y^2 e^x - x^2 e^y) dxdy = \int_0^3 \left[\int_0^2 (y^2 e^x - x^2 e^y) dx \right] dy$$

$$= \int_0^3 \left[y^2 [e^x]_0^2 - e^y \left[\frac{x^3}{3} \right]_0^2 \right] dy$$

$$= \int_0^3 (y^2 (e^2 - 1) - \frac{8}{3} e^y) dy = (e^2 - 1) \left[\frac{y^3}{3} \right]_0^3 - \frac{8}{3} [e^y]_0^3$$

$$= \frac{e^2 - 1}{3} (27 - 0) - \frac{8}{3} (e^3 - 1) = \boxed{9(e^2 - 1) - \frac{8}{3} (e^3 - 1)} \text{ Ans.}$$

N.B The normal derivative of R of a soln $w(x,y)$ is denoted by $\frac{\partial w}{\partial n}$ and the Green's Theorem to find the integral of the normal derivative $\oint \frac{\partial w}{\partial n} ds$ counterclockwise over 'C' can be evaluated by the formula.

$$\oint_C \frac{\partial w}{\partial n} ds = \iint_R \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) ds = \iint_R \iint \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} dxdy = \iint_R \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} \right) dxdy.$$

Ex Evaluate $\oint_C \frac{\partial w}{\partial n} ds$, $w = e^x + e^y$ R: Rectangle $0 \leq x \leq 2, 0 \leq y \leq 1$.

$$\text{soln } w = e^x + e^y \Rightarrow \frac{\partial^2 w}{\partial x^2} = e^x, \frac{\partial^2 w}{\partial y^2} = e^y$$

$$\text{Now } \oint_C \frac{\partial w}{\partial n} ds = \iint_R \left(\frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} \right) dxdy = \int_0^1 \left(\int_0^2 (e^x + e^y) dx \right) dy$$

$$= \int_0^1 ((e^x)_0^2 + e^y (x)_0^2) dy = \int_0^1 (e^2 - 1 + 2e^y) dy = (e^2 - 1) [y]_0^1 + 2[e^y]_0^1$$

$$= \boxed{(e^2 - 1) + 2(e - 1)} \text{ Ans.}$$

Assignments: [Problem set 9.4]

Surfaces and Surface Normals

Parametric Representation of surfaces:

<u>Name of surface</u>	<u>Parametric representation</u>
General cartesian form $z = f(x,y)$ or $f(x,y) = 0$	$\mathbf{r}(u,v) = \mathbf{x}(u,v)\hat{i} + \mathbf{y}(u,v)\hat{j} + \mathbf{z}(u,v)\hat{k}$
1. Sphere ($x^2 + y^2 + z^2 = a^2$)	$\mathbf{r}(u,v) = a \cos u \sin v \hat{i} + a \sin u \sin v \hat{j} + a \cos v \hat{k}$
2. Cylinder ($x^2 + y^2 = a^2, -1 \leq z \leq 1$)	$\mathbf{r}(u,v) = a \cos u \hat{i} + a \sin u \hat{j} + v \hat{k}$
3. XY-plane ($z = 0$)	$\mathbf{r}(u,v) = u \hat{i} + v \hat{j}$
4. Cone	$\mathbf{r}(u,v) = u \cos v \hat{i} + u \sin v \hat{j}$
5. Paraboloid of Revolution	$\mathbf{r}(u,v) = u \cos v \hat{i} + u \sin v \hat{j} + u^2 \hat{k}$
6. Elliptic Paraboloid	$\mathbf{r}(u,v) = a \cos v \hat{i} + b \sin v \hat{j} + c \sin v \hat{k}$
7. Ellipsoid	$\mathbf{r}(u,v) = a \cos v \hat{i} + b \sin v \hat{j} + c \cosh u \hat{k}$
8. Hyperboloid	$\mathbf{r}(u,v) = a \sinh u \cos v \hat{i} + b \sinh u \sin v \hat{j} + c \cosh u \hat{k}$
9. Helicoid	$\mathbf{r}(u,v) = u \cos v \hat{i} + u \sin v \hat{j} + v \hat{k}$
10. Elliptic cylinder	$\mathbf{r}(u,v) = a \cos v \hat{i} + b \sin v \hat{j} + u \hat{k}$

Surface Normals

Defn A normal vector of a surface 'S' at a point P is a vector perpendicular to the tangent plane of 'S' at P.

N.B (Tangent plane means the plane containing tangent vectors i.e. $\mathbf{r}_u(\frac{\partial \mathbf{r}}{\partial u})$, $\mathbf{r}_v(\frac{\partial \mathbf{r}}{\partial v})$)

As all the derivatives (first derivative) represents the tangent vectors, hence $\frac{\partial \mathbf{r}}{\partial u}(\mathbf{r}_u)$ & $\frac{\partial \mathbf{r}}{\partial v}(\mathbf{r}_v)$ are the tangent vectors.

We also know that the cross product of two vectors \vec{a} & \vec{b} ($\vec{a} \times \vec{b}$) is in the direction \perp^{bc} to the plane containing \vec{a} & \vec{b} .

