Akanksha Murali

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EDUCATION

New York University, Tandon School of Engineering - New York

May 2025

Master of Science in Mechatronics, Robotics and Automation Engineering

Relevant Coursework: Deep Learning & Robot Perception, Reinforcement Learning & Optimal Control for Robotics

PES University - Bangalore, India

May 2023

Bachelor of Technology in Electronics and Electrical Engineering

Relevant Coursework: Control Systems, Digital Image Processing, Neural Networks & Fuzzy Logic Systems

TECHNICAL SKILLS

Machine Learning: TensorFlow, PyTorch, Scikit-learn, Deep Learning, CNNs, RNNs, Reinforcement Learning

Computer Vision: OpenCV, Feature Matching, Object Detection, Visual Odometry, SLAM

Programming Languages: Python, C++, C, Java, HTML, SQL, Linux Bash

Data Engineering: Pandas, Spark, NumPy, ETL, Data Cleaning, SQL

Frameworks & Libraries: PyTorch, ROS Humble, OpenCV, SciPy, Pinocchio, Simulink, MATLAB Robotics Toolbox

Tools & Others: Git, Jira, LabVIEW, LPKF CircuitPro, KiCad, Overleaf

Relevent Experience

ModeliCon Infotech | Machine Learning & Simulation Engineer | Bangalore, India

Aug 2022 - Jun 2023

- Built an ML-based training simulator using Python, and Unity to replicate real-world diagnostic scenarios
- Engineered visual recognition pipelines and automated diagnostics, improving operational efficiency by 20%
- Collaborated in **Agile sprints**, emphasizing **clean code practices**, modular design, and version control

Nivetti Systems | Machine Learning Intern | Bangalore, India

Jan 2022 - Jul 2022

- Developed a distributed ROS2 software architecture for a robotic arm, incorporating mapping and motion planning nodes
- Improved system responsiveness by optimizing inter-process communication using ROS2 pub-sub and service calls
- Collaborated with a cross-functional engineering team, integrating C++ modules into a unified robotic control stack

Equinox PESU | Project Lead | Bengaluru, India

Mar 2021 - Jun 2021

- Led an 8-member engineering team to design a terrain-adaptive Mars rover prototype in collaboration with ISRO
- Developed CNN-based terrain classifiers and implemented sensor fusion for resilient autonomous navigation
- Simulated real-time path planning with A* and Dijkstra algorithms, optimizing mission-critical mobility

ACADEMIC PROJECTS

Hexapod | NYU Capstone Project | New York

Fall 2024 - Spring 2024

- Developed and optimized an MPC based control software for a 6-legged robot using Python
- Integrated real-time sensor feedback, applying PID and MPC algorithms for locomotion

Embodied AI Visual Navigation | NYU | New York

Fall 2024

- Designed a real-time ML pipeline for place recognition and target identification within 5 seconds
- Applied CNN-SVM hybrid models for obstacle classification and safe trajectory estimation generalizability

Robot Perception - NYU Course Project | NYU | New York

Fall 2024

- Engineered a vision system combining SIFT-based querying, plane fitting, and ICP alignment for spatial localization
- Integrated Aruco-based AR overlays and optical flow tracking to support dynamic object interaction

Robotic Arm for Mobile Payload Carrier | PES Capstone Project | Bangalore, India

Spring 2023

- Designed **embedded logic in C++** to control a robotic arm for multi-floor payload delivery
- Developed an elevator interface and floor recognition module, integrating ultrasonic and IR sensor data
- Created a user-friendly HMI interface using Arduino-based control software

Library Management System | PES | Bangalore, India

Summer 2022

- Built a modular library management system using Flask, SQL, and JavaScript, featuring user authentication and role-based access
- Designed a responsive UI structure to handle real-time book inventory and user transactions

LEADERSHIP EXPERIENCE

Graduate Adjunct | NYU | New York

Summer 2024 - Summer 2025

- Mentored 220+ students in machine learning, algorithm design, and simulation frameworks
- Led hands-on labs and designed a **project-based ML course**, promoting STEM engagement through coding & prototyping