

Tutorial - 5

1. What is difference between DFS and BFS. Write an application of both the algorithm.

BFS

BFS stands for breadth First Search.

- BFS uses Queue to find the shortest path.
- BFS is better when target is closer to source.
- As BFS considers all neighbours so it is not suitable for decision tree used in puzzle games.
- BFS is slower than DFS.

Time complexity = $O(V+E)$

V = Vertices

E = Edge.

Application.

- Used in GPS navigations to find neighboring places.
- Use to find the path.
- Use to find cell the neighbour needs.

DFS

DFS stands for Depth First Search.

- DFS uses stack to find the shortest path.
- DFS is better when target is far from sources.
- DFS is more suitable for decision tree. As with one decision, we need to traverse further to argument the decision. If we reach the conclusion we won.
- DFS is faster than BFS.

Time complexity = $O(V+E)$

Application

- Use to Detect cycle in a graph.
- Use to find the Path from source to destination.
- Used to perform topological Sorting.

2. Which Data structure is used to implement BFS and DFS.

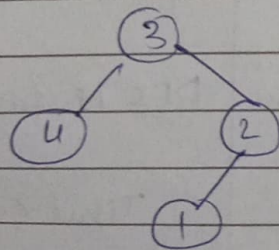
Data structures used in case of BFS and DFS are queue and stack respectively.

BFS requires queue data structure because it traverses a graph in breadthward motion & uses a queue to remember to get the next vertex to start a search, when a dead end occurs in any iteration.

→ DFS requires stack data structure because it traverses a graph in depthward motion & uses a stack to remember to get to the next vertex to start a search, when a dead end occurs in iteration.

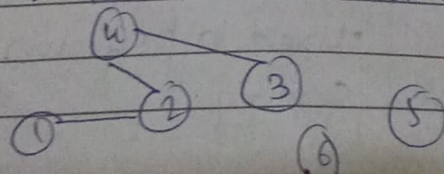
3. Dense Graph

is a graph in which no. of edge is close to the maximal number of edges.



• Sparse Graph

is a graph in which number of edges is close to minimal number of edges.

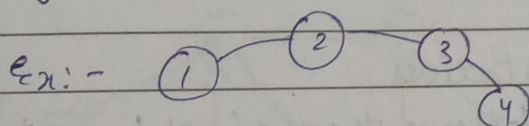


It is ideal to use sparse graphs by adjacency list and dense graph by an adjacency matrix.

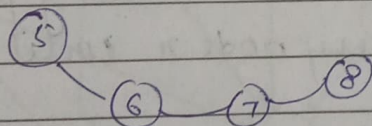
4. ~~Detect cycle using BFS~~

5. Disjoint Set

- Disjoint Set Data structure is also known as union-find data structure and merge-find set.
- It is a data structure that contains a collection of disjoint or non-overlapping sets.
- The disjoint set means that when the set is partitioned into disjoint subsets.



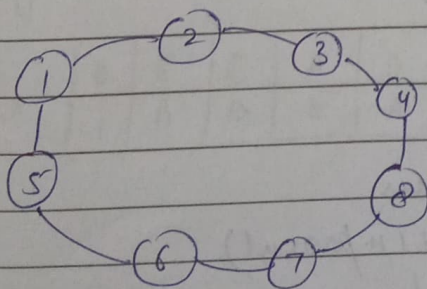
$$S_1 = \{1, 2, 3, 4\}$$



$$S_2 = \{5, 6, 7, 8\}$$

Union of these two sets are.

$$S_1 \cup S_2 = \{1, 2, 3, 4, 5, 6, 7, 8\} = S_3$$



Disjoint set supports three operations

① Making new sets.

The make set operation adds a new element into a new set containing only the new element, and the new set is added to the data structure.

If the data structure is instead ~~of~~ viewed as a partition of a set, then the MakeSet operation enlarges the set by adding the new element and it extends the existing partition by putting the new element into a new subset containing only the new element.

function MakeSet(x) is

if x is not already in the forest then

$x.parent = x$

$x.size = 1$

$x.rank = 0$

end if

end function.