Hence $\frac{\partial \mathbf{r}}{\partial u} \times \frac{\partial \mathbf{r}}{\partial v}(\mathbf{r}_u \times \mathbf{r}_v)$ is a vector perpendicular to the plane containing \mathbf{r}_u & \mathbf{r}_v i.e. tangent plane and hence ' $\mathbf{r}_u \times \mathbf{r}_v$ ' represents the surface normal vector.

$$N = \mathbf{r}_u \times \mathbf{r}_v \quad (\text{Surface Normal})$$

∴ Unit Normal vector = $\hat{n} = \frac{\mathbf{r}_u \times \mathbf{r}_v}{|\mathbf{r}_u \times \mathbf{r}_v|}$ gmp

Also from application of gradient, we know that gradient of a surface $f(x,y,z)=0$ represents the surface normal vector.

PP-2
Date _____

Home the unit normal vector of a surface $\text{def}(x, y, z) = 0$

$$\hat{n} = \frac{\text{grad } f}{\|\text{grad } f\|}$$

Q1 Find the surface ^{unit} normal vector of the followings

1. XY-plane: $r(u, v) = u\hat{i} + v\hat{j}$
2. Cone: $r(u, v) = u\cos v\hat{i} + u\sin v\hat{j} + u\hat{k}$

Solⁿ 1: $r(u, v) = u\hat{i} + v\hat{j}$
 $\Rightarrow ru = \frac{\partial r}{\partial u} = \frac{\partial}{\partial u} (u\hat{i} + v\hat{j}) = \hat{i}$
 $rv = \frac{\partial r}{\partial v} = \frac{\partial}{\partial v} (u\hat{i} + v\hat{j}) = \hat{j}$

$\therefore N = ru \times rv = \hat{i} \times \hat{j} = \hat{k}$ Ans
Unit normal vector $\hat{n} = \frac{\hat{k}}{\|\hat{k}\|} = \frac{\hat{k}}{1} = \hat{k}$ Ans

Solⁿ 2: $r(u, v) = u\cos v\hat{i} + u\sin v\hat{j} + u\hat{k}$
 $\Rightarrow ru = \frac{\partial r}{\partial u} = \cos v\hat{i} + \sin v\hat{j} + \hat{k}$
 $rv = \frac{\partial r}{\partial v} = -u\sin v\hat{i} + u\cos v\hat{j}$

Note! Surface Normal $= N = ru \times rv = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \cos v & \sin v & 0 \\ -u\sin v & u\cos v & 1 \end{vmatrix}$
 $\therefore N = -u\cos v\hat{i} + (-u\sin v)\hat{j} + u(\cos^2 v + \sin^2 v)\hat{k}$
 $\therefore \hat{n} = \frac{-u\cos v\hat{i} - u\sin v\hat{j} + u\hat{k}}{\sqrt{\cos^2 v + \sin^2 v + 1}} = \frac{1}{u\sqrt{c^2+1}} (-u\cos v\hat{i} - u\sin v\hat{j} + \hat{k})$

Q Find the surface and unit normal vector of the cartesian surface.

Solⁿ $4x^2 + y^2 + 9z^2 = 36$.
Surface normal $= \text{grad } f$, $f = 4x^2 + y^2 + 9z^2 - 36$
 $\therefore N = \text{grad } f = \frac{\partial f}{\partial x}\hat{i} + \frac{\partial f}{\partial y}\hat{j} + \frac{\partial f}{\partial z}\hat{k}$, $\frac{\partial f}{\partial x} = 8x$, $\frac{\partial f}{\partial y} = 2y$, $\frac{\partial f}{\partial z} = 18z$

$\Rightarrow N = 8x\hat{i} + 2y\hat{j} + 18z\hat{k}$
Unit normal $= \hat{n} = \frac{\text{grad } f}{\|\text{grad } f\|} = \frac{8x\hat{i} + 2y\hat{j} + 18z\hat{k}}{\sqrt{(8x)^2 + (2y)^2 + (18z)^2}}$
 $\therefore \hat{n} = \frac{8x\hat{i} + 2y\hat{j} + 18z\hat{k}}{\sqrt{64x^2 + 4y^2 + 324z^2}}$

Assignments

Surface Integrals

The surface integral of a vector function \vec{F} is defined as:

$$\iint_S \vec{F} \cdot \hat{n} dA = \iint_R \vec{F}(r(u,v)) \cdot \vec{N}(u,v) du dv$$

Where $\vec{N}(u,v)$ is the surface normal vector ($\vec{r}_{uv} \times \vec{r}_{vv}$). This is also called the flux integral.

Evaluation of Surface Integrals

Step-1 Note the given vector function $\vec{F} = F_1 \hat{i} + F_2 \hat{j} + F_3 \hat{k}$ and write the parametric representation of the surface as $r(u,v) = x(u,v) \hat{i} + y(u,v) \hat{j} + z(u,v) \hat{k}$ and note x, y, z .

Step-2 Substitute x, y, z of $r(u,v)$ in \vec{F} to get $\vec{F}(r(u,v))$.

Step-3 Find $\vec{r}_{uu} = \frac{\partial r}{\partial u}$ & $\vec{r}_{vv} = \frac{\partial r}{\partial v}$ & hence $\vec{r}_{uv} \times \vec{r}_{vv}$

$$\Rightarrow \vec{N} = \vec{r}_{uv} \times \vec{r}_{vv} = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial x}{\partial u} & \frac{\partial y}{\partial u} & \frac{\partial z}{\partial u} \\ \frac{\partial x}{\partial v} & \frac{\partial y}{\partial v} & \frac{\partial z}{\partial v} \end{vmatrix}$$

Step-4 Find the limits for u & v on S . $u \in [a, b]$ & $v \in [c, d]$

Step-5 Find the dot product of $\vec{F}(r(u,v))$ & $\vec{N}(u,v)$
i.e. $\vec{F}(r(u,v)) \cdot \vec{N}(u,v)$

Step-6 Integrate to get the surface integral $\iint_S \vec{F} \cdot \hat{n} dA$

$\iint_S \vec{F} \cdot \hat{n} dA = \iint_R (\vec{F}(r(u,v)) \cdot \vec{N}(u,v)) du dv$. & evaluate the double integral to get the desired surface integral.

Q: Compute the flux of water through the parabolic cylinder $S: y = x^2, 0 \leq x \leq 2, 0 \leq z \leq 3$ if the velocity vector $\vec{v} = [3z^2, 6, 6xz]$ ($\rho = 1 \text{ g/cm}^3$)

Sol: To get the flux of water (total mass flow) through the pipe, we have to compute the surface integral $\iint_S \vec{v} \cdot \hat{n} dA$.

Hence $F = V = [3z^2, 6, 6xz, z] = 3z^2\hat{i} + 6\hat{j} + 6xz\hat{k}$ (PP-4)

Surface S: $y = x^2$, $0 \leq x \leq 2$, $0 \leq z \leq 3$.

Let $x=u$, $z=v$,

$$\Rightarrow y = u^2$$

Thus parametric form of 'S' is

$$S: r(u, v) = ui + u^2j + vk \quad 0 \leq u \leq 2 \quad 0 \leq v \leq 3 \quad (\text{Step-1})$$

$$\Rightarrow x=u, y=u^2, z=v.$$

$$\text{Now } F = 3z^2\hat{i} + 6\hat{j} + 6xz\hat{k}$$

$$\Rightarrow F(r(u, v)) = 3v^2\hat{i} + 6\hat{j} + 6uv\hat{k} \quad (\because x=u, y=u^2, z=v)$$

$$\text{Here } r(u, v) = ui + u^2j + vk$$

$$\Rightarrow ru = \frac{\partial r}{\partial u} = \hat{i} + 2u\hat{j}$$

$$rv = \frac{\partial r}{\partial v} = \hat{k}$$

$$\text{Now } N = ru \times rv = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ 1 & 2u & 0 \\ 0 & 0 & 1 \end{vmatrix} = 2u\hat{i} - \hat{j} \quad (\text{Step-3})$$

$$\therefore N(u, v) = 2u\hat{i} - \hat{j}$$

As per defn of S: $0 \leq u \leq 2, 0 \leq v \leq 3$ (Step-4)

$$\text{Now } F(r(u, v)) \cdot N(u, v)$$

$$= (3v^2\hat{i} + 6\hat{j} + 6uv\hat{k}) \cdot (2u\hat{i} - \hat{j}) \quad (\text{Step-5})$$

$$\Rightarrow [F(r(u, v)) \cdot N(u, v)] = 6uv^2 - 6 \quad (\because a \cdot b = a_1a_2 + b_1b_2 + c_1c_2)$$

$$\text{Now total flux} = \iint_S F \cdot \hat{n} dA = \iint_R F(r(u, v)) \cdot N(u, v) du dv$$

$$= \int_0^3 \int_0^2 (6uv^2 - 6) du dv = \int_0^3 \left[\int_0^2 (6uv^2 - 6) du \right] dv$$

$$= \int_0^3 \left(6v^2 \left[\frac{u^3}{3} \right]_0^2 - 6 \left[u^2 \right]_0^2 \right) dv \quad (\text{treat } v \text{ as const})$$

$$= 12 \left[\frac{v^3}{3} \right]_0^3 - 12 \left[v^2 \right]_0^3 = 4 \times (27 - 0) - 12 \times (3 - 0)$$

$$= 108 - 36 = 72 \text{ (m}^3/\text{sec)}.$$

Example-2:

Evaluate the surface integral $\iint_S F \cdot \hat{n} dA$, where

$$F = [x^2, e^y, 1] = x^2 i + e^y j + k, S: x+y+z=1, x \geq 0, y \geq 0, z \geq 0$$

Soln Hence $F = x^2 i + e^y j + k, S: x+y+z=1, x \geq 0, y \geq 0, z \geq 0$

Parametric representation of 'S'

$$x+y+z=1, \text{ let } x=u, y=v, \Rightarrow z=1-u-v \\ \therefore S: r(u,v) = ui + vj + (1-u-v)k, 0 \leq u \leq 1 \quad (\text{step-1})$$

$$\text{Now } x=u, y=v, z=1-u-v$$

$$\Rightarrow F(r(u,v)) = u^2 i + e^v j + k$$

$$\text{Now } r(u,v) = ui + vj + (1-u-v)k$$

$$\Rightarrow ru = \frac{\partial r}{\partial u} = i - k$$

$$rv = \frac{\partial r}{\partial v} = j - k$$

$$\Rightarrow N(u,v) = ru \times rv = \begin{vmatrix} i & j & k \\ 1 & 0 & -1 \\ 0 & 1 & -1 \end{vmatrix} = i + j + k \quad (\text{step-3})$$

Hence $0 \leq u \leq 1, 0 \leq v \leq 1 \quad (\text{step-4})$

$$\text{Now } F(r(u,v)) \cdot N(u,v) = (u^2 i + e^v j + k) \cdot (i + j + k)$$

$$= u^2 + e^v + 1$$

$$\Rightarrow F(r(u,v)) \cdot N(u,v) = u^2 + e^v + 1$$

$$\text{Hence } \iint_S F \cdot \hat{n} dA = \iint_S F(r(u,v)) \cdot N(u,v) du dv \quad (\text{step-5})$$

$$= \int_0^1 \int_0^1 (u^2 + e^v + 1) du dv = \int_0^1 \left[\int_0^1 (u^2 + e^v + 1) du \right] dv$$

$$= \int_0^1 \left(\left[\frac{u^3}{3} \right]_0^1 + e^v [u]_0^1 + [v]_0^1 \right) dv = \int_0^1 \left(\frac{1}{3} + e^v + 1 \right) dv$$

$$= \frac{1}{3} [v]_0^1 + [e^v]_0^1 + [v]_0^1 = \frac{1}{3} + (e^1 - 1) + 1 = \underline{\underline{e + \frac{1}{3}}} \quad \text{Ans.}$$

Theorem (Change of orientation)

The replacement of \hat{n} by $-\hat{n}$ in the surface integral $\iint_S F \cdot \hat{n} dA$ corresponds to the multiplication of the integral by (-1) .

Applications of Surface Integral

(PP-6)

Another type of surface integral is

$\iint_S G(\mathbf{r}) dA = \iint_R G(\mathbf{r}(u,v)) |\mathbf{N}(u,v)| du dv$ which is independent of orientation.

$$\text{Hence } dA = |\mathbf{N}| du dv = |\mathbf{r}_u \times \mathbf{r}_v| du dv.$$

Hence the total mass density of 'S' ($\rho=1$) gives the area.

Thus Area of $S = A(S) = \iint_S dA = \iint_R |\mathbf{r}_u \times \mathbf{r}_v| du dv.$

Ex Find the area of the sphere $x^2 + y^2 + z^2 = a^2$.
Soln Hence parametric form of $S: \mathbf{r}(u,v) = a \cos u \cos v \mathbf{i} + a \sin u \cos v \mathbf{j} + a \sin v \mathbf{k}$
Now $|\mathbf{r}_u \times \mathbf{r}_v| = \sqrt{a^2 \sin^2 u \cos^2 v + a^2 \sin^2 u \sin^2 v + a^2 \sin^2 v} = a^2 \sqrt{\cos^2 u + \sin^2 u} = a^2$

$$= a^2 \int_0^{2\pi} \int_0^{\pi} a^2 du dv = a^2 \cdot 2\pi \cdot \pi = 2\pi a^2$$

$$\text{Now } A(S) = \iint_S dA = \iint_R |\mathbf{r}_u \times \mathbf{r}_v| du dv = \int_{-\pi/2}^{\pi/2} \int_0^{2\pi} a^2 \cos v du dv = 2\pi a^2 \int_{-\pi/2}^{\pi/2} \cos v dv = 2\pi a^2 [\sin v]_{-\pi/2}^{\pi/2} = 2\pi a^2 (1+1) = 4\pi a^2$$

Moment of Inertia

$$I = \iint_S \mu D^2 dA$$

$\mu = \mu(x, y, z)$ = mass distribution
 $D(u, y, z)$ = distance of the point.

Another representation of Surface integral

$$\iint_S G(\mathbf{r}) dA = \iint_{R^*} G(x, y, f(x, y)) \sqrt{1 + (\frac{\partial f}{\partial x})^2 + (\frac{\partial f}{\partial y})^2} dx dy$$

Hence R^* is projection of 'S' in XY-plane.

$$A(S) = \iint_{R^*} \sqrt{1 + (\frac{\partial f}{\partial x})^2 + (\frac{\partial f}{\partial y})^2} dx dy$$

Area of S'

Assignments

Triple Integrals and Gauss Divergence Theorem

(PP-1)

The triple integral is a generalization of double integrals. Let $f(x, y, z)$ is a function defined in a closed & bounded region T in space. We subdivide this 3-dimensional region T by planes to the 3 co-ordinate planes. Then these boxes of subdivision that lie entirely inside T are numbered 1 to n , then the triple integral is in the form of the sum.

$$J_n = \sum_{k=1}^n f(x_k, y_k, z_k) \Delta V_k, \quad \Delta V_k = \text{volume of } k^{\text{th}} \text{ box.}$$

i.e. $\iiint_T f(x, y, z) dxdydz = \iiint_T f(x, y, z) dV = \sum_{k=1}^n f(x_k, y_k, z_k) \Delta V_k$

Hence $\iiint_T f(x, y, z) dV$ or $\iiint_T f(x, y, z) dxdydz$ is the representation of the triple integrals. Its evaluation process is very similar as the double integrals.

Ex Evaluate the triple integral $\iiint_T (x^2 + y^2 + z^2) dxdydz$, where $T: |x| \leq 1, |y| \leq 3, |z| \leq 2$

Sol'n Here $T: |x| \leq 1, |y| \leq 3, |z| \leq 2$

$$|x| \leq 1 \Rightarrow -1 \leq x \leq 1, |y| \leq 3 \Rightarrow -3 \leq y \leq 3, |z| \leq 2 \Rightarrow -2 \leq z \leq 2$$

$$\text{Now } \iiint_T (x^2 + y^2 + z^2) dxdydz = \int_{-2}^2 \int_{-3}^3 \int_{-1}^1 (x^2 + y^2 + z^2) dx dy dz$$

$$= \int_{-2}^2 \int_{-3}^3 \left[\int_{-1}^1 (x^2 + y^2 + z^2) dx \right] dy dz$$

$(y \& z \text{ const.})$

$$= \int_{-2}^2 \int_{-3}^3 \left(\left[\frac{x^3}{3} \right]_{-1}^1 + (y^2 + z^2) \left[x \right]_{-1}^1 \right) dy dz$$

$$= \int_{-2}^2 \int_{-3}^3 \left[\frac{2}{3} + 2(y^2 + z^2) \right] dy dz$$

$(\text{treat } z \text{-const})$

$$= \int_{-2}^2 \left(\frac{2}{3} \left[y \right]_{-3}^3 + 2 \left[\frac{y^3}{3} \right]_{-3}^3 + z^2 \left[y \right]_{-3}^3 \right) dz$$

$$= \int_{-2}^2 \left(\frac{2}{3} (6) + 2 \left[\frac{y^4}{3} \right]_{-3}^3 + 6z^2 \left[y \right]_{-3}^3 \right) dz = \int_{-2}^2 (40 + 6z^2) dz$$

$$= \int_{-2}^2 (40 + 6z^2) dz = 40 \left[z \right]_{-2}^2 + \frac{6}{3} \left[z^3 \right]_{-2}^2$$

$$= 40 \times 4 + 2 \times 16 = 160 + 32$$

$$= 192 \quad \text{Ans.}$$

The Divergence theorem of Gauss

(Transformation between volume integral and surface Integral)

Let T is a closed and bounded region in space whose boundary is a piecewise smooth orientable surface S . Let $F(x, y, z)$ be a vector function that is continuous and has C¹ first order partial derivative in some domain containing T . Then

$$\iiint_T \operatorname{div} F \, dV = \iint_S F \cdot \hat{n} \, dA.$$

$$\operatorname{div} F = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z}$$

Here \hat{n} is the outer unit normal vector of S .

Example: Using Gauss Divergence theorem, evaluate the following surface integral.

$$\iint_S x^3 dy dz + x^2 y dz dx + x^2 z dy dx, \quad S: \text{closed surface consisting of the cylinder } x^2 + y^2 = a^2 \\ (0 \leq z \leq b) \text{ & circular disk } z=0 \text{ & } z=b (x^2 + y^2 \leq a^2)$$

Soln we have to evaluate $\iint_S F \cdot \hat{n} \, dA$, where

$$F = x^3 i + x^2 y j + x^2 z k, \quad \text{ie. } F_1 = x^3, F_2 = x^2 y, F_3 = x^2 z \\ \text{Now } \operatorname{div} F = \frac{\partial F_1}{\partial x} i + \frac{\partial F_2}{\partial y} j + \frac{\partial F_3}{\partial z} k = \frac{\partial F_1}{\partial x} = 3x^2, \frac{\partial F_2}{\partial y} = x^2, \frac{\partial F_3}{\partial z} = x^2 \\ \Rightarrow \operatorname{div} F = 3x^2 + x^2 + x^2 = 5x^2 \Rightarrow \operatorname{div} F = 5x^2$$

As per Gauss Divergence theorem

$$\iint_S F \cdot \hat{n} \, dA = \iiint_T \operatorname{div} F \, dV$$

Introducing polar co-ordinate for the surface/region, we have
(Cylindrical co-ordinate r, θ, z)

$$x = r \cos \theta, y = r \sin \theta, \dots$$

$$\text{we have } dr dy dz = r dr d\theta dz$$

$$\text{Now } \iint_S F \cdot \hat{n} \, dA = \iiint_T 5r^2 dr dy dz = \int_{z=0}^b \int_{r=0}^a \int_{\theta=0}^{2\pi} 5r^2 \cos^2 \theta r dr d\theta dz$$

$$= \int_{z=0}^b \int_{r=0}^a \left[\int_{\theta=0}^{2\pi} [r^2 \cos^2 \theta] d\theta \right] dr dz = \int_{z=0}^b \int_{r=0}^a r^2 \left(\frac{1}{2} [\theta]_0^{2\pi} + \left[\frac{\sin 2\theta}{2} \right]_0^{2\pi} \right) dr dz$$

$$= 5 \int_{z=0}^b \left[\int_{r=0}^a \pi r^3 dr \right] dz = 5 \int_0^b \left[\frac{\pi r^4}{4} \right]_0^a dz$$

$$= \frac{5\pi}{4} \times a^4 \int_0^b dz = \frac{5\pi}{4} a^4 [z]_0^b = \frac{5\pi a^4 b}{4}$$

$$= \frac{5\pi}{4} a^4 b \quad \underline{\text{Ans}}$$

Verification through Example

Evaluate and verify the Gauss Divergence theorem of the following surface integral.

$$\iint_S (7xi - zk) \cdot \hat{n} dA, \text{ over the surface } S: x^2 + y^2 + z^2 = 4 \text{ (sphere)}$$

Pf We know that the Gauss Divergence theorem is

$$\iiint_T \operatorname{div} F dV = \iint_S F \cdot \hat{n} dA.$$

$$\text{Here } F = 7xi - zk, S: x^2 + y^2 + z^2 = 4$$

$$\text{LHS } F_1 = 7x, F_2 = 0, F_3 = -z$$

$$\Rightarrow \frac{\partial F_1}{\partial x} = 7, \frac{\partial F_2}{\partial y} = 0, \frac{\partial F_3}{\partial z} = -1$$

$$\text{Hence } \operatorname{div} F = \frac{\partial F_1}{\partial x} + \frac{\partial F_2}{\partial y} + \frac{\partial F_3}{\partial z} = 7 + 0 - 1 = 6$$

$$\text{Hence } \iint_T \operatorname{div} F dV = \iint_S 6 dA = 6 \times \text{volume of the sphere}$$

$$(\because \text{Radius} = r = 2) = 6 \times 4 \pi \times 2^3 = \frac{6 \times 4 \times 8}{3} \pi$$

$$\text{RHS } \text{The given surface is } S: x^2 + y^2 + z^2 = 2^2$$

P Parametric representation of 'S' is

$$S: r(u, v) = 2 \cos u \cos v \hat{i} + 2 \sin u \cos v \hat{j} + 2 \sin v \hat{k} \quad (0 \leq u \leq 2\pi, -\frac{\pi}{2} \leq v \leq \frac{\pi}{2})$$

$$\Rightarrow \frac{\partial r}{\partial u} = r_u = -2 \sin u \cos v \hat{i} + 2 \cos u \cos v \hat{j}$$

$$\frac{\partial r}{\partial v} = r_v = -2 \cos u \sin v \hat{i} - 2 \sin u \sin v \hat{j} + 2 \cos v \hat{k}$$

$$\text{Now } N = r_u \times r_v = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ -2 \sin u \cos v & 2 \cos u \cos v & 0 \\ -2 \cos u \sin v & -2 \sin u \sin v & 2 \cos v \end{vmatrix} =$$

$$\Rightarrow N(u, v) = 4 \cos u \cos^2 v \hat{i} + 4 \sin u \cos^2 v \hat{j} + 4 \sin v \cos v \hat{k}$$

$$F(r(u, v)) = 14 \cos u \cos v \hat{i} - 2 \sin v \hat{k}.$$

$$\Rightarrow F(r(u, v)) \cdot N(u, v) = (14 \cos u \cos v)(4 \cos^2 v \cos u) + (-2 \sin v)(4 \cos u \cos v)$$

$$\Rightarrow F(r(u, v)) \cdot N(u, v) = 56 \cos^3 v \cos^2 u - 8 \sin^2 v \cos v$$

$$\text{Hence } \iint_S F \cdot \hat{n} dA = \iint_{T'} \left[56 \cos^3 v \cos^2 u - 8 \cos v \sin^2 v \right] du dv$$

treat v as const

$$= \int_{-\pi/2}^{\pi/2} \left[(56 \cos^3 v) \pi - (8 \cos v \sin^2 v) (2\pi) \right] dv$$

$$= 56\pi (2 - \frac{2}{3}) - 16\pi (\frac{2}{3}) = 64\pi$$

As LHS = RHS \Rightarrow Gauss Divergence theorem is proved & value of the integral is (64π) Ans.

Example

Evaluate $\iint_S F \cdot \hat{n} dA$ by using the divergence theorem of Gauss, where

$$F = e^x \hat{i} + e^y \hat{j} + e^z \hat{k} \text{ & } S: |x| \leq 1, |y| \leq 1, |z| \leq 1$$

SOLN Hence $F = e^x \hat{i} + e^y \hat{j} + e^z \hat{k} \Rightarrow F_1 = e^x, F_2 = e^y, F_3 = e^z$
 $\frac{\partial F_1}{\partial x} = e^x, \frac{\partial F_2}{\partial y} = e^y, \frac{\partial F_3}{\partial z} = e^z \Rightarrow \text{grad } F = e^x \hat{i} + e^y \hat{j} + e^z \hat{k}$

According to the divergence theorem of Gauss

$$\iiint_T \operatorname{div} F \, dv = \iint_S F \cdot \hat{n} \, dA, \quad T: |x| \leq 1, |y| \leq 1, |z| \leq 1 \\ \Rightarrow -1 \leq x \leq 1, -1 \leq y \leq 1, -1 \leq z \leq 1$$

Hence $\iint_S F \cdot \hat{n} \, dA = \iiint_T \operatorname{div} F \cdot dx dy dz$

$$= \int_{-1}^1 \int_{-1}^1 \int_{-1}^1 [(e^x + e^y + e^z) dx] dy dz \\ = \int_{-1}^1 \int_{-1}^1 \left([e^x]_1 + e^y [x]_1 + e^z [x]_1 \right) dy dz \\ = \int_{-1}^1 \int_{-1}^1 \left(e - \frac{1}{e} + 2e^y + 2e^z \right) dy dz = \int_{-1}^1 \left[\left(e - \frac{1}{e} \right) + 2e^y + 2e^z \right] dy dz \\ = \int_{-1}^1 \left(e - \frac{1}{e} \right) [y]_1 + 2 [e^y]_1 + 2e^z [y]_1 dz \\ = \int_{-1}^1 \left(2(e - \frac{1}{e}) + 2(e - \frac{1}{e}) + 4e^z \right) dz \\ = \int_{-1}^1 (4e - \frac{4}{e}) + 4e^z dz = (4e - \frac{4}{e}) + 4[e^z]_1 = 8 - \frac{8}{e} + 4(e - \frac{1}{e}) \\ = 12(e - \frac{1}{e}) \quad \text{Ans.}$$

Note If $\sigma = f(x, y, z)$ is the mass distribution in a region 'T' in space then the total mass is given by.

$$\boxed{\text{Total mass} = \iiint_T \sigma(x, y, z) \, dv}$$

$$f(x, y, z) = 1$$

The moment of Inertia of a mass distribution is given by
 $I_x = \iiint_T (y^2 + z^2) \, dv, I_y = \iiint_T (z^2 + x^2) \, dv, I_z = \iiint_T (x^2 + y^2) \, dv$

The Divergence theorem of Gauss can be expressed in components as

$$\iiint_T \operatorname{div} F \, dv = \iint_S (F_1 \cos \alpha + F_2 \cos \beta + F_3 \cos \gamma) \, dA$$

Here $\hat{n} = \cos \alpha \hat{i} + \cos \beta \hat{j} + \cos \gamma \hat{k}$

Also

$$\iiint_T \operatorname{div} F \, dv = \iint_S F_1 \, dy \, dz + F_2 \, dz \, dx + F_3 \, dx \, dy$$

Assignments

Stokes Theorem

(Transformation between Surface Integral & Line Integral)

Statement

Let S be a piecewise smooth oriented surface in space and the boundary of S be a piecewise smooth oriented simple closed curve C . Let $F(x, y, z)$ be a continuous vector function that has continuous first partial derivatives in a domain in space containing S , then

$$\iint_S (\operatorname{curl} F) \cdot \hat{n} dA = \oint_C F \cdot r(s) ds$$

Where \hat{n} = normal vector of S and, depending on n , the integration around C is taken counterclockwise & $r(s) = \frac{ds}{ds}$ is unit tangent vector & s is length of C .

$$N = r(u) \times r(v) = N_1 \hat{i} + N_2 \hat{j} + N_3 \hat{k} = [N_1, N_2, N_3]$$

In components

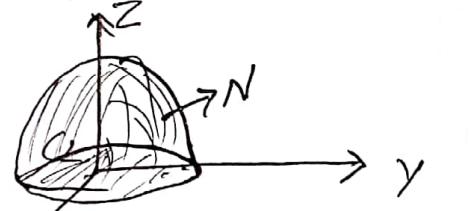
$$\iint_S \left[\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) N_1 + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) N_2 + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) N_3 \right] du dv = \oint_C (F_1 dx + F_2 dy + F_3 dz)$$

Verification through Example

Verify Stoke's theorem for the function $F = y \hat{i} + z \hat{j} + x \hat{k}$ if S is the paraboloid $Z = f(x, y) = 1 - (x^2 + y^2)$, $Z \geq 0$

LHS

From the figure, it is clear that the curve C is the circle $r(s) = \cos s \hat{i} + \sin s \hat{j}$. Its tangent vector is $\frac{dr}{ds} = -\sin s \hat{i} + \cos s \hat{j}$. \Rightarrow Unit tangent vector $\hat{n} = \frac{-\sin s \hat{i} + \cos s \hat{j}}{\sqrt{\sin^2 s + \cos^2 s}} = -\sin s \hat{i} + \cos s \hat{j}$



$$\text{Hence } \oint_C F \cdot dr = \oint_C (F(r(s)) \cdot \frac{dr}{ds}) ds$$

$$= \oint_C ((\sin s \hat{i} + \cos s \hat{k}) \cdot (-\sin s \hat{i} + \cos s \hat{j})) ds$$

$$= \int_0^{2\pi} -\sin^2 s ds = \int_0^{2\pi} \left(\frac{\cos 2s - 1}{2} \right) ds = \frac{1}{2} \left[\frac{\sin 2s}{2} \right]_0^{2\pi} - \frac{1}{2} [s]_0^{2\pi} = \underline{-\pi}$$

$$\text{LHS } \iint_S (\operatorname{curl} F) \cdot \hat{n} dA = \iint_S \left(\left(\frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) N_1 + \left(\frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) N_2 + \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) N_3 \right) dA$$

$$\text{Now } \operatorname{curl} F = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ y & z & x \end{vmatrix} = -\hat{i} - \hat{j} - \hat{k}$$

Now $N = \text{grad} f$, $f = x^2 + y^2 + z - 1 \Rightarrow \text{grad} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j} + \frac{\partial f}{\partial z} \hat{k}$
 $\Rightarrow N = \text{grad} f = 2x \hat{i} + 2y \hat{j} + \hat{k}$

Hence $\text{curl} F \cdot N = (-i - j - k) \cdot (2x \hat{i} + 2y \hat{j} + \hat{k}) = -2x - 2y - 1$

Hence $\iint_S (\text{curl} F \cdot \hat{n}) dA = \iint_R (-2x - 2y - 1) dx dy$ $\begin{matrix} z = 1 - (x^2 + y^2) \\ \text{base is circle } x^2 + y^2 = 1 \end{matrix}$

Using polar co-ordinates: $x = r \cos \theta, y = r \sin \theta, dxdy = r dr d\theta$

$\therefore R: r \leq 1, 0 \leq \theta \leq 2\pi$

Hence $\iint_S (\text{curl} F \cdot \hat{n}) dA = \iint_R (-2x - 2y - 1) dxdy$

$$\begin{aligned} &= \iint_R (-2r \cos \theta - 2r \sin \theta - 1) r dr d\theta \\ &= \iint_0^{2\pi} \left[\left(-2r^2 (\cos \theta + \sin \theta) - r \right) dr \right] d\theta \end{aligned}$$

$$\begin{aligned} &= \int_0^{2\pi} \left(-\frac{2}{3} [r^3]_0^1 (\cos \theta + \sin \theta) - \left[\frac{r^2}{2} \right]_0^1 \right) d\theta = \int_0^{2\pi} \left(-\frac{2}{3} (8 \sin \theta + 8 \cos \theta) - \frac{1}{2} \right) d\theta \\ &= -\frac{2}{3} \left\{ [\cos \theta]_0^{2\pi} + [\sin \theta]_0^{2\pi} \right\} - \frac{1}{2} \int_0^{2\pi} d\theta = -\frac{2}{3} (0) - \pi = -\pi \quad \text{LHS.} \end{aligned}$$

$\therefore \text{LHS} = \text{RHS} \Rightarrow \text{Stokes theorem is proved. & value of integral} = -\pi$

Example Evaluate $\oint_C F \cdot \mathbf{r}'(s) ds$ using Stoke's theorem, where $F = [5y, 4x, z]$

& 'C' is the circle $x^2 + y^2 = 4, z = 1$

Soln As per Stokes theorem $\oint_C F \cdot \mathbf{r}'(s) ds = \iint_S \text{curl} F \cdot \hat{n} dA$.

$$F = -5y \hat{i} + 4x \hat{j} + z \hat{k} \Rightarrow \text{curl} F = \begin{vmatrix} \hat{i} & \hat{j} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -5y & 4x & z \end{vmatrix} = 0 \cdot \hat{i} + 0 \cdot \hat{j} + (4+5) \hat{k} = 9 \hat{k}$$

Hence the circle $x^2 + y^2 = 4$ is on XY-plane $\Rightarrow \hat{n} = \hat{k}$

$$\begin{aligned} \text{Now } \oint_C F \cdot \mathbf{r}'(s) ds &= \iint_S (\text{curl} F \cdot \hat{n}) dA = \iint_S 9 dA = 9 \times \text{Area of } S = 9 \times \pi \times 2^2 \\ &= 36\pi \end{aligned}$$

N.B Green's theorem is a special case of Stokes theorem when $F = F_1 \hat{i} + F_2 \hat{j}$ & S is bounded by a simple closed curve C which is piecewise smooth in XY-plane. Then

$$\iint_S \left(\frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy = \oint_C F_1 dx + F_2 dy$$

Assignments