Finding Set Representatives

The find operation follows the chain of parent pointers from a specified query node x until it reaches a root element.

This root element represents the set to which x belongs and may be x itself. Find returns the root element it reaches.

function find(x) is

if $x.parent \neq x$ then

$x.parent = find(x.parent)$

return $x.parent$

else

return x

end if

end function.

Merge two sets

The operation union (x, y) replace the set containing x and the set containing y with their union.

Ex: function Union (x, y) is

$x = \text{find}(x)$

$y = \text{find}(y)$

if $x = y$ then

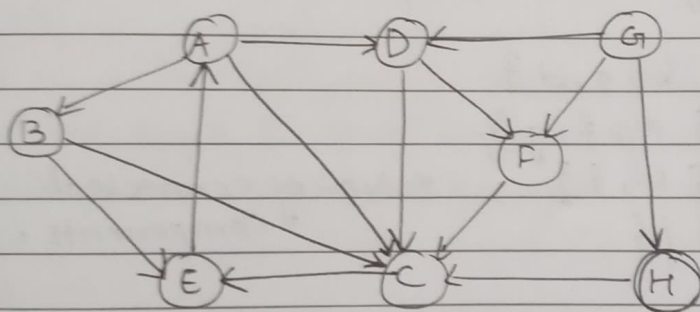
return

end if

$y.\text{parent} = x$

$x.\text{size} = x.\text{size} + y.\text{size}$

end function.

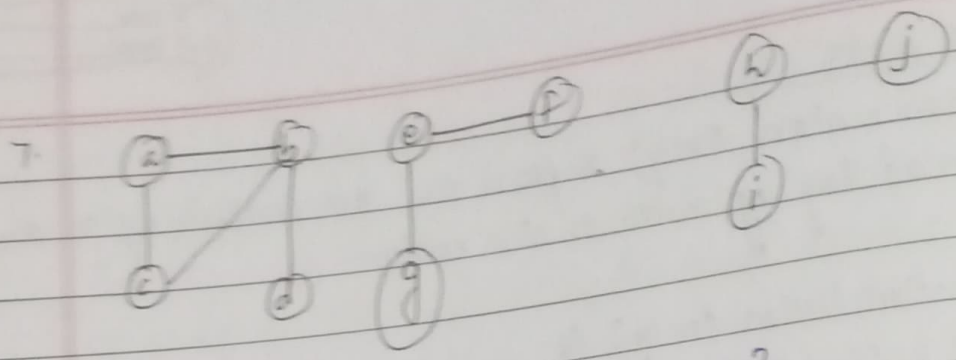


using BFS

Node	B	E	C	A	D	F
parent	-1	B	B	E	A	D

DFS

B	E	A	D	F	C
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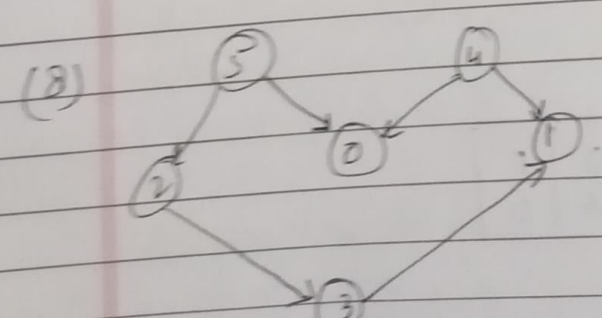


$U = \{a, b, c, d, e, f, g, h, i, j\}$
 Now make find and union operation will be performed.

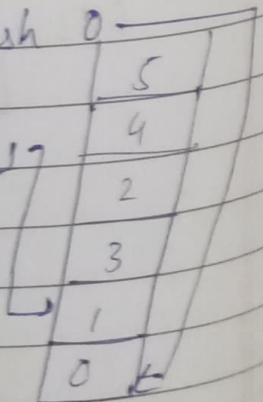
- First each vertex will be parent of itself.
- If an edge exists between vertices, then we perform find operation & check if their parents are same & perform union operation on them.

- $S_1 = \{a, b, c, d\}$
- $S_2 = \{e, f, g\}$
- $S_3 = \{h, i\}$
- $S_4 = \{j\}$

* No. of connected components = 3



topo sort (0)
 As we cannot visit any other node push 0
 topo sort (1)
 we cannot visit any other node push 1
 topo sort (2) - topo sort (3)
 first push 3 then 2
 topo sort (4)
 push 4 to stack



topoSort(5)

push 5 to stack as other are visited

$\therefore 5 \quad 4 \quad 2 \quad 3 \quad 1 \quad 0$

- (a) We can use heaps to implement the priority queue. It will take $O(\log N)$ time to insert & delete each element in priority queue.

Based on heap structure, priority queue has also two types Max Priority & Min-Priority

Some algorithms we need to use Priority queue

(i) Dijkstra's

It is used in calculating shortest path in the algorithm when the graph is stored in form of adjacency list a matrix priority queue can be used to extract efficient.

(ii) Prims

It is used to implement Prims' algo to store key of nodes & extract minimum key node at every step.

(iii) Data Compression

It is used in Huffman's coding which is used to compress data.

10

Min Heap

In a minheap the key present at root must be less than or equal to among the key present at all of its children.

- The minimum key element is present at the root.

• Uses ascending priority.

Here the smallest element has a priority.

• The smallest element is to be popped from heap.

Max heap

In a max heap the key present at the root node must be greater than or equal to among the keys present at all of its children.

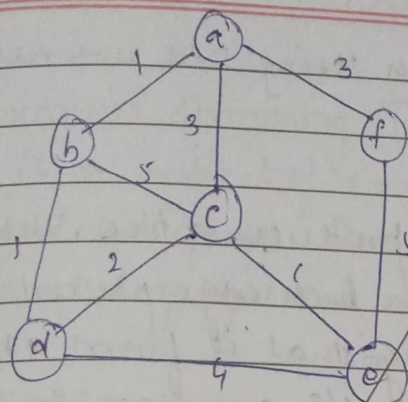
The maximum key element is present at root.

- Uses descending priority.

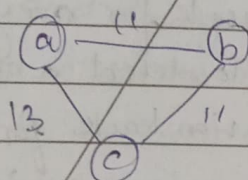
• Here the largest element has a priority.

• The largest element is to be popped from heap.

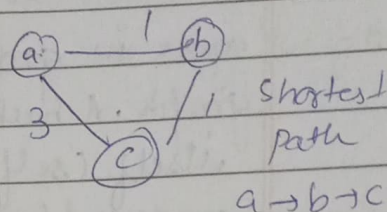
(4)



If we add 10:



If we add the weight of the graph by 10, YES the shortest path can change then consider.



Shortest path
 $a \rightarrow c$

There is no change in the

Q. 4th How can you detect a cycle in a graph using BFS and DFS?
For Detecting cycle in a graph using BFS we need to use Kahn's algorithm for Topological Sorting.

- 1) Compute in-degree (no. of incoming edge) for each of vertex present in graph & initialize count of visited node as 0.
- 2) Pick all vertices with in-degree as 0 and add them in a queue.
- 3) Remove a vertex from queue and then
 - increment count of visited node by 1.
 - Decrease in-degree by 1 for all the neighbouring
 - If in-degree of neighbouring nodes is reduced to 0 then add queue.
- 4) Repeat (3) until queue is empty.
- 5) If count of visited node is not equal to no. of nodes in a graph has cycle otherwise not.

For Detecting cycle in graph using DFS we need to do following:

DFS for a connected graph produces a tree. There is cycle in graphs if there is a back edge present in the graph. A back edge is an edge that is from a node to itself (self-loop) or one of its ancestors in the tree produced by DFS. For a disconnected graph get DFS forest as output. To detect cycle check for a cycle in individual trees by checking back edges. To detect a back edge, keep track of vertices currently in recursion stack for DFS traversal. If a vertex is reached that is already in recursion stack then there is a cycle